DSC 40A: Theoretical Foundations of Data Science

Lecture 13 Part II Feature engineering and data transformations

October 27, 2025

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- Prepare by practicing old exam problems on practice.dsc40a.com

Varun and Owen will be hosting a midterm review session this Thursday 10/30 from 5pm-7pm in **Ledden Auditorium** (near HSS/APM)

Stay tuned for further details via Campuswire

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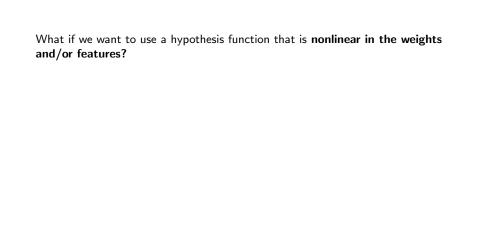
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Question: What do each of these have in common?

These are **all linear** in the weights w_i .



What if we want to use a hypothesis function that is nonlinear in the weights and/or features?



Example A nonlinear hypothesis function

Consider the following hypothesis function, which depends on a single scalar-valued feature and two weights w_0, w_1 :

$$H(x) = w_0 e^{w_1 x}.$$

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This function is **nonlinear** in both the weights and the feature x. We can create a new hypothesis function $T(x) = b_0 + b_1 x$, which is linear in the weights b_0 , b_1 , by applying the transformation

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The weights are related by the equations $b_0 = \ln(w_0)$ and $b_1 = w_1$.



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We will explore this example.	s in an interactive note	book, continuing fr	rom last week's



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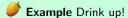


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You would like to model y_i , the liters of finished bottled product during week i, in terms of measurable quantities.



After discussing things with your in-house econometrics guru, you arrive at the following hypothesis function:

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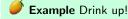
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= $\ln(w_0) + w_1 \ln(x^{(1)}) + w_2 \ln(x^{(2)}) + w_3 \ln(x^{(3)}).$



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where we have defined the transformed features

$$z^{(j)}=\ln(x^{(j)}),\quad j=1,2,3,$$
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Finally, we can recover the optimal weights for the original hypothesis via

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$$w_0^* = e^{b_0^*}, \ w_1^* = b_1^*,$$

 $w_2^* = b_2^*,$ $w_3^* = b_3^*.$

Note: unlike before, we need to transform our features as well as our

Question

Answer at q.dsc40a.com.

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Which of the following hypothesis functions is **not** linear in the parameters?

(A)
$$H(\vec{x}) = w_1(x^{(1)}x^{(2)}) + \frac{w_2}{x^{(1)}}\sin(x^{(2)})$$

(B)
$$H(\vec{x}) = 2^{w_1} x^{(1)}$$

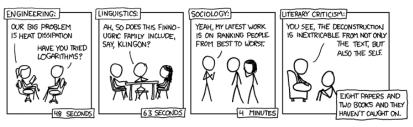
(C)
$$H(\vec{x}) = \vec{w} \cdot \text{Aug}(\vec{x})$$

(D)
$$H(\vec{x}) = w_1 \cos(x^{(1)}) + w_2 2^{x^{(2)} \log x^{(3)}}$$

(E) More than one of the above.

Have you tried using logarithms?

MY HOBBY:
SITTING DOWN WITH GRAD STUDENTS AND TIMING
HOW LONG IT TAKES THEM TO FIGURE OUT THAT
I'M NOT ACTUALLY AN EXPERT IN THEIR FIELD.



xkcd #451

Sometimes, it's just not possible to transform a hypothesis function to be li in terms of some parameters.	near

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$$R_{sq}(w_0, w_1) = \frac{1}{n} \sum_{i=1}^{n} (y_i - w_0 \sin(w_1 x))^2.$$

o One method: gradient descent, the topic of the next lecture!

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Hypothesis functions that are linear in the parameters are much easier to work with.

Roadmap
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- Now, we'll introduce gradient descent, a technique for minimizing functions that can't be minimized directly using calculus or linear algebra.
- o After the Midterm Exam, we'll switch gears to probability theory.

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Lecture 14 Part I Gradient Descent

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$$\frac{df}{dt}(t) = 5t^4 - t^3 - 5t^2 + 2t - 9$$

Then what?

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1 A /1

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