Lecture 3

Empirical Risk Minimization - mean absolute error

DSC 40A, Fall 2025

Agenda

- Recap: Mean squared error.
- Another loss function.
- Minimizing mean absolute error.



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Remember, you can always ask questions at q.dsc40a.com!

The modeling recipe

We've implicitly introduced a three-step process for finding optimal model parameters (like h^*) that we can use for making predictions:

1. Choose a model.

2. Choose a loss function.

3. Minimize average loss to find optimal model parameters.

Recap: Mean squared error

Minimizing using calculus

We'd like to minimize:

$$R_{ ext{sq}}(h) = rac{1}{n} \sum_{i=1}^n (y_i - h)^2$$

In order to minimize $R_{
m sq}(h)$, we:

- 1. take its derivative with respect to h,
- 2. set it equal to 0,
- 3. solve for the resulting h^* , and
- 4. perform a second derivative test to ensure we found a minimum.

Step 4: Second derivative test

$$R_{sq}(h) = \frac{1}{5} \left((72 - h)^2 + (90 - h)^2 + (61 - h)^2 + (85 - h)^2 + (92 - h)^2 \right)$$

$$\begin{array}{c} 700 - \\ 600 - \\ 500 - \\ 300 - \\ 200 - \\ \end{array}$$

We already saw that $R_{\rm sq}(h)$ is **convex**, i.e. that it opens upwards, so the h^* we found must be a minimum, not a maximum.

$$\frac{d^{2}}{dh^{2}} R_{sq}(h) = \frac{d}{dh} \left(\frac{2}{h} \sum_{i=1}^{n} (h - y_{i}) \right) = \frac{2}{h} \sum_{i=1}^{n} \frac{d}{dh} h = \frac{2}{h} \sum_{i=1}^{n} 1 = \frac{2}{h} \cdot n = 2 > 0$$

$$\frac{d^2}{d^2} R_{sy}(h) > 0 \implies h^* \text{ is a minimizer}$$

The mean minimizes mean squared error!

• The problem we set out to solve was, find the h^* that minimizes:

$$R_{ ext{sq}}(h) = rac{1}{n} \sum_{i=1}^n (y_i - h)^2$$

• The answer is:

$$h^* = \operatorname{Mean}(y_1, y_2, \dots, y_n)$$

- The **best constant prediction**, in terms of mean squared error, is always the **mean**.
- This answer is always unique!
- We call h^* our **optimal model parameter**, for when we use:
 - \circ the constant model, H(x)=h, and
 - \circ the squared loss function, $L_{
 m sq}(y_i,h)=(y_i-h)^2$.

Bonus: the mean is easy to compute

```
def mean(numbers):
    total = 0
    for number in numbers:
        total = total + number
    return total / len(numbers)
```

• Time complexity $\Theta(n)$

Aside: Notation

Another way of writing

$$h^*$$
 is the value of h that minimizes $\frac{1}{n}\sum_{i=1}^n (y_i-h)^2$

is

$$h^* = \mathop{
m argmin}_h \ \left(rac{1}{n} \sum_{i=1}^n (y_i - h)^2
ight)$$

 h^* is the solution to an **optimization problem**.

Another loss function

Another loss function

• Last lecture, we started by computing the **error** for each of our predictions, but ran into the issue that some errors were positive and some were negative.

$$e_i = y_i - H(x_i)$$

• The solution was to **square** the errors, so that all are non-negative. The resulting loss function is called **squared loss**.

$$L_{ ext{sq}}(\pmb{y}_i,\pmb{H}(\pmb{x}_i)) = (\pmb{y}_i - \pmb{H}(\pmb{x}_i))^2$$

• Another loss function, which also measures how far $H(x_i)$ is from y_i , is **absolute** loss.

$$L_{\mathrm{abs}}(\pmb{y_i},\pmb{H}(\pmb{x_i})) = |\pmb{y_i} - \pmb{H}(\pmb{x_i})|$$

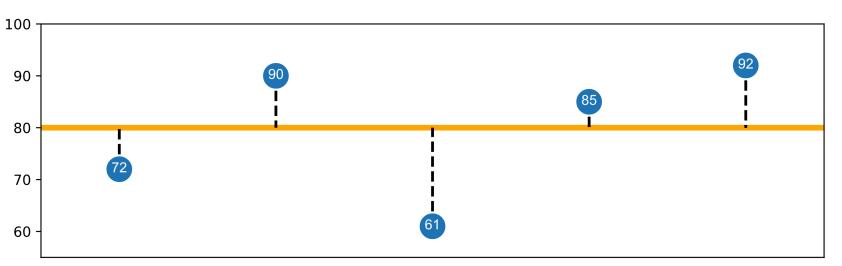
Squared loss vs. absolute loss

For the constant model, $H(x_i) = h$, so we can simplify our loss functions as follows:

- Squared loss: $L_{\mathrm{sq}}(\boldsymbol{y_i},\boldsymbol{h}) = (\boldsymbol{y_i} \boldsymbol{h})^2$.
- Absolute loss: $L_{\rm abs}(y_i, h) = |y_i h|$.

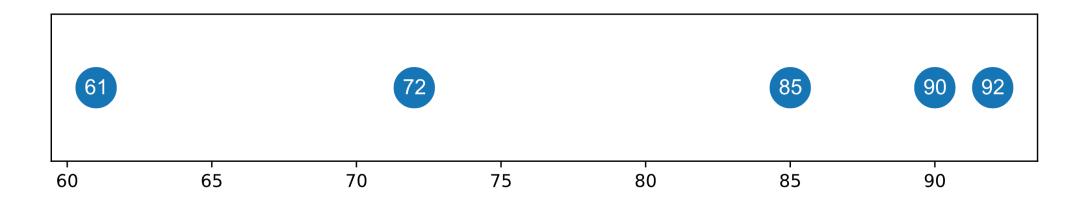
Consider, again, our example dataset of five commute times and the prediction h = 80.

$$y_1 = 72$$
 $y_2 = 90$ $y_3 = 61$ $y_4 = 85$ $y_5 = 92$



Squared loss vs. absolute loss

- When we use squared loss, h^* is the point at which the average **squared** loss is minimized.
- When we use absolute loss, h^* is the point at which the average **absolute** loss is minimized.



Mean absolute error

- Suppose we collect n commute times, y_1, y_2, \ldots, y_n .
- The <u>average</u> absolute loss, or <u>mean</u> absolute error (MAE), of the prediction h is:

$$R_{\mathrm{abs}}(h) = rac{1}{n} \sum_{i=1}^n |y_i - h|$$

- We'd like to find the best prediction, h^* .
- Previously, when using squared loss we used calculus to find the optimal model parameter h^* that minimized $R_{\rm sq}$.
- Can we use calculus to minimize $R_{
 m abs}(h)$, too?

Minimizing mean absolute error

Minimizing using calculus, again

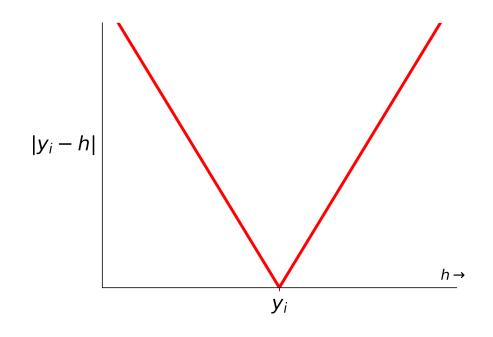
We'd like to minimize:

$$R_{\mathrm{abs}}(h) = rac{1}{n} \sum_{i=1}^n |y_i - h|$$

In order to minimize $R_{\rm abs}(h)$, we:

- 1. take its derivative with respect to h,
- 2. set it equal to 0,
- 3. solve for the resulting h^* , and
- 4. perform a second derivative test to ensure we found a minimum.

Step 0: The derivative of $|y_i - h|$



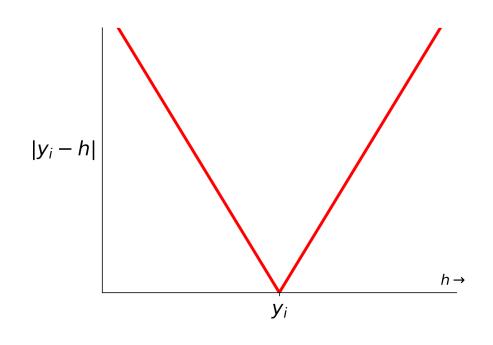
Remember that |x| is a piecewise linear function of x:

$$|x|=egin{cases} x & x>0 \ 0 & x=0 \ -x & x<0 \end{cases}$$

So, $|y_i - h|$ is also a piecewise linear function of h:

$$|y_i-h| = egin{cases} y_i-h & h < y_i \ 0 & y_i = h \ h-y_i & h > y_i \end{cases}$$

Step 0: The "derivative" of $|y_i - h|$



$$|y_i-h| = egin{cases} y_i-h & h < y_i \ 0 & y_i = h \ h-y_i & h > y_i \end{cases}$$

What is $rac{d}{dh}|y_i-h|$?

Step 1: The "derivative" of $R_{ m abs}(h)$

$$rac{d}{dh}R_{
m abs}(h) = rac{d}{dh}\left(rac{1}{n}\sum_{i=1}^n|y_i-h|
ight)$$

Question 🤔

Answer at q.dsc40a.com

The slope of $R_{
m abs}$ at h is

$$\frac{1}{n}[(\# \text{ of } y_i < h) - (\# \text{ of } y_i > h)]$$

Suppose that the number of points n is odd. At what value of h does the slope change from negative to positive?

- A) $h = \text{mean of } \{y_1, \dots, y_n\}$
- B) h = median of $\{y_1,\ldots,y_n\}$
- C) $h = \text{mode of } \{y_1, \dots, y_n\}$

Steps 2 and 3: Set to 0 and solve for the minimizer, h^{st}

The median minimizes mean absolute error!

• The new problem we set out to solve was, find the h^* that minimizes:

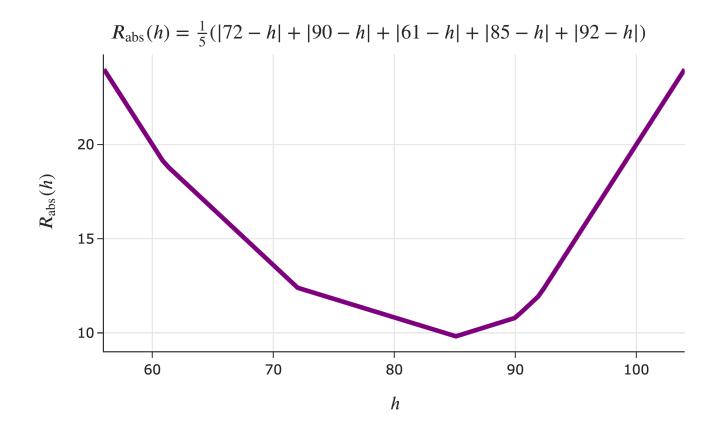
$$R_{\mathrm{abs}}(h) = rac{1}{n} \sum_{i=1}^n |y_i - h|$$

• The answer is:

$$h^* = \mathrm{Median}(y_1, y_2, \dots, y_n)$$

- This is because the median has an equal number of data points to the left of it and to the right of it.
- To make a bit more sense of this result, let's graph $R_{
 m abs}(h)$.

Visualizing mean absolute error



Consider, again, our example dataset of five commute times.

Where are the "bends" in the graph of $R_{\rm abs}(h)$ – that is, where does its slope change?

Question 🤔

Answer at q.dsc40a.com

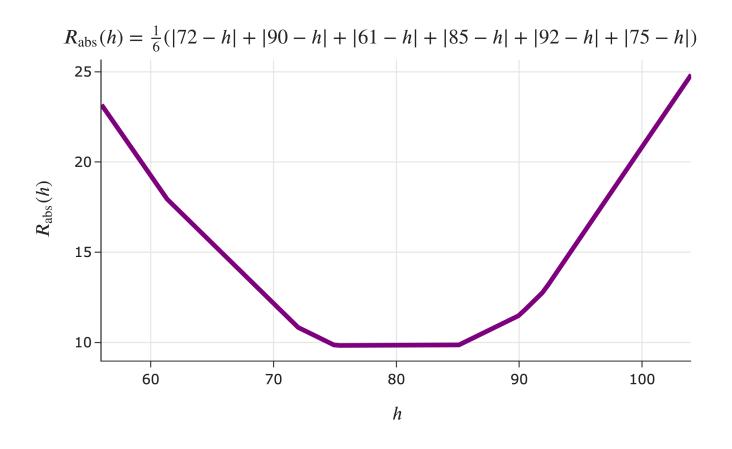
Consider, again, our example dataset of five commute times.

Suppose we add a sixth point so that our data is now

Which of the following correctly describes the h* that minimizes mean absolute error for our new dataset?

- A) 85 only
- B) 75 only
- C) 80 only
- D) Any value between 75 and 85 inclusive

Visualizing mean absolute error, with an even number of points



What if we add a sixth data point?

72, 90, 61, 85, 92, 75

Is there a unique h^* ?

The median minimizes mean absolute error!

• The new problem we set out to solve was, find the h^* that minimizes:

$$R_{\mathrm{abs}}(h) = rac{1}{n} \sum_{i=1}^n |y_i - h|$$

• The answer is:

$$h^* = \mathrm{Median}(y_1, y_2, \dots, y_n)$$

The best constant prediction, in terms of mean absolute error, is always the median.

- When *n* is odd, this answer is unique.
- When n is even, any number between the middle two data points (when sorted) also minimizes mean absolute error.
- ullet When n is even, define the median to be the mean of the middle two data points.

The modeling recipe, again

We've now made two full passes through our "modeling recipe."

1. Choose a model.

2. Choose a loss function.

3. Minimize average loss to find optimal model parameters.

Empirical risk minimization

- The formal name for the process of minimizing average loss is **empirical risk minimization**.
- Another name for "average loss" is **empirical risk**.
- When we use the squared loss function, $L_{sq}(y_i, h) = (y_i h)^2$, the corresponding empirical risk is mean squared error:

$$R_{ ext{sq}}(h) = rac{1}{n} \sum_{i=1}^n (y_i - h)^2$$

• When we use the absolute loss function, $L_{\rm abs}(y_i,h)=|y_i-h|$, the corresponding empirical risk is mean absolute error:

$$R_{
m abs}(h) = rac{1}{n} \sum_{i=1}^n |y_i - h|$$

Empirical risk minimization, in general

Key idea: If $L(y_i, h)$ is any loss function, the corresponding empirical risk is:

$$R(h) = rac{1}{n} \sum_{i=1}^n L(y_i,h)$$

Question 👺

Answer at q.dsc40a.com

What questions do you have?

Summary, next time

- $h^* = \operatorname{Mean}(y_1, y_2, \ldots, y_n)$ minimizes mean squared error, $R_{\operatorname{sq}}(h) = \frac{1}{n} \sum_{i=1}^n (y_i h)^2.$
- $h^*=\operatorname{Median}(y_1,y_2,\ldots,y_n)$ minimizes mean absolute error, $R_{\operatorname{abs}}(h)=rac{1}{n}\sum_{i=1}^n|y_i-h|.$
- $R_{\rm sq}(h)$ and $R_{\rm abs}(h)$ are examples of **empirical risk** that is, average loss.
- Next time: What's the relationship between the mean and median? What is the significance of $R_{\rm sq}(h^*)$ and $R_{\rm abs}(h^*)$?