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Education

SNU (Seoul National University)

Seoul, Korea

Ph.D. in Mechanical & Aerospace Engineering

September. 2021 - Present

• Research topics: "Deep Reinforcement Learning, Robotics, Generative Model, Machine Learning."

SNU (Seoul National University)

Seoul, Korea

M.S. IN MECHANICAL & AEROSPACE ENGINEERING

September. 2019 - Aug. 2021

• Thesis topic: "Dual-arm Manipulation Using Hierarchical Reinforcement Learning."

SNU (Seoul National University)

Seoul, Korea

B.S. IN MECHANICAL & AEROSPACE ENGINEERING

Mar. 2013 - Aug. 2019

• Thesis topic: "Dynamic Obstacle Removal in ORB-SLAM2 via CNN-based Object Detection."

Publication

Daesol Cho, Seungjae Lee and H. Jin. Kim. (2023). Diversify & Conquer: Outcome-directed Curriculum RL via Out-of-Distribution Disagreement, Neural Information Processing Systems (NeurIPS).

Seungjae Lee, Daesol Cho, Jonghae Park and H. Jin. Kim. (2023). CQM: Curriculum Reinforcement Learning with a Quantized World Model, Neural Information Processing Systems (NeurIPS).

Jigang Kim*, Daesol Cho* and H. Jin. Kim. (2023). Demonstration-free Autonomous Reinforcement Learning via Implicit and Bidirectional Curriculum, International Conference on Machine Learning (ICML).

Seungjae Lee, Jongho Shin, Hyeong-Geun Kim, Daesol Cho and H. Jin. Kim. (2023). Deep End-to-end Imitation Learning for Missile Guidance With Infrared Images, International Journal of Control, Automation and Systems (IJCAS).

Daesol Cho*, Seungjae Lee* and H. Jin. Kim. (2023). [Spotlight] Outcome-Directed Reinforcement Learning by Uncertainty & Temporal Distance-Aware Curriculum Goal Generation, International Conference on Learning Representations (ICLR).

Daesol Cho*, Dongseok Shim* and H. Jin. Kim. (2022). S2P: State-conditioned Image Synthesis for Data Augmentation in Offline Reinforcement Learning", Neural Information Processing Systems (NeurIPS).

Jigang Kim, J. hyeon Park, Daesol Cho and H. Jin. Kim. (2022). [presented in ICRA 2023] Automating Reinforcement Learning With Example-Based Resets, IEEE Robotics and Automation Letters (RA-L).

Daesol Cho, Jigang Kim and H. Jin. Kim. (2022). [presented in IROS 2022] Unsupervised Reinforcement Learning for Transferable Manipulation Skill Discovery, IEEE Robotics and Automation Letters (RA-L).

Honors & Awards & Scholarships_

| 2023 | Youlchon AI Young Researcher Fellowship |
|-----------|---|
| 2022-2023 | Brain Korea 21 Plus (BK21+) Ph.D Fellowship Scholarship |
| 2022 | Lecture & Research Scholarship |
| 2019 | Summa Cum Laude, Seoul National University |
| 2017-2018 | National Scholarship for Science and Engineering |
| 2017-2018 | System Technology Excellence Foundation (STX Foundation) Domestic Scholarship |
| 2013-2014 | National Scholarship for Academic Excellence |

Experience

^{*} indicates equal contribution.

Deepest, SNU deep learning society

Seoul, Korea

Research Group Project Leader, Member September. 2021 - August. 2022

- · Conduct an offline RL project.
- Attend Kaggle on Kore 2022 challenges (Top 11% in competition).

Projects

Transfer of Driving Dynamics Parameter between Car Models

Seoul, Korea

April. 2022 - Present

PROJECT LEADER

Hyundai Motor Company

Transfer Learning for Multi-agent Systems

Seoul, Korea

October. 2019 - October. 2021

MEMBERAgency for Defense Development

BabyMind: Infant-Mimic Developmental Machine Learning

Seoul, Korea

April. 2019 - December. 2020

Korea Ministry of Science and ICT

RL Application of an A/C Unit via Domain Randomization

Seoul, Korea

August. 2019 - November. 2020

LG Electronics

MEMBER

Academic Activities

2023-2024 Reviewer (NeurIPS, ICML, ICRA, IROS).

Hyundai Motors and LG Group AI Boosting Camp (AIBC) Reinforcement Learning Instructor.

Teaching Assistant at Seoul National University (Aerospace Engineering Experiment).

Teaching Assistant at Seoul National University (Introductory Engineering Probability).

2019 Tutor at Seoul National University (Basic Calculus).

Skills_

Programming Python, PyTorch, Tensorflow, Matlab, C/C++, LaTeX

Languages Korean, English