

MACHINE LEARNING, ROBOTICS RESEARCHER

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Education

SNU (Seoul National University)

Seoul, Korea

Ph.D. IN MECHANICAL & AEROSPACE ENGINEERING

September. 2021 - Present

• Research topics: "Deep Reinforcement Learning, Robotics, Generative Model, Machine Learning."

SNU (Seoul National University)

Seoul, Korea

M.S. IN MECHANICAL & AEROSPACE ENGINEERING

September. 2019 - Aug. 2021

• Thesis topic: "Dual-arm Manipulation Using Hierarchical Reinforcement Learning."

SNU (Seoul National University)

Seoul, Korea

B.S. IN MECHANICAL & AEROSPACE ENGINEERING

Mar. 2013 - Aug. 2019

• Thesis topic: "Dynamic Obstacle Removal in ORB-SLAM2 via CNN-based Object Detection."

Publication

Daesol Cho, Jigang Kim and H. Jin. Kim. (2024). Boosting Autonomous Reinforcement Learning via Action-Free Video and Plasticity Preservation, Robotics: Science and Systems (RSS) workshop.

Daesol Cho, Seungjae Lee and H. Jin. Kim. (2023). Diversify & Conquer: Outcome-directed Curriculum RL via Out-of-Distribution Disagreement, Neural Information Processing Systems (NeurIPS).

Seungjae Lee, **Daesol Cho**, Jonghae Park and H. Jin. Kim. (2023). CQM: Curriculum Reinforcement Learning with a Quantized World Model, Neural Information Processing Systems (NeurIPS).

Jigang Kim*, **Daesol Cho*** and H. Jin. Kim. (2023). Demonstration-free Autonomous Reinforcement Learning via Implicit and Bidirectional Curriculum, International Conference on Machine Learning (ICML), IROS 2023 workshop

Seungjae Lee, Jongho Shin, Hyeong-Geun Kim, **Daesol Cho** and H. Jin. Kim. (2023). Deep End-to-end Imitation Learning for Missile Guidance With Infrared Images, International Journal of Control, Automation and Systems (IJCAS).

Daesol Cho*, Seungjae Lee* and H. Jin. Kim. (2023). [Spotlight] Outcome-Directed Reinforcement Learning by Uncertainty & Temporal Distance-Aware Curriculum Goal Generation, International Conference on Learning Representations (ICLR).

Daesol Cho*, Dongseok Shim* and H. Jin. Kim. (2022). S2P: State-conditioned Image Synthesis for Data Augmentation in Offline Reinforcement Learning", Neural Information Processing Systems (NeurIPS).

Jigang Kim, J. hyeon Park, **Daesol Cho** and H. Jin. Kim. (2022). [presented in ICRA 2023] Automating Reinforcement Learning With Example-Based Resets, IEEE Robotics and Automation Letters (RA-L).

Daesol Cho, Jigang Kim and H. Jin. Kim. (2022). [presented in IROS 2022] Unsupervised Reinforcement Learning for Transferable Manipulation Skill Discovery, IEEE Robotics and Automation Letters (RA-L).

Projects_____

Transfer of Driving Dynamics Parameter between Car Models

Seoul, Korea

PROJECT LEADER

April. 2022 - Present

Hyundai Motor Company

Seoul, Korea

RESEARCHER
Agency for Defense Development

October. 2019 - October. 2021

BabyMind: Infant-Mimic Developmental Machine Learning

Transfer Learning for Multi-agent Systems

Seoul, Korea

RESEARCHER

April. 2019 - December. 2020

Korea Ministry of Science and ICT

July 10, 2024 Daesol Cho · Curriculum Vitae

^{*} indicates equal contribution.

August. 2019 - November. 2020

RESEARCHER LG Electronics

Experience

Deepest, SNU deep learning society

Seoul, Korea

September. 2021 - August. 2022

RESEARCH GROUP PROJECT LEADER, RESEARCHER

- Conduct an offline RL project.
- Attend Kaggle on Kore 2022 challenges (Top 11% in competition).

Honors & Awards & Scholarships _____

2023	Youlchon AI Young Researcher Fellowship
2022-2023	Brain Korea 21 Plus (BK21+) Ph.D Fellowship Scholarship
2022	Lecture & Research Scholarship
2019	Summa Cum Laude, Seoul National University
2017-2018	National Scholarship for Science and Engineering
2017-2018	System Technology Excellence Foundation (STX Foundation) Domestic Scholarship
2013-2014	National Scholarship for Academic Excellence

Academic Activities _____

2023-2024	Reviewer (NeurIPS, ICML, ICRA, IROS).
2023	Hyundai Motors and LG Group Al Boosting Camp (AIBC) Reinforcement Learning Instructor.
2020-2021	Teaching Assistant at Seoul National University (Aerospace Engineering Experiment).
2019	Teaching Assistant at Seoul National University (Introductory Engineering Probability).
2019	Tutor at Seoul National University (Basic Calculus).

Skills_____

Programming Python, PyTorch, Tensorflow, Matlab, C/C++, LaTeX

Languages Korean, English