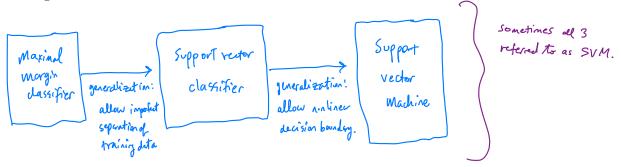
# Chapter 9: Support Vector Machines

/ Categorical response.

The *support vector machine* is an approach for classification that was developed in the computer science community in the 1990s and has grown in popularity.

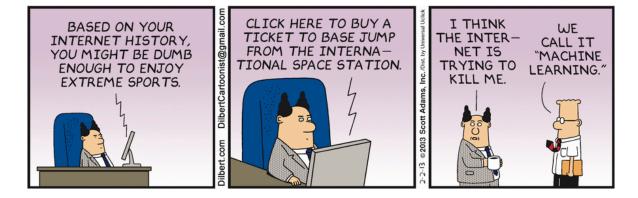
The support vector machine is a generalization of a simple and intuitive classifier called the *maximal margin classifier*.



Support vector machines are intended for binary classification, but there are extensions for more than two classes.

Cutegorical response

W/ only 2 classes.



Credit: https://dilbert.com/strip/2013-02-02

# Maximal Margin Classifier | based on a hyperplane seperator.

In p-dimensional space, a hyperplane is a flat affine subspace of dimension p-1.

e.g. In 2 dimensions a hyperplane is a flat 1 dimensional subspace. - line.
In 3 dimensions, a hyperplane is a flat 2 dimensional subspace - plane.

In p 73 dimension, hardor the visualize, but \$11 a flat p-1 directional subspace. The mathematical definition of a hyperplane is quite simple,

In 2 dimensions, a hyperplan is refined by 
$$\frac{1}{2}$$
 of  $\frac{1}{2}$ ,  $\frac{1}{2}$ ,  $\frac{1}{2}$ ,  $\frac{1}{2}$ ,  $\frac{1}{2}$ 

This can be easily extended to the p-dimensional setting.

$$\beta_0 + \beta_1 X_1 + ... + \beta_p X_p = 0$$
 defines a p-dim hyperplane.

We can think of a hyperplane as dividing p-dimensional space into two halves.

If 
$$\beta_0 + \beta_1 \times_1 + ... + \beta_p \times_p > 0$$
 then  $\underline{X} = (x_1,...,x_p)$  lies on one side of the hyperplace.  
 $\beta_0 + \beta_1 \times_1 + ... + \beta_p \times_p < 0$  then  $\underline{X} = (x_{11},...,x_p)$  lies on other side of the hyperplace.

You can determine which side of the hyperplane by just determining the sign of 
$$\beta$$
 of  $\beta$ ,  $\chi$ ,  $+\dots+$   $\beta$ ,  $\chi$ , ...

### 1.1 Classification Using a Separating Hyperplane

Suppose that we have a  $n \times p$  data matrix X that consists of n training observations in p-dimensional space.

$$\frac{\chi}{\chi_{(p)}} = \begin{pmatrix} \chi_{(1)} \\ \vdots \\ \chi_{(p)} \end{pmatrix} \qquad \qquad \chi_{n} = \begin{pmatrix} \chi_{n_1} \\ \vdots \\ \chi_{n_p} \end{pmatrix}$$
trainly observations.

and that these observations fall into two classes.

We also have a test observation.

$$x^* = (x_1^*, ..., x_p^*)^T$$
 p-vector of observed features.

Our Goal: Develop a classifier based on training data that will correctly classify the test observation based on feature weasurements.

Suppose it is possible to construct a hyperplane that separates the training observations perfectly according to their class labels.

separating hyperplane

Then a separating hyperplane has the property that

$$\beta_0 + \beta_1 x_{i_1} + \dots + \beta_p x_{ip} > 0 \iff \gamma_i = 1 \text{ and}$$

$$\beta_0 + \beta_1 x_{i_1} + \dots + \beta_p x_{ip} < 0 \iff \gamma_i = 1$$

$$\iff \gamma_i \left( \beta_0 + \beta_i x_{i_1} + \dots + \beta_p x_{ip} \right) \geq 0 \quad \forall i = 1, \dots, n.$$

If a separating hyperplane exists, we can use it to construct a very natural classifier:

That is, we classify the test observation  $x^*$  based on the sign of  $f(x^*) = \beta_0 + \beta_1 x_1^* + \cdots + \beta_p x_p^*$ .

If 
$$f(x^*) > 0$$
 assign  $x^*$  to class 1  
If  $f(x^*) < 0$  assign  $x^*$  to class -1.

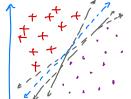
We can also use the magnitude of  $f(x^*)$ .

If 
$$f(x^*)$$
 is far from zero, thus mens  $x^*$  lies for from the hyperplane.  
 $\Rightarrow$  we can be confident about our class assignment for  $x^*$ .  
If  $f(x^*)$  is close to zero, this means  $x^*$  is located near the hyperplane  $\Rightarrow$  we are less sure about class assignment.

Note: a classifier based on a separatily hyperplane leads to a linear decision boundary

### 1.2 Maximal Margin Classifier

If our data cab be perfectly separated using a hyperplane, then there will exist an infinite number of such hyperplanes.

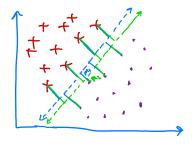


a given separating bypurpline can be shifted a fing bit or rotated without which one to carry into contect u/ any observations. Use for our classifier?

A natural choice for which hyperplane to use is the *maximal margin hyperplane* (aka the *optimal separating hyperplane*), which is the hyperplane that is farthest from the training observations.

- We compute the perpudicular distance from each observation to a given separating hyperplane
- the smallest distance is known as the margin.

The maximal magin hyperplane is the one / largest margin, i.e. furthest from all training data points.



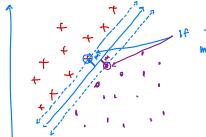
M2 < M1 ⇒ blue hyperplane larger magin.

>> blue is my preferred hyperplane.

We can then classify a test observation based on which side of the maximal margin hyperplane it lies – this is the *maximal margin classifier*.

- hopefully a large margin or training data will lead to a large margin on test data > classify test data correctly.

- When p is large, overtrating with occur.



these point mores the meximal maps as well.

Support rectors because they
are p-dim vectors that
"Support" the hyperplane

NOTE: the maximal weight hyperplane only depends on the support rectors!

The rest of the posts can more and it doesn't matter.

We now need to consider the task of constructing the maximal margin hyperplane based on a set of n training observations and associated class labels.

The maximal margin hyperplane is the solution to the optimization problem

The aximize 
$$M = M^2$$
 magners  $M = M^2$  aximize  $M = M^2$  subject the  $\sum_{j=1}^{p} \beta_j^2 = 1^2$  
$$\text{Wi} \left( \beta_0 + \beta_1 x_{i_1} + ... + \beta_p x_{i_p} \right) \geq M \quad \forall i = 1,...,n. \text{ }$$

- 3) means each observation will be on the correct side of the hyperplane (MZO) with some cushion (if MZO).
- a cusure of ( $\beta_0 + \beta_1 X_{i_1} + \dots + \beta_p X_{ip}$ ) is perp. distance to hyperplane and (3) means the point  $X_i$  is at least M distance away => M is the margin.
- 1) chooses po, -, pp, M to maximize the mergin.

This problem can be solved efficiently, but the details are outside the scope of this course.

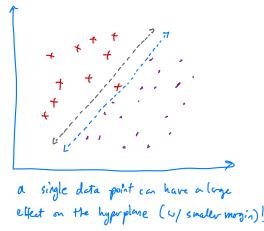
What happens when no separating hyperplane exists?

# 2 Support Vector Classifiers

It's not always possible to separate training observations by a hyperplane. In fact, even if we can use a hyperplane to perfectly separate our training observations, it may not be desirable.

A chasafter based on a sperfectly superating hyperplane will perfectly classify all training observations.

This can lead to prosensitivity to individual objectations (overfitting).



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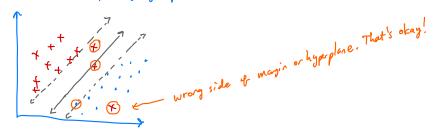
We might be willing to consider a classifier based on a hyperplane that does <u>not perfectly</u> separate the two classes in the interest of

- · greater robustness to individual observations
- · proper classification of most of the training observations

i.e. it might be worthwile to unissclussify a few training observations to do a beller gob classifying the lest data.

The *support vector classifier* does this by finding the largest possible margin between classes, but allowing some points to be on the "wrong" side of the margin, or even on the "wrong" side of the hyperplane.

Lywhen there is no separating hyperplace this is inentable.



The support vector classifier classifies a test observation depending on which side of the hyperplane it lies. The hyperplane is chosen to correctly separate **most** of the training observations.

Solution to the following optimization problem:

Maximize M

[Bo,..., Bo) 
$$\epsilon_1,...,\epsilon_n$$
, M

Subject to

$$\sum_{i=1}^{p} p_i^2 = 1$$

$$\gamma_i \left( \beta_0 + \beta_i x_{i1} + ... + \beta_p x_{ip} \right) \geq M \left( 1 - \epsilon_i \right)$$

$$\epsilon_i \geq 0 , \quad \sum_{i=1}^{n} \epsilon_i \leq C$$

I nonnegative tuning parameter

"slack variables"

(budget for how every we are withing to be on training data).

allow observations to be on the wrong side of the margin (or hyperplane).

Once we have solved this optimization problem, we classify  $x^*$  as before by determining which side of the hyperplane it lies.

classify 
$$x^*$$
 based on sign of  $f(x^*) = \beta_0 + \beta_1 x^* + ... + \beta_p x^*_p$ .

$$\epsilon_i$$
 - tell us where the training obsertion lies relative to hyperplane and magning if  $\epsilon_i$  = 0 => obs. In correct side of the magnin  $\epsilon_i$  = 0 >> obs. on wrong side of the magnin (violated magnin)  $\epsilon_i$  => obs. on wrong side of hyperplane.

$$C$$
 - tuning parameter, bounds the sum of  $\mathcal{E}_i$ 's  $\Rightarrow$  determines  $\#$  and serving of violations we will allow.   
think of  $C$  as a budget for amount of violations.

If  $C=0\Rightarrow$  no budget for violations  $\Rightarrow$   $\mathcal{E}_p=...=\mathcal{E}_n=0\Rightarrow$  SV classifier  $=$  maximal magnin dessifier.

If  $C \Rightarrow 0\Rightarrow$  no were then  $C$  obs. can be on the waving side of the hyperplane.

because  $\mathcal{E}_i \Rightarrow 1$  and  $\sum_{i=1}^n \mathcal{E}_i \Rightarrow C$ .

Small C => narrow margins, large C => wider, allow more violations. lors-various tradeoff.

The optimization problem has a very interesting property.

Observations that lie directly on the margin or on the wrong side of the margin are called support vectors.

These observations do offert the classifier.

The fact that only support vectors affect the classifier is in line with our assertion that C controls the bias-variance tradeoff.

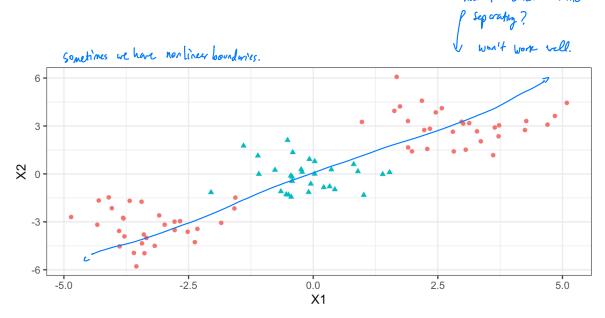
Because the support vector classifier's decision rule is based only on a potentially small subset of the training observations means that it is robust to the behavior of observations far away from the hyperplane.

distinct from Inhanior of other classifier methods.

e.g. LDA depends on mem of observations with in each class I within class coverience within

# 3 Support Vector Machines

The support vector classifier is a natural approach for classification in the two-class setting... if the decision borndary is linear!



We've seen ways to handle non-linear classification boundaries before.

In the case of the support vector classifier, we could address the problem of possible non-linear boundaries between classes by enlarging the feature space.

Then our optimization problem would become

Maximize M

Popa, ..., 
$$\beta_{1p}$$
,  $\beta_{21}$ , ...,  $\beta_{2p}$ ,  $\epsilon_{13}$ ,  $\epsilon_{n}$ ,  $\epsilon_{n}$ .

Subject to

$$\sum_{j=(k=1)}^{2} \frac{2}{\beta_{kj}} = 1$$

$$y_{i} \left(\beta_{0} + \sum_{j=1}^{p} \beta_{1j} x_{ij} + \sum_{j=1}^{p} \beta_{2j} x_{ij}^{2}\right) \geq M((-\epsilon_{i}))$$

$$\epsilon_{i} \geq 0, \quad \sum_{i=1}^{n} \epsilon_{i} \leq C.$$

could consider higher order forms or other functions.

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using "Komels"

The support vector machine allows us to enlarge the feature space used by the support classifier in a way that leads to efficient computation.

It turns out that the solution to the support vector classification optimization problem involves only inner products of the observations (instead of the observations themselves).

inner product: 
$$\langle a,b \rangle = \sum_{i=1}^{n} a_i b_i^*$$
  
inner product of two training obs:  $\langle x_i, x_{i'} \rangle = \sum_{j=1}^{p} x_{ij} x_{i'j}$ 

It can be shown that

• The (linear) support rector classifier can be written as 
$$f(x) = \beta_0 + \sum_{i=1}^{n} \alpha_i^i \langle x, x_i \rangle \qquad \alpha_i^i, i=1,...,n \text{ additional parameters.}$$

• To estimate 
$$\alpha_1,...,\alpha_n$$
 and  $\beta_0$  need  $\binom{n}{2} = \frac{n(n-1)}{n_1 n_2 n_3}$  between all training observations.

=> rewrite 
$$f(x) = \beta_0 + \sum_{i \in S} q_i(x_i, x_i)$$
  $S = indices of support vectors.$ 

Now suppose every time the inner product shows up in the SVM representation above, we replaced it with a generalization.

e.g. 
$$K(X_i, X_{i'}) = \sum_{j=1}^{p} X_{ij} X_{i'j}$$
 results in support restor classifier "linear kernel" ble linear boundary.

$$K(X_i, X_{i'}) = \left(1 + \sum_{j=1}^{p} X_{ij} X_{i'j}\right)^{d} = \text{pos. integer}$$

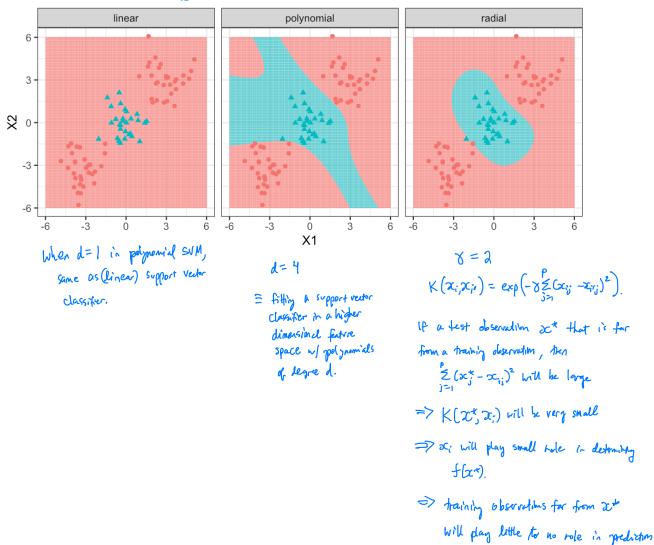
"polynomial kernel"

$$K(X_i, X_{i'}) = \exp\left(-\chi \int_{j=1}^{p} (X_{ij} - X_{i'j})^2\right)$$

"radial kernel"

pos. constant

$$S(x) = \beta_0 + \sum_{i \in S} d_i K(x, x_i).$$



Why use a kernel instead of enlarging feature space using functions of features?

- computation only need to amounte K(I; I; I) at district pairs i, i'

- don't have to explicitly workin enlarged space

Comey he too large to compute hyperplane).

- radial Kernel = enlarged feature space is infinite dimensional!

## 4 SVMs with More than Two Classes

So far we have been limited to the case of binary classification. How can we exted SVMs to the more general case with some arbitrary number of classes?

#### Two popular options:

Suppose we would like to perform classification using SVMs and there are K > 2 classes.

#### One-Versus-One

- (1) Construct (2) SUMS, each comparing a pair of classes
- 2) Classify a fest observation using each of the (K) SVMs
- 3) Assign test observation to class it was most frequently assigned to.

One-Versus-All let 2\* be a fest observation.

- 1) Fit K SVMs company each class to remaining K-1 classes
- (2) assign X\* to class for which Box + BIXX\* + ... + Box Xp\* is largest.

  (results in high level of confidence test observation belongs to km class over any offer).