Robotic Flagpole

Advisor: David Thompson

Project Goal:

Create a flagpole that utilizes pneumatic systems to make a flag appear as if it were blowing in the wind in an indoor environment

Challenges:

- Location: This is a large art structure, so finding a permanent placement is important
- Sound: Using an air compressor at all times is very loud, so sound dampening is a key goal
- Funding: Components for the flagpole and the related systems can be very expensive, which limits how functional our system is without funds

Results:

- Designed two different flagpole models, one with underground air compressor for noise suppression and one with above ground that is easier to move
 - Created three programs to simultaneously run on three
 PLCs to control air flow
 - Talked to multiple different sources regarding funding and flagpole locations

Figure 1: Flagpole CAD Models

Daniel Sennett (CS)

Daniel Blosser (ME)

Alex Adamsky
(ME)



Technologies:



Figure 2:
Interface Cad
Model





