// connect motor controller pins to Arduino digital pins

// Linear Actuator

int LIN\_enA = 39;

int LIN\_in1 = 37;

int LIN\_in2 = 35;

// Right Back - Motor A

int RB\_enA = 22;

int RB\_in1 = 24;

int RB\_in2 = 26;

// Right Front- Motor B

int RF\_enB = 32;

int RF\_in3 = 28;

int RF\_in4 = 30;

// Left Back - Motor B

int LB\_enA = 33;

int LB\_in1 = 31;

int LB\_in2 = 29;

// Left Front- Motor A

int LF\_enB = 23;

int LF\_in3 = 27;

int LF\_in4 = 25;