// connect motor controller pins to Arduino digital pins

// Linear Actuator - A

int LIN\_enB = 46;

int LIN\_in3 = 50;

int LIN\_in4 = 48;

// Left front - Motor - A

int LF\_enA = 2;

int LF\_in1 = 3;

int LF\_in2 = 4;

// Left Back- Motor B

int LB\_in3 = 5;

int LB\_in4 = 6;

int LB\_enB = 7;

// Right Front- Motor B

int RF\_enB = 8;

int RF\_in4 = 9;

int RF\_in3 = 10;

// Right Back - Motor A

int RB\_in2 = 11;

int RB\_in1 = 12;

int RB\_enA = 13;