

# Derivation of 4th Order Runge-Kutta Method

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Consider the initial value problem given by

$$\begin{cases} y'(t) &= f(t, y(t)) \\ y(t_0) &= y_0 \end{cases}$$

for a function Lipschitz continuous function  $f$ . To approximate the solution  $y(t)$ , the Runge-Kutta method uses an intermediate  $y$  value to enhance the approximation of each successive approximation  $y_k \approx y(t_k)$  as

$$\begin{aligned} \tilde{y}_{k+\alpha} &= y_k + \alpha h f(t_k, y_k) \\ \tilde{y}_{k+\delta} &= y_k + \delta h f(t_k, y_k) \\ y_{k+1} &= y_k + \beta h f(t_k, y_k) + \gamma h f(t_k + \alpha h, \tilde{y}_{k+\alpha}) + \eta h f(t_k + \delta h, \tilde{y}_{k+\delta}) \end{aligned}$$

for some  $\alpha, \beta, \gamma, \delta$ , and  $\eta$  that must be consistent with the Taylor expansion of  $y' = f$ . Define  $f_y$  and  $f_t$  as the partial derivatives of  $f$  with respect to  $y$  and  $t$  respectively. Moreover, since  $f$  is continuously differentiable, the mixed partials of  $f$  are equivalent. Then the chain rule and Taylor's theorem gives us

$$\begin{aligned} f(t_k + \alpha h, \tilde{y}_{k+\alpha}) &= f(t_k + \alpha h, y_k + \alpha h f(t_k, y_k)) \\ &= f(t_k, y_k) + \alpha h [f_t + f f_y] + \frac{(\alpha h)^2}{2} [f_{tt} + f f_{ty} + f^2 f_{yy}] + \mathcal{O}(h^3) \end{aligned}$$

as  $\alpha$  is arbitrary this also holds for  $f(t_k + \delta h, \tilde{y}_{k+\delta})$ . Thus the iterative step for  $y_{k+1}$  is given by

$$\begin{aligned} y_{k+1} &= y_k + \beta h f(t_k, y_k) + \gamma h f(t_k + \alpha h, \tilde{y}_{k+\alpha}) + \eta h f(t_k + \delta h, \tilde{y}_{k+\delta}) \\ &= \beta h f(t_k, y_k) + \gamma h \left( f(t_k, y_k) + \alpha h [f_t + f f_y] + \frac{(\alpha h)^2}{2} [f_{tt} + f f_{ty} + f^2 f_{yy}] \right) \\ &\quad + \eta h \left( f(t_k, y_k) + \delta h [f_t + f f_y] + \frac{(\delta h)^2}{2} [f_{tt} + f f_{ty} + f^2 f_{yy}] \right) + \mathcal{O}(h^3) \end{aligned}$$

Moreover, the Taylor expansion of the actual solution  $y(t_{k+1})$  is given by

$$\begin{aligned} y(t_{k+1}) &= y(t_k) + h y'(t_k) + \frac{h^2}{2} y''(t_k) + \frac{h^3}{6} y'''(t_k) + \frac{h^4}{24} y^{(4)}(t_k) + \frac{h^5}{120} y^{(5)}(t_k) + \mathcal{O}(h^6) \\ &= y(t_k) + h f + \frac{h^2}{2} [f_t + f f_y] + \frac{h^3}{6} [f_{tt} + f f_{ty} + f^2 f_{yy}] + \mathcal{O}(h^4) \end{aligned}$$

Hence, we must choose  $\alpha, \beta, \gamma, \delta$ , and  $\eta$  so that  $y(t_{k+1}) = y_{k+1}$ . Since, the separate terms are independent

the corresponding coefficients of  $h$  must be equal. Here we obtain a system of equations given by

$$\gamma + \eta = 1$$

$$\gamma\alpha = \frac{1}{2}$$

$$\eta\delta = \frac{1}{2}$$

Thus we have a parametrized solution for the 5 variables.