



PART I: OPEN VISUALISATION ENVIRONMENT (OVE)

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INSTALLING OVE

- **Pre-requisites:** Docker, Docker-Compose
- **Optional:** Python, Git
- **Recommended:** Google Chrome
- [https://ove.readthedocs.io/en/latest/docs/INSTALLATION.html
#downloading-the-ove-installers](https://ove.readthedocs.io/en/latest/docs/INSTALLATION.html#downloading-the-ove-installers)
- Make the change suggested in **Running the installers**
- Install the **latest** version of OVE
- You need to **configure OVE before running** it

CONFIGURING OVE

- Open the location where you downloaded the OVE installer on a command line
- git clone <https://github.com/dsi-icl/soton-wstnet-ss-2019>
- Copy soton-wstnet-ss-2019/config/Spaces.json to config/Spaces.json
- Copy soton-wstnet-ss-2019/ove_maps_config.json to ove_maps_config.json (to the location where you downloaded the OVE installer)
- Edit docker-compose.setup.ove.yml and ove_maps_config.json

CONFIGURING OVE: DOCKER-COMP.

ovehub-ove-apps:

image: ovehub/ove-apps:latest-unstable

...

environment:

...

OPENVIDU_SECRET: "MY_SECRET"

OVE_MAPS_CONFIG_JSON: "/run/secrets/ove_maps_config.json"

secrets:

- **ove_maps_config.json**

CONFIGURING OVE: DOCKER-COMP.

... (bottom of the file)

secrets:

ove_maps_config.json:

file: ove_maps_config.json

CONFIGURING OVE: MAPS CONFIG

- Replace **localhost** with **<your_ip>** (this can be found out by running **ifconfig** or **ipconfig**)
- Familiarise yourself with the configuration of this file, as we will be making some changes in the future
- More information can be found in
https://ove.readthedocs.io/en/latest/ove-apps/packages/ove-app-maps/docs/MAP_LAYERS_JSON.html

RUNNING OVE

- docker-compose -f docker-compose.setup.ove.yml pull
- docker-compose -f docker-compose.setup.ove.yml up -d
- To validate whether OVE is running open <http://localhost:8080> on a web browser
- To restart OVE run:
 - docker-compose -f docker-compose.setup.ove.yml down
 - docker-compose -f docker-compose.setup.ove.yml up -d

HOSTING APPLICATION DATA

- Open soton-wstnet-ss-2019/web
- python -m server
- SimpleHTTPServer in Python does not work as it does not support CORS (Which is why we need the above script)
 - See <https://stackoverflow.com/a/21957017> for more information
- Alternatively you could also install the http-server from Node.js/NPM and run “http-server --cors -p 8000”

LAUNCHING THE APPLICATION

- Open <http://localhost:8080/ui/launcher> on a web browser
- Step 1: Select **Maps** application
- Step 2: Use the **DO12** space with x: **0**, y: **0**, w: **5760**, h: **4320** (please type these in).
- Step 3: Select the **Southampton** state
- Step 4: Delete existing sections and open the controller (i.e. **Yes** and **Yes**)
- Step 5: Press **Launch**.
- Add **&layers=0,1,2** to the URL and reload page.

USING THE DATA OBSERVATORY

- Open http://<your_ip>:8080/view.html?oveViewId=DO12-0 (or http://<your_ip>:8080/view.html?oveViewId=DO16-0) in the respective Data Observatory section
- **Note:** The observatory can be anything and need not specifically be the one at Imperial, as OVE is designed to run on any client-side infrastructure with a web browser

MORE INFORMATION

- Other OVE Apps
 - Use the launcher to try out other apps such as Images, Videos, and HTML
 - For the videos app, if you are using YouTube videos, use the suggested URL format
 - See <https://ove.readthedocs.io/en/latest/ove-apps/README.html> for more information
- Python SDK - <https://ove.readthedocs.io/en/latest/ove-sdks/python/README.html>

MORE INFORMATION

- Developer Mailing List -
<https://mailman.ic.ac.uk/mailman/listinfo/ove-dev>
- Installing OVE from source code
 - OVE can also be installed by cloning the source code of the OVE-* repositories
 - More information is available on the Documentation



PART II: WORKING WITH “GEO” DATASETS

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POPULAR PLATFORMS/LIBRARIES

- OpenLayers
- Leaflet
- CARTO/Torque.js
- ArcGIS
- OpenStreetMap
- Mapbox
- Google Maps

POPULAR STANDARDS

- Raster (Base Maps)
 - Several options publicly available
 - See <https://wiki.openstreetmap.org/wiki/Tiles#Servers>
- Vector
 - GeoJSON
 - TopoJSON (same authors of D3.js)
 - Open Geospatial Consortium – GML, KML, WKT CRS
 - Commercial – ArcGIS, Esri, IGC

GEOJSON

- Most popular format for Vector Maps
- A majority of the other formats can be converted to this format
- To convert OSM to GeoJSON use:
<https://tyrasd.github.io/osmtogeojson/>
 - May need more memory to convert larger files (export NODE_OPTIONS=--max_old_space_size=3000000)
 - OSM files can be downloaded from
<https://download.geofabrik.de/europe/great-britain/england.html>
- Read more at <https://geojson.org/> and try <http://geojson.io>

OPENSTREETMAP (OSM)

- A collaborative project to create map of the world
- Contributed by many people all over the world
- Can be used to supplement other datasets (crime, housing, traffic, ..., etc.)
- Provides a wide variety of services,
[https://wiki.openstreetmap.org/wiki/List_of_OSM-based services](https://wiki.openstreetmap.org/wiki/List_of_OSM-based_services)
- Read more at <https://www.openstreetmap.org>

WORKING WITH OSM DATA

- Useful for us:
 - osmium – can be used to extract data or a geographical area from OSM files
 - osmosis – mainly used to generate dumps/changesets, but can also be used to extract certain types of objects (speed cameras, highways)
- Other popular options:
 - imposm – imports OSM into PostgreSQL/PostGIS databases
 - mkgmap – uses OSM data to produce maps for Garmin sat-nav devices

CSV TO GEOJSON

- Can be done easily using the Python GeoJSON library (<https://pypi.org/project/geojson/>)
- Sample code found inside soton-wstnet-ss-2019/crime
 - The code accepts a CSV file as input and produces a JSON file as the output (with the same name)
 - Currently it filters crimes and ignores everything other than “Criminal damage and arson”
 - Can be modified to process any CSV file or to output other types of GeoJSON features
- Sample datasets: <https://www.kaggle.com/datasets>

VIEWING GEOJSON WITH OVE

- Each GeoJSON feature collection needs to be configured as a layer on OVE (using the `ove_maps_config.json`)
- The OVE Maps application provides two libraries, OpenLayers and Leaflet; and both of them support GeoJSON
 - See https://ove.readthedocs.io/en/latest/ove-apps/packages/ove-app-maps/docs/MAP_LAYERS_JSON.html#openlayers-configuration-format and https://ove.readthedocs.io/en/latest/ove-apps/packages/ove-app-maps/docs/MAP_LAYERS_JSON.html#leaflet-configuration-format
- OpenLayers support many vector formats whilst Leaflet only supports GeoJSON and TopoJSON
- But, Leaflet also supports embedding GeoJSON within the OVE Map Layers configuration unlike OpenLayers, which is useful at times

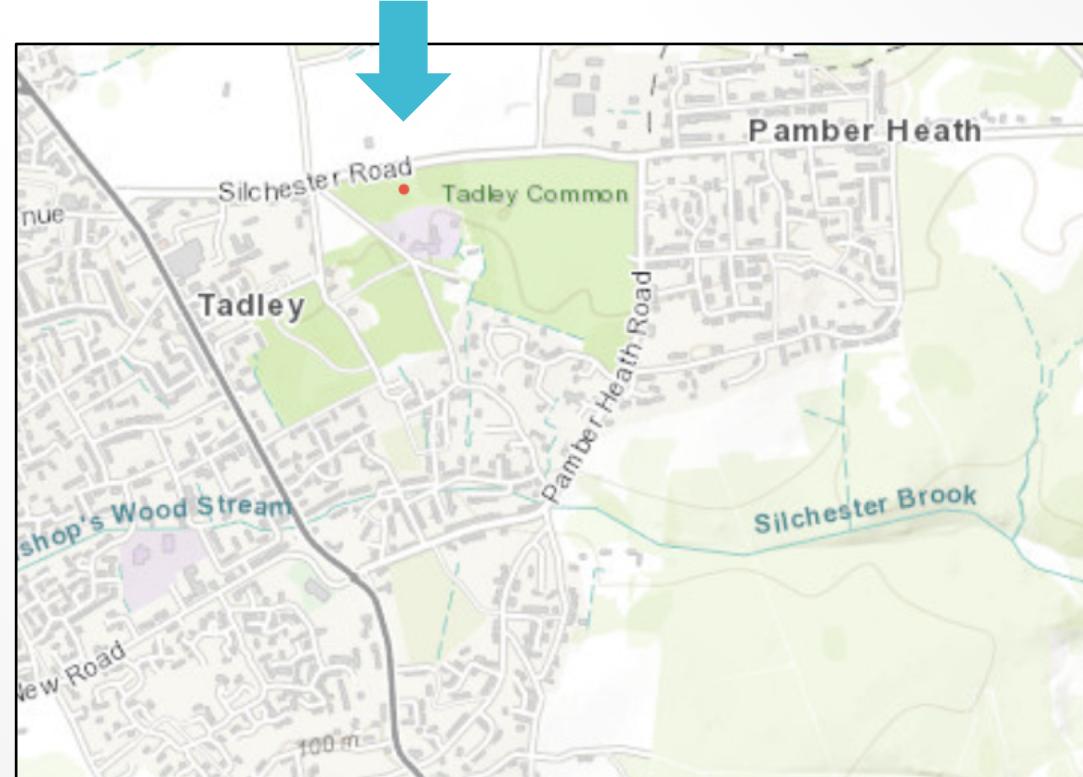
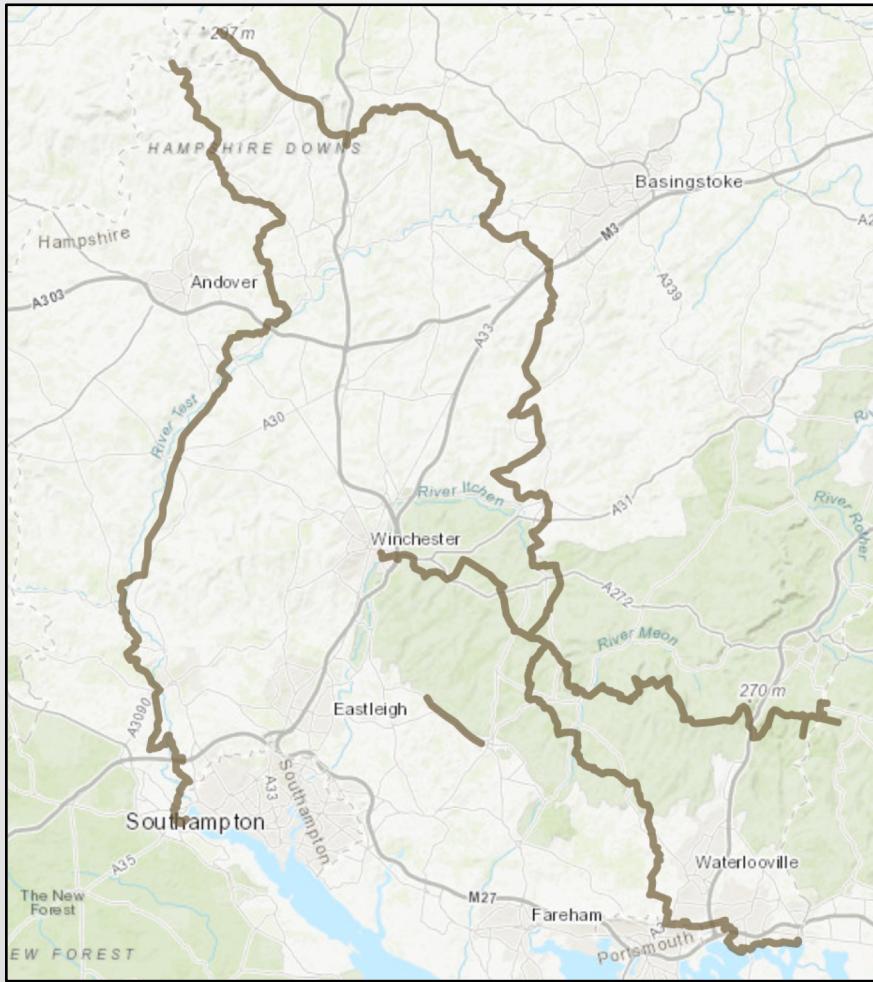
VIEWING GEOJSON WITH OVE

- Whenever the `ove_maps_config.json` file's content changes you need to restart the OVE Maps application
 - For simplicity, as this is not a production deployment, please restart OVE as explained earlier under **Running OVE**
- **Please note:** OVE only stores URLs of GeoJSON files when using OpenLayers and therefore it is not required to restart OVE if only the contents of the GeoJSON file has changed
- You don't need to restart the viewers when you restart OVE, but you need to relaunch the application if you have not setup a configuration persistence service for OVE

CHANGING THE BASE MAP

- It is important to have an appropriate base map for us to be able to interpret the data
- By default OVE uses the ArcGIS World Topographic Map
- It is possible to change the base map to something else:
 - CARTO Dark (aka “dark matter”) – great for large screens
 - Stamen Toner – great for projectors
- It is also possible to use commercial providers (such as BingMaps)

EXAMPLES



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