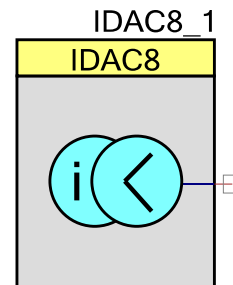


8-Bit Current Digital to Analog Converter (IDAC8)

1.70

Features

- Three ranges: 2040 μ A, 255 μ A, and 31.875 μ A
- Current sink or source selectable
- Software- or clock-driven output strobe
- Data source may be CPU, DMA, or UDB



General Description

The IDAC8 component is an 8-bit current output DAC (Digital to Analog Converter). The output can source or sink current in three ranges. The IDAC8 can be controlled by hardware, software, or by a combination of both hardware and software.

Input/Output Connections

This section describes the various input and output connections for the IDAC8. An asterisk (*) in the list of I/Os indicates that the I/O may be hidden on the symbol under the conditions listed in the description of that I/O.

Iout – Analog

The Iout terminal is the connection to the current source/sink. It can be routed to any analog-compatible pin on the device. When the highest current range is selected (2040 μ A), the output should only be routed to a specific set of pins that provide a direct low resistive path. These port pins are P0[6], P0[7], P3[0], or P3[1].

data[7:0] – Input *

This 8-bit-wide data signal connects the IDAC8 directly to the DAC bus. The DAC bus may be driven by UDB-based components or control registers, or routed directly from GPIO pins. Enable this input by setting the **Data Source** parameter to **DAC Bus**. If you select the **CPU or DMA** option instead, the bus connection disappears from the component symbol.

Use the data[7:0] input when hardware is capable of setting the proper value without CPU intervention. When using this option, you should enable **Strobe Mode** as well.

For many applications this input is not required, but instead the CPU or DMA will write a value directly to the data register. In firmware, you may use the IDAC_SetValue() function or directly write a value to the IDAC8_1_Data register (assuming an instance name of "IDAC8_1").

strobe – Input *

The strobe input is an optional signal input and is selected with the **Strobe Mode** parameter. If **Strobe Mode** is set to **External**, the pin is visible and must be connected to a valid digital source. In this mode, the data is transferred from the IDAC8 register to the DAC on the next positive edge of the strobe signal.

If this parameter is set to **Register Write** the pin disappears from the symbol and any write to the data registers is immediately transferred to the DAC.

For audio or periodic sampling applications, the same clock used to clock the data into the DAC can also be used to generate an interrupt. In this case, each rising edge of the clock transfers data to the DAC and causes an interrupt to get the next value loaded into the DAC register.

Component Parameters

Drag an IDAC8 component onto your design and double click it to open the **Configure** dialog.

Configure 'IDAC8'

Name: IDAC8_1

Configure Built-in

IDAC

Polarity

- ☐ Positive (Source)
- ☒ Negative (Sink)

Speed

- ☒ Low Speed
- ☐ High Speed

Range

- ☒ 0 - 31.875 uA (1/8 uA/bit)
- ☐ 0 - 255 uA (1 uA/bit)
- ☐ 0 - 2.04 mA (8 uA/bit)

Data Source

- ☐ DAC Bus
- ☒ CPU or DMA (Data Bus)

Strobe Mode

- ☐ External
- ☒ Register Write

Value

uA: 15

8 bit Hex: 78

Note: Changing any value field recalculates the others

Datasheet OK Apply Cancel

The IDAC8 component provides the following parameters.

Polarity

The **Polarity** parameter allows you to select whether the IDAC8 sinks or sources current to its load. When the **Positive (Source)** option is selected, the output of the DAC sources current to a load that is connected to V_{SS} or other voltage that is at least 1.0 V below V_{DDA} . In the **Negative (Sink)** mode, it supplies current to a load that is connected to V_{DD} or other voltage at least 1.0 V above V_{SS} . Depending on which polarity is selected, the symbol shows the direction of the current.

Range

This parameter allows you to set one of three current ranges as the default value. The range may be changed at any time during runtime with the IDAC_SetRange() function. If you select the highest current range, **0 – 2040 μ A**, you should route the output to one of the special pins that provide a low resistive path. These pins are P0[6], P0[7], P3[0], and P3[1].

Range	Lowest Value	Highest Value	Step Size
0 – 31.875 μ A	0.0 μ A	31.875 μ A	0.125 μ A
0 – 255 μ A	0.0 μ A	255 μ A	1 μ A
0 – 2040 μ A	0.0 μ A	2040 μ A	8 μ A

Value

This is the initial value the IDAC8 presents after the IDAC_Start() command is executed. The IDAC_SetValue() function or a direct write to the DAC register overrides the default value at any time. Legal values are between 0 and FF, inclusive. The **μ A** field represents IDAC8 source and sink current in microamps. **8 bit Hex** represents IDAC8 input data value in hexadecimal format.

Data Source

This parameter selects the source of the data to be written into the DAC register. If the CPU (firmware) or the DMA will write data to the IDAC8, then select **CPU or DMA (Data Bus)**. If data is written directly from the UDBs or a UDB-based component, then select **DAC Bus**. Note that there is only one DAC bus that is shared by all of the viDAC8 analog blocks. When **Data Source** is set as **DAC Bus**, the customizer automatically sets the **Strobe Mode** to **External** and disables the option so that you cannot change it.

Speed

This parameter provides two settings for the designer, **Low Speed** and **High Speed**. In the Low Speed mode, the settling time is slower but it consumes less operating current. In the High Speed mode, the current settles much faster, but at a cost of more operating current.



Strobe Mode

This parameter selects whether the data is immediately written to the DAC as soon as the data is written into the IDAC8 data register. This mode is selected when the **Register Write** option is selected. When the **External** option is selected, a clock or signal from UDBs controls when the data is written from the DAC register to the actual DAC.

Resources

Analog Blocks	Digital Blocks					API Memory (Bytes)		Pins (per External I/O)
	Datapaths	Macro cells	Status Registers	Control Registers	Counter7	Flash	RAM	
1 VIDAC fixed block	N/A	N/A	N/A	N/A	N/A	417	3	1

The IDAC8 uses one vIDAC8 analog block.

Application Programming Interface

Application Programming Interface (API) routines allow you to configure the component using software. The following table lists and describes the interface to each function. The subsequent sections cover each function in more detail.

By default, PSoC Creator assigns the instance name “IDAC8_1” to the first instance of a component in a given design. You can rename the instance to any unique value that follows the syntactic rules for identifiers. The instance name becomes the prefix of every global function name, variable, and constant symbol. For readability, the instance name used in the following table is “IDAC8.”

Function	Description
IDAC8_Start()	Initializes the IDAC8 with default customizer values. Enables and powers up the IDAC8.
IDAC8_Stop()	Disables the IDAC8 and sets it to the lowest power state.
IDAC8_SetSpeed()	Sets DAC speed.
IDAC8_SetPolarity()	Sets the output mode to current sink or source.
IDAC8_SetRange()	Sets full-scale range for IDAC8.
IDAC8_SetValue()	Sets value between 0 and 255 with the given range.
IDAC8_Sleep()	Stops and saves the user configuration.
IDAC8_WakeUp()	Restores and enables the user configuration.
IDAC8_Init()	Initializes or restores default IDAC8 configuration



Function	Description
IDAC8_Enable()	Enables the IDAC8.
IDAC8_SaveConfig()	Saves the current configuration
IDAC8_RestoreConfig()	Restores the configuration.

Global Variables

Variable	Description
IDAC8_initVar	Indicates whether the IDAC8 has been initialized. The variable is initialized to 0 and set to 1 the first time IDAC8_Start() is called. This allows the component to restart without reinitialization after the first call to the IDAC8_Start() routine. If reinitialization of the component is required, then the IDAC8_Init() function can be called before the IDAC8_Start() or IDAC8_Enable() function.

void IDAC8_Start(void)

Description: This is the preferred method to begin component operation. IDAC8_Start() sets the initVar variable, calls the IDAC8_Init() function, and then calls the IDAC8_Enable() function. Enables and powers up the IDAC8 to the given power level. A power level of 0 is the same as executing the stop function.

Parameters: None

Return Value: None

Side Effects: If the initVar variable is already set, this function only calls the IDAC_Enable() function.

void IDAC8_Stop(void)

Description: Powers down IDAC8 to lowest power state and disables output.

Parameters: None

Return Value: None

Side Effects: None



void IDAC8_SetSpeed(uint8 speed)**Description:** Sets DAC speed.**Parameters:** uint8 speed: Sets DAC speed, see the following table for valid parameters.

Option	Description
IDAC8_LOWSPEED	Low speed (low power)
IDAC8_HIGHSPEED	High speed (high power)

Return Value: None**Side Effects:** None**void IDAC8_SetPolarity(uint8 polarity)****Description:** Sets output polarity to sink or source.**Parameters:** uint8 polarity: Sets current sink or source functionality, see the following table.

Option	Description
IDAC8_SOURCE	Set mode as current source.
IDAC8_SINK	Set mode to current sink.

Return Value: None**Side Effects:** None**void IDAC8_SetRange(uint8 range)****Description:** Sets full-scale range for IDAC8**Parameters:** uint8 range: Sets full-scale range for IDAC8. See the following table for ranges.

Option	Description
IDAC8_RANGE_32uA	Set full scale range to 31.875 μ A
IDAC8_RANGE_255uA	Set full scale range to 255 μ A
IDAC8_RANGE_2mA	Set full scale range to 2.040 mA

Return Value: None**Side Effects:** None

void IDAC8_SetValue(uint8 value)

- Description:** Sets value to output on IDAC8. Valid values are between 0 and 255.
- Parameters:** uint8 value: Value between 0 and 255. A value of 0 is the lowest (zero) and a value of 255 is the full-scale value. The full-scale value depends on the range, which is selected with the IDAC_SetRange() API.
- Return Value:** None
- Side Effects:** On PSoC 3 ES2, PSoC 3 Production, and PSoC 5, the IDAC8_SetValue() function should be called after enabling the power to the IDAC.

void IDAC8_Sleep(void)

- Description:** This is the preferred API to prepare the component for sleep. The IDAC8_Sleep() API saves the current component state. Then it calls the IDAC8_Stop() function and calls IDAC8_SaveConfig() to save the hardware configuration.
- Call the IDAC_Sleep() function before calling the CyPmSleep() or the CyPmHibernate() function. Refer to the PSoC Creator *System Reference Guide* for more information about power-management functions.
- Parameters:** None
- Return Value:** None
- Side Effects:** None

void IDAC8_Wakeup(void)

- Description:** This is the preferred API to restore the component to the state when IDAC8_Sleep() was called. The IDAC8_Wakeup() function calls the IDAC8_RestoreConfig() function to restore the configuration. If the component was enabled before the IDAC8_Sleep() function was called, the IDAC_Wakeup() function will also re-enable the component.
- Parameters:** None
- Return Value:** None
- Side Effects:** Calling the IDAC8_Wakeup() function without first calling the IDAC8_Sleep() or IDAC8_SaveConfig() function may produce unexpected behavior.



void IDAC8_Init(void)

- Description:** Initializes or restores the component according to the customizer Configure dialog settings. It is not necessary to call IDAC8_Init() because the IDAC8_Start() API calls this function and is the preferred method to begin component operation.
- Parameters:** None
- Return Value:** None
- Side Effects:** All registers will be set to values according to the customizer Configure dialog. This will reinitialize the component. Calling the IDAC8_Init() function requires a call to IDAC8_SetValue() if you intend to set a new value other than what is currently in the register.

void IDAC8_Enable(void)

- Description:** Activates the hardware and begins component operation. It is not necessary to call IDAC8_Enable() because the IDAC8_Start() API calls this function, which is the preferred method to begin component operation.
- Parameters:** None
- Return Value:** None
- Side Effects:** None

void IDAC8_SaveConfig(void)

- Description:** This function saves the component configuration and nonretention registers. It also saves the current component parameter values, as defined in the Configure dialog or as modified by appropriate APIs. This function is called by the IDAC8_Sleep() function.
- Parameters:** None
- Return Value:** None
- Side Effects:** None

void IDAC8_RestoreConfig(void)

- Description:** This function restores the component configuration and nonretention registers. This function also restores the component parameter values to what they were before calling the IDAC8_Sleep() function.
- Parameters:** None
- Return Value:** None
- Side Effects:** Calling this function without first calling the IDAC8_Sleep() or IDAC8_SaveConfig() function may produce unexpected behavior.



Sample Firmware Source Code

PSoC Creator provides numerous example projects that include schematics and example code in the Find Example Project dialog. For component-specific examples, open the dialog from the Component Catalog or an instance of the component in a schematic. For general examples, open the dialog from the Start Page or **File** menu. As needed, use the **Filter Options** in the dialog to narrow the list of projects available to select.

Refer to the “Find Example Project” topic in the PSoC Creator Help for more information.

Functional Description

The DAC generates either a voltage or a current output. It is built using current mirror architecture; current is mirrored from a reference source to a mirror DAC. Calibration and value current mirrors are responsible for the 8-bit calibration [DACx_TR] and the 8-bit DAC value. The current is then diverted into the scaler to generate the current corresponding to the DAC value. The DAC value can either be gotten from the register DACx_D or from eight lines from the UDB. This is selected using the DACx_CR1[5] bit.

The DAC is strobed to get its output to change for the input code. The strobe control is enabled by the DACx_STROBE[3] bit. The strobe sources for the DAC can be selected from the bus write strobe, analog clock strobe, or any UDB signal strobe. This is selected based on the setting in DACx_STROBE[2:0].

Current (IDAC) Mode

The two mirrors for the current source and sink provide output as a current source or current sink, respectively. These mirrors also provide range options in the current mode.

When used as an IDAC, the output is an 8-bit digital-to-analog conversion current. This is done by setting the DACx_CR0 [4] register. The reference source is a current reference from the analog reference, called IREF(DAC). In this mode, there are three output ranges selected by register DACx_CR0 [3:2]:

- 0 to 2.040 mA, 8 μ A/bit
- 0 to 255 μ A, 1 μ A/bit
- 0 to 31.875 μ A, 0.125 μ A/bit

For each level, there are 255 equal steps of $M/256$ where $M = 2.040 \text{ mA}$, $255 \text{ } \mu\text{A}$, or $31.875 \text{ } \mu\text{A}$. In the 2.040-mA configuration, the block is intended to output a current into an external 600- Ω load. The output may be delivered into any resistance or to a fixed voltage, as long as the minimum headroom requirement of 1.0 V is met. This means that the maximum voltage for sourced current is $V_{DDA} - 1.0 \text{ V}$ and the minimum output voltage for sunk current is 1.0 V above V_{SSA} .



The IDAC is calibrated at $V_{OUT} = 0.0\text{ V}$ for current source and $V_{OUT} = V_{DD}$ for current sink. When sourcing current, the value of the output current is slightly sensitive to the terminating voltage. At output voltages higher than 0.0 V , the output current is reduced. The current deviation is directly proportional to the code value and proportional to the ratio of the output voltage to the supply voltage. The deviation follows the form:

$$\%I_{ERROR} = -\frac{\text{code}}{255} \left(0.8 \left(\frac{V_{OUT}}{V_{DD}} \right) + 0.8 \left(\frac{V_{OUT}}{V_{DD}} \right)^2 \right)$$

The typical deviation is less than 1.2 percent of full scale range for $V_{DD} > 3.3\text{ V}$ and $V_{OUT} < V_{DD} = 1.0\text{ V}$. At maximum current, routing resistance slightly affects the output and the current deviation increases. At $V_{DD} = 1.71\text{ V}$, there is not enough headroom for the IDAC to operate properly at currents larger than 1.0 mA .

Note This paragraph may be modified or expanded when current sink performance is evaluated.

The IDAC can convert up to 8 Msps. You can also select whether the output is a current source or a sink. This is done by the DACx_CR1[2] register. The selection between source and sink for the IDAC can also be made using a UDB input. UDB control for the source sink selection is enabled using the DACx_CR1[3] bit.

DMA

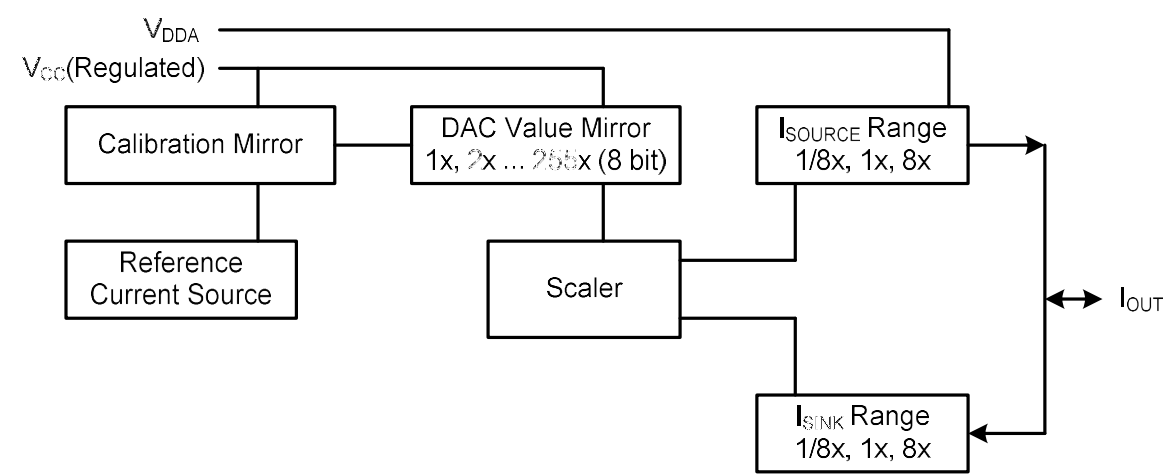
IDAC8 components do not require implementation of a DMA Request signal. The typical usage is signal generation. The data rate to IDAC8 components should be controlled externally. The DMA Wizard can be used to configure DMA operation as follows:

Name of DMA Source/Destination in DMA Wizard	Direction	DMA Req Signal	DMA Req Type	Description
IDAC8_Data_PTR	Destination	N/A	N/A	Stores the DAC value between 0 to 255

Block Diagram and Configuration

Figure 1 shows the block diagram for the IDAC8 component.

Figure 1. Block Diagram



Registers

The functions provided support most of the common runtime functions that are required for most applications. The following register reference provides a brief description for the advanced user. The IDAC8_Data register may be used to write data directly to the DAC without using the API. This may be useful for either the CPU or DMA.

IDAC8_CR0

Bits	7	6	5	4	3	2	1	0
Value	reserved			mode	range[1:0]		hs	reserved

- mode: Sets DAC to either voltage or current mode
- range[1:0]: DAC range settings
- hs: Sets data speed

IDAC8_CR1

Bits	7	6	5	4	3	2	1	0
Value	reserved		mx_data	reset_u db_e n	mx_idir	idirbit	Mx_ioff	ioffbit

- mx_data: Selects data source



- reset_udb_en: DAC reset enable
- mx_idir: Mux selection for DAC current direction control
- idirbit: Register source for DAC current direction
- mx_off: Mux selection for DAC current off control
- ioffbit: Register source for DAC current off

IDAC8_DATA

Bits	7	6	5	4	3	2	1	0
Value	Data[7:0]							

- Data[7:0]: DAC data register

DC and AC Electrical Characteristics

Unless otherwise specified: Typical = 25 °C, $V_{DDA} = 5.0$ V, headroom = 1.0 V minimum, specifications apply to all ranges: 0 to 31.875 μ A, 0 to 255 μ A, 0 to 2.04 mA.

IDAC8 DC Characteristics

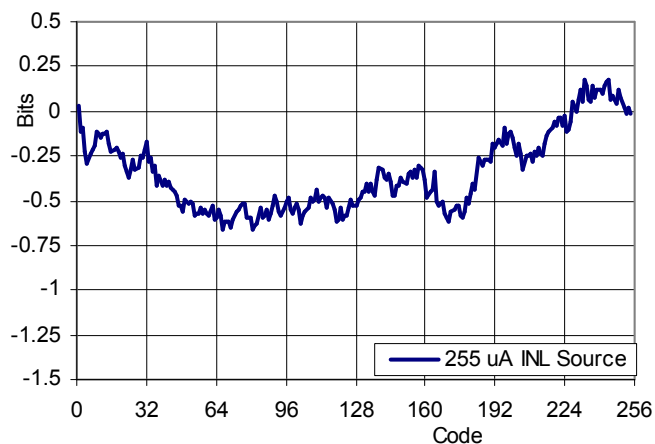
Parameter	Description	Conditions	Min	Typ	Max	Units
	Resolution		–	–	8	bits
I_{OUT}	Output current at code = 255	Range = 2.040 mA, code = 255, $V_{DDA} \geq 2.7$ V, $R_{LOAD} = 600 \Omega$	–	2.040	–	mA
		Range = 2.040 mA, High mode, code = 255, $V_{DDA} \leq 2.7$ V, $R_{LOAD} = 300 \Omega$	–	2.040	–	mA
		Range = 255 μ A, code = 255, $R_{LOAD} = 600 \Omega$	–	255	–	μ A
		Range = 31.875 μ A, code = 255, $R_{LOAD} = 600 \Omega$	–	31.875	–	μ A
	Monotonicity		–	–	Yes	
Ezs	Zero scale error		–	0	± 1	LSB
Eg	Gain error	Range = 2.04 mA, 25 °C	–	–	± 2.5	%
		Range = 255 μ A, 25 °C	–	–	± 2.5	%
		Range = 31.875 μ A, 25 °C	–	–	± 3.5	%



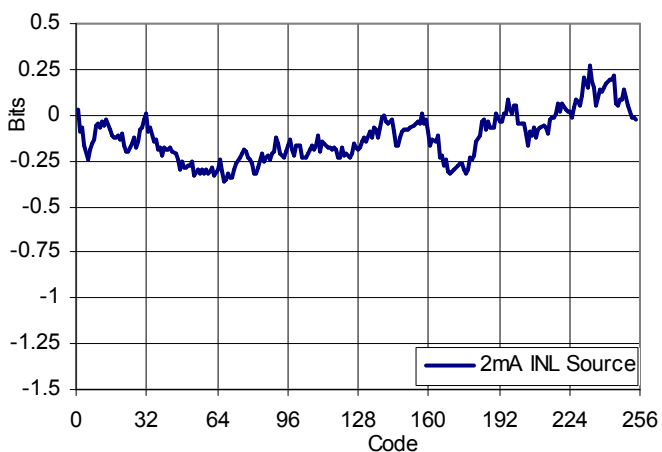
Parameter	Description	Conditions	Min	Typ	Max	Units
TC_Eg	Temperature coefficient of gain error	Range = 2.04 mA	–	–	0.04	%/°C
		Range = 255 μ A	–	–	0.04	% / °C
		Range = 31.875 μ A	–	–	0.05	% / °C
INL	Integral nonlinearity	Sink mode, range = 255 μ A, Codes 8 to 255, $R_{LOAD} = 2.4 \text{ k}\Omega$, $C_{LOAD} = 15 \text{ pF}$	–	± 0.9	± 1	LSB
		Source mode, range = 255 μ A, Codes 8 – 255, $R_{LOAD} = 2.4 \text{ k}\Omega$, $C_{LOAD} = 15 \text{ pF}$	–	± 1.2	± 1.5	LSB
DNL	Differential nonlinearity	Sink mode, range = 255 μ A, $R_{LOAD} = 2.4 \text{ k}\Omega$, $C_{LOAD} = 15 \text{ pF}$	–	± 0.3	± 1	LSB
		Source mode, range = 255 μ A, $R_{LOAD} = 2.4 \text{ k}\Omega$, $C_{LOAD} = 15 \text{ pF}$	–	± 0.3	± 1	LSB
Vcompliance	Dropout voltage, source or sink mode	Voltage headroom at max current, R_{LOAD} to V_{DDA} or R_{LOAD} to V_{SSA} , V_{DIFF} from V_{DDA}	1	–	–	V
Idev	Voltage-dependent current deviation	Source mode, $V_{OUT} = 0.0 \text{ V}$ Sink mode, $V_{OUT} = V_{DD}$	–	1.0%	–	μ A
I _{DD}	Operating current, code = 0	Slow mode, source mode, range = 31.875 μ A	–	44	100	μ A
		Slow mode, source mode, range = 255 μ A,	–	33	100	μ A
		Slow mode, source mode, range = 2.04 mA	–	33	100	μ A
		Slow mode, sink mode, range = 31.875 μ A	–	36	100	μ A
		Slow mode, sink mode, range = 255 μ A	–	33	100	μ A
		Slow mode, sink mode, range = 2.04 mA	–	33	100	μ A
		Fast mode, source mode, range = 31.875 μ A	–	310	500	μ A
		Fast mode, source mode, range = 255 μ A	–	305	500	μ A
		Fast mode, source mode, range = 2.04 mA	–	305	500	μ A
		Fast mode, sink mode, range = 31.875 μ A	–	310	500	μ A

Parameter	Description	Conditions	Min	Typ	Max	Units
		Fast mode, sink mode, range = 255 μ A	–	300	500	μ A
		Fast mode, sink mode, range = 2.04 mA	–	300	500	μ A

Figures

INL versus DAC Code, Range = 255 μ A, Source ModeINL versus DAC Code, Range = 255 μ A, Sink Mode

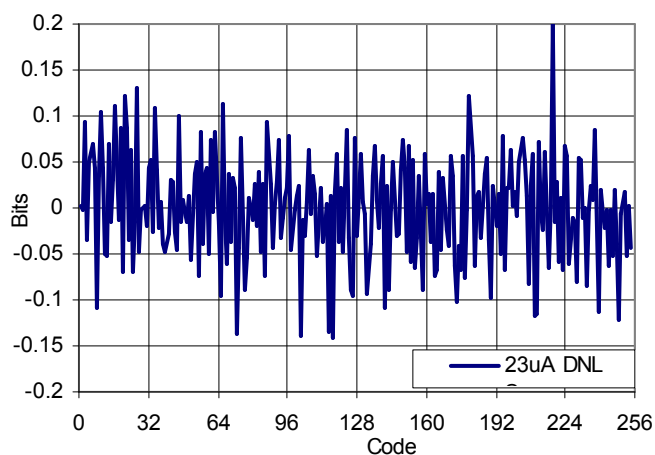
INL versus DAC Code, Range = 2.040 mA, Source Mode



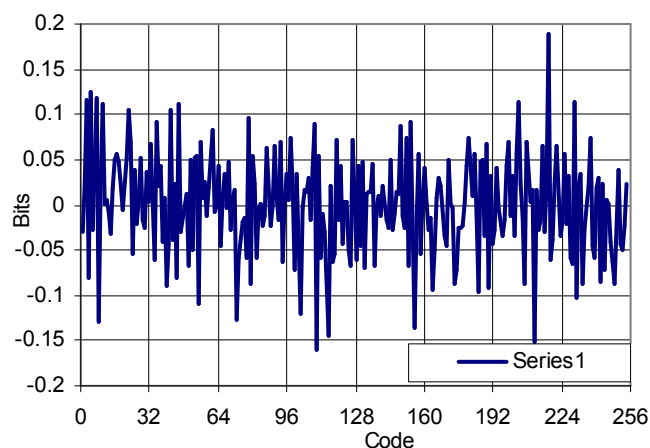
INL versus DAC Code, Range = 2.040 mA, Sink Mode



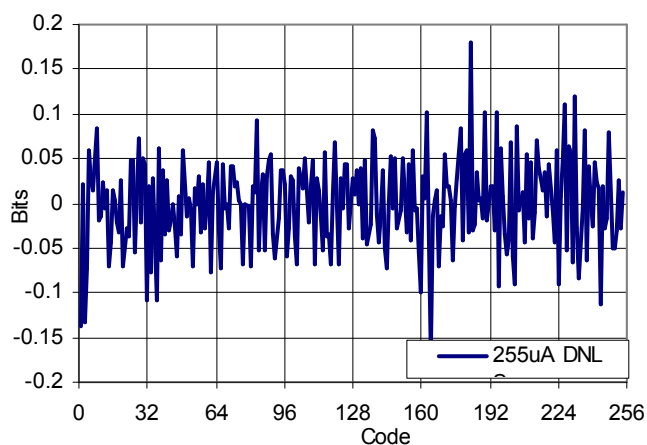
DNL versus DAC Code, Range = 31.875 μ A, Source Mode



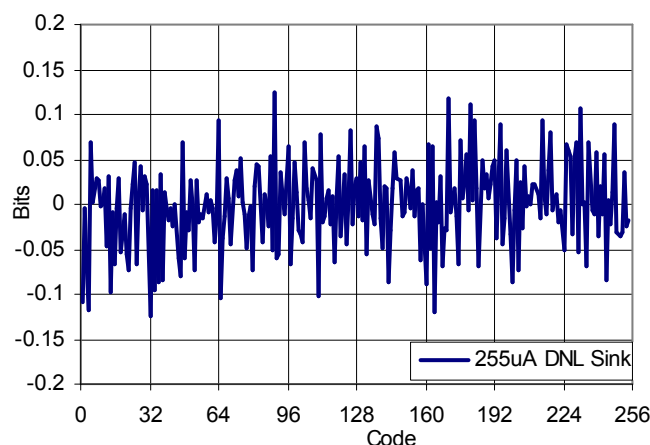
DNL versus DAC Code, Range = 31.875 μ A, Sink Mode



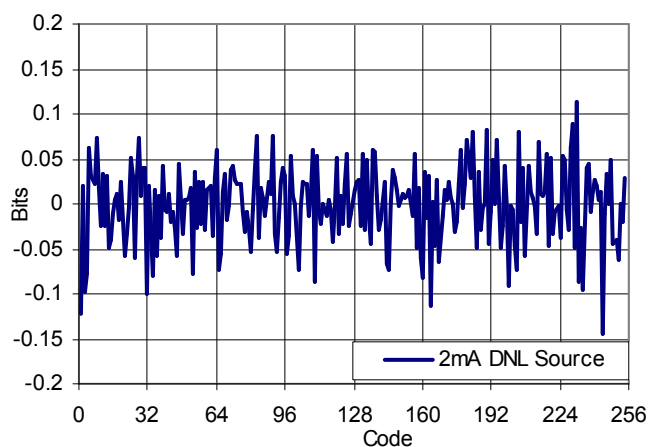
DNL versus DAC Code, Range = 255 μ A, Source Mode



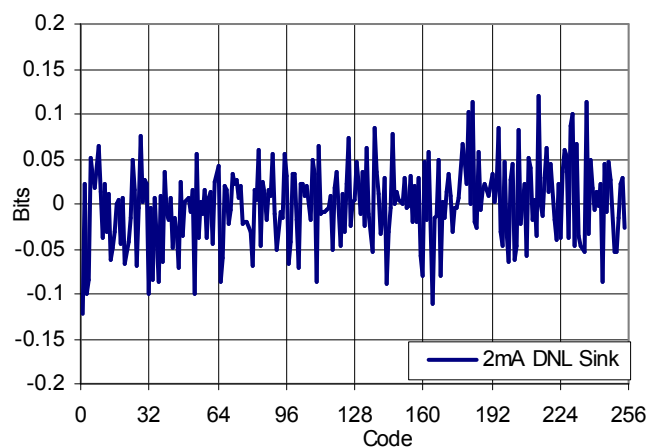
DNL versus DAC Code, Range = 255 μ A, Sink Mode

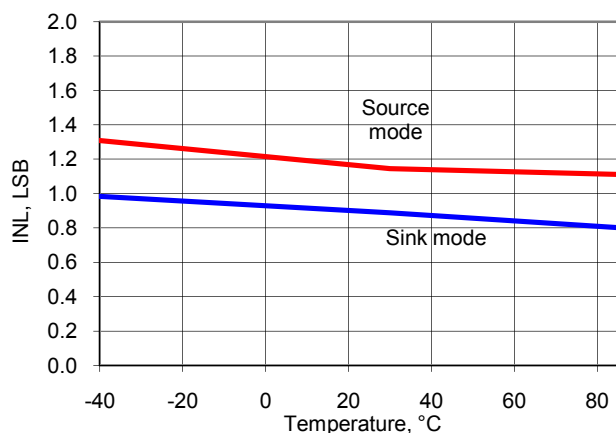
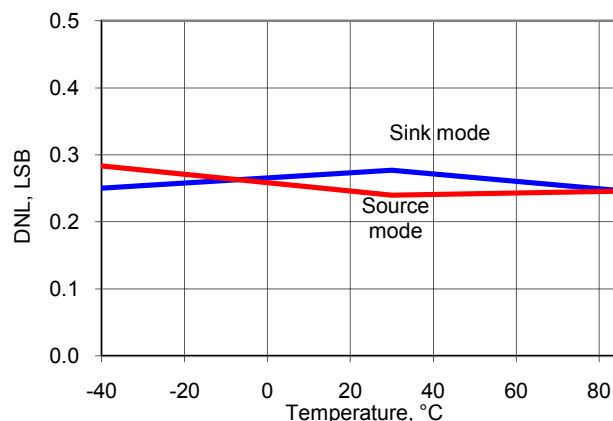
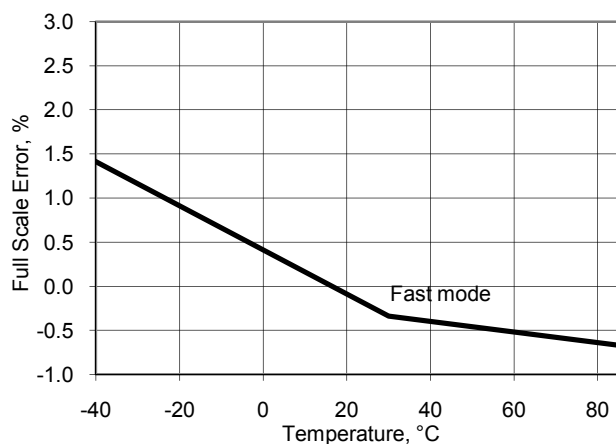
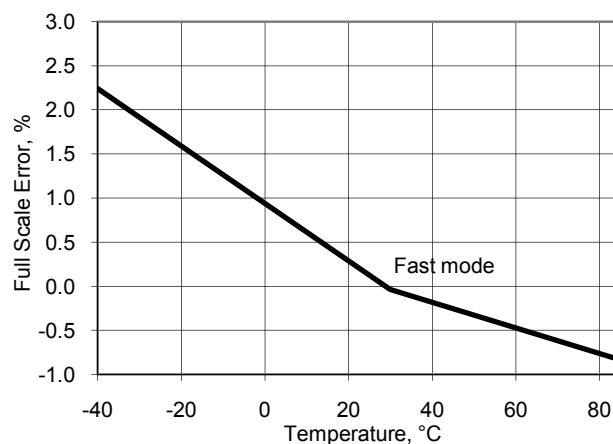
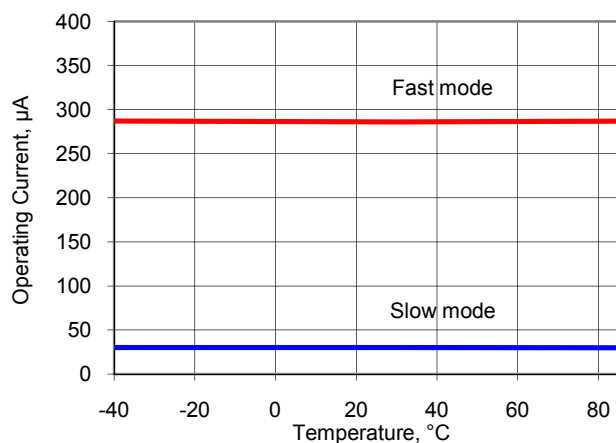
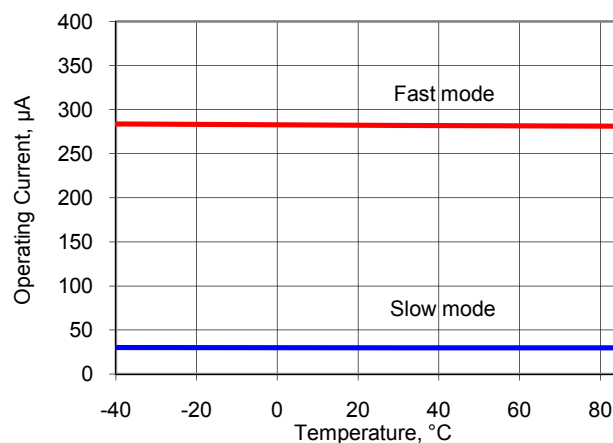


DNL versus DAC Code, Range = 2.04 mA, Source Mode

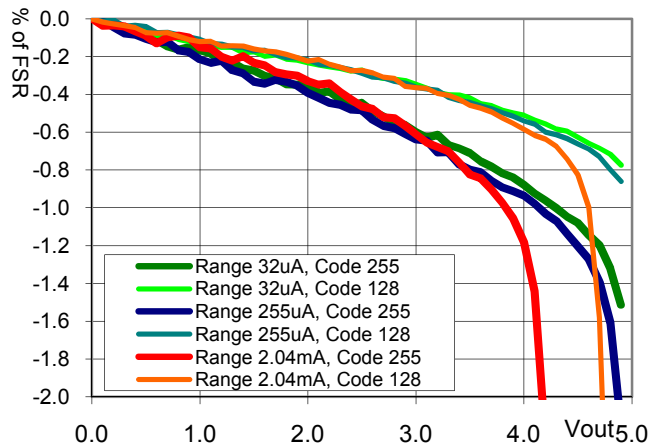


DNL versus DAC Code, Range = 2.04 mA, Sink Mode



IDAC INL versus Temperature, Range = 255 μ A, Fast ModeIDAC DNL versus Temperature, Range = 255 μ A, Fast ModeIDAC Full Scale Error versus Temperature, Range = 255 μ A, Source ModeIDAC Full Scale Error versus Temperature, Range = 255 μ A, Sink ModeIDAC Operating Current versus Temperature, Range = 255 μ A, Code = 0, Source ModeIDAC Operating Current versus Temperature, Range = 255 μ A, Code = 0, Sink Mode

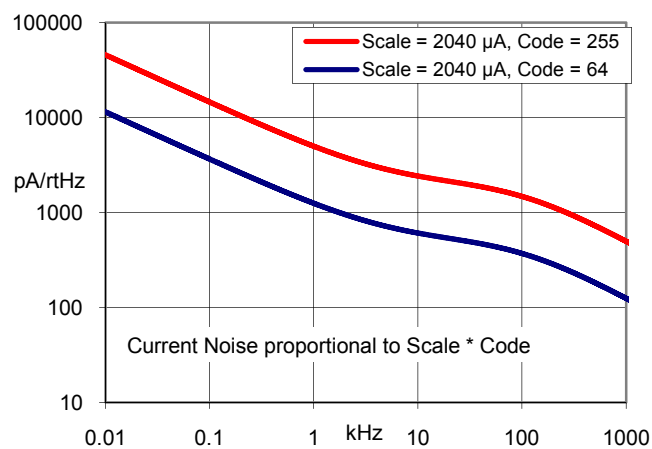
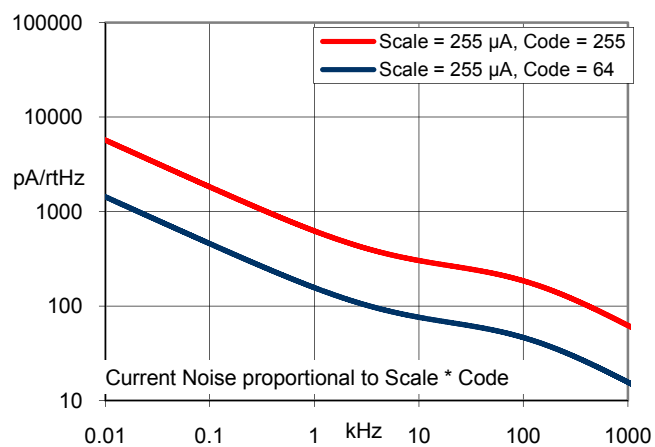
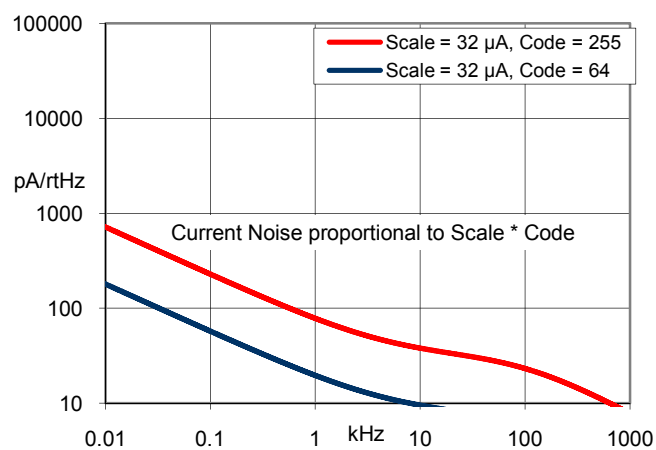
Current Difference from Nominal into Vout (% of FSR),
V_{DD} = 5.5 V, T = 25 °C



IDAC8 AC Characteristics

Parameter	Description	Conditions	Min	Typ	Max	Units
F _{DAC}	Update rate		–	–	8	Msp/s
T _{SETTLE}	Settling time to 0.5 LSB	Independent of IDAC range setting (I _{OUT}), full-scale transition, 600-Ω load, C _L = 15 pF, Fast mode	–	–	125	ns
		Independent of IDAC range setting (I _{OUT}), full-scale transition, 600-Ω load, C _L = 15 pF, Slow mode	–	–	1000	ns
In2040 μA	Current Noise	Fast mode, source mode, range = 2040 μA, code = 255, V _{DDA} = 5 V, 10 kHz	–	2.7	–	nA/rHz
In255 μA		Fast mode, source mode, range = 255 μA, code = 255, V _{DDA} = 5 V, 10 kHz	–	340	–	pA/rHz
In32 μA		Fast mode, source mode, range = 31.875 μA, code = 255, V _{DDA} = 5 V, 10 kHz	–	40	–	pA/rHz

Figures

Noise versus Frequency, 2040 μ ANoise versus Frequency, 255 μ ANoise versus Frequency, 32 μ A

Component Changes

This section lists the major changes in the component from the previous version.

Version	Description of Changes	Reason for Changes / Impact
1.70	IDAC8_Stop() API changes for PSoC 5	Change required to prevent the component from impacting unrelated analog signals when stopped, when used with PSoC 5.
	Updated IDAC8 customizer GUI	<ul style="list-style-type: none"> ▪ To allow user to enter float values in uA field. ▪ To force the Strobe mode to External when Data Source is selected as DAC Bus. ▪ To make IDAC8 GUI consistent with VDAC8 GUI.
1.60	Added a GUI Configuration Editor	Previous configuration window did not provide enough information for ease of use.
	Added characterization data to datasheet	
	Minor datasheet edits and updates	
1.50	Added Sleep/Wakeup and Init/Enable APIs.	To support low-power modes, as well as to provide common interfaces to separate control of initialization and enabling of most components.
	Added DMA capabilities file to the component.	This file allows the IDAC8 to be supported by the DMA Wizard tool in PSoC Creator.

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