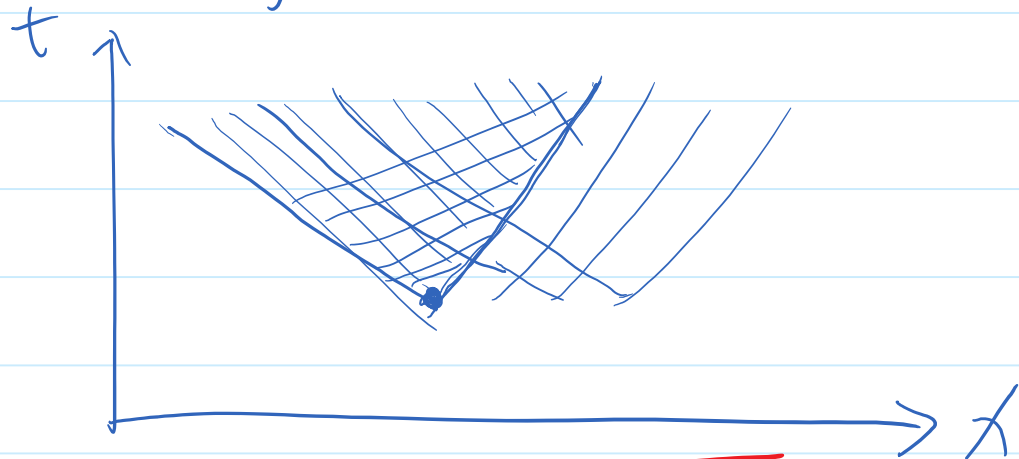


# Systems of conservation laws -- flux reconstruction via numerical dissipation

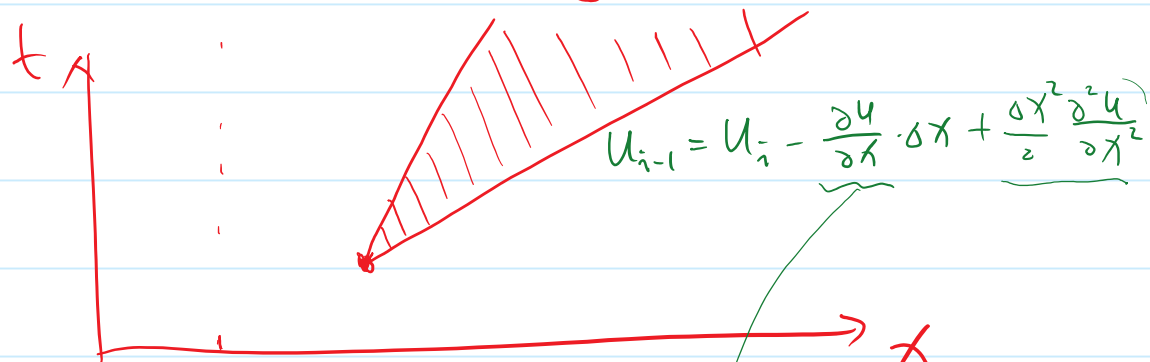
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$$\frac{\partial \vec{u}}{\partial t} + \left( \frac{\partial \vec{f}}{\partial \vec{u}} \right) \cdot \nabla \vec{u} = 0$$

eigenvalues  $\rightarrow$  characteristic speeds



shallow water eqn:  $C = u \pm \sqrt{gh}$



$$u_{i+1} = u_i - \frac{\partial u}{\partial x} \cdot \Delta x + \frac{\Delta x^2}{2} \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = 0$$

upwind  
1st order

$$\frac{du_i}{dt} + \frac{u_i - u_{i-1}}{\Delta x} = 0$$

higher order

$$\frac{\partial u}{\partial t} + C \frac{\partial u}{\partial x} = 0$$

upwindy

$$\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = \frac{\Delta x}{2} \frac{\partial^2 u}{\partial x^2}$$

if  $C < 0$

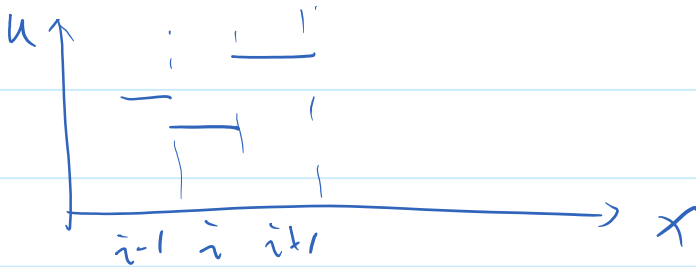
$$\frac{du_i}{dt} + \frac{u_{i+1} - u_i}{\Delta x} = 0$$

$$\frac{\partial u}{\partial t} + C \frac{\partial u}{\partial x} = \frac{\Delta x}{2} |C| \frac{\partial^2 u}{\partial x^2}$$

o c n z ~ .

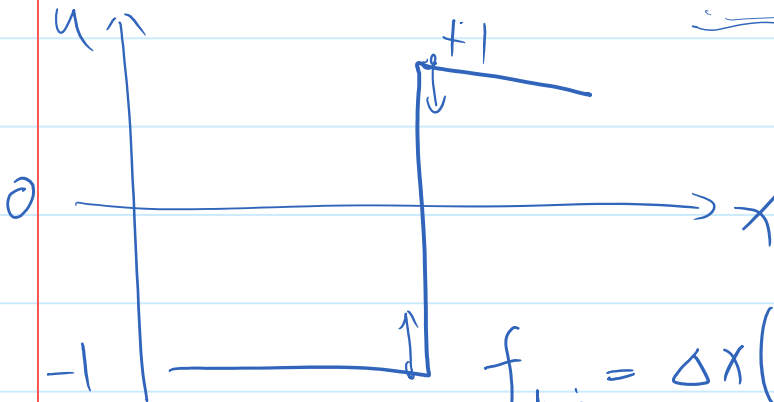
# Systems of conservation laws -- flux reconstruction via numerical dissipation

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$$f_{i+\frac{1}{2}} = \frac{f(u_i) + f(u_{i+1})}{2} + \Delta x \cdot \underbrace{\left| \frac{df}{du} \right|_{\max}}_2 \frac{u_{i+1} - u_i}{\Delta x}$$

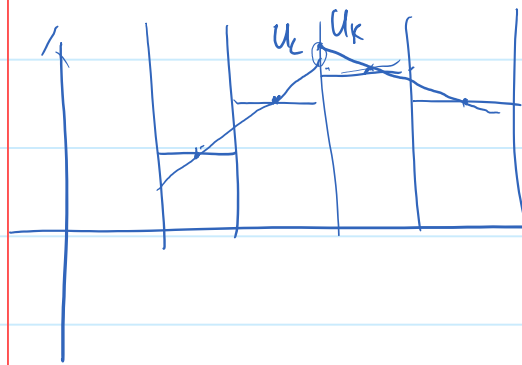
$$\frac{du_i}{dt} = \frac{f_{i-\frac{1}{2}} - f_{i+\frac{1}{2}}}{\Delta x} = \frac{f(u_{i+1}) - f(u_{i-1})}{2\Delta x} + \frac{u_{i+1} - 2u_i + u_{i-1}}{\Delta x^2} + \underbrace{\left| \frac{df}{du} \right|_{\max}}_2 \Delta x$$



$$f_{\text{dissip}} = \Delta x \left( |u| + \sqrt{gh} \right) \frac{u_{i+1} - u_i}{\Delta x}$$

# Systems of conservation laws -- JST scheme

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$$f = \frac{f(u_k) + f(u_{k+1})}{2} + f_{\text{dissip.}}$$

$$\phi(r) = 1$$

$$f_{\text{dissip}} = \Delta x \left| \frac{df}{du} \right| \frac{u_k - u_{k+1}}{\Delta x}$$

$$= \left| \frac{df}{du} \right| (u_k - u_{k+1})$$

$$= \left| \frac{df}{du} \right| \left( u_{i+1} - \frac{\Delta x}{2} \frac{u_{i+2} - u_{i+1}}{\Delta x} - \left( u_i + \frac{\Delta x}{2} \frac{u_i - u_{i-1}}{\Delta x} \right) \right)$$

$$= \left| \frac{df}{du} \right| \left( -\frac{1}{2} u_{i+2} + \frac{3}{2} u_{i+1} - \frac{3}{2} u_i + \frac{1}{2} u_{i-1} \right)$$

$$= \left| \frac{df}{du} \right| \left( -\frac{1}{2} (u_{i+2} - 2u_{i+1} + u_i) + \frac{1}{2} (u_{i+1} - 2u_i + u_{i-1}) \right)$$

$$= -\frac{1}{2} \Delta x^3 \left| \frac{df}{du} \right| \frac{\partial^3 u}{\partial x^3}$$

$$\frac{du_i}{dt} = \frac{-f_{i+1/2} + f_{i-1/2}}{\Delta x} = \frac{-f_{i+1/2,c} + f_{i-1/2,c}}{\Delta x} + \frac{-f_{i+1/2,\text{dissip}} + f_{i-1/2,\text{dissip}}}{\Delta x}$$

① Construct limiter  $\phi = \begin{cases} 0 & \text{nonsmooth} \\ 1 & \text{smooth} \end{cases} \Delta x$

②  $\Delta x \frac{\partial u}{\partial x} \left| \frac{df}{du} \right| \rightarrow \phi \times (1 - \phi)$

③  $\Delta x^3 \frac{\partial^3 u}{\partial x^3} \left| \frac{df}{du} \right| \rightarrow \phi \times 1$

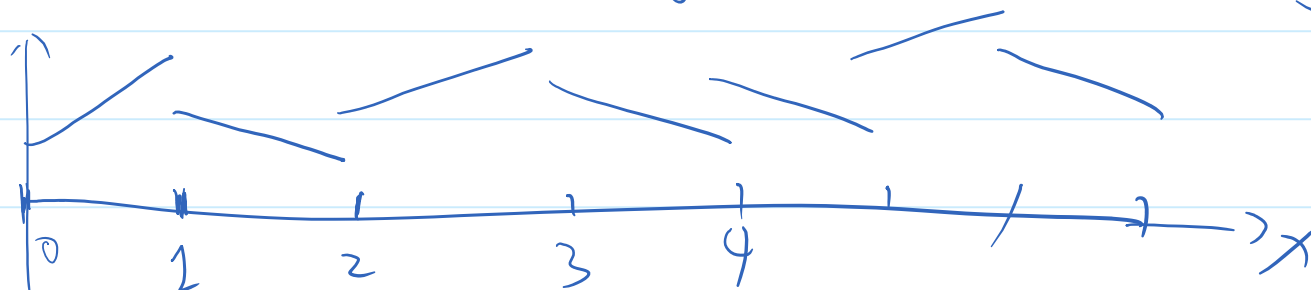
# Systems of conservation laws -- JST scheme

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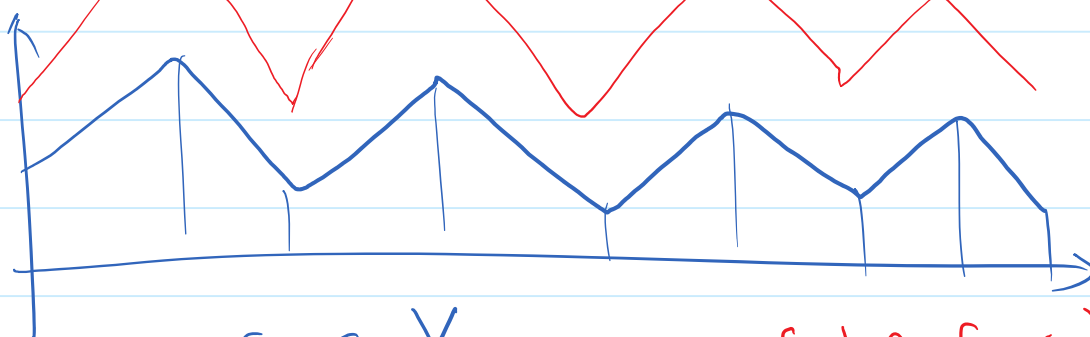
# Finite element -- Linear space and basis

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①  $X = \left\{ f(x), x \in [0, 1], \text{ s.t. for all } i \right.$   
 $\left. f(x) \text{ is linear in } x \in [\chi_{i-1}, \chi_i] \right\}$



②  $X = \left\{ f(x), x \in [0, 1], f \text{ is continuous, and } \forall i \right.$   
 $\left. f(x) \text{ is linear in } x \in [\chi_{i-1}, \chi_i] \right\}$



Linearity  $\forall f_1, f_2 \in X$   
 $a_1 f_1 + a_2 f_2 \in X$   
 for  $\forall a_1$  and  $a_2$

Basis:  $\{\chi_1, \chi_2, \dots, \chi_n\}$  is a basis of  $X$  iff

①  $\forall x \in X, \quad x = \sum_{i=1}^n a_i \chi_i$

②  $\forall x \in X, \quad (a_i, i=1, \dots, n) \text{ s.t. } x = \sum a_i \chi_i$

$\min_{x \in X} \text{dist}(f, x) \iff \min_{a \in \mathbb{R}^n} \text{dist}(f, \sum_{i=1}^n a_i \chi_i)$   
 is unique.

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$$\min_{g \in X}$$

$$g^* f \perp X := \forall g' \in X, \int_a (g-f) \cdot g' dx = 0$$

$$g' = g - g^x$$

$$\int_a^b (f-g)^2 dx = \int_a^b (f-g^x - g')^2 dx$$

$$= \int_a^b \left( (f-g^x)^2 - 2g'(f-g^x) + \underbrace{g'^2}_{>0} \right) dx$$

$$\stackrel{=0}{=} \int_a^b (f-g^x)^2 dx$$

if  $\int_a^b g'(f - g^*) dx = 0$

then

$$\int_a^b (f-g)^2 dx = \int_a^b (f-g^*)^2 dx + \int_a^b g'^2 dx$$

i.e.  $g^*$  minimizes  $\int_a^b (f-g)^2 dx$   
among all  $g \in X$

Optimization  $\implies \int_a^b g'(f - g^*) dx = 0$  for all  $g' \in X$

express  $g^* = \sum_{i=1}^n a_i \phi_i$  where  $\{\phi_i\}$  is a basis for  $X$

if  $\int_{a_n}^b \phi_j (f - \sum_{i=1}^n a_i \phi_i) dx = 0 \quad j=1, \dots, n$

then  $\forall q' = \sum b_i \phi_i \quad \sum b_i \int \phi_i (f - \sum a_i \phi_i) dx = 0$

$$\text{then } \forall g' = \sum_{j=1}^n b_j \phi_j, \quad \sum_{j=1}^n b_j \int_a^b \phi_j (f - \sum_{i=1}^n a_i \phi_i) dx = 0$$



# Finite element -- projection as a linear system

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$$\int_a^b \phi_j \left( f - \sum_{i=1}^n a_i \phi_i \right) dx = 0$$

$$\underbrace{\int_a^b \phi_j f dx} - \sum_{i=1}^n a_i \underbrace{\int_a^b \phi_j \phi_i dx} = 0$$

If we construct  $\phi_1, \phi_2, \dots$

define  $\vec{b} = \begin{pmatrix} \int_a^b \phi_1 f dx \\ \int_a^b \phi_2 f dx \\ \vdots \\ \int_a^b \phi_n f dx \end{pmatrix}$  ⊥

$$\vec{A} = \begin{pmatrix} \int \phi_1 \phi_1 dx & \int \phi_1 \phi_2 dx & \dots & \int \phi_1 \phi_n dx \\ \vdots & \vdots & \ddots & \vdots \\ \int \phi_n \phi_1 dx & \int \phi_n \phi_2 dx & \dots & \int \phi_n \phi_n dx \end{pmatrix}$$

$$\vec{A} \vec{a} = \vec{b}$$