



Accelerating Eulerian fluid simulation with convolutional networks.

J Tompson, K Schlachter, P Sprechmann, K Perlin

Presenter: Robin Walters
CS 7180

March 28, 2019

Goal

Simulate fluid flow in 3D space.

Goal

Simulate fluid flow in 3D space.

- Around solid objects.

Goal

Simulate fluid flow in 3D space.

- Around solid objects.
- Fluid: gas or liquid

Goal

Simulate fluid flow in 3D space.

- Around solid objects.
- Fluid: gas or liquid
- We assume fluid is *incompressible* (like water)

Goal

Simulate fluid flow in 3D space.

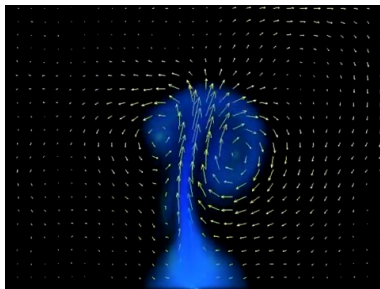
- Around solid objects.
- Fluid: gas or liquid
- We assume fluid is *incompressible* (like water)
- And *has no viscosity*.

wikipedia.org

Mathematical Representation for Fluid Flow

Represent the fluid's *velocity* at every time t and point in space \vec{x} as vector field

$$\vec{u}(t, \vec{x})$$



Evolution of the Flow

Flow evolves with time $\frac{\partial \vec{u}}{\partial t}$, by Navier-Stokes equations.

First: Newton's second law

$$\vec{F} = m\vec{a}$$

Evolution of the Flow

Flow evolves with time $\frac{\partial \vec{u}}{\partial t}$, by Navier-Stokes equations.

First: Newton's second law

$$\vec{F} = m\vec{a}$$

Uniform density $\implies m = 1$. So...

Evolution of the Flow

Flow evolves with time $\frac{\partial \vec{u}}{\partial t}$, by Navier-Stokes equations.

First: Newton's second law

$$\vec{F} = \vec{a}$$

Evolution of the Flow

Flow evolves with time $\frac{\partial \vec{u}}{\partial t}$, by Navier-Stokes equations.

First: Newton's second law

$$\vec{a} = \vec{F}$$

Evolution of the Flow

Flow evolves with time $\frac{\partial \vec{u}}{\partial t}$, by Navier-Stokes equations.

First: Newton's second law

$$\vec{a} = \vec{F}$$

\vec{u} is a vel., so $\frac{\partial \vec{u}}{\partial t}$ is accel. So

$$\frac{\partial \vec{u}}{\partial t} = \vec{F} = \text{sum of all forces}$$

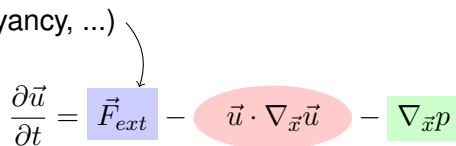
Navier-Stokes for no viscosity (AKA Euler)

- External Forces
(gravity, bouyancy, ...)

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} p$$

Navier-Stokes for no viscosity (AKA Euler)

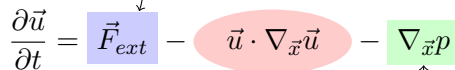
- External Forces
(gravity, bouyancy, ...)

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} p$$


- Convection
Flow moves because of flow

Navier-Stokes for no viscosity (AKA Euler)

- External Forces
(gravity, bouyancy, ...)

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} p$$


- Convection
Flow moves because of flow
- Pressure

Both equations

- Newton's 2nd

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} p \quad (\text{N})$$

Both equations

- Newton's 2nd

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} p \quad (\text{N})$$

- Incompressible

$$\nabla_{\vec{x}} \cdot \vec{u} = 0 \quad (\text{I})$$

Both equations

- Newton's 2nd

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} p \quad (\text{N})$$

- Incompressible

$$\nabla_{\vec{x}} \cdot \vec{u} = 0 \quad (\text{I})$$

- Two equations, two unknowns \vec{u} and p

Numerical Solving

Discretize

$$\vec{u}_{n,i} = \vec{u}(t_n, \vec{x}_i)$$

Numerical Solving

Discretize

$$\vec{u}_{n,i} = \vec{u}(t_n, \vec{x}_i)$$

Solve back and forth

$$\dots \implies \vec{u}_n \xRightarrow{(N), p=0} \hat{u}_{n+1} \xRightarrow{(I)} p_{n+1} \implies \vec{u}_{n+1} \xRightarrow{(N), p=0} \hat{u}_{n+2} \xRightarrow{(I)} p_{n+2} \dots$$

Numerical Solving

Discretize

$$\vec{u}_{n,i} = \vec{u}(t_n, \vec{x}_i)$$

Solve back and forth

$$\dots \implies \vec{u}_n \xrightarrow{(N),p=0} \hat{u}_{n+1} \xrightarrow{(I)} p_{n+1} \implies \vec{u}_{n+1} \xrightarrow{(N),p=0} \hat{u}_{n+2} \xrightarrow{(I)} p_{n+2} \dots$$

$p_{n-1} \implies \vec{u}_{n-1} \implies \hat{u}_n$ **is easy and fast,**
But $\hat{u}_n \implies p_n$ **is hard and slow!**

$$\hat{u}_{n+1} \implies p_{n+1}$$

By (I),

$$\Delta p = \nabla \cdot \hat{u}_n$$

$$(b = \nabla \cdot \hat{u}_n)$$

$$\Delta p = b$$

$$\hat{u}_{n+1} \implies p_{n+1}$$

By (I),

$$\Delta p = \nabla \cdot \hat{u}_n$$

$$(b = \nabla \cdot \hat{u}_n)$$

$$\Delta p = b$$

$$\frac{\partial^2}{\partial x^2} p + \frac{\partial^2}{\partial y^2} p = b$$

$$\hat{u}_{n+1} \implies p_{n+1}$$

By (I),

$$\Delta p = \nabla \cdot \hat{u}_n$$

$$(b = \nabla \cdot \hat{u}_n)$$

$$\Delta p = b$$

$$\frac{\partial^2}{\partial x^2} p + \frac{\partial^2}{\partial y^2} p = b$$

Replace derivatives with finite differences

$$\frac{\frac{p_{i+1,j} - p_{i,j}}{\Delta x} - \frac{p_{i,j} - p_{i-1,j}}{\Delta x}}{\Delta x} + \frac{\frac{p_{i,j+1} - p_{i,j}}{\Delta y} - \frac{p_{i,j} - p_{i,j-1}}{\Delta y}}{\Delta y} = b_{i,j}$$

$$\hat{u}_{n+1} \implies p_{n+1}$$

By (I),

$$\Delta p = \nabla \cdot \hat{u}_n$$

$$(b = \nabla \cdot \hat{u}_n)$$

$$\Delta p = b$$

$$\frac{\partial^2}{\partial x^2} p + \frac{\partial^2}{\partial y^2} p = b$$

Replace derivatives with finite differences

$$\frac{\frac{p_{i+1,j} - p_{i,j}}{\Delta x} - \frac{p_{i,j} - p_{i-1,j}}{\Delta x}}{\Delta x} + \frac{\frac{p_{i,j+1} - p_{i,j}}{\Delta y} - \frac{p_{i,j} - p_{i,j-1}}{\Delta y}}{\Delta y} = b_{i,j}$$

$$\frac{1}{l^2} (p_{i+1,j} + p_{i-1,j} + p_{i,j-1} + p_{i,j+1} - 4p_{i,j}) = b_{i,j}$$

Note each $b_{i,j}$ depends is a linear combination of 5 values of $p_{i,j}$ (7 in 3D).

$$\hat{u}_{n+1} \implies p_{n+1}$$

The (very sparse) matrix is then

$$\begin{pmatrix} \vdots & & \vdots & & \vdots & & \vdots \\ \dots & 0 & 1 & 1 & -4 & 1 & 1 & 0 & 0 & \dots \\ \dots & 1 & 0 & 0 & 1 & -4 & 0 & 1 & 1 & \dots \\ \vdots & & \vdots & & \vdots & & \vdots \end{pmatrix} \begin{pmatrix} \vdots \\ p_{i,j-1} \\ p_{i-1,j} \\ p_{i,j} \\ p_{i+1,j} \\ p_{i,j+1} \\ \vdots \end{pmatrix} = \begin{pmatrix} \vdots \\ \vdots \\ \vdots \\ b_{i,j} \\ b_{i+1,j} \\ \vdots \\ \vdots \end{pmatrix} l^2$$

$$\hat{u}_{n+1} \implies p_{n+1}$$

The (very sparse) matrix is then

$$\begin{pmatrix} \vdots & & \vdots & & \vdots & & \vdots \\ \dots & 0 & 1 & 1 & -4 & 1 & 1 & 0 & 0 & \dots \\ \dots & 1 & 0 & 0 & 1 & -4 & 0 & 1 & 1 & \dots \\ \vdots & & \vdots & & \vdots & & \vdots \end{pmatrix} \begin{pmatrix} \vdots \\ p_{i,j-1} \\ p_{i-1,j} \\ p_{i,j} \\ p_{i+1,j} \\ p_{i,j+1} \\ \vdots \end{pmatrix} = \begin{pmatrix} \vdots \\ \vdots \\ \vdots \\ b_{i,j} \\ b_{i+1,j} \\ \vdots \\ \vdots \end{pmatrix} l^2$$

(This is the graph Laplacian for a grid graph.)

$$\hat{u}_{n+1} \implies p_{n+1}$$

The (very sparse) matrix is then

$$\begin{pmatrix} \vdots & & \vdots & & \vdots & & \vdots \\ \dots & 0 & 1 & 1 & -4 & 1 & 1 & 0 & 0 & \dots \\ \dots & 1 & 0 & 0 & 1 & -4 & 0 & 1 & 1 & \dots \\ \vdots & & \vdots & & \vdots & & \vdots \end{pmatrix} \begin{pmatrix} \vdots \\ p_{i,j-1} \\ p_{i-1,j} \\ p_{i,j} \\ p_{i+1,j} \\ p_{i,j+1} \\ \vdots \end{pmatrix} = \begin{pmatrix} \vdots \\ \vdots \\ \vdots \\ b_{i,j} \\ b_{i+1,j} \\ \vdots \\ \vdots \end{pmatrix} l^2$$

(This is the graph Laplacian for a grid graph.)

We need to solve this equation $Lp = b$ for p in terms of b ! AHH!

Solving Methods (Related Work)

- Iterative technique: Conjugate Descent
 - Takes a long time

Solving Methods (Related Work)

- Iterative technique: Conjugate Descent
 - Takes a long time
- Iterative technique: Jacobi Method
 - Faster, but low accuracy

Solving Methods (Related Work)

- Iterative technique: Conjugate Descent
 - Takes a long time
- Iterative technique: Jacobi Method
 - Faster, but low accuracy
- Yang et al: Why not use a CNN!?! $p = \text{CNN}(b)$
 - Faster, but hard to train (need true p)
 - generalizes poorly
 - Long term stability issues

Solving Methods (Related Work)

- Iterative technique: Conjugate Descent
 - Takes a long time
- Iterative technique: Jacobi Method
 - Faster, but low accuracy
- Yang et al: Why not use a CNN!?! $p = \text{CNN}(b)$
 - Faster, but hard to train (need true p)
 - generalizes poorly
 - Long term stability issues
- This work
 - Use unsupervised training
 - Use multi-resolution CNN
 - Use long-term loss function

Unsupervised Training

- Start with \vec{u}_n .

Unsupervised Training

- Start with \vec{u}_n .
- Get \hat{u}_{n+1} from (N) without pressure term ($p = 0$)

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} \Pi \quad (\text{N}), p = 0$$

Unsupervised Training

- Start with \vec{u}_n .
- Get \hat{u}_{n+1} from (N) without pressure term ($p = 0$)

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} p \quad (\text{N}), p = 0$$

- p_{n+1} is correction to \hat{u}_{n+1} so (I) holds too.

$$\nabla_{\vec{x}} \cdot \vec{u} = 0 \quad (\text{I})$$

Unsupervised Training

- Start with \vec{u}_n .
- Get \hat{u}_{n+1} from (N) without pressure term ($p = 0$)

$$\frac{\partial \vec{u}}{\partial t} = \vec{F}_{ext} - \vec{u} \cdot \nabla_{\vec{x}} \vec{u} - \nabla_{\vec{x}} p \quad (\text{N}), p = 0$$

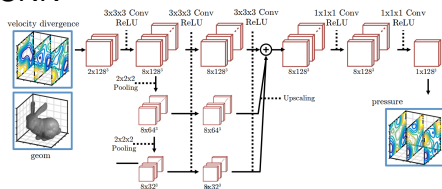
- p_{n+1} is correction to \hat{u}_{n+1} so (I) holds too.

$$\nabla_{\vec{x}} \cdot \vec{u} = 0 \quad (\text{I})$$

- Don't need true p_{n+1} , just use $|\nabla_{\vec{x}} \cdot \vec{u}| = |\text{div}(\vec{u})|$ as loss.

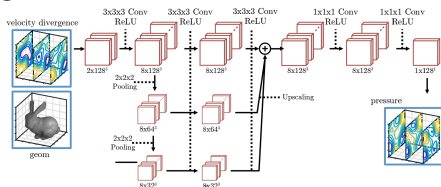
Multi-Resolution CNN and Long-term Loss

● CNN

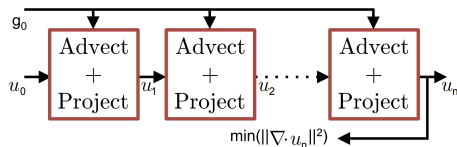


Multi-Resolution CNN and Long-term Loss

● CNN



● Long-term Loss



Results

- Fast runtimes (for capped loss)

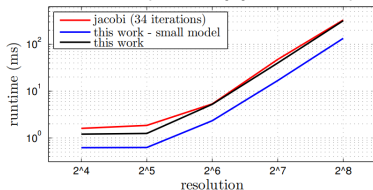


Figure 5. Pressure projection time (ms) versus resolution (PCG not shown for clarity).

Results

- Fast runtimes (for capped loss)

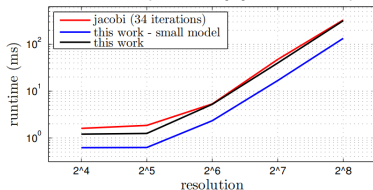
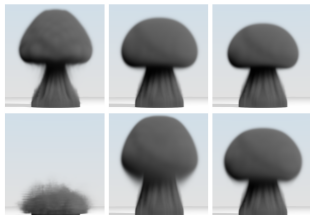


Figure 5. Pressure projection time (ms) versus resolution (PCG not shown for clarity).

- Visually comparable results



Discussion

Strengths

- 1 Hybrid approach use NN when best and PDE when best

Discussion

Strengths

- 1 Hybrid approach use NN when best and PDE when best
- 2 Unsupervised training technique is very clever

Discussion

Strengths

- 1 Hybrid approach use NN when best and PDE when best
- 2 Unsupervised training technique is very clever

Weakness/Improvement

- 1 Lack of quantitative metrics (could use simpler “wind tunnel” tests and macro effects)

Discussion

Strengths

- ① Hybrid approach use NN when best and PDE when best
- ② Unsupervised training technique is very clever

Weakness/Improvement

- ① Lack of quantitative metrics (could use simpler “wind tunnel” tests and macro effects)
- ② No 2D examples, No moving solids

Discussion

Strengths

- 1 Hybrid approach use NN when best and PDE when best
- 2 Unsupervised training technique is very clever

Weakness/Improvement

- 1 Lack of quantitative metrics (could use simpler “wind tunnel” tests and macro effects)
- 2 No 2D examples, No moving solids
- 3 Comparison to Yang et al. fails

Discussion Questions

- ❶ Possible quantitative metrics?

Discussion Questions

- 1 Possible quantitative metrics?
- 2 Applications other than animation?

Discussion Questions

- 1 Possible quantitative metrics?
- 2 Applications other than animation?
- 3 Why is a CNN good at solving sparse linear systems?

Discussion Questions

- 1 Possible quantitative metrics?
- 2 Applications other than animation?
- 3 Why is a CNN good at solving sparse linear systems?
- 4 “vorticity confinement?”

[More Piazza Discussion.](#)