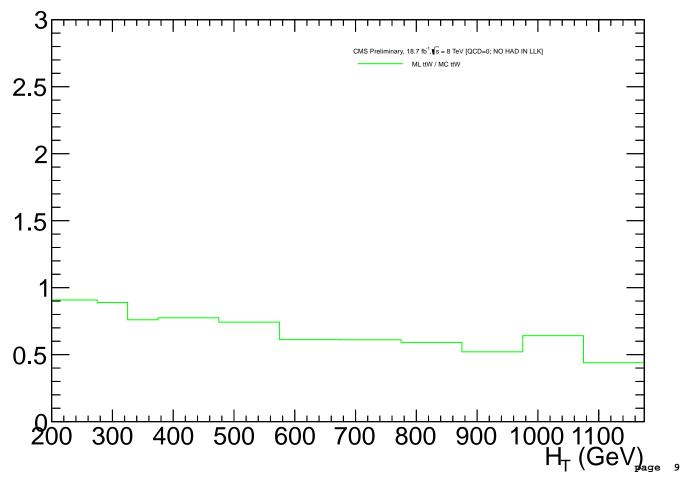
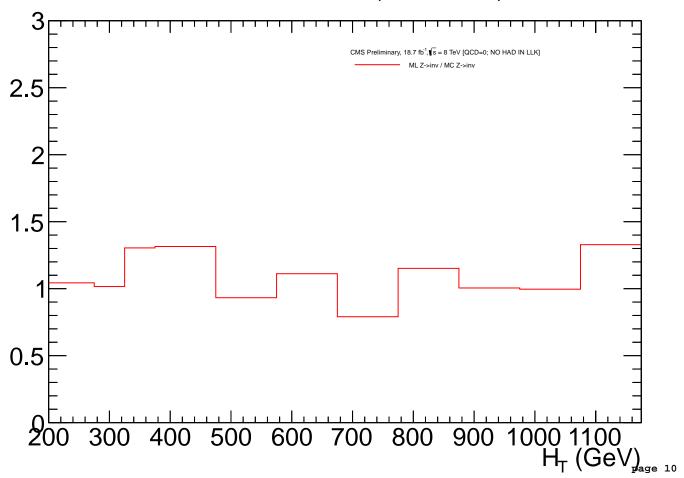


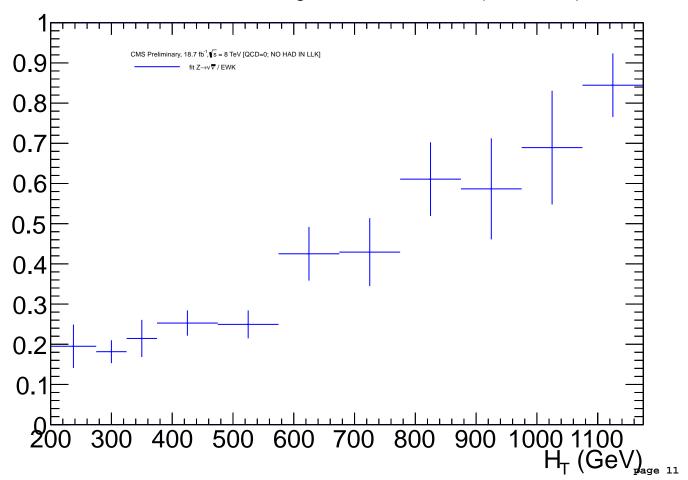
## ttW scale factor (result of fit)

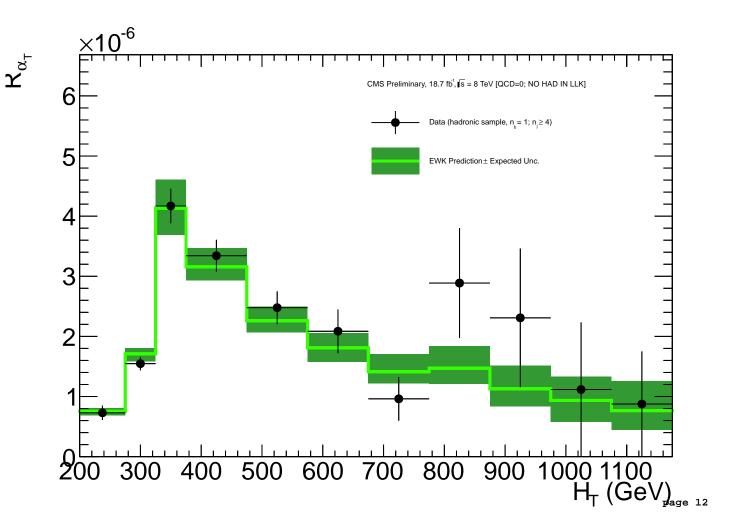


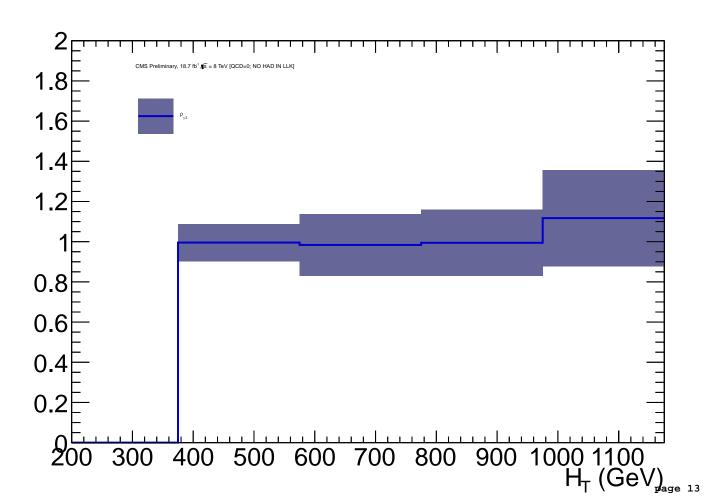
## Zinv scale factor (result of fit)

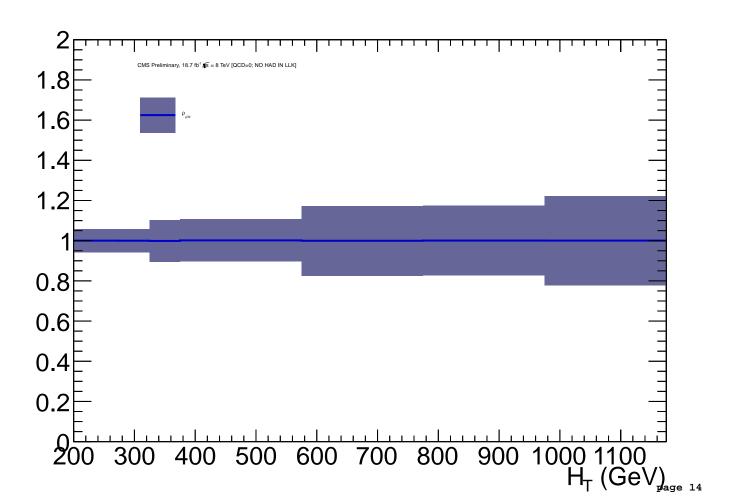


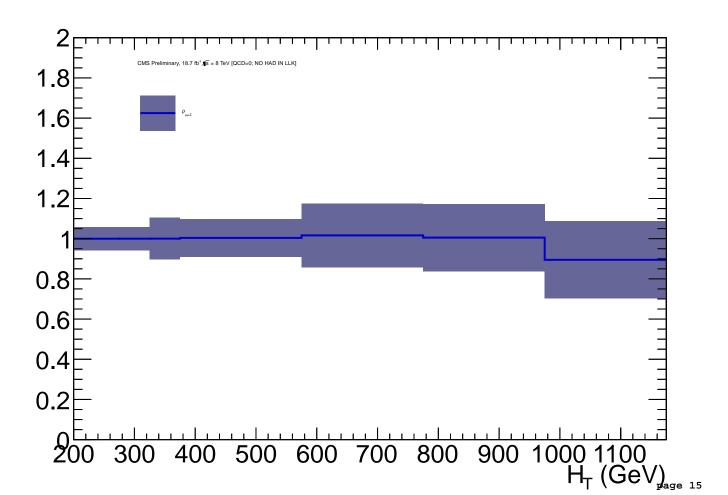
## fraction of EWK background which is Zinv (result of fit)











par name:	value	+/-	error	[	min	-	max	]
ewk 1b ge4j 0:	3.92e+01	+/-	3.4e+00	[0	.0e+00	_	3.8e+0	2]
fZinv 1b ge4j 0:	1.95e-01						1.0e+0	
ewk_1b_ge4j_1:	2.15e+02	+/-	1.3e+01				2.0e+0	
fZinv_1b_ge4j_1:	1.82e-01	+/-	2.8e-02	[0	.0e+00	_	1.0e+0	0]
ewk_1b_ge4j_2:	2.08e+02	+/-	2.1e+01	[0	.0e+00	-	2.1e+0	3]
fZinv_1b_ge4j_2:	2.14e-01	+/-	4.6e-02	[0	.0e+00	-	1.0e+0	0]
ewk_1b_ge4j_3:	1.50e+02	+/-	1.3e+01	[0	.0e+00	-	1.6e+0	3]
fZinv_1b_ge4j_3:	2.53e-01	+/-	3.1e-02	[0	.0e+00	-	1.0e+0	0]
ewk_1b_ge4j_4:	7.58e+01	+/-	6.9e+00	[ 0	.0e+00	-	8.3e+0	2]
fZinv_1b_ge4j_4:	2.49e-01	+/-	3.5e-02				1.0e+0	
ewk_1b_ge4j_5:	2.86e+01	+/-	3.9e+00	[ 0	.0e+00	-	3.3e+0	2]
fZinv_1b_ge4j_5:	4.25e-01						1.0e+0	
ewk_1b_ge4j_6:	1.03e+01			-			7.0e+0	_
fZinv_1b_ge4j_6:	4.29e-01	+/-	8.5e-02				1.0e+0	
ewk_1b_ge4j_7:	5.10e+00						1.0e+0	
fZinv_1b_ge4j_7:	6.11e-01						1.0e+0	
ewk_1b_ge4j_8:	1.96e+00			-			4.0e+0	_
fZinv_1b_ge4j_8:	5.87e-01						1.0e+0	
ewk_1b_ge4j_9:	8.37e-01						1.0e+0	
fZinv_1b_ge4j_9:	6.89e-01						1.0e+0	
ewk_1b_ge4j_10:	8.75e-01			-			1.0e+0	_
fZinv_1b_ge4j_10:	8.45e-01						1.0e+0	
rhoPhotZ_1b_ge4j_3:	9.96e-01						3.0e+0	
rhoPhotZ_1b_ge4j_4:	9.84e-01						3.0e+0	
rhoPhotZ_1b_ge4j_5:	9.94e-01			-			3.0e+0	-
rhoPhotZ_1b_ge4j_6:	1.12e+00						3.0e+0	
rhoMuonW_1b_ge4j_0:	1.00e+00						3.0e+0	
rhoMuonW_1b_ge4j_1:	1.00e+00						3.0e+0	
rhoMuonW_1b_ge4j_2:	9.99e-01			-			3.0e+0	_
rhoMuonW_1b_ge4j_3:	1.00e+00						3.0e+0	
rhoMuonW_1b_ge4j_4:	1.00e+00						3.0e+0	
rhoMuonW_1b_ge4j_5:	1.00e+00						3.0e+0	
rhoMuonW_1b_ge4j_6:	1.00e+00			-			3.0e+0	_
rhoMumuZ_1b_ge4j_0:	1.00e+00						3.0e+0	
rhoMumuZ_1b_ge4j_1:	1.00e+00						3.0e+0	
rhoMumuZ_1b_ge4j_2:	1.00e+00						3.0e+0	
rhoMumuZ_1b_ge4j_3:	1.00e+00			-			3.0e+0	_
rhoMumuZ_1b_ge4j_4:	1.02e+00						3.0e+0	
rhoMumuZ_1b_ge4j_5:	1.01e+00 8.95e-01						3.0e+0	
rhoMumuZ_1b_ge4j_6:	8.95e-01	+/-	1.9e-01	ι 0	.ue+00	-	3.UE+U	0 ]

## correlation\_matrix

