

# Tutorial 11 : Quadratic Curves (cntd.)

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Course of Essentials of Analytical Geometry and Linear Algebra I

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## □ Quadratic Curves

- Parabolas
- Circles
- Ellipses

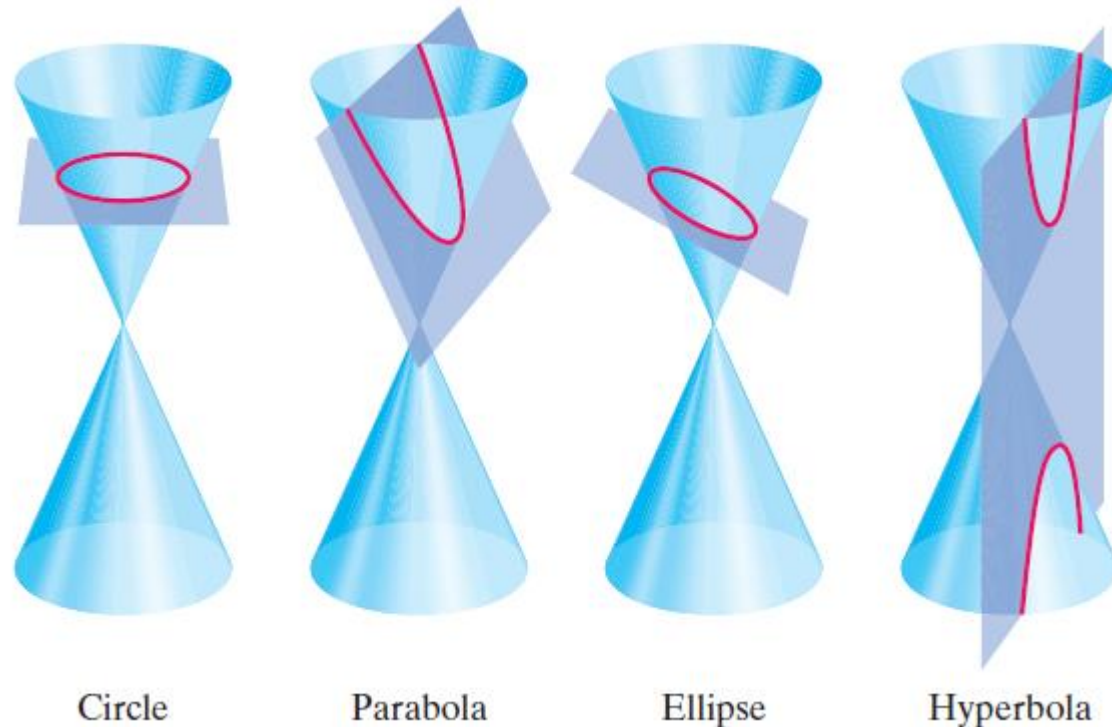
## □ Quadratic Curves

- Hyperbolas
- Rotation of axes

# Conic Sections

**Conic sections** are the curves obtained by intersecting a plane and a right circular cone.

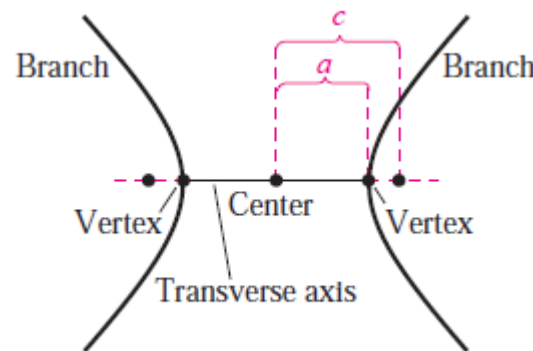
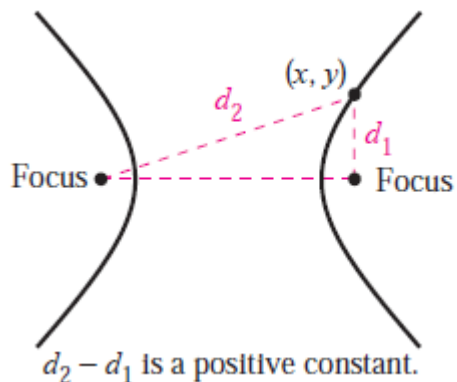
- ❖ A plane perpendicular to the cone's axis cuts out a circle;
- ❖ A plane parallel to a side of the cone produces a parabola;
- ❖ A plane at an arbitrary angle to the axis of the cone forms an ellipse;
- ❖ A plane parallel to the axis cuts out a hyperbola.



\*Figure from internet.

# Hyperbola (1/2)

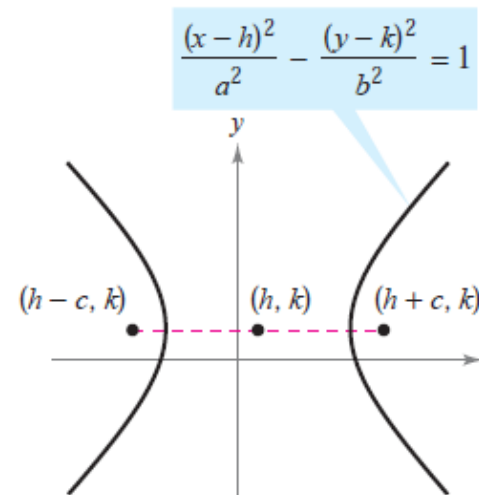
A **hyperbola** is the set of points in a plane such that the absolute value of the difference of the distance of each point from two fixed points is constant. Each fixed point is called a *focus*, and the point midway between the foci is called the *center*. The line containing the foci is the **transverse axis**. The graph is made up of two parts called **branches**. Each branch intersects the transverse axis at a point called the *vertex*.



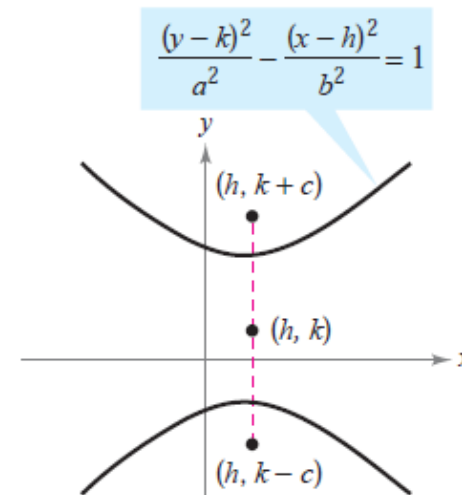
## The standard form of the equation

of a hyperbola with center at  $(h, k)$  can be seen in figure.

The vertices are  $a$  units from the center, and the foci are  $c$  units from the center. Moreover,  $c^2 = a^2 + b^2$ .



Transverse axis is horizontal.



Transverse axis is vertical.

# Hyperbola (2/2)

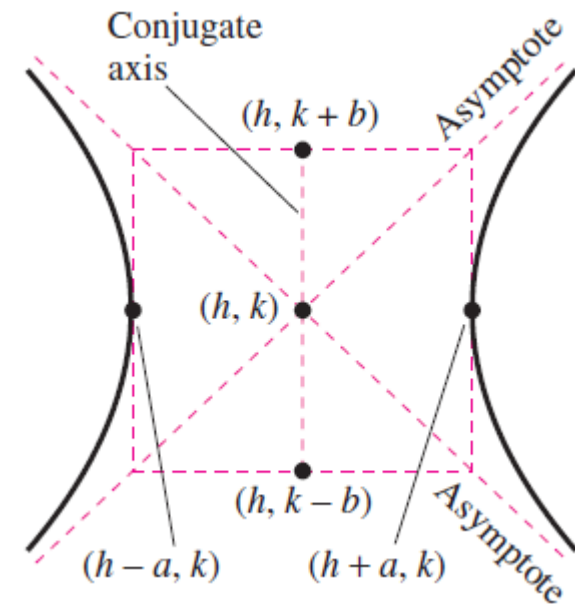
## Asymptotes of a Hyperbola

Each hyperbola has two asymptotes that intersect at the center of the hyperbola.

The asymptotes pass through the corners of a rectangle of dimensions  $2a$  by  $2b$ , with its center at  $(h, k)$ , as shown in figure.

Equations of Asymptotes of a Hyperbola	
Asymptotes for <b>horizontal</b> transverse axis	Asymptotes for <b>vertical</b> transverse axis
$y = k \pm \frac{b}{a}(x - h)$	$y = k \pm \frac{a}{b}(x - h)$

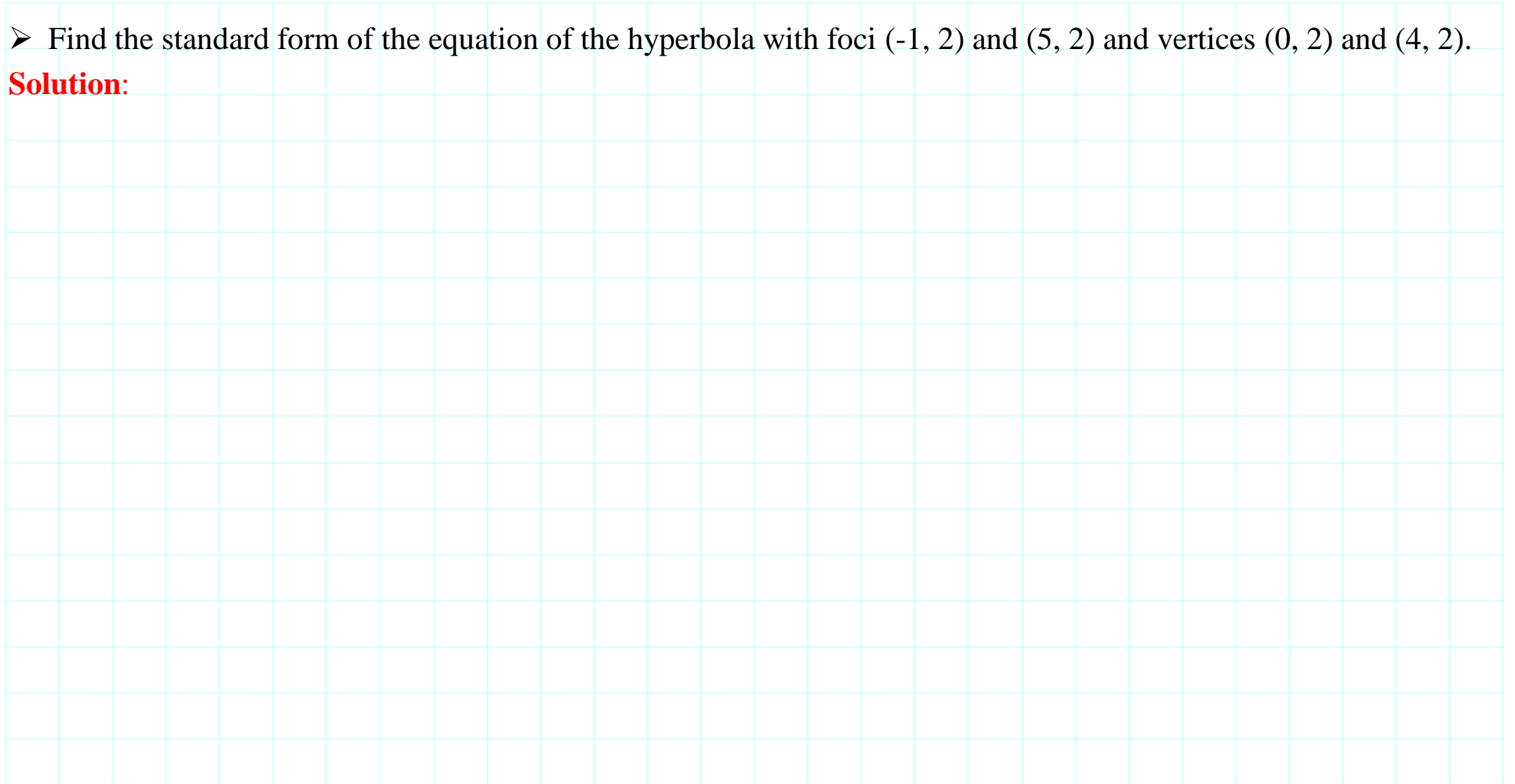
The conjugate axis of a hyperbola is the line segment of length  $2b$  joining  $(h, k + b)$  and  $(h, k - b)$  if the transverse axis is horizontal, and the line segment of length  $2b$  joining  $(h + b, k)$  and  $(h - b, k)$  if the transverse axis is vertical.



# Example 1

➤ Find the standard form of the equation of the hyperbola with foci  $(-1, 2)$  and  $(5, 2)$  and vertices  $(0, 2)$  and  $(4, 2)$ .

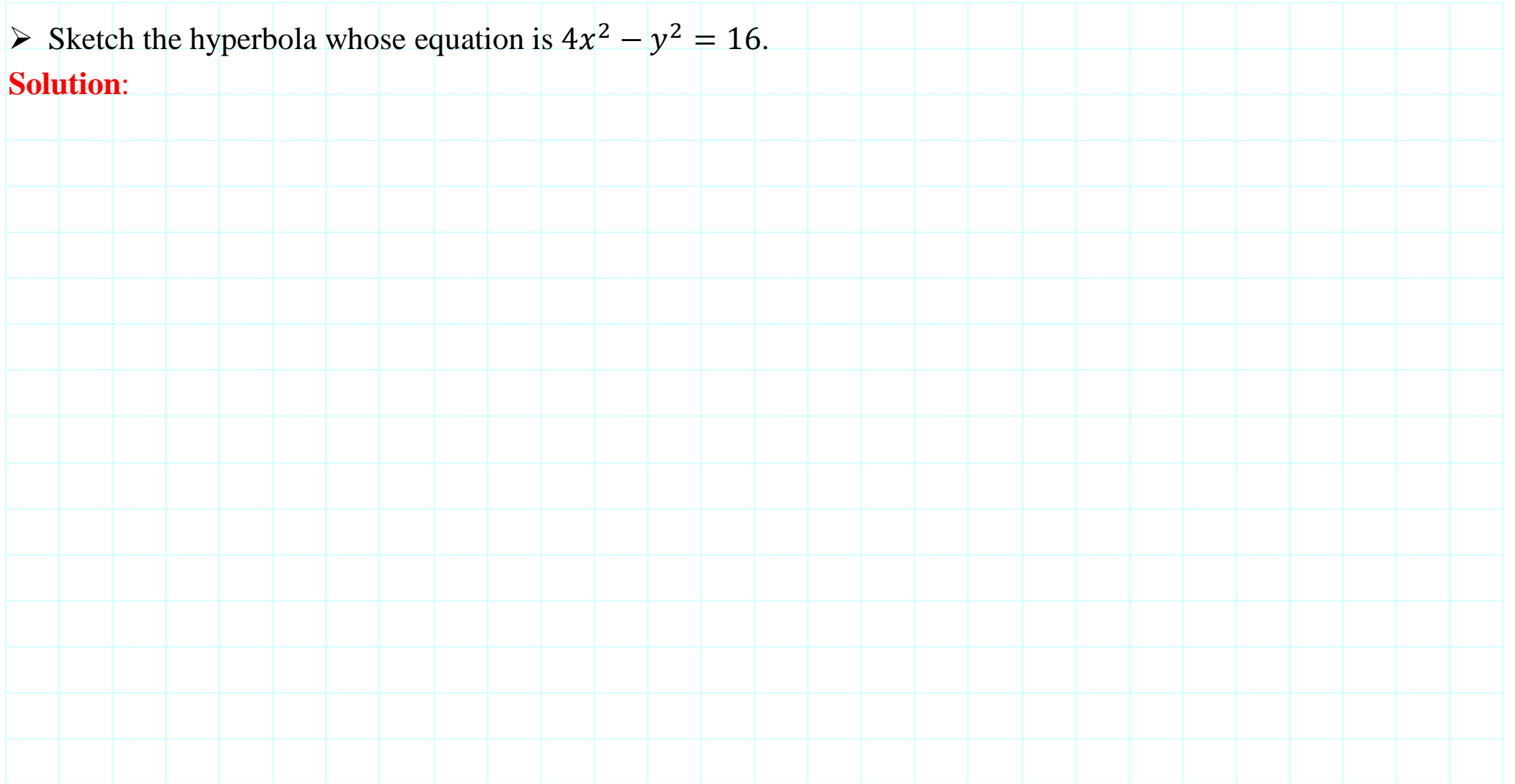
**Solution:**



## Example 2

➤ Sketch the hyperbola whose equation is  $4x^2 - y^2 = 16$ .

**Solution:**

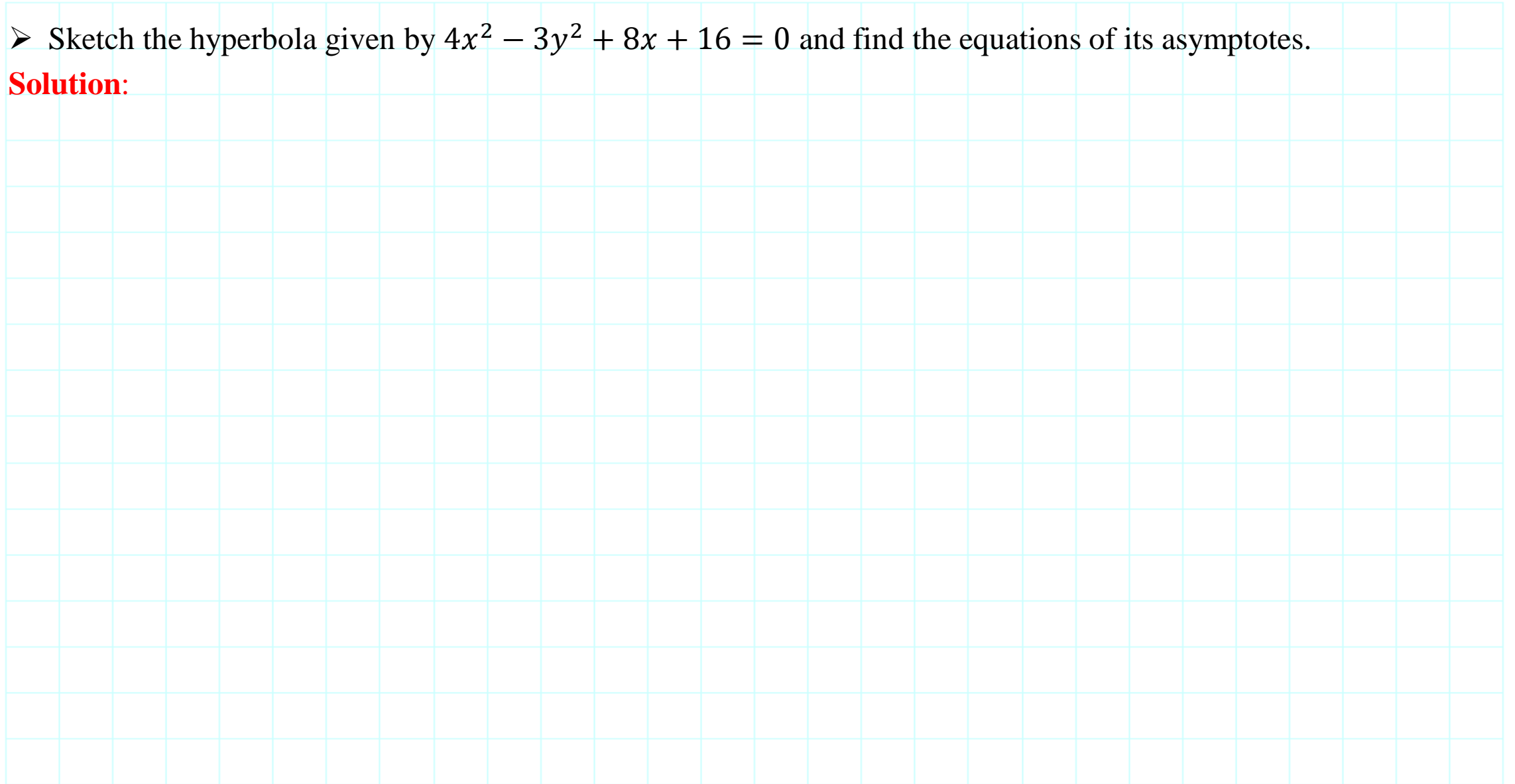




## Example 3

➤ Sketch the hyperbola given by  $4x^2 - 3y^2 + 8x + 16 = 0$  and find the equations of its asymptotes.

**Solution:**



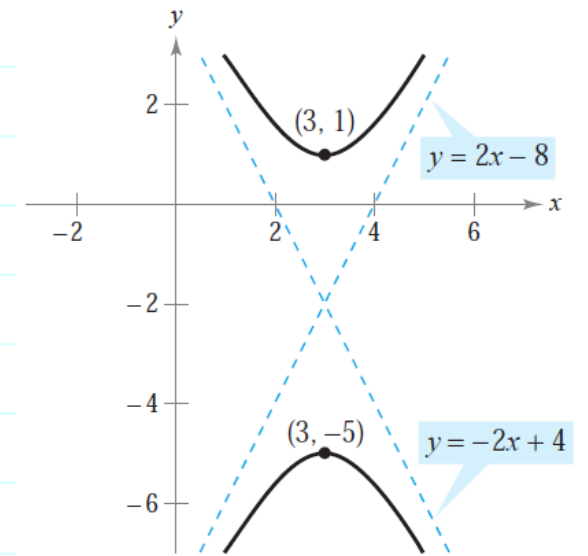
## Example 4

➤ Find the standard form of the equation of the hyperbola having vertices  $(3, -5)$  and  $(3, 1)$  and having asymptotes

$$y = 2x - 8 \text{ and } y = -2x + 4$$

as shown in figure.

**Solution:**



## Example 5

➤ Two microphones, 1 mile apart, record an explosion. Microphone A receives the sound 2 seconds before microphone B. Where did the explosion occur? (Assume sound travels at 1100 feet per second.)

**Solution:**

# Rotation (1/2)

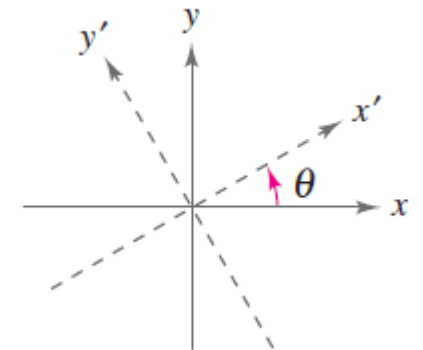
It is known that the equation of a conic with axes parallel to the coordinate axes has a standard form that can be written in the general form

$$Ax^2 + Cy^2 + Dx + Ey + F = 0. \quad \text{Horizontal or vertical axes}$$

In this section, you will study the equations of conics whose axes are rotated so that they are not parallel to either the  $x$ -axis or the  $y$ -axis. The general equation for such conics contains an  $xy$ -term.

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0 \quad \text{Equation in } xy\text{ - plane}$$

To eliminate this  $xy$ -term, you can use a procedure called **rotation of axes**. The objective is to rotate the  $x$ - and  $y$ -axes until they are parallel to the axes of the conic. The rotated axes are denoted as the  $x'$ -axis and the  $y'$ -axis, as shown in the figure.



## Rotation of Axes to Eliminate an $xy$ -Term

The general second-degree equation

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$

can be rewritten as

$$A'x'^2 + C'y'^2 + D'x' + E'y' + F' = 0$$

by rotating the coordinate axes through an angle  $\theta$ , where  $\cot 2\theta = \frac{A-C}{B}$ . The coefficients of the new equation are obtained by making the substitutions

$$x = x' \cos \theta - y' \sin \theta \text{ and } y = x' \sin \theta + y' \cos \theta.$$

# Rotation (2/2)

## Rotation Invariants

The rotation of the coordinate axes through an angle  $\theta$  that transforms the equation  $Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$  into the form  $A'x'^2 + C'y'^2 + D'x' + E'y' + F' = 0$  has the following rotation invariants.

1)  $F = F'$

2)  $A + C = A' + C'$

3)  $B^2 - 4AC = (B')^2 - 4A'C'$

Note that because  $B' = 0$ , the invariant  $B^2 - 4AC$  reduces to

$$B^2 - 4AC = -4A'C' \quad \text{Discriminant}$$

## Classification of Conics by the Discriminant

The graph of the equation  $Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$  is, except in degenerate cases, determined by its discriminant as follows.

1. Ellipse or circle:  $B^2 - 4AC < 0$

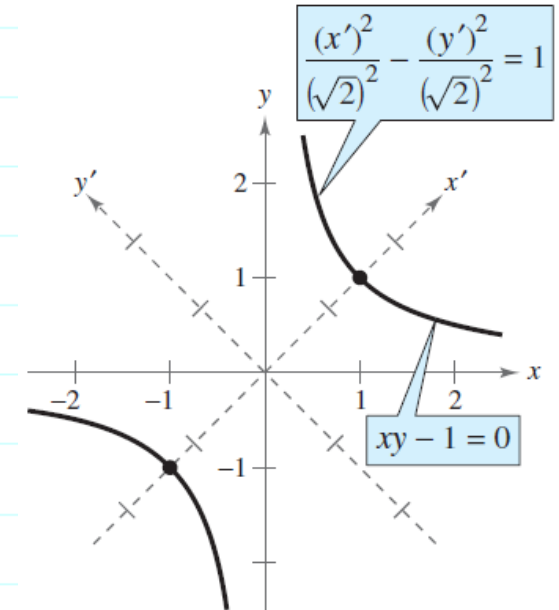
2. Parabola:  $B^2 - 4AC = 0$

3. Hyperbola:  $B^2 - 4AC > 0$

## Example 6

- Rotate the axes to eliminate the  $xy$ -term in the equation  $xy - 1 = 0$ . Then write the equation in standard form and sketch its graph.

**Solution:**



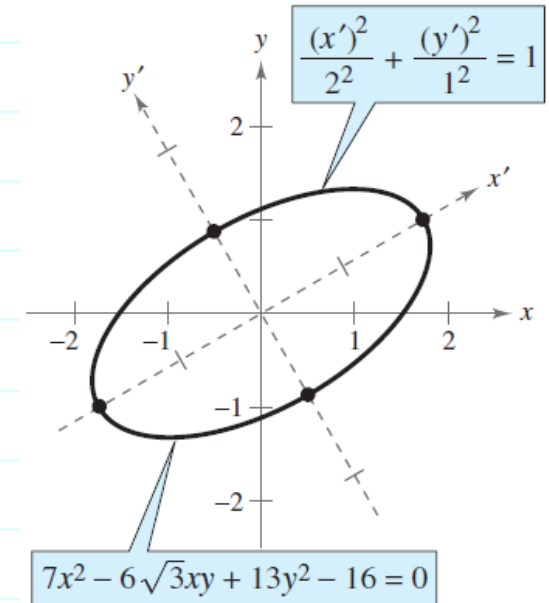
## Example 7

➤ Rotate the axes to eliminate the  $xy$ -term in the equation

$$7x^2 - 6\sqrt{3}xy + 13y^2 - 16 = 0.$$

Then write the equation in standard form and sketch its graph.

**Solution:**



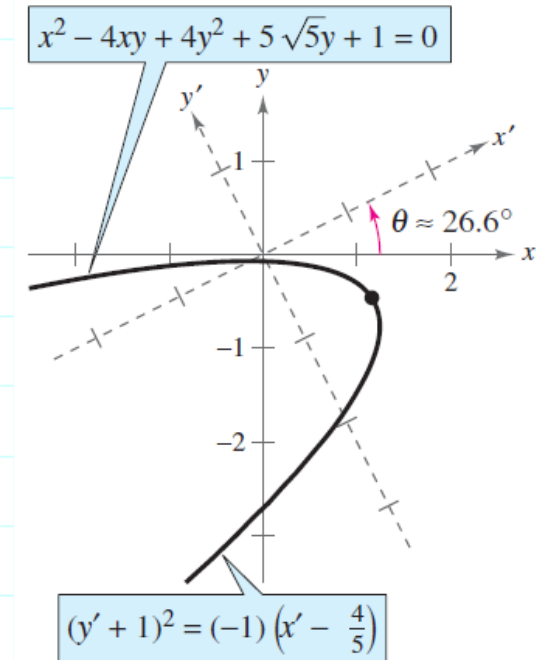
## Example 8

➤ Rotate the axes to eliminate the  $xy$ -term in the equation

$$x^2 - 4xy + 4y^2 + 5\sqrt{5}y + 1 = 0.$$

Then write the equation in standard form and sketch its graph.

**Solution:**





□ Quadratic Surfaces

# Good Luck