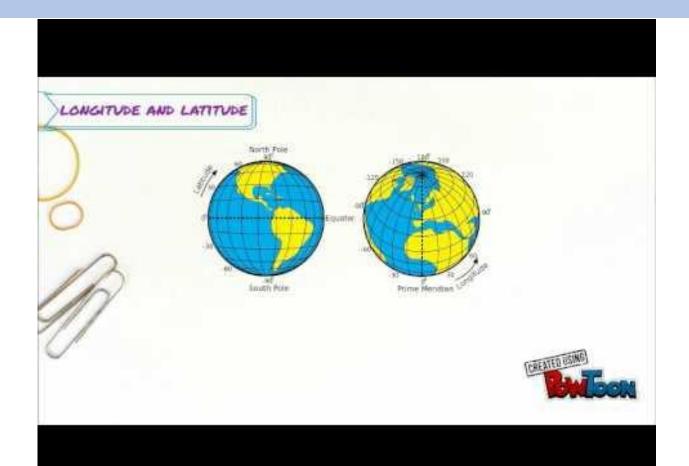


### Essentials of Analytical Geometry and Linear Algebra 1

Line on the plane







## **Objectives**

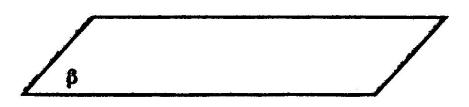
- To see the structure of all formulas which were covered
- To understand how to transform 1 form to another form
- How to use all this stuff

#### What elements do we know

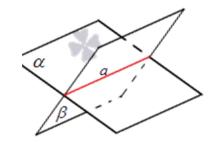
Line in plane

 $\sqrt{\alpha}$ 

Plane

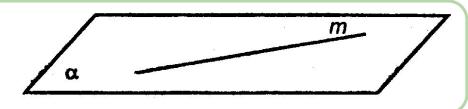


Line in space

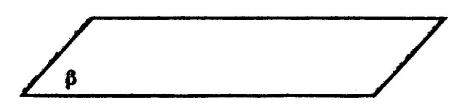


### What elements do we know

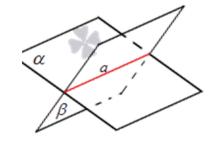
Line in plane



Plane



Line in space





# Line in plane (formulas)

go General eq. Ax +By +C=0	By = - n.V.
Slope-intercept $y = kx + 6$ 3 Canonical $\frac{x - x_0}{a_x} = \frac{y - y_0}{a_y} = 7$	
14 favametrical $\chi = \chi_0 + \alpha_2 \gamma$	
Slying normal line (v.n)= -C	
$(\bar{r}-r_0,\bar{n})=0 \bar{n}=(A)$	

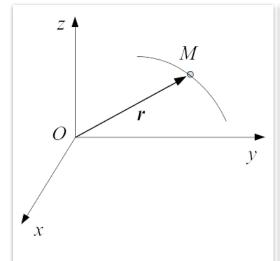


## Why do we need parametric form?

- 1. Robotics (kinematics)
- 2. CAD (computer aided design)

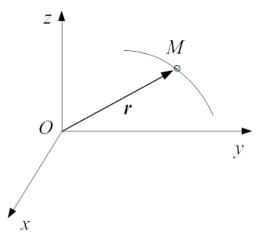


### Methods of Describing Motion of a Particle

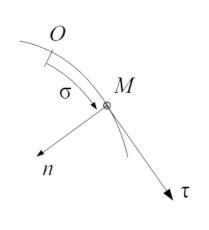


Vector

$$r = r(t) r = x i + y j + z k$$



Coordinate



Natural

$$\sigma = OM = \sigma(t)$$

## Velocity of a particle (1)

Velocity direction is always tangent to the path

$$V = \frac{\mathrm{d} \mathbf{r}}{\mathrm{d} t} = \dot{r}$$

$$V = \frac{\mathrm{d} (x \, \mathbf{i} + y \, \mathbf{j} + z \, \mathbf{k})}{\mathrm{d} t} = \frac{\mathrm{d} (x \, \mathbf{i})}{\mathrm{d} t} + \frac{\mathrm{d} (y \, \mathbf{j})}{\mathrm{d} t} + \frac{\mathrm{d} (z \, \mathbf{k})}{\mathrm{d} t} = \frac{\dot{x} \, \mathbf{i} + \dot{y} \, \mathbf{j} + \dot{z} \, \mathbf{k}}$$

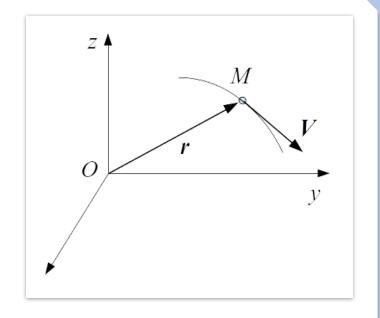
$$V = \begin{bmatrix} \dot{x}(t) \\ \dot{y}(t) \\ \dot{z}(t) \end{bmatrix}$$

$$V_{x} = \dot{x}(t)$$

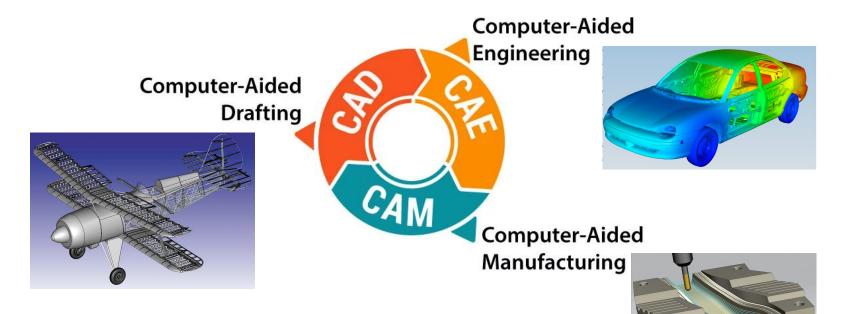
$$V_{y} = \dot{y}(t)$$

$$V_{z} = \dot{z}(t)$$

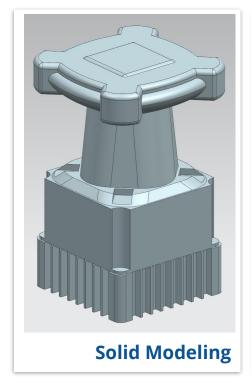
 $V = \sqrt{V_x^2 + V_y^2 + V_z^2}$ 



### Computer Aided Design (1)



## Computer Aided Design (2)







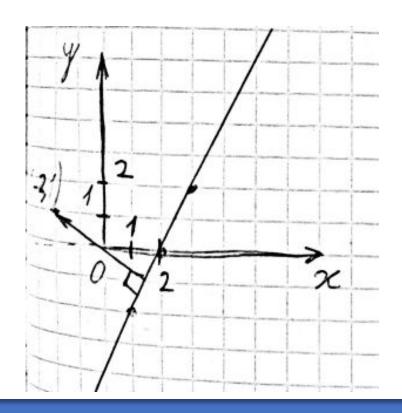
# Computer Aided Design (3)

Type ◆	Form +	Example +	Description +
1. Explicit	y=f(x)	y = mx + b	Line
2. Implicit	f(x,y)=0	$(x-a)^2+(y-b)^2=r^2$	Circle
3. Parametric $x=rac{g(t)}{w(t)};y=rac{h}{u}$	$x = \frac{g(t)}{t}$ $y = \frac{h(t)}{t}$	$x=a_0+a_1t; y=b_0+b_1t$	Line
	$w = w(t)^{-1} y = w(t)^{-1}$	$x=a+r\cos t;y=b+r\sin t$	Circle



# Line in plane (Task)

Write down all forms of the line





# Line in plane (Answer)

$$\begin{cases} 0 = k2 + 6 & = 7 \cdot 6 = -2k = 76 = -4 \\ 2 = k3 + 6 & k = 2 \end{cases}$$

$$2) \quad y = 2 \times -4$$

$$1) \quad -2 \times +1 \cdot y + 9 = 0$$

$$1) \quad A \quad B \quad C$$

$$3) \quad y = 2 \cdot 2 - 2$$

$$2 \quad 4) \quad \begin{cases} x = 2 + 7 \\ y = 2 \end{cases}$$

$$4) \quad \begin{cases} x = 2 + 7 \\ y = 2 \end{cases}$$

$$5) \quad (x) \begin{pmatrix} -2 \\ y \end{pmatrix} \begin{pmatrix} -2 \\ 1 \end{pmatrix} = -4 \cdot (x + 2) \begin{pmatrix} -2 \\ 1 \end{pmatrix} = 0$$



### Formulas of distances

1) Point to line 
$$d = [R-V_0, \alpha]$$
 Umnov 107

[a]

2) Line to Line  $= \text{if collinear } h = [LV_2-V_1, \alpha]$  Unnov 117

Skew  $h = [V_2-V_1, \alpha_1, \alpha_2]$ 

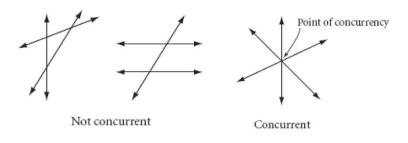
#### Tasks 1 and 2

- 1. Find the slope of the line joining the points (2,3) and (4,-5).
- 2. Find the slope of the line 2x 3y + 7 = 0.



3. Find the equation of the straight line, the portion of which between the axes is bisected at the point (2, -5).

- 5. Find the equation of the straight line concurrent with the lines 2x+3y=3 and x+2y=2 and also concurrent with the lines 3x-y=1 and x+5y=11.
  - Concurrent Lines or segments that have three or more points in common



7. Find the centroid of the triangle formed by the lines given by the equations  $12x^2 - 20xy + 7y^2 = 0$  and 2x - 3y + 4 = 0.



7. Find the centroid of the triangle formed by the lines given by the equations  $12x^2 - 20xy + 7y^2 = 0$  and 2x - 3y + 4 = 0.



# Task 5 (hints) (possible solution)

7. Find the centroid of the triangle formed by the lines given by the equations  $12x^2 - 20xy + 7y^2 = 0$  and 2x - 3y + 4 = 0.

$$C = rac{1}{3}(L+M+N) = \left(rac{1}{3}(x_L+x_M+x_N), \;\; rac{1}{3}(y_L+y_M+y_N)
ight).$$

