## Introduction to Deep Learning with Keras

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### Slides

• Slides available from (this will redirect to my github repo.):

#### https://git.io/knu-slides-2019

- Other Resources:
  - Keras documentation: http://keras.io/
  - Tensorflow's guide to Keras:
    - https://www.tensorflow.org/guide/keras
  - Another tutorial presentation: https://uwaterloo.ca/data-science/sites/ca.data-science/fil

### Goals

- If you're already a deep learning master, not the talk for you!
- Get up and running quickly with Deep Learning
  - In particular, the goal is to build neural networks you can take home today!
- Therefore, use Keras to get up and running quickly
- Outline of the session:
  - Basic Usage of Keras (Iris)
  - Convolutional Neural Net in Keras (MNIST)
  - GANs (using MNIST)
- For this lecture, I recommend using google colaboratory
  - Machine learning education and research tool setup by google, all the packages are installed, just need a google account to sign in

https://colab.research.google.com

## Dependencies

However,

If you want to follow along with a local setup:

With python and pip installed, you can pull the dependencies by pip

installing (you might need to add '-user' to the end of the command lines):

```
# Optional, setup a separate virtualenv to keep everything clean
virtualenv ENV
source ENV/bin/activate
# Download dependencies, tensorflow will be the CPU version
pip install matplotlib tensorflow seaborn scikit-learn h5py jupyter
# Then you could start a notebook
jupyter notebook
```

For a GPU tensorflow, usually best to build yourself (out of scope)

Now, let's setup a new workspace

# Google Colab / Jupyter Basic Usage

- https://colab.research.google.com/notebook
- Offers free jupyter-notebook-as-a-service in the cloud
  - Even offers free access to cloud-based GPUs
- Has all the packages we'll need for today pre-installed
- Demo
  - Basic jupyter usage

```
!ls # execute external commands
import os
?os # help at your fingertips
pi = 3.14159 # interpreter persists over cells
pi*2

def area(radius):
    return pi*radius**2

area(1)
# inline plotting
import numpy as np
import numpy as np
import matplotlib.pyplot as plt

x = np.linspace(-3.14, 3.14, 100)
y = np.sin(x)
plt.plot(x, y)
plt.show()
```

#### Keras





- Deep learning framework built by Google engineer François Chollet
- High-level interface built allowing eg Theano or Tensorflow as a backend
  - Has been accepted into mainline Tensorflow, so always accessible there
- Library written in python, user-friendly interface
- Easy to get started building networks
- Highly modular and easily expandable
  - Can drop down into the underlying library when complex/bespoke operations are needed
- Quickly build and train serious models

#### imports

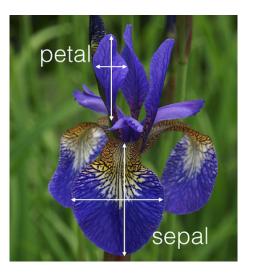
- Follow along either on the web-based service, or your own machine
- Lets pull in all the imports and definitions we'll need

```
import h5pv
import matplotlib
# matplotlib.use("AGG") # To batch graphics
import matplotlib.pyplot as plt
import os
import seaborn as sns
from sklearn.model_selection import train_test_split
import sklearn
import numpy as np
import tensorflow as tf
keras = tf.keras
Sequential = keras. Sequential
Activation = keras.layers.Activation
Dense = keras.layers.Dense
LeakyReLU = keras.layers.LeakyReLU
BatchNormalization = keras.layers.BatchNormalization
Reshape = keras.lavers.Reshape
UpSampling2D = keras.layers.UpSampling2D
Dropout = keras.layers.Dropout
Conv2D = keras.lavers.Conv2D
MaxPooling2D = keras.lavers.MaxPooling2D
Flatten = keras.layers.Flatten
SGD = keras.optimizers.SGD
mnist = keras datasets mnist
```

# Overarching Idea of (Supervised) Maching Learning

- Framework for Machine Learning: given a set of data, and set of expected outputs (typically categories), build a system which learns how to connect data to output
- Neural Network is one type, connect stacks of tensor operators with fixed linear and non-linear transformations
- Optimize transformation parameters so as to approximate expected outputs

### The iris dataset and a basic network with Keras



- Let's take a concrete example
- The iris dataset is a classic classification task, first studied by Fisher in 1936.
- The goal is, given features measured from a particular iris, classify it into one of three species
  - Iris setosa, virginica, versicolor.
- The variables are: Sepal width and length, petal width and length (all in cm).

### Iris dataset

We begin by loading the iris dataset, helpfully available from the seaborn pacakge, which also lets us create plots showing the correlations between the variables.

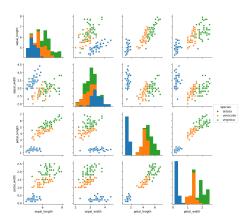
```
iris = sns.load_dataset("iris")
iris.head()
```

	sepal_length	sepal_width	petal_length	petal_width	species
0	5.1	3.5	1.4	0.2	setosa
1	4.9	3.0	1.4	0.2	setosa
2	4.7	3.2	1.3	0.2	setosa
3	4.6	3.1	1.5	0.2	setosa
4	5.0	3.6	1.4	0.2	setosa

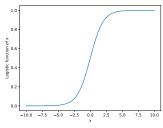
#### Iris Variables

Lets view the basic variables we have. Setosa (blue) looks easily separable by the petal length and width, but versicolor and virginica are a little tricky.

```
plot = sns.pairplot(iris, hue="species")
plot.savefig('iris.png'); 'iris.png'
```

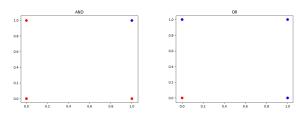


## The Logistic Function and Logistic Regression



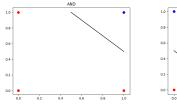
- The logistic (or sigmoid) function is defined as  $f(x) = \frac{1}{1+e^{-x}}$ 
  - Looks like a classic "turn-on" curve
- Concentrate on the case of two classes (cat/dog or electron/photon), and ask what we want from a classifier output
  - We need to distinguish between the two classes using the output:
  - If the value is 0, it represents the classifier identifying one class (cat)
  - If its near 1, the classifier is identifies the other class (dog)
  - Thus, we need to transform the input variables into 1D, then pass through the logistic function
- This is a simple classification technique called logistic regression

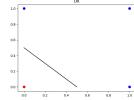
# Some very simple examples for simple logistic regression



- Let's think about approximating some simple binary functions
- OR and AND gates
  - OR is 0 (red) if both input are 0, 1 (blue) otherwise
  - AND is 1 if both inputs are 1, 0 otherwise
- Can we find logistic function approximations for this?
  - $\bullet$  That is,  $f(x_1,x_2)$  returns approximately 1 or 0 at the indicated points

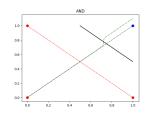
# Some very simple examples for simple logistic regression

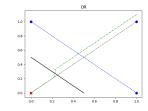




- Let's think about approximating some simple binary functions
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  - OR is 0 (red) if both input are 0, 1 (blue) otherwise
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- Can we find logistic function approximations for this?
  - $\bullet$  That is,  $f(\textit{x}_{1},\textit{x}_{2})$  returns approximately 1 or 0 at the indicated points
- Yes! Take the projection perpendicular to the line

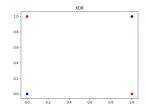
# Some very simple examples for simple logistic regression





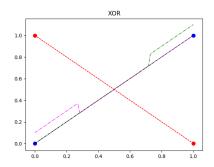
- Let's think about approximating some simple binary functions
- OR and AND gates
  - OR is 0 (red) if both input are 0, 1 (blue) otherwise
  - AND is 1 if both inputs are 1, 0 otherwise
- Can we find logistic function approximations for this?
  - ullet That is,  $f(x_1,x_2)$  returns approximately 1 or 0 at the indicated points
- Yes! Take the projection perpendicular to the line
- and have the logistic turn on at the line (in the 2D plane the logistic function will turn on as a "wave-front" along the black line shown)
  - e.g.  $f(x_1, x_2) = \sigma(2x_1 + 2x_2 1)$  for OR,  $f(x_1, x_2) = \sigma(2x_1 + 2x_2 - 3)$  for AND  $[\sigma]$  is our logistic function]

# Very simple example with issues for Logistic Regression



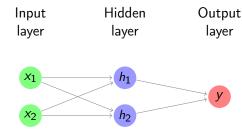
- Now consider the XOR gate: 1 if both inputs are the same, 0 otherwise
- The XOR gate can't be generated with a logistic function!
- Try it: no matter what line you draw, can't draw a logistic function that turns on only the blue!

# How to Fix: more logistic curves!



- Can fix by having 2 turn-on curves, one turning on either of the blue points, then summing the result
- $f(x_1, x_2) = \sigma(2x_1 + 2x_2 1) + \sigma(-2x_1 2x_2 + 1)$

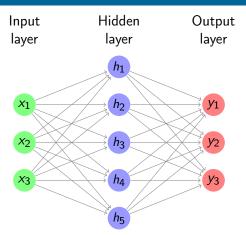
### The Feed-Forward Neural Network



- Consider the structure of what we just made
  - $y = f(x_1, x_2) = \sigma(-1 + 2x_1 + 2x_2) + \sigma(1 2x_1 2x_2)$
- Decompose the function into:
  - the input layer of  $\hat{x}$ ,
  - the hidden layer which calculates  $h_i = \beta_i \cdot x$  then passes if through the activation function  $\sigma$ , (called "sigmoid" in NN terms)
    - There is an extra  $\beta_0$ , called the *bias*, which controls how big the input into the node must be to activate
  - the *output layer* which sums the results of the hidden layer and gives y

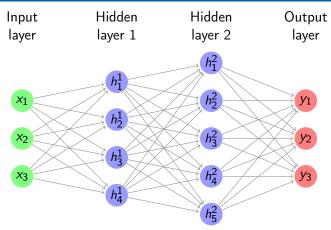
• 
$$y = 0 + 1 \cdot \sigma(h_1) + 1 \cdot \sigma(h_2)$$

### Feed-Forward Neural Network



- In general, we could have several input variables, and output variables
- In the case of classification, we would usually have a final softmax applied to  $\hat{y}$ , but could use any activation  $\varphi$  here also
  - softmax normalizes the output layer so it sums to 1:  $f_k(x) = \frac{e^{-y_k}}{\sum_i e^{-y_i}}$

### Feed-Forward Neural Network



- We can even have several hidden layers
  - The previous layer acts the same as an input layer to the next layer
- We call each node in the network a neuron
- The deep learning algorithms we will see later are just variations on this theme, using more complicated transformations

## Universal Approximation Thereom

Let  $\varphi: \mathbb{R} \to \mathbb{R}$  be a nonconstant, bounded, and continuous function. Let  $I_m$  denote the m-dimensional unit hypercube  $[0,1]^m$ . The space of real-valued continuous functions on  $I_m$  is denoted by  $C(I_m)$ . Then, given any  $\varepsilon > 0$  and any function  $f \in C(I_m)$ , there exist an integer N, real constants  $v_i, b_i \in \mathbb{R}$  and real vectors  $w_i \in \mathbb{R}^m$  for  $i = 1, \ldots, N$  such that we may define:

$$F(x) = \sum_{i=1}^{N} v_i \varphi\left(w_i^T x + b_i\right)$$

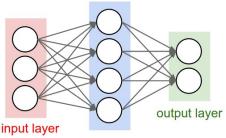
as an approximate realization of the function f; that is,

$$|F(x) - f(x)| < \varepsilon$$

for all  $x \in I_m$ . In other words, functions of the form F(x) are dense in  $C(I_m)$ . This still holds when replacing  $I_m$  with any compact subset of  $\mathbb{R}^m$ .

- In brief: with a hidden layer (of enough nodes), any (sensible) function  $f: \mathbb{R}^m \to \mathbb{R}$  can be approximated by a feed-forward NN
  - ullet Any (sensible) activation  $\varphi$  can work, not just  $\sigma$
- There is a simple, graphical proof for those who are interested: http://neuralnetworksanddeeplearning.com/chap4.html

### Neural Networks Overview



hidden layer

- Example shown: input vector  $\vec{x}$ , goes through  $\vec{y}_{hidden} = W\vec{x} + \vec{b}$ , then  $\vec{y}_{output} = \sigma(\vec{y}_{hidden})$  ( $\sigma$  is some non-linear turn-on curve)
- I.e. hidden layer combines  $\vec{x}$  by some weights, then if the weighted sum passes a threshold  $\vec{b}$ , we turn on the output (with the  $\sigma(x)=1/(1+e^{-x})$  to gate the ops)
- Need to train the weight matrix W and the bias vector b and optimize
   a "loss" function that represents a distance from the target output

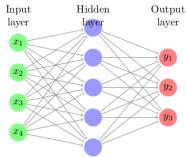
# Backpropagation

- The algorithm to train neural networks is called backpropagation
- Its essentially a gradient descent implemented taking the network structure into account to speed up evaluation of the partials
- To apply gradient descent, need a function of a single variable, called the loss
  - $L(x_i|\sigma) = \sum_i |x_i y_i|^2$  for inputs  $x_i$  and network output  $y_i(\sigma)$
- We start with the parameters set to arbitrary values, usually picked from e.g. unit gaussian
- We run a forward pass through the network and calculate the loss
- Using the chain rule, calculate *all* the derivates backward from the loss to the higher layers
- Propagate changes based on the gradient  $\Delta w_i = -\eta \frac{\partial f}{\partial w_i}$
- For more on how backpropagation works: http://neuralnetworksanddeeplearning.com/chap2.html

#### Keras Networks

In order to classify the irises, we'll build a simple network in Keras.

- The basic network type in Keras is the Sequential model.
- The Sequential model builds a neural network by stacking layers
  - Keras also has a Graph model that allows arbitrary connections
- It builds up like lego, adding one layer on top of another and connecting between the layers
  - Keras comes with a menagerie of pre-built layers for you to use.
- Interface to/from the model with numpy arrays



## Model

- Our model will be a simple NN with a single hidden layer
- We start by building a Sequential model and add a Dense (fully-connected) layer, with sigmoid activation
- Dense: standard layer, all inputs connect to all outputs:  $\hat{y} = W\hat{x} + \hat{b}$ 
  - keras.layers.Dense(output\_dim)
  - Can also set the initalization, add an activation layer inline, add regularizers inline, etc.
- Activation: essentially acts as a switch for a given node, turns output on/off based on threshold
  - keras.layers.Activation( type )
    - Where *type* might be:
  - *sigmoid*:  $f(x) = \frac{1}{1 + e^{-x}}$
  - tanh:  $f(x) = tanh x = \frac{e^x e^{-x}}{e^x + e^{-x}}$
  - relu:  $f(x) = \max(0, x)$ , 'rectified linear unit'
  - softplus:  $f(x) = \ln(1 + e^x)$ , smooth approx. to relu
  - softmax:  $f_k(x) = \frac{e^{-x_k}}{\sum_i e^{-x_i}}$  for the k'th output, as last layer of categorical distribution, represents a probability distribution over the outputs

# Build a model: Python code

```
# Build a model
model = Sequential()
model.add(Dense(128, input_shape=(4,)))
model.add(Activation('sigmoid'))
# model.add(Dense(128))
# model.add(Activation('sigmoid'))
model.add(Dense(3))
model.add(Activation('softmax'))
model.compile(optimizer='adam', loss='categorical_crossentropy',
               metrics=['accuracy'])
model.summary()
Layer (type)
                     Output Shape
dense 1 (Dense)
            (None, 128)
activation_1 (Activation) (None, 128)
dense_2 (Dense) (None, 3)
activation 2 (Activation) (None, 3)
```

Total params: 1,027

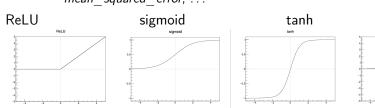
# More on model building

- When add'ing layers, keras takes care of input/output size details
  - Except for the input layer, which must be specified
  - We explicitly gave the network (4,) for our 4 input variables
- The final layer we make size 3 after a softmax activiation
  - This will output the network probability for each of the potential iris classes as a numpy array (nsamples, (psetosa, pvirginica, pversicolor))
- We compile the model with an optimizer and loss function
  - The loss function will be minimized during the training phase
- We can give auxilliary metrics which will be calculated with the loss
- Keras automatically takes care of calculating derivatives through the network for the backprop phase
- We could be more explicit in creating the functions if we want more control over hyperparameters:

# More on model building

Here we used the adam optimizer which automatically updates the step sizes used for parameter optimization, with a categorical cross-entropy loss, which measures  $-\sum_i t_i \log p_i$  where  $t_i$  is 1 for the true label and  $p_i$  is the probability of the *i*th label assigned by the model. As the model assigns higher probability to the correct label, the cross-entropy goes to 0.

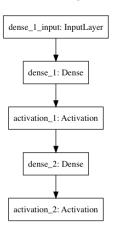
- Other options to consider:
  - Activation: sigmoid, softmax, linear, tanh, relu, ...
  - Optimizer: SGD, RMSprop, Adagrad, Adadelta, Adam, ...
  - Loss: categorical\_crossentropy, binary\_crossentropy, mean squared error, ...



## Model picture

If pydot is installed we can also output a picture of the network

keras.utils.plot\_model(model, to\_file='iris\_model.png')



## Training Code

```
# Split the variables to train, and the target
variables = iris.values[:, :4]
species = iris.values[:, 4]
# One hot encode the species target
smap = {'setosa' : 0, 'versicolor' : 1, 'virginica' : 2}
species_enc = np.eye(3)[list(smap[s] for s in species)]
# To show we are simply passing numpy arrays of the data
print(variables[0], species[0], species_enc[0])
train_X, test_X, train_v, test_v = \
  train_test_split(variables, species_enc, train_size=0.8, random_state=0)
model.fit(train_X, train_y, epochs=15, batch_size=1, verbose=1)
[5.1 3.5 1.4 0.2] setosa [ 1. 0. 0.]
Epoch 1/15
120/120 [============] - Os - loss: 0.2873 - acc: 0.9500
Epoch 15/15
```

## **Training**

- Now we fit to the training data.
- We can set the number of epochs, batch\_size, and verbose'ity
  - Epochs: number of training passes through the complete dataset
  - Batch size: number of datapoints to consider together when updating the network
- We pass through the input data as a numpy array (nsamples, 4)
- We pass the output as (nsamples, 3) where for each sample one of the positions is 1, corresponding to the correct class.
- We use the np.eye identity matrix creator to help us transform the raw species information (which labels classes setosa, virginica, versicolor) to the expected format
  - Setosa = (1, 0, 0)
  - Versicolor = (0, 1, 0)
  - Virginica = (0, 0, 1)
- We fit the model to a labelled dataset simply by calling fit with the dataset train\_X and the true labels train\_y

### **Evaluation**

- After running the model, we can evaluate how well it works on the labelled test data we kept aside for overfitting evaluation purposes.
  - Overfitting is when the model fits to the training set in a way that doesn't generalize to unseen samples
  - One usually also has a separate validation set, use the test set on a single model, choose a model you like, then check the hyperparameters didn't cause bias by checking the validation

```
# The evaluation passes out the overall loss,
# as well as any other metrics you included
# when compiling the model
loss, accuracy = model.evaluate(test_X, test_y, verbose=0)
print("Loss={:.2f}\nAccuracy = {:.2f}".format(loss, accuracy)
```

Loss=0.11 Accuracy = 0.97

### Prediction

- And we can ask the model to predict some unlabelled data
  - For illustration, we just use our test data, and compare the true label against the 'prediction'
  - In the output, I stack the true answers (first rows), and the prediction, which can basically be interpreted as the model's probability for each category (second rows)

```
pred_y = model.predict(test_X)
print(np.stack([test_y, pred_y], axis=1)[:10])
    0.0000000e+00
                    0.00000000e+00
                                     1.0000000e+001
    2.63856982e-05
                    8.96630138e-02
                                     9.10310626e-01]]
    0.00000000e+00 1.0000000e+00
                                    0.0000000e+00]
    1.57812089e-02
                    9.63519156e-01
                                     2.06995625e-0211
    1.00000000e+00
                    0.00000000e+00
                                     0.0000000e+001
    9.96497989e-01
                    3.50204227e-03
                                     1.25929889e-0911
    0.00000000e+00
                                    1.00000000e+001
                    0.00000000e+00
    4.74178378e-05
                                     8.67359996e-01]]
                    1.32592529e-01
                                     0.0000000e+001
    1.0000000e+00
                    0.0000000e+00
```

## MNIST digit recognition and Convolutional Networks

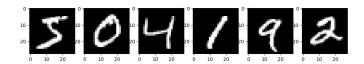
- Another, more recent, classic classification task.
- Given a 28x28 image of a handwritten digit, can you train a classifier to recognize the numbers from 0 to 9?
- Keras has the ability to download the dataset and parse it into numpy arrays. We use to\_categorical to one hot encode the true labels (which number did they write?) as for the irises

## Examples

- We can use matplotlib.pyplot to show a few example digits
- In jupyter, matplotlib results will show automatically, so you don't need to print it out (or resize it for that matter)

```
print(x_train.shape, y_train_enc.shape)
plt.clf()
for i in range(6):
    plt.subplot(1,6,i+1)
    plt.imshow(x_train[i], cmap='gray')

F = plt.gcf(); F.set_size_inches((14,2))
plt.savefig('mnist-examples.png');
```



## Simple Network

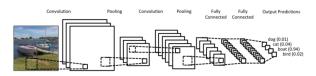
- We can start by simply trying a basic neural network as before.
- 'Flatten' takes the 2D input and concatenates the rows together to a 1D form suitable for passing to a 'Dense' layer.

#### Simple Network

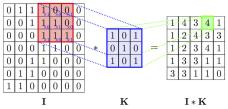
And fit and evaluate as we did before

```
model.fit(x_train, y_train_enc, epochs=3, verbose=1)
loss, accuracy = model.evaluate(x_test, y_test_enc, verbose=0)
print("Loss={:.2f}\nAccuracy = {:.2f}".format(loss, accuracy))
Epoch 1/3
60000/60000 [============= ] - 4s - loss: 0.5373 - acc: 0.8
Epoch 2/3
60000/60000 [============] - 4s - loss: 0.3729 - acc: 0.8
Epoch 3/3
60000/60000 [============= ] - 4s - loss: 0.3207 - acc: 0.9
Loss=0.30
Accuracy = 0.91
```

#### A Convolutional Network



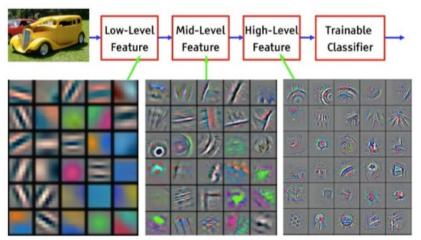
- One of the great advances in image classification in recent times
- We have some filter kernel K of size  $n \times m$  which we apply to every  $n \times m$  cell on the original image to create a new filtered image.
- It has been seen that applying these in multiple layers of a network can build up multiple levels of abstraction to classify higher-level features.
  - And, importantly, is trainable many, many layers deep



 $\textbf{Reference: http://www.wildml.com/2015/11/understanding-convolutional-neural-networks-for-nlp/linear-neural$ 

## What is the Network Learning?

- In general a difficult question to answer
- Here, Zeiler and Fergus (2013) took a trained network and *optimized* the input to activate particular nodes to give an idea
  - Start with noise, then GD on the input, optimizing the node activation



## Reshaping data for Keras

- Convolution of this type in Keras is provided by the Conv2D layer
- Conv2D requires passing an array of width x height x channels
  - Where channels might represent colors of an image
- We have black and white images so we'll just reshape it into the required form with a single channel.
- We plot the image just check show the shaping is correct

```
x_train_dense = x_train.reshape((len(x_train), 28,28,1))
x_test_dense = x_test.reshape((len(x_test), 28,28,1))

plt.clf()
plt.imshow(x_train_dense[0,:,:,0], cmap="gray")
F = plt.gcf(); F.set_size_inches((2,2)); plt.savefig("testimg.png");

0
10
10
10
10
```

## Building a Convolutional Neural Network in Keras

- Now, lets build a convolutional neural network!
- Generally, Conv2D will be stacked on top of each other with MaxPooling2D layers and learn edge detection at lower layers and higher level feature extraction in subsequent layers.
- But just to show how to use them in keras, we'll just create one convolution layer with 32 filters, then Flatten it into a 1D array and pass it into a Dense hidden layer before the output.
- We can set the kernel\_size (m x n size of the filter), and the number of filters used

## Building a Convolutional Neural Network in Keras

 We can set the kernel\_size (m x n size of the filter), and the number of filters used

```
model = Sequential()
model.add(Conv2D(32, kernel_size=(3,3),input_shape=(28,28,1)))
model.add(Activation('relu'))
model.add(Flatten())
model.add(Dense(128))
model.add(Activation('sigmoid'))
model.add(Dense(10))
model.add(Activation('softmax'))
model.compile(optimizer='adam',
              loss='categorical_crossentropy',
      metrics=['accuracy'])
```

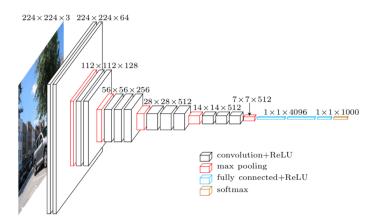
#### **Training**

And train the model. This is already starting to get to the point where a GPU would be extremely helpful!

```
model.fit(x_train_dense, y_train_enc, epochs=4, verbose=1)
Epoch 1/4
60000/60000 [============= ] - 65s - loss: 0.4544 - acc: 0.
Epoch 2/4
60000/60000 [============= ] - 70s - loss: 0.1745 - acc: 0.
Epoch 3/4
60000/60000 [============] - 68s - loss: 0.1369 - acc: 0.
Epoch 4/4
<keras.callbacks.History object at 0x11d742390>
loss, accuracy = model.evaluate(x_test_dense, y_test_enc, verbose=0)
print("Loss={:.3f}\nAccuracy = {:.3f}".format(loss, accuracy))
```

Loss=0.117 Accuracy = 0.964

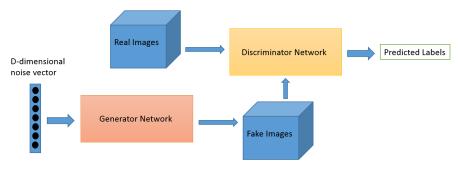
#### Realistic Networks



- Example of a real network used for image classification, VGG-16
- Typically, networks consist of several convolution layers following by max pooling layers (take the max from a 2x2 square)

#### A Convolution GAN

- The idea is to train two adverserial networks,
  - One is trying to create images equivalent to the MNIST dataset
    - Given an input of noise, the latent space
  - The other trying to label the images as either from the dataset or fake
    - Fake = generated by the opposing dataset



- References:
  - For more on GANs and their uses: https://arxiv.org/pdf/1701.00160.pdf
  - Code based on: https://github.com/jacobgil/keras-dcgan
  - Some tricks for training GANs https://github.com/soumith/ganhacks

## Idea: Image generator network

- We start with the image generation network
- Essentially a image classifier in reverse.
- The top layer is for high-level feature inputs which we'll randomly set during the training.
- We then pass through Dense layers and then reshape into a 7 x 7 x channels image-style layer.
- We Upsampling2D and pass through convolutional filters until the last layer which outputs a 28x28x1 image as expected of an MNIST greyscale image.
  - Essentially we're *adding* features as we go up, instead of *extracting* features as we go down
- BatchNormalization is a technique to improve the network stability by providing the next layer inputs with zero mean and unit variance

#### Generator

```
# Complete code for the generator model
nfeatures = 100
generate = Sequential()
generate.add(Dense(1024, input_dim=nfeatures))
generate.add(Activation('tanh'))
generate.add(Dense(128*7*7))
generate.add(BatchNormalization())
generate.add(Activation('tanh'))
generate.add(Reshape((7, 7, 128)))
generate.add(UpSampling2D(size=(2,2)))
generate.add(Conv2D(64, (5,5), padding='same'))
generate.add(Activation('tanh'))
generate.add(UpSampling2D(size=(2,2)))
generate.add(Conv2D(1, (5, 5), padding='same'))
generate.add(Activation('sigmoid'))
generate.compile(loss="binary_crossentropy", optimizer="SGD")
```

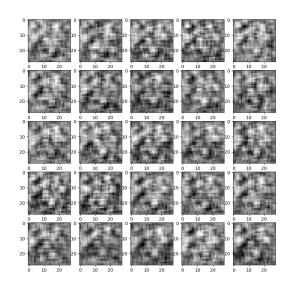
#### Generator Test

Now, just to check everythings put together properly, randomly pass some data through the network and check we get image outputs as expected.

```
nim = 25
pred = generate.predict(np.random.uniform(0, 1, (nim,nfeatures)))
plt.clf()
for i in range(nim):
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[i,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10))
plt.savefig("genimg_no.png")
```

## Example images, pre-training



#### Discriminator

- Next, we create the discriminating network, with an image input
- As for classification, we have a convolutional layer attached to Dense layers.
- For the output, we now have a single sigmoid with interpretation:
  - 0: The network thinks its definitely a generated image
  - 1: The network thinks its definitely a real MNIST dataset image

#### Discriminator

```
# Complete code for the discriminator network
discr = Sequential()
discr.add(Conv2D(64, (5,5), input_shape=(28,28,1), padding='same'))
discr.add(Activation('tanh'))
discr.add(MaxPooling2D((2,2)))
discr.add(Conv2D(128, (5,5)))
discr.add(Activation('tanh'))
discr.add(MaxPooling2D((2,2)))
discr.add(Dropout(0.5))
discr.add(Flatten())
discr.add(Dense(1024))
discr.add(Activation('tanh'))
discr.add(Dense(1))
discr.add(Activation('sigmoid'))
discr.compile(loss='binary_crossentropy',
              optimizer=SGD(lr=0.0005, momentum=0.9,
                            nesterov=True))
```

#### Test the discriminator

- Test the network with a few MNIST images and some random images.
- Since the network isn't trained we don't yet expect any differences in the output.

```
x_prepred = np.concatenate(
    [x_train[:5,:,:].reshape(5,28,28,1) / 256.,
    np.random.uniform(0, 1, (5, 28, 28, 1))], axis=0)
discr.predict(x_prepred)
```

#### **GAN**

- Now we set up a network which will be used to train the generation network.
- Keras allows us to simply add the models we just created together into a Sequential like they were ordinary layers.
- So, we feed the generator output into the discriminator input and set up an optimizer which will try to drive the generator to produce MNIST-like images (i.e. to fool the discriminator).
- Keras allows us to turn layer training on and off through the "trainable" variable attached to a layer, so when we train the generator we can easily turn training for the discriminator off.

## Setup GAN

- Using Keras, we can simply add the generator and discriminator sub-networks into a new, combined network, similarly to any other layer!
- We can also simply tell it to turn off training the discriminator weights when we are optimizing the generator!

## Training the GAN

- Finally, we have the actual training
- Here, we setup the batches ourselves and alternate between training the discriminator and generator
  - model.train\_on\_batch
  - This was previously put together by Keras itself
- We start by taking a batch of MNIST images (labeled 1), and generator images (labeled 0) and run a training batch on the discriminator network
- Then, we turn off training off the discriminator and run training on the generator+discriminator network with random high-level feature inputs to the generator
- We try to drive all the outputs to 1, i.e. train the generator to more MNIST-like images (as according to the discriminator network)
- Last remark: we are saving the networks after each epoch with model.save
  - Load with keras.models.load\_model

## Training the GAN

```
batch size = 100
n = pochs = 10
print_every_nth_epoch = 50
x_tu_all = x_tu_i - (len(x_tu_all), 28, 28, 1) / 256.
zeros = np.array([0]*batch_size)
ones = np.array([1]*batch_size)
oneszeros = np.arrav([1]*batch size + [0]*batch size)
losses d = []
losses g = []
for epoch in range(n_epochs):
    print ("Epoch", epoch)
    discr.save("/discr-"+str(epoch))
    generate.save("/generate-"+str(epoch))
    for i in range(0, len(x_train), batch_size):
x_gen = generate.predict(np.random.uniform(0, 1, (batch_size, nfeatures)))
x tru = x tru all[i:i+batch size]
# Train the discriminator by taking example MNIST and generator-produced images
discr.trainable=True
loss d = discr.train on batch(np.concatenate([x tru, x gen], axis=0), oneszeros)
# Now, turn discriminator training off, so we can train the generator
discr.trainable=False
loss_g = gen_discr.train_on_batch(np.random.uniform(0, 1, (batch_size, nfeatures)), ones)
if i % (print_every_nth_epoch*batch_size) == 0:
    print (i / batch_size, "discr", loss_d, "--", "gen", loss_g[0], "( acc.", loss_g[1], ")")
losses_g.append(loss_g)
losses d.append(loss d)
```

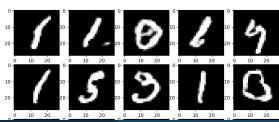
#### Checking results

Lets see how we did, lets just generate a bunch of images

```
nim = 25
pred = generate.predict(np.random.uniform(0, 1, (nim,nfeatures)))

plt.clf()
for i in range(nim):
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[i,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("genimg_after.png"); "genimg")
```



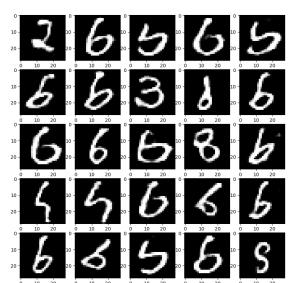
#### Good images

- Whats the "best" being produced by the GAN?
- Only accept above 0.9 from discriminator

```
nim = 25
target = .9
plt.clf()
for i in range(nim):
    best = 0; pred=None
    while best < target:
        pred = generate.predict(np.random.uniform(0, 1, (1,nfeatures)))
        best = discr.predict(pred)[0][0]
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[0,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("genimg40_best.9.png"); "genimg40_best.9.png"</pre>
```

## Good Images



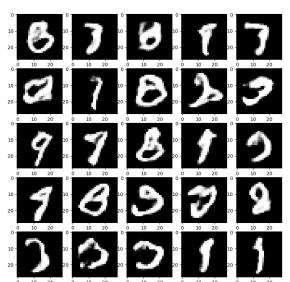
## Bad images

- Whats the "worst" being produced by the GAN?
- Only accept below 0.1 from discriminator

```
nim = 25
target = .1

plt.clf()
for i in range(nim):
    best = 1; pred=None
    while best > target:
        pred = generate.predict(np.random.uniform(0, 1, (1,nfeatures)))
        best = discr.predict(pred)[0][0]
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[0,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("genimg40_worst.1.png"); "genimg40_worst.1.png"
```



#### Extensions

- Try different networks, what works well, what fails badly?
- Add another set of inputs hot-one encoding the number you want to generate,
  - The discriminator will need to say which number it believes its seeing as well as how likely it is to be real
  - The generator will need to train with the number output as a loss also
- Some further ideas on the next pages, work in progress code :-)

## Train requiring GAN to also output the correct number

```
nfeatures = 100
generate = Sequential()
generate.add(Dense(1024, input_dim=(nfeatures + 10)))
generate.add(Activation('tanh'))
generate.add(Dense(128*7*7))
generate.add(Bense(128*7*7))
generate.add(Activation('tanh'))
generate.add(Activation('tanh')))
generate.add(UpSampling2D(size=(2,2)))
generate.add(Cov2D(64, (5,5), padding='same')))
generate.add(Cov2D(64, (5,5), padding='same')))
generate.add(Cov2D(1, (5, 5), padding='same')))
generate.compile(loss="binary_crossentropy", optimizer="SGD")
```

#### Create the Discriminator

#### Create the combined network

# Pre-train the discriminator on the (untrained) generator output and real MNIST

```
# pre train the gan to be able to distinguish numbers
pre_losses_d = []
for epoch in range(5):
    print ("Epoch", epoch)
    for i in range(0, len(x_train), batch_size):
        one_hot_gen = np.eye(10)[np.random.random_integers(0, 9, size=(batch_size,))]
        x inp = np.concatenate([np.random.uniform(0, 1, (batch size, nfeatures)), one hot gen], axis=1)
        x_gen = generate.predict(x_inp)
        x tru = x tru all[i:i+batch size]
        y_tru = y_train_enc[i:i+batch_size]
        discr.trainable = True
        for_d_tru = np.concatenate([np.zeros((batch_size,1)), y_tru], axis=1)
        for d gen = np.concatenate([np.ones((batch size.1)), np.zeros((batch size.10))], axis=1)
        loss_d = discr.train_on_batch(np.concatenate([x_tru, x_gen], axis=0),
                              np.concatenate([for_d_tru, for_d_gen], axis=0))
        if i % (print every nth epoch*batch size) == 0:
            print (i / batch size, "discr", loss d)
        pre_losses_d.append(loss_d)
loss, accuracy = discr.evaluate(x test dense,
                                np.concatenate([np.zeros((len(y_test_enc),1)), y_test_enc], axis=1), verbose=0)
print("Loss={:.3f}\nAccuracy = {:.3f}".format(loss, accuracy))
```

## Train the generator and discriminator together

```
losses d = []
losses g = []
for epoch in range(n epochs):
   print ("Epoch", epoch)
   discr.save("discr-num-"+str(epoch))
    generate.save("generate-num-"+str(epoch))
   for i in range(0, len(x_train), batch_size):
        one_hot_gen = np.eye(10)[np.random.random_integers(0, 9, size=(batch_size,))]
        x_inp = np.concatenate([np.random.uniform(0, 1, (batch_size, nfeatures)), one_hot_gen], axis=1)
       x_gen = generate.predict(x_inp)
       x_tru = x_tru_all[i:i+batch_size]
       v tru = v train enc[i:i+batch size]
        discr trainable = True
       for_d_tru = np.concatenate([np.zeros((batch_size,1)), y_tru], axis=1)
        for_d_gen = np.concatenate([np.ones((batch_size,1)), np.zeros((batch_size,10))], axis=1)
        loss d = discr.train on batch(np.concatenate([x tru, x gen], axis=0),
                              np.concatenate([for_d_tru, for_d_gen], axis=0))
       discr.trainable=False
        for g = np.concatenate([np.zeros((batch size.1)), one hot gen], axis=1)
       new_inp_g = np.concatenate([np.random.uniform(0, 1, (batch_size, nfeatures)), one_hot_gen], axis=1)
        loss_g = gen_discr.train_on_batch(new_inp_g, for_g)
        if i % (print every nth epoch*batch size) == 0:
           print (i / batch size, "discr", loss d, "--", "gen", loss g[0], "( acc.", loss g[1], ")")
        losses_g.append(loss_g)
        losses_d.append(loss_d)
```

print ("done")

## Check the output of the labelled GAN

```
# generate = tf.keras.models.load_model('generate-num-41')
nim = 25
numb = 1
pred = generate.predict(np.concatenate([np.random.uniform(0, 1, (nim,nfeatures)), np.eye(10)[[numb,]*nim]], ax
plt.clf()
for i in range(nim):
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[i,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("gen-num-img_after-%d.png" % numb); "gen-num-img_after-%d.png" % numb)
```

# Some examples from labelled GAN

