



Linear Regression Model

for

Time Series Prediction

- ① Consider $X = \{x_1, x_2, \dots, x_t, \dots, x_T\}$ the sequence $x_t \in \mathbb{R}$, $1 \leq t \leq T$, of stock-related price values.
- ② Our aim is to construct a linear regression model that will provide an estimation / prediction for the future price value \hat{x}_t based on a window of past price values of size $K \in \mathbb{N}^*$ such that:

$$\hat{x}_t = f(x_{t-1}, x_{t-2}, \dots, x_{t-K}) \quad (1)$$

③ Since we assume a linear functional form, we may write that:

$$\hat{x}_t = w_1 \cdot x_{t-1} + w_2 \cdot x_{t-2} + \dots + w_K \cdot x_{t-K} + w_0 \quad (2)$$

Eq. (2) may be equivalently be written

as:

$$\hat{x}_t = \sum_{z=1}^{z=K} w_z \cdot x_{t-z} + w_0 \quad (3)$$

④ Eq. (3) suggests that the original sequence π needs to be partitioned into overlapping windows of size K as follows:

$$\begin{aligned}\underline{x}_1^T &= [x_K \ x_{K-1} \ \dots \ x_2 \ x_1] \in \mathbb{R}^K \\ \underline{x}_2^T &= [x_{K+1} \ x_K \ \dots \ x_3 \ x_2] \in \mathbb{R}^K \\ &\vdots && \vdots \\ \underline{x}_t^T &= [x_{t+K-1} \ x_{t+K-2} \ \dots \ x_{t+1} \ x_t] \in \mathbb{R}^K \\ &\vdots \\ \underline{x}_{T-K}^T &= [x_{T-1} \ x_{T-2} \ \dots \ x_{T-K+1} \ x_{T-K}] \in \mathbb{R}^K\end{aligned} \quad (4)$$

⑤ Each vector \underline{x}_t of past price values will be associated with a corresponding target regression variable:

$$y_t = \underline{x}_{t+K}, 1 \leq t \leq T-K \quad (5)$$

⑥ In this context, our dataset will be composed by row-wise concatenating vectors $\underline{x}_1, \underline{x}_2, \dots, \underline{x}_{T-K}$ such that:

$$\underline{x} = \begin{bmatrix} \underline{x}_1^T \\ \vdots \\ \underline{x}_t^T \\ \vdots \\ \underline{x}_{T-K}^T \end{bmatrix} \in \mathbb{R}^{(T-K) \times K} \quad (6)$$

⑦ The corresponding vector of target

regression values will be composed as:

$$\underline{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_t \\ \vdots \\ y_{T-K} \end{bmatrix} \in \mathbb{R}^{T-K} \quad (7)$$

⑧ Thus, the model output \hat{y}_t provides

its prediction for the true target value

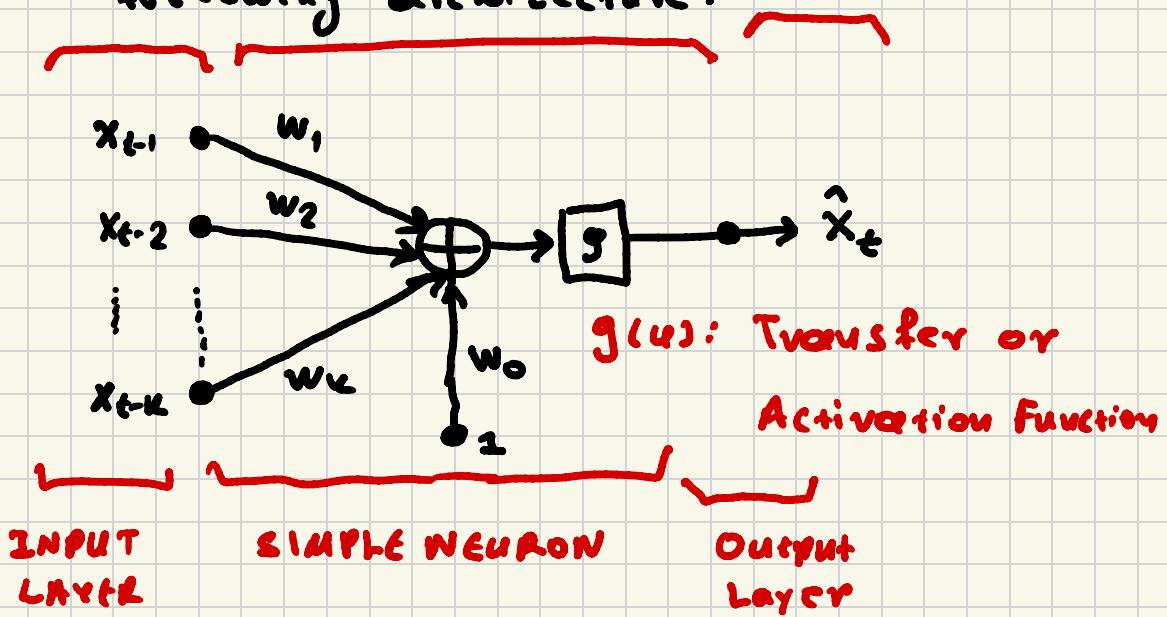
y_t based on the input pattern \underline{x}_t as:

$$\hat{y}_t = f(\underline{x}_t) = \underline{w}^\top \cdot \underline{x}_t + w_0 \quad (8)$$

where $\underline{w} = \begin{bmatrix} w_K \\ w_{K-1} \\ \vdots \\ w_2 \\ w_1 \end{bmatrix} \in \mathbb{R}^K \quad (9)$

$$w_0 \in \mathbb{R}$$

⑨ Eqs. (8), (9) provide the functionality of a Perceptron Neural Network of the following architecture:



For a Linear Neural Network as the one above, the transfer function is purely linear, i.e.
$$g(u) = u \quad (10)$$

⑩ We need to obtain the optimal configuration of weight parameters w^* and w_0^* based on the training patterns \underline{X} and corresponding target values \underline{Y} .

11 We may define the error for the t -th data point as:

$$e_t = y_t - \hat{y}_t, \quad 1 \leq t \leq T-K \quad (11)$$

which may be also written as:

$$e_t = y_t - (\underline{w}^T \cdot \underline{x}_t + w_0) \quad (12)$$

12 In this context, the overall loss function (objective function) may be defined as:

$$J(\underline{w}, w_0) = \sum_{t=1}^{T-K} e_t^2 \quad (13)$$

Letting $N = T-K$ to denote the total number of training patterns, we may write that:

$$J(\underline{w}, w_0) = \sum_{t=1}^N (y_t - (\underline{w}^T \cdot \underline{x}_t + w_0))^2 \quad (14)$$

13) Acquiring the optimal values for \underline{w}^* and w_0^* requires addressing the following optimization problem:

$$(\underline{w}^*, w_0^*) = \arg \min_{(\underline{w}, w_0)} J(\underline{w}, w_0) \quad (15)$$

14) Given the quadratic form of the QLS function, obtaining the optimal values for \underline{w}^* and w_0^* can be achieved by imposing the First-Order Conditions (FOCs):

$$\left\{ \begin{array}{l} \frac{\partial J}{\partial \underline{w}} = \underline{0} \in \mathbb{R}^k \\ \frac{\partial J}{\partial w_0} = 0 \in \mathbb{R} \end{array} \right. \quad (16)$$

(15) Gradient with Respect to w:

$$\frac{\partial J}{\partial \underline{w}} = \frac{\partial}{\partial \underline{w}} \left\{ \sum_{t=1}^N e_t^2 \right\} = \sum_{t=1}^N \frac{\partial}{\partial \underline{w}} e_t^2 \quad (17)$$

Utilizing the chain rule, we may get that:

$$\frac{\partial}{\partial \underline{w}} e_t^2 = 2 e_t \cdot \frac{\partial e_t}{\partial \underline{w}} \quad (18)$$

Accordingly, we may write that:

$$\frac{\partial e_t}{\partial \underline{w}} = \frac{\partial}{\partial \underline{w}} \left\{ \gamma_t - (\underline{w}^\top \cdot \underline{x}_t + w_0) \right\} \Rightarrow$$

$$\frac{\partial e_t}{\partial \underline{w}} = - \frac{\partial}{\partial \underline{w}} \left\{ \underline{w}^\top \cdot \underline{x}_t + w_0 \right\} \Rightarrow$$

$$\frac{\partial e_t}{\partial \underline{w}} = - \underline{x}_t \quad (19)$$

Substituting Eq.(19) into Eq.(18), yields:

$$\frac{\partial e_t^2}{\partial \underline{w}} = -2 e_t \cdot \underline{x}_t \quad (20)$$

Thus, Eq.(17) may be written as:

$$\frac{\partial J}{\partial \underline{w}} = -2 \sum_{t=1}^N (y_t - (\underline{w}^\top \cdot \underline{x}_t + w_0)) \cdot \underline{x}_t \quad (21)$$

Enforcing the respective First Order Condition:

$$\frac{\partial J}{\partial \underline{w}} = \underline{0} \Rightarrow$$

$$\sum_{t=1}^N (y_t - (\underline{w}^\top \cdot \underline{x}_t + w_0)) \underline{x}_t = \underline{0} \quad (22)$$

or

$$\sum_{t=1}^N e_t \cdot \underline{x}_t = \underline{0} \quad (22')$$

16 Gradient with Respect to w_0 :

$$\frac{\partial J}{\partial w_0} = \frac{\partial}{\partial w_0} \left\{ \sum_{t=1}^n e_t^2 \right\} = \sum_{t=1}^n \frac{\partial}{\partial w_0} e_t^2 \quad (23)$$

Utilizing the chain rule again:

$$\frac{\partial e_t^2}{\partial w_0} = 2 e_t \frac{\partial e_t}{\partial w_0} \quad (24)$$

Accordingly, we may write that:

$$\frac{\partial e_t}{\partial w_0} = \frac{\partial}{\partial w_0} \left\{ y_t - (\underline{w}^T \cdot \underline{x}_t + w_0) \right\} \Rightarrow$$

$$\frac{\partial e_t}{\partial w_0} = - \frac{\partial}{\partial w_0} \left\{ \underline{w}^T \cdot \underline{x}_t + w_0 \right\} \Rightarrow$$

$$\frac{\partial e_t}{\partial w_0} = -1 \quad (25)$$

Substituting Eq.(25) into Eq.(24) yields:

$$\frac{\partial C_t^2}{\partial w_0} = -2 \cdot e_t \quad (26)$$

Thus, Eq. (23) may be written as:

$$\frac{\partial J}{\partial w_0} = -2 \sum_{t=1}^N (y_t - (\underline{w}^\top \cdot \underline{x}_t + w_0)) \quad (27)$$

Enforcing the respective First Order Condition:

$$\frac{\partial J}{\partial w_0} = 0 \Rightarrow$$

$$\sum_{t=1}^N (y_t - (\underline{w}^\top \cdot \underline{x}_t + w_0)) = 0 \quad (28)$$

or

$$\sum_{t=1}^N e_t = 0 \quad (28)'$$

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Matrix Formulation:

Having defined the matrix of input patterns $\underline{\underline{X}} \in \mathbb{R}^{N \times K}$ where row t is \underline{x}_t^T and the vector of target regression values $\underline{Y} \in \mathbb{R}^N$, we may also define the augmented data matrix $\hat{\underline{\underline{X}}} = \underline{\underline{X}}$ to include a column of ones to account for w_0 , as:

$$\hat{\underline{\underline{X}}} = \begin{bmatrix} \underline{x}_1^T & 1 \\ \vdots & \vdots \\ \underline{x}_t^T & 1 \\ \vdots & \vdots \\ \underline{x}_N^T & 1 \end{bmatrix} \quad (2a) \quad \hat{\underline{\underline{X}}} \in \mathbb{R}^{N \times (K+1)}$$

Likewise, we may define the augmented weight vector

$$\hat{\underline{w}} = \begin{bmatrix} \underline{w} \\ \vdots \\ w_0 \end{bmatrix} \in \mathbb{R}^{K+1} \quad (3a)$$

In this context, the vector $\hat{\underline{y}} \in \mathbb{R}^N$ of network predictions may be defined as:

$$\hat{\underline{y}} = \hat{\underline{X}} \cdot \hat{\underline{w}} \quad (31)$$

$[\text{N} \times 1] \quad [\text{N} \times (\text{K}+1)] \cdot [(\text{K}+1) \times 1]$

Therefore, the set of FOCs can be written in matrix form as:

$$\hat{\underline{X}}^T \cdot (\underline{y} - \hat{\underline{y}}) = \underline{\Theta} \quad (32)$$

$[(\text{K}+1) \times \text{N}] \quad [\text{N} \times 1] \quad [(\text{K}+1) \times 1]$

Taking into consideration the fact that the error vector $\underline{e} = \underline{y} - \hat{\underline{y}}$ and the form of the augmented data matrix $\hat{\underline{X}}$, we may write that:

$$\hat{\underline{X}}^T \cdot \underline{e} = \underline{\Theta} \in \mathbb{R}^{K+1} \quad (33)$$

Moreover,

$$\hat{\underline{x}}^T = \begin{bmatrix} \frac{x_1}{1} & \frac{x_2}{1} & \dots & \frac{x_n}{1} \end{bmatrix} \in \mathbb{R}^{(n+1) \times N}$$
 (34)

Eqs. (33) and (34) may be combined as:

$$\begin{bmatrix} \frac{x_1}{1} & \frac{x_2}{1} & \dots & \frac{x_n}{1} \end{bmatrix} \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{bmatrix} = \underline{1}_{[(n+1) \times 1]} \quad (35)$$

Expanding Eq. (35) results in:

$$\left\{ \sum_{t=1}^N e_t \underline{x}_t = \underline{1}_{[K \times 1]} \right.$$

$$\left. \sum_{t=1}^N e_t = 0 \in \mathbb{R} \right.$$

which are the FOCs that we have already derived.

Thus, by substituting Eq. (31) into Eq. (32), we get that:

$$\hat{\underline{X}}^T \cdot (\underline{y} - \hat{\underline{X}} \cdot \hat{\underline{W}}) = \mathbf{0}_{[(k+1) \times 1]} \Rightarrow$$

$$\hat{\underline{X}}^T \cdot \underline{y} - \underbrace{\hat{\underline{X}}^T \cdot \hat{\underline{X}} \cdot \hat{\underline{W}}}_{\downarrow} = \mathbf{0}_{[(k+1) \times 1]} \Rightarrow$$

$\begin{matrix} [(k+1) \times N] & [N \times 1] \\ [(k+1) \times 1] & \end{matrix}$

$$\begin{matrix} [(k+1) \times N] \cdot [N \times (k+1)] \cdot [(k+1) \times 1] \\ [(k+1) \times (k+1)] \cdot [(k+1) \times 1] \\ [(k+1) \times 1] \end{matrix}$$

$$\hat{\underline{X}}^T \cdot \hat{\underline{X}} \cdot \hat{\underline{W}} = \hat{\underline{X}}^T \cdot \underline{y} \Rightarrow$$

$$\hat{\underline{W}}^* = (\hat{\underline{X}}^T \cdot \hat{\underline{X}})^{-1} \cdot \hat{\underline{X}}^T \cdot \underline{y}$$

OPTIMAL WEIGHT VECTOR