# DATASCI207-005/007 Applied Machine Learning

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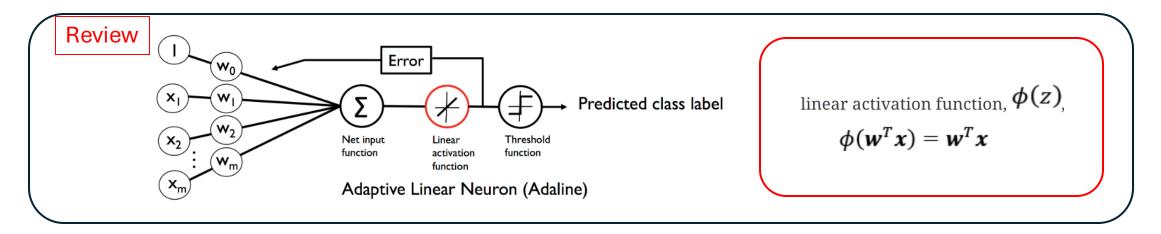
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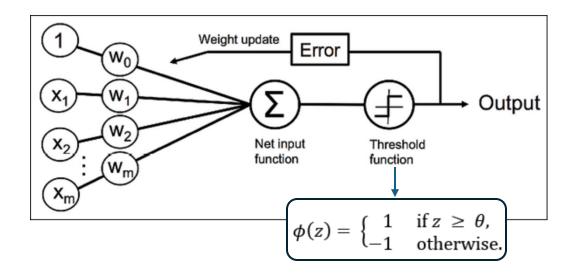
Week 6: 02/12/2024 - 02/13/2024

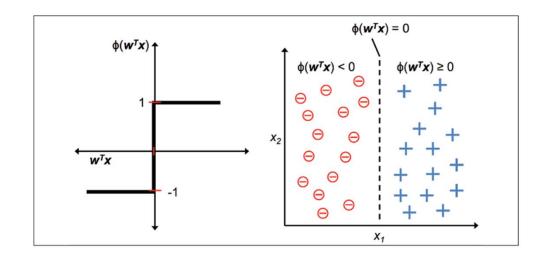
# Today's Agenda

- Feedforward Neural Nets
- Activation Functions
- Regularization
- Walkthroughs:
  - Regularization: L1, L2, Dropout (NNs)
  - XOR
    - TensorFlow: NNs

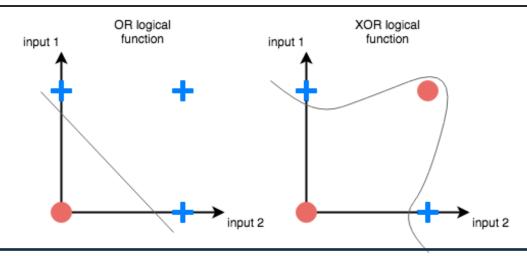
# Perceptron: Binary Classification



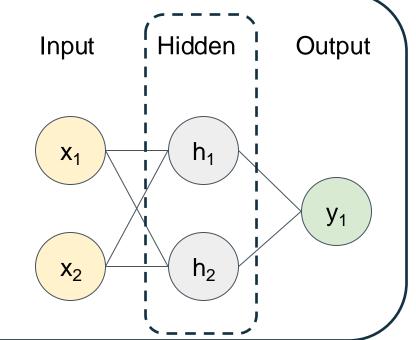




# Constructing XOR



<b>X</b> <sub>1</sub>	X <sub>2</sub>	h <sub>1</sub> =OR(x <sub>1</sub> ,x <sub>2</sub> )	$h_2$ =NAND( $x_1, x_2$ )	y=AND(h <sub>1</sub> ,h <sub>2</sub> )
0	0	0	1	0
0	1	1	1	1
1	0	1	1	1
1	1	1	0	0

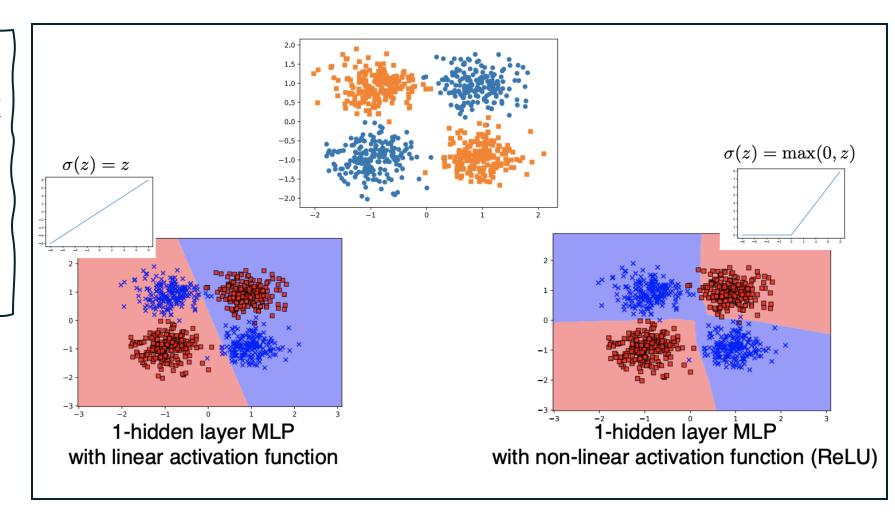


#### Neural Nets: Activation Functions & XOR

Animations of ReLU in action:

https://blog.dailydoseofds.com/p/ a-visual-and-intuitive-guide-towhat

https://nnfs.io/mvp/



# Multilayer Feedforward Neural Net (or MLP)

- Thus far:
- Ex.: Softmax Regression
  - Input Softmax Output

- Learning Algorithm
  - Gradient Descent

- Multilayer Perceptron (MLP)
  - Fully connected feedforward neural nets with 1(+) hidden layers
    - Feedforward: going in one direction, left to right (Input → Output)
    - More hyperparameters:
      - number of layers
      - units
- Learning Algorithm
  - Backpropagation
    - Gradient descent using the chain rule

# MLP: Examples, Classifiers

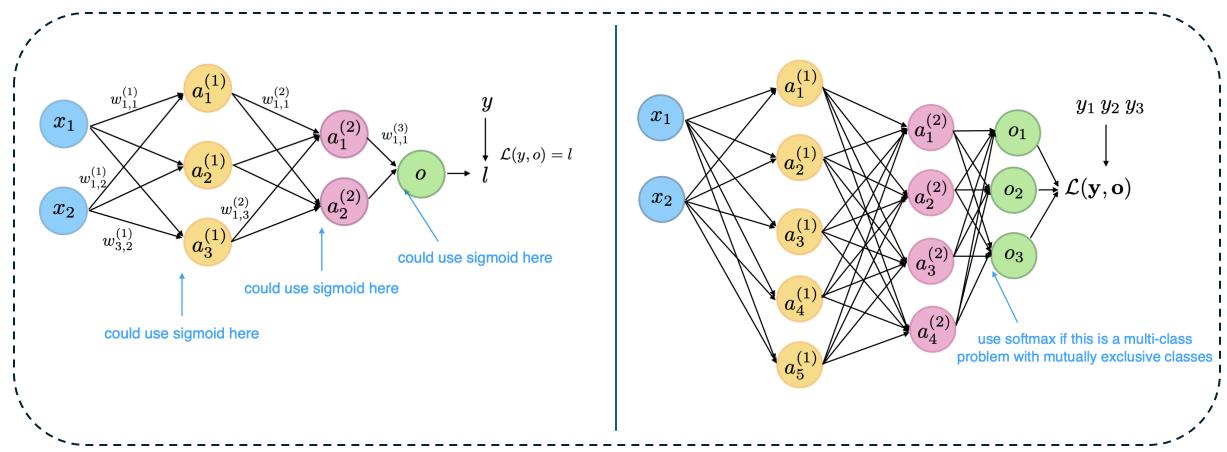


Image Source: Sebastian Raschka, Introduction to Deep Learning and Generative Models

## **Activation Functions**

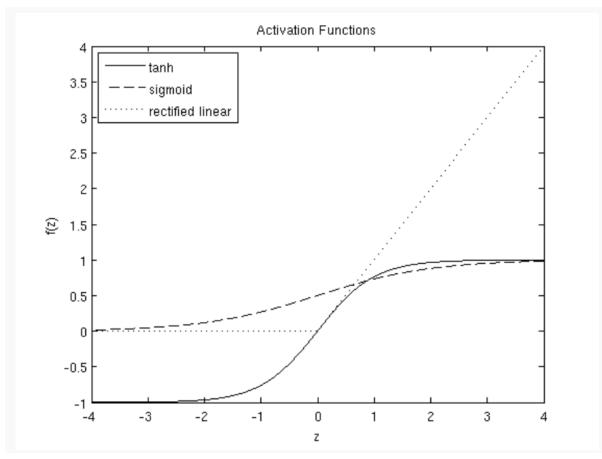
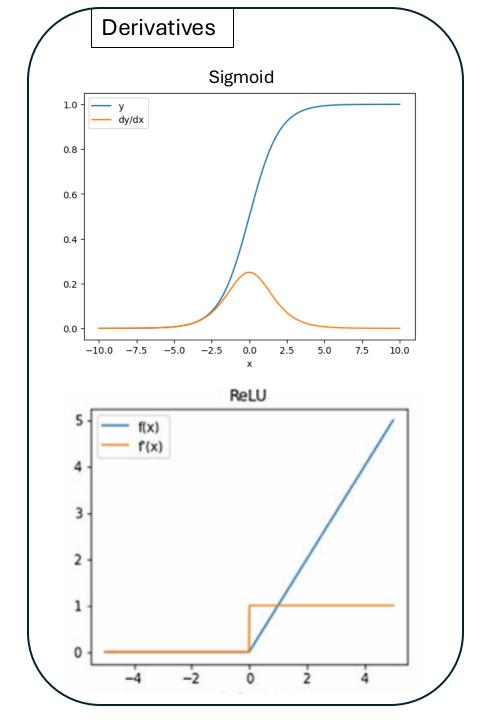
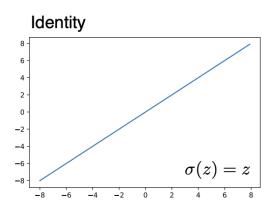
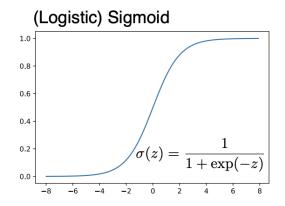


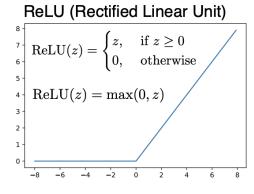
Image Source: http://deeplearning.stanford.edu/tutorial/supervised/MultiLayerNeuralNetworks/

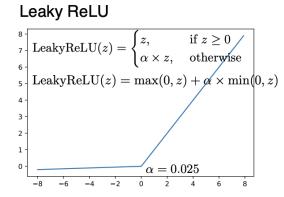


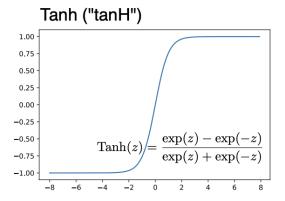
## **Activation Functions: Some Others**

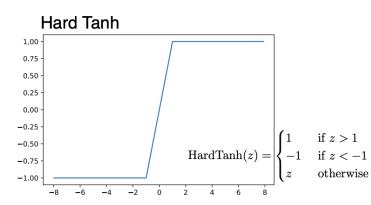


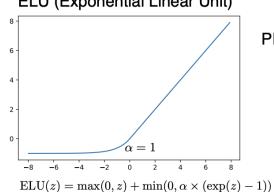












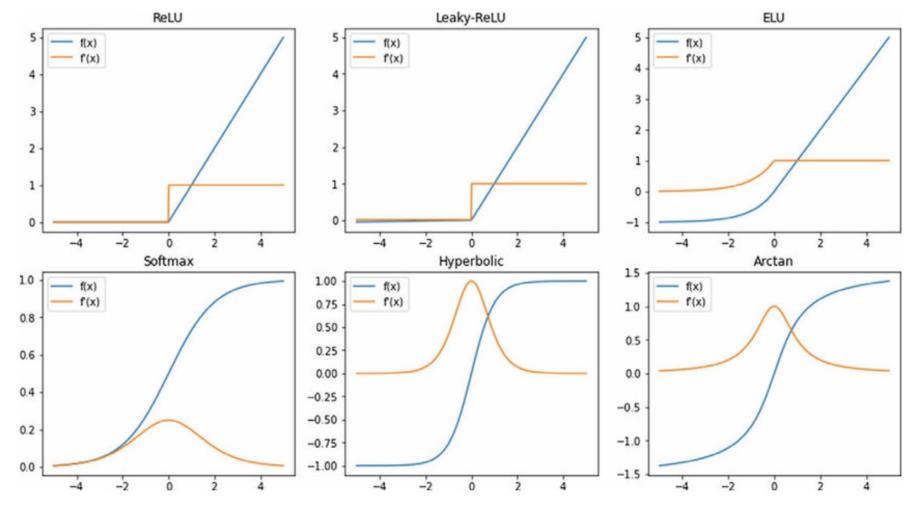
PReLU (Parameterized Rectified Linear Unit)

here, alpha is a trainable parameter

 $PReLU(z) = \max(0, z) + \alpha \times \min(0, z)$ 

**ELU (Exponential Linear Unit)** 

## **Activation Functions: Derivatives**

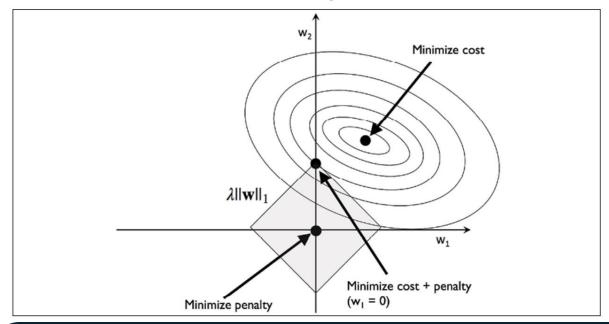


Commonly used activation functions, f(x) and their derivatives, f(x) for  $x \in [-5, 5]$ 

Image Source: A. Seth, A. Nikou and M. Daoutis. A scalable species-based genetic algorithm for reinforcement learning problems. The Knowledge Engineering Review 37(e9): 1–46.

# Regularization: L1 (Lasso) vs. L2 (Ridge)

$$L1: \|\mathbf{w}\|_1 = \sum_{j=1}^m |w_j|$$



#### Keras API info on regularizers:

https://keras.io/api/layers/regularizers/

#### Example Implementation:

https://github.com/fchollet/deep-learning-with-pythonnotebooks/blob/master/first\_edition/4.4-overfitting-and-underfitting.ipynb

$$L2: ||\mathbf{w}||_2^2 = \sum_{j=1}^m w_j^2$$

$$\operatorname{Cost}_{\mathbf{w},\mathbf{b}} = \frac{1}{n} \sum_{i=1}^{n} \mathcal{L}(y^{[i]}, \hat{y}^{[i]})$$

$$\operatorname{L2-Regularized-Cost}_{\mathbf{w},\mathbf{b}} = \frac{1}{n} \sum_{i=1}^{n} \mathcal{L}(y^{[i]}, \hat{y}^{[i]}) + \left(\frac{\lambda}{n} \sum_{j} w_{j}^{2}\right)$$

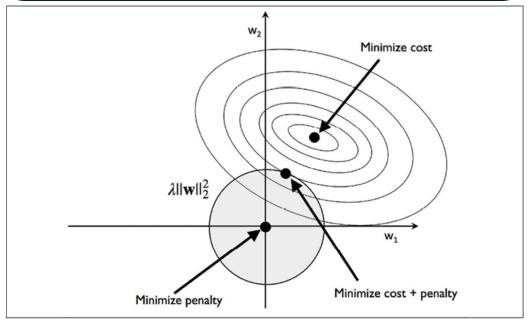
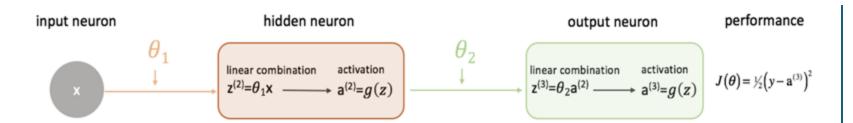


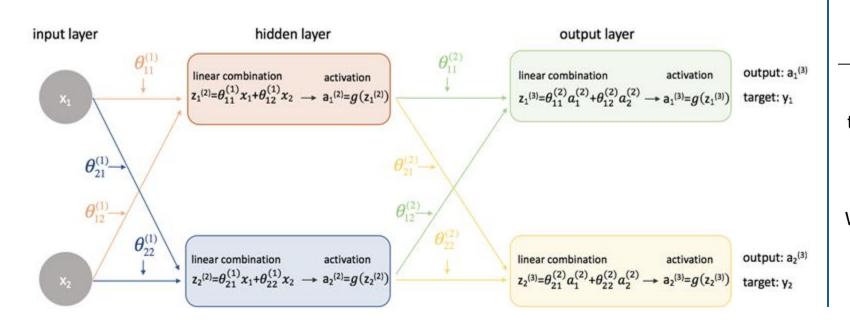
Image Ref.: Raschka, S., & Mirjalili, V. (2019). Python Machine Learning, Third Edit.

# Neural Nets: Backpropagation



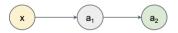
$$\frac{\partial J(\theta)}{\partial \theta_2} = \left(\frac{\partial J(\theta)}{\partial a^{(3)}}\right) \left(\frac{\partial a^{(3)}}{\partial z}\right) \left(\frac{\partial z}{\partial \theta_2}\right)$$

$$\frac{\partial J(\theta)}{\partial \theta_1} = \left(\frac{\partial J(\theta)}{\partial \mathbf{a}^{(3)}}\right) \left(\frac{\partial \mathbf{a}^{(3)}}{\partial z^{(3)}}\right) \left(\frac{\partial z^{(3)}}{\partial \mathbf{a}^{(2)}}\right) \left(\frac{\partial \mathbf{a}^{(2)}}{\partial z^{(2)}}\right) \left(\frac{\partial z^{(2)}}{\partial \theta_1}\right)$$



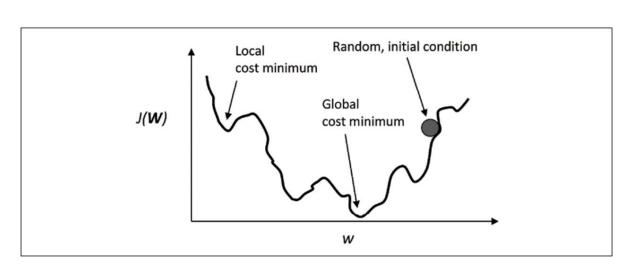
#### Non-linear Functions

If f is a linear function and g is a linear function, then their composition f(g(x)) is a linear function



Without non-linear activations, all neural network functions could be reduced to a single layer

## Multilayer NNs: Cost Functions



Ref.: Raschka, S., & Mirjalili, V. (2019). Python Machine Learning, Third Edit.

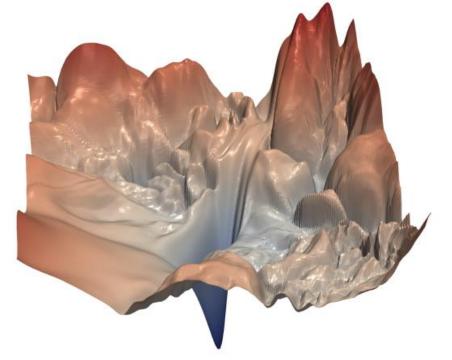


Image Source: Li, H., Xu, Z., Taylor, G., Studer, C., & Goldstein, T. (2018). Visualizing the loss landscape of neural nets. Advances in neural information processing systems, 31.