

Introduction to The Next Generation of Distribution Analysis Tools

Summer course D3

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Electric Power Research Institute - EPRI



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Areas of focus











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The instructor



Davis Montenegro, Member, IEEE

Davis Montenegro-Martinez serves as Engineer/Scientist III at the Electric Power Research Institute (EPRI) in the areas of power system modeling, analysis and high performance computing. He received his B.Sc. degree in electronics engineering from Universidad Santo Tomás, Bogotá, Colombia (2004); he is M.Sc. in electrical engineering from Universidad de los Andes (2015), and a Ph.D. in electrical engineering from Universidad de los Andes (2015), and a Ph.D. in electrical engineering from the University Grenoble-Alpes, France (2015).

Before joining EPRI, Davis served for 10 years as a lecturer for Universidad Santo Tomas in Colombia, during this time he was also technology consultant in the areas of industrial automation, software and electronic hardware design focused in the electric power industry, specifically in monitoring and control for meter calibration laboratories. His expertise in parallel computing techniques is being used at EPRI for incorporating multi-core processing to power system analysis methods such as QSTS, reducing the computational time required to perform these analysis using standard computing architectures.

Dr. Montenegro is also a member of the International Council on Large Electric Systems CIGRE, he was awarded with the IEEE 2016 I&CPS Ralph H. Lee Department Prize Paper Award at the 2017 I&CPS Technical Conference Awards luncheon in Niagara Falls, ON, Canada, for the paper titled "Energy Storage Modeling for Distribution Planning." He was also awarded an IEEE recognition in 2017 for notable services and contributions towards the advancement of IEEE and the engineering professions chairing of IM09 (Instrumentation and Measurements) Society Chapter, Colombian Section 2015–2017.

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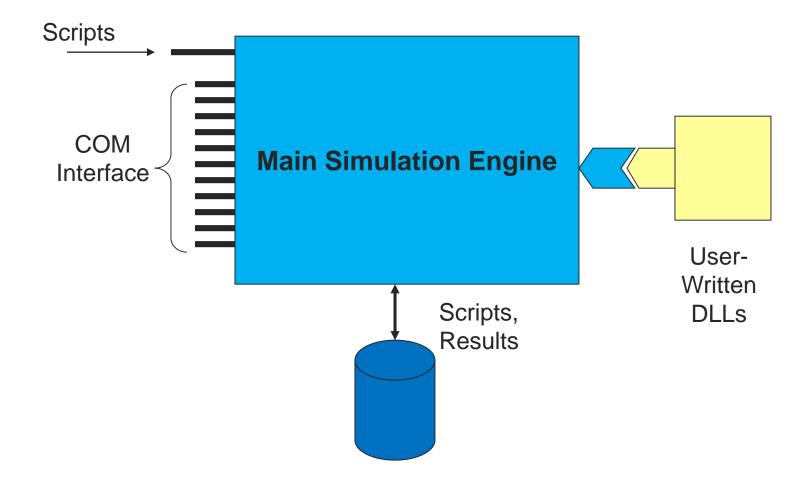
- Why You Might Want to Write Some Code ...
 - There is no looping in the DSS scripting language
 - To implement an algorithm not in OpenDSS
 - For optimizing device siting ...
 - Generators
 - Capacitors
 - Reclosers
 - To automate some repetitive analysis task
 - To develop a new device model or control
 - Using the COM interface
 - Writing a Dynamic-Linked Library (DLL)



- Why You Might Want to Write Some Code ...
 - COM Interface
 - Microsoft standard: Windows only
 - Well-supported in MS Office, Python, Matlab, etc.
 - DirectDLL Interface
 - Standard function call library
 - Use a separate program to generate DSS scripting code
 - Run with standalone EXE
 - Create a file with DSS commands
 - Redirect to it

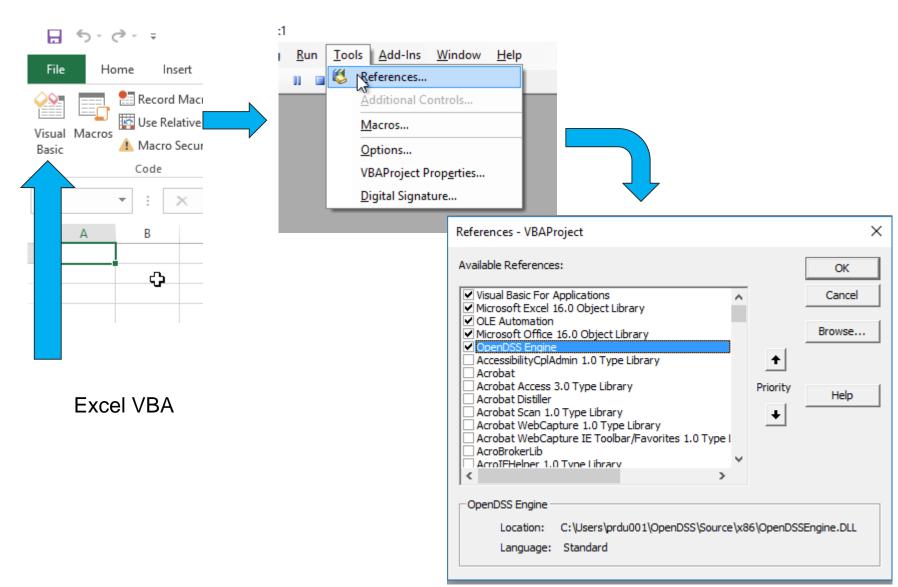


Why You Might Want to Write Some Code ...



COM interface

- There are many interfaces supplied by the COM server
- There is one registered *In-Process COM* interface:
 - OpenDSSEngine.DSS
 - The DSS interface is the one your program instantiates
 - The DSS interface then creates all the others.
 - This is for simplicity for users who are not necessarily familiar with COM programming

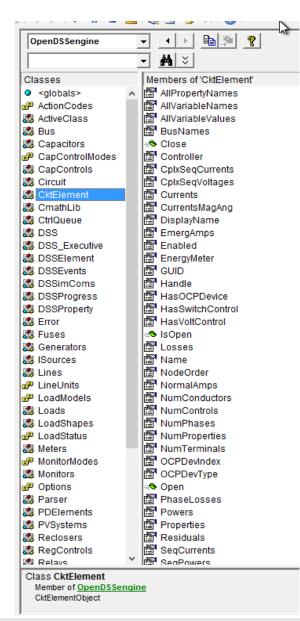


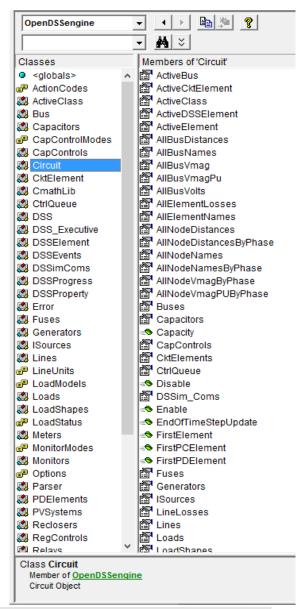
- COM interface
 - The interfaces generally act on the <u>ACTIVE object</u>
 - Active circuit,
 - Active circuit element,
 - Active bus, etc.
 - The interfaces generally point to the active object
 - To work with another object, change the active object
 - There are methods for selecting objects
 - You may also use script commands



COM interface

The Object Browser in MS Office VBA is a good way to learn what is available through the OpenDSS COM Interface







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COM interface

- Excel VBA
- VB.net
- C#
- C/C++
- Delphi, Free Pascal
- MATLAB
- Python
- Java
- LabView
- R
- Fortran (for DLLs, with DirectDLL)
- Julia (with DirectDLL)



COM interface

Examples of accessing the COM server in various languages

```
In MATLAB:
```

```
- DSSobj = actxserver('OpenDSSEngine.DSS');
```

In Excel VBA: (Early binding)

```
Public DSSobj As OpenDSSEngine.DSS
Set DSSobj = New OpenDSSEngine.DSS
```

In Delphi

```
- {Import Type Library}
- DSSObj := coDSS.Create;
```

In PYTHON:

```
- self.engine = win32com.client.Dispatch("OpenDSSEngine.DSS")
```

Direct DLL interface

- Your programming language does not support COM
 - In a non-Windows environment such as Apache server
- Your programming language does not support early bindings in COM and you want to speed things up
 - MATLAB
 - See "COM Speed Comparison.pdf" in the Doc folder
- If your programming language supports early binding in COM, continue to use the COM interface
 - The properties implemented in this library are the same implemented in the COM interface; Just accessed differently



Direct DLL interface

BUSI	0x00a4a9f0	0x0064a9f0	124 (0x7c)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
BUSS	0x00a4b220	0x0064b220	122 (0x7a)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
BUSV	0x00a4b340	0x0064b340	121 (0x79)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CapacitorsF	0x00a5c160	0x0065c160	86 (0x56)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CapacitorsI	0x00a5bd40	0x0065bd40	87 (0x57)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CapacitorsS	0x00a5c330	0x0065c330	85 (0x55)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CapacitorsV	0x00a5c5e0	0x0065c5e0	84 (0x54)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CapControlsF	0x00a5f270	0x0065f270	74 (0x4a)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CapControlsI	0x00a5ee40	0x0065ee40	75 (0x4b)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CapControlsS	0x00a5f920	0x0065f920	73 (0x49)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CapControlsV	0x00a5fdc0	0x0065fdc0	72 (0x48)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CircuitF	0x00a47390	0x00647390	127 (0x7f)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
Circuitl	0x00a46e30	0x00646e30	128 (0x80)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CircuitS	0x00a47440	0x00647440	126 (0x7e)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CircuitV	0x00a47ab0	0x00647ab0	125 (0x7d)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CktElementF	0x00a428a0	0x006428a0	133 (0x85)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CktElementI	0x00a42320	0x00642320	134 (0x86)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CktElementS	0x00a42b20	0x00642b20	132 (0x84)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function
CktElementV	0x00a430e0	0x006430e0	131 (0x83)	OpenDSSDirect.dll	C:\Users\prdu001\OpenDSS\Source\x64\OpenDSSDirect.dll	Exported Function

https://sourceforge.net/p/electricdss/code/HEAD/tree/trunk/Version8/Distrib/Doc/OpenDSS Direct DLL.pdf

- Dynamics simulation mode
 - Dynamics mode is used for
 - Fault current calculations including Generator contributions
 - Single time-step solution
 - Machine transients
 - Inverter transients
 - Typical time step: 0.2 1 ms
 - Depends on time constants in model
 - A converged power flow is required to initialize the model.



Dynamics simulation mode – basic algorithm

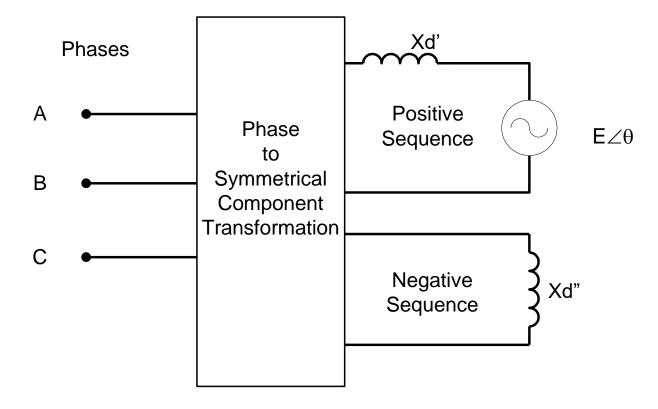
```
• Increment time;
{Predictor}
            IterationFlag := 0;
            IntegratePCStates;
            SolveSnap;
         {Corrector}
            IterationFlag := 1;
            IntegratePCStates;
            SolveSnap;
```

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- Dynamics simulation mode use
 - Initialize state variables in all PC Elements
 - For example, in a Generator object currently:
 - Compute voltage, E_1 , behind Xd' and Initialize the phase angle, θ , to match power flow (approximately)
 - Set derivatives of the state variables to zero
 - For the Generator: Speed (relative to synch frequency), Angle
 - Set controlmode=time
 - When running in time steps of a few seconds or less, controls that depend on the control queue for instructions on delayed actions will be automatically sequenced when the solution time reaches the designated time for an action to occur.



3-Phase Generator Model in Dynamics Mode



Differential Equations for Default Generator (1-Mass)

Derivative Calculation:

$$\frac{dv}{dt} = \frac{Pshaft - Pterm - Dv}{M}$$

$$\frac{d\theta}{dt} = v$$

Integration

Trapezoidal integration formula for θ , for example:

$$\theta_{n+1} = \theta_n + \frac{\Delta t}{2} \left[\frac{d\theta}{dt} \bigg|_n + \frac{d\theta}{dt} \bigg|_{n+1} \right]$$

Dynamics simulation mode – use

Let's run an example



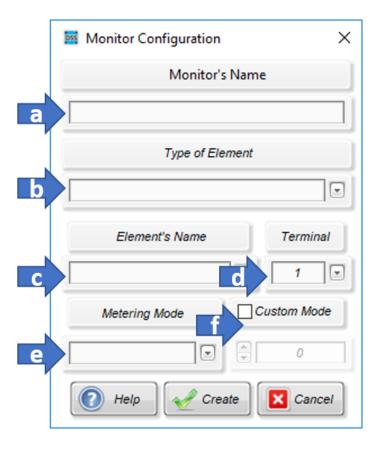
Visualizing data

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Monitors



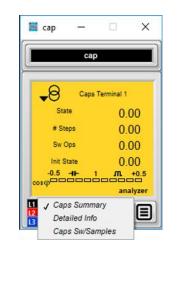


Monitors

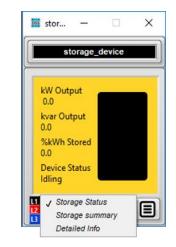
5 fdr_... fdr_05410_mon_vi V L-L V Terminal 1 0.00 (a) L2/3 0.00 0.00 60.00 m +0.5 analyzer √ Voltage L-L Voltage L-N Active Power (P) Aparent Power (S) Reactive Power (Q) Power Factor Voltages L-N (phasors) Voltages L-N /samples Currents /samples Active power /samples Reactive Power /samples

(b) (e)

5 fdr_... fdr_05410_mon_va **-**8 kW Terminal 1 0.00 0.00 0.00 0.00 1 JR +0.5 analyzer Aparent Power (S) Reactive Power (Q) Power Factor kW/samples kvars /samples sub... subxfmr taps Taps Terminal 2 0.00 0.00 LTC Ops 0.00 0.00







(d)

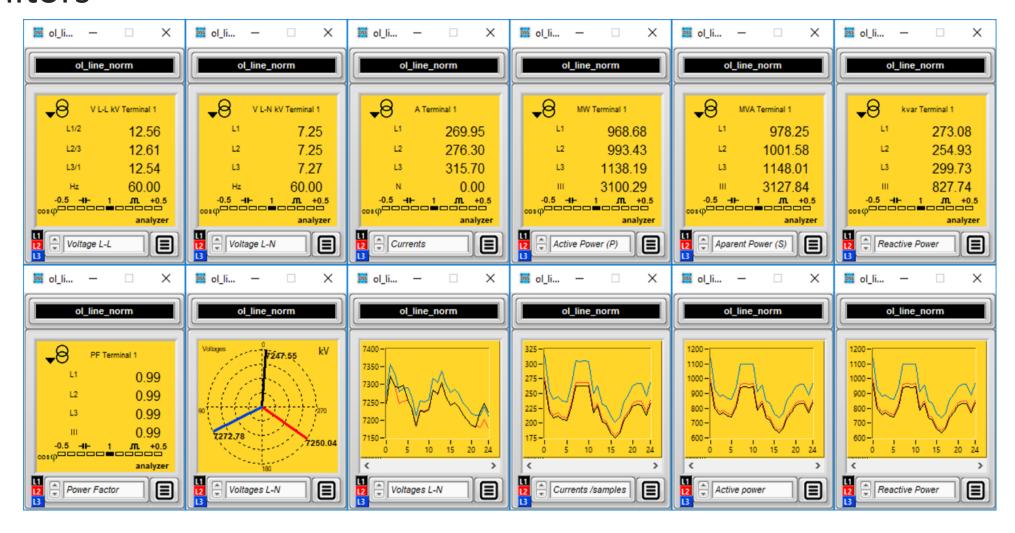
/ Taps summary

Detailed info Taps/samples M. +0.5

(f)

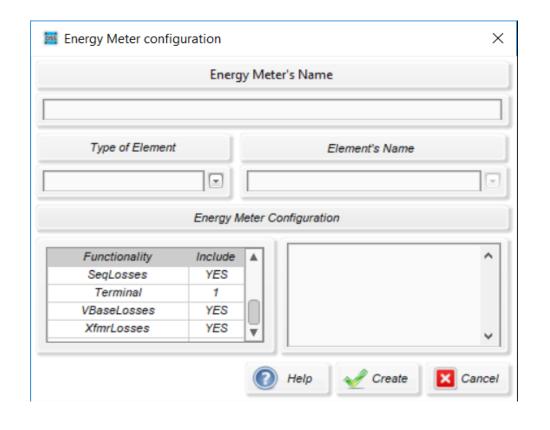
(c)

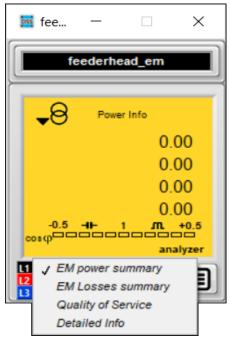
Monitors



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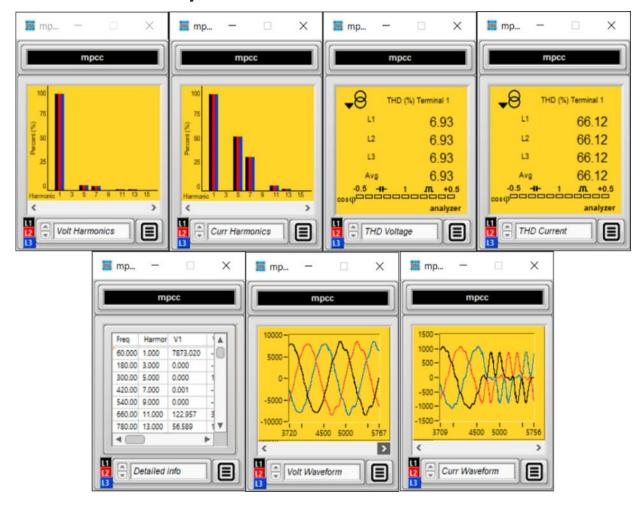
Energy meters







Special mode (Harmonics)



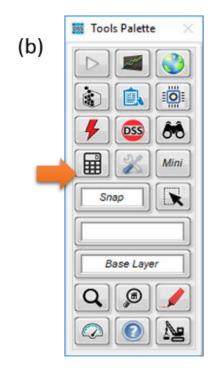
Let's run an example

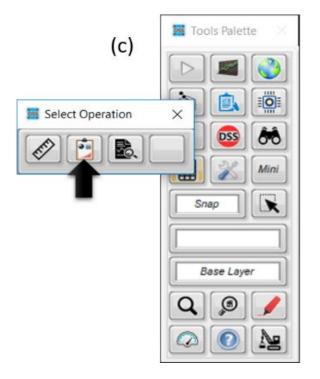


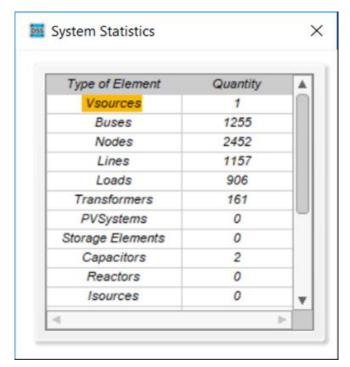
Model statistics

Getting information about the model





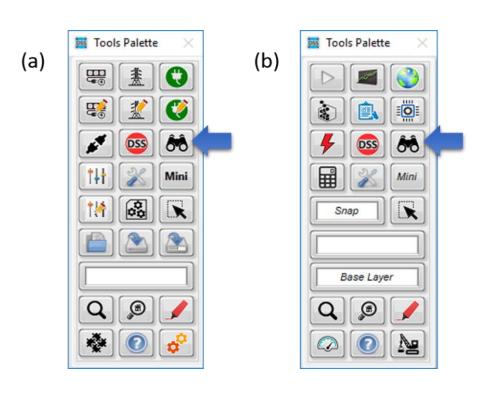


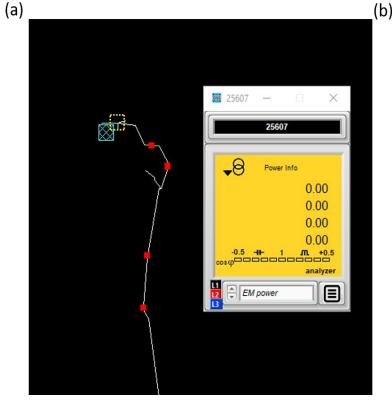


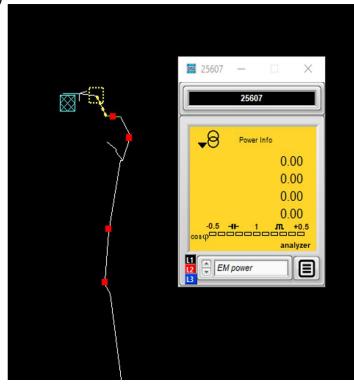
(d)

Finding elements within the model

Getting information about the elements within model





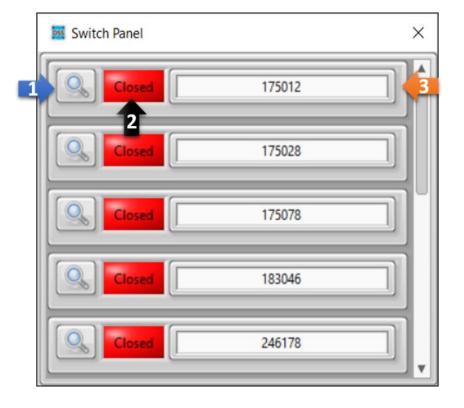


Interacting with the model

Close/open switching elements

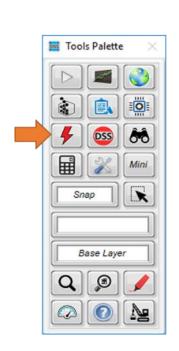


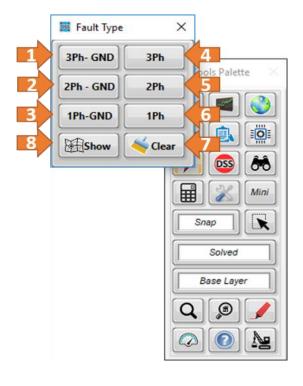


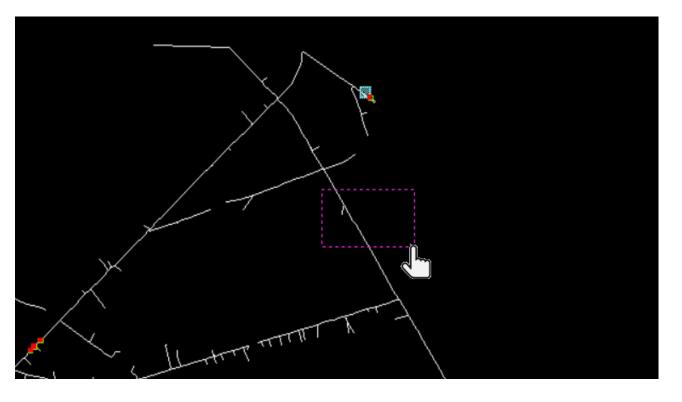


Interacting with the model

Adding faults

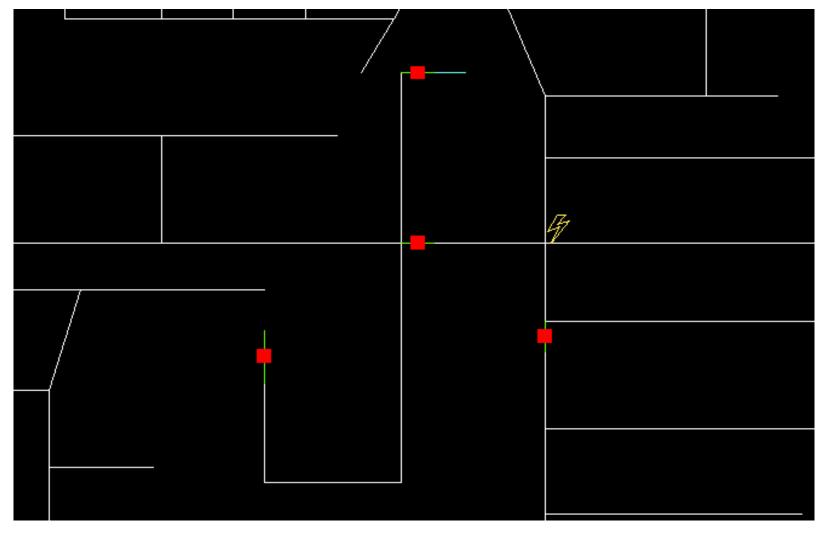






Interacting with the model

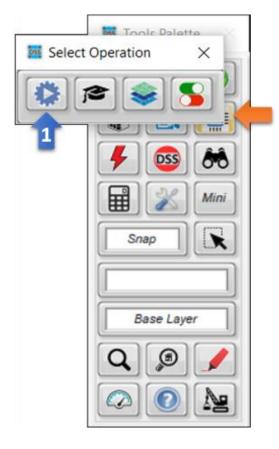
Adding faults

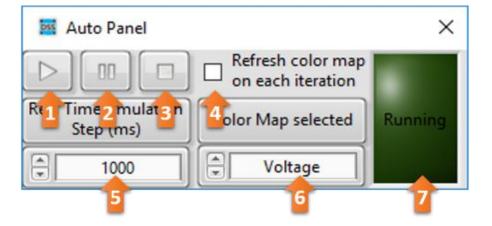


Real-Time simulation

Real-Time simulation module

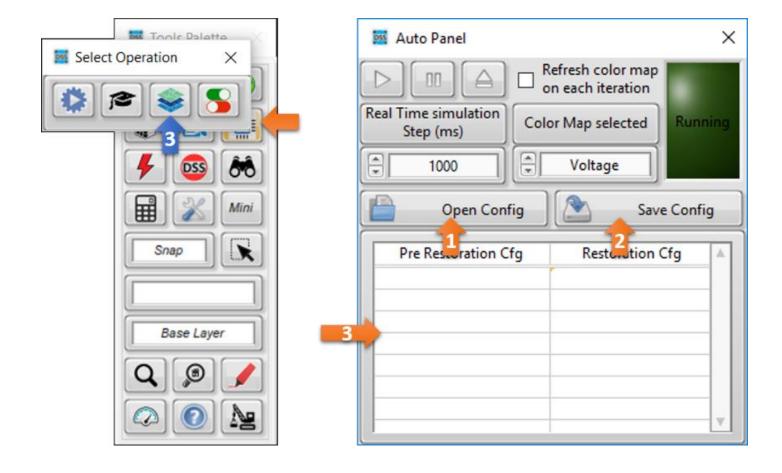






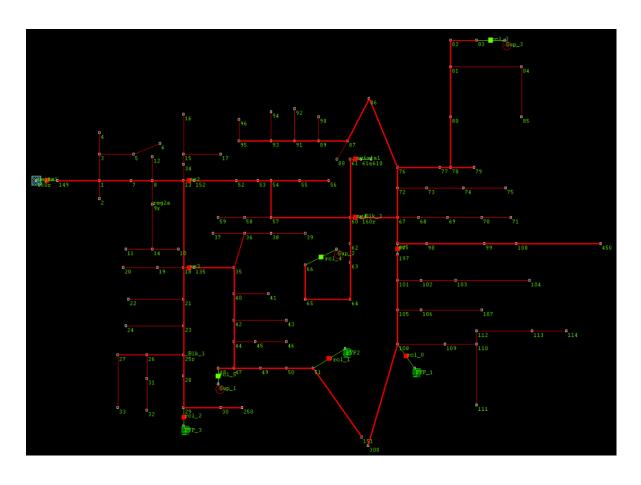
Real-Time simulation

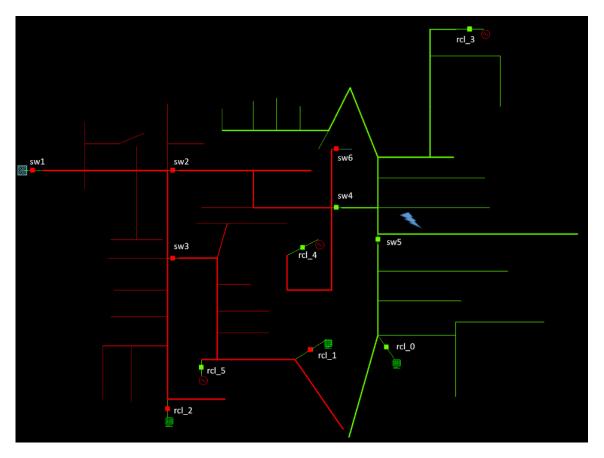
 FLISR (Fault Location, Isolation and Service Restoration) simulation module



Real-Time simulation

 FLISR (Fault Location, Isolation and Service Restoration) simulation module

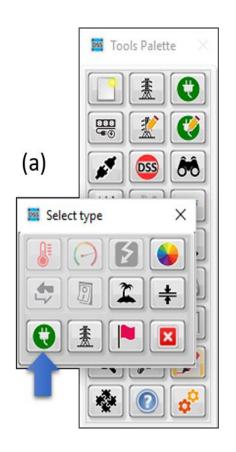


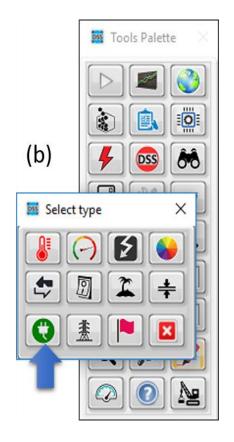




Visualizing elements within the model

The elements palette







Co-Simulating with OpenDSS-G

The TCP-IP server

OpenDSS-G has a TCP/IP server integrated for co-simulation with other platforms. The document that describes the protocol and uses can be downloaded from

https://sourceforge.net/projects/dssimpc/files/Documents/DSTCP-Comm.pdf/download.

Co-simulation examples for MATLAB and NI LabVIEW can be found at https://sourceforge.net/p/dssimpc/code/HEAD/tree/trunk/Distribution/Examples/.



Co-Simulation with OpenDSS-G

Let's run an example



Today's challenge

Today's challenge

Given the system at

https://sourceforge.net/p/dssimpc/code/HEAD/tree/trunk/Distribution/ Examples/Ckt_7_Storage/

Automate a process to evaluate the valid alternatives (technically) to solve the issues in the feeder during three years. The whole analysis cannot take more than 5 min. The alternatives can combine to provide a complete solution during the three years.



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