# EE 16A: Homework 6

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### 1. Matt Soh 3032109159, William Song 3031799759.

I worked alone for 5 hours then met up with William and Matt to discuss how to approach and solve each problem.

### 2. Nodal Analysis

(a) Solve for all node voltages using nodal analysis. Verify with superposition.

We would like to compute the node potentials at  $V_1$  and  $V_2$ . So, let us perform nodal analysis by summing the current (flow) that goes in and out of these two nodes.

For  $V_1$ , we have:

$$-1 + \frac{1}{10}(V_1 - 0) + \frac{1}{20}(V_1 - V_2) = 0 \tag{1}$$

which simplifies to

$$\frac{3}{20}V_1 - \frac{1}{20}V_2 = 1. (2)$$

For  $V_2$ , we have:

$$2 + \frac{1}{50}(V_2 - 0) + \frac{1}{20}(V_2 - V_1) = 0 \tag{3}$$

which simplifies to

$$\frac{1}{20}V_1 - \frac{7}{100}V_2 = 2. (4)$$

By putting equations (2) and (4) into the matrix-vector form Av = b, we get

$$\begin{bmatrix} \frac{3}{20} & -\frac{1}{20} \\ \frac{1}{20} & -\frac{7}{100} \end{bmatrix} v = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
 (5)

Using ipython notebook to solve for  $V_1$  and  $V_2$  using numpy (code provided in the back), we get

$$\boxed{V_1 = -3.75V}$$

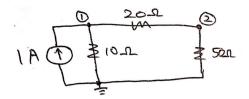
$$\boxed{V_2 = -31.25V}$$

$$(6)$$

$$(7)$$

$$V_2 = -31.25V \tag{7}$$

Verifying with superposition: first we consider the left current source (1A):

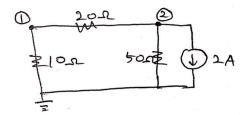


$$V_{1} = IR_{eq} = (1A)\left(\frac{1}{\frac{1}{10\Omega} + \frac{1}{70\Omega}}\right) = \frac{70}{8}V$$

$$V_{2} = \left(\frac{50\Omega}{20\Omega + 50\Omega}\right)V_{1} = \frac{50}{8}V$$
(9)

$$V_2 = (\frac{50\Omega}{20\Omega + 50\Omega})V_1 = \frac{50}{8}V\tag{9}$$

next, the right current source (2A):



$$V_2 = IR_{eq} = (-2A)\left(\frac{1}{\frac{1}{30\Omega} + \frac{1}{50\Omega}}\right) = -\frac{150}{4}V$$
 (10)

$$V_1 = (\frac{10\Omega}{10\Omega + 20\Omega})V_2 = -\frac{50}{4}V\tag{11}$$

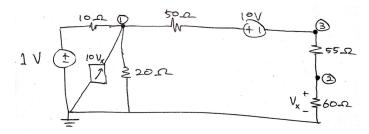
Thus, by adding equations (8) + (11) and (9) + (10) we get

$$V_1 = \frac{70}{8}V - \frac{50}{4}V \implies V_1 = -\frac{15}{4}V$$
 (12)

$$V_2 = \frac{50}{8}V - \frac{150}{4}V \implies V_2 = -\frac{125}{4}V$$
 (13)

(b) Solve for all node voltages using nodal analysis.

Redraw the circuit with an added node 3:



Notice that  $V_2 = V_x$  since  $V_2$  is connected to the ground through the  $60\Omega$  resistor. Keeping this in mind, we proceed with nodal analysis on each node (1,2,3):

For  $V_1$ , we have:

$$\frac{1}{10\Omega}(V_1 - 1V) - 10V_2 + \frac{1}{20\Omega}(V_1 - 0) + \frac{1}{50\Omega}(V_1 - 10V - v_3) = 0$$
 (14)

For  $V_2$ , we have:

$$\frac{1}{60\Omega}(V_2 - 0) + \frac{1}{55\Omega}(V_2 - V_3) = 0 \tag{15}$$

For  $V_3$ , we have:

$$\frac{1}{50\Omega}(V_3 + 10V - V_1) + \frac{1}{55\Omega}(V_3 - V_2) = 0 \tag{16}$$

With some rearranging into the matrix-vector form (Av = b, where v =

then solving through iPython(code in the back), we get

$$V_1 = 10.402V$$

$$V_2 = 0.146V$$
(17)

$$V_2 = 0.146V$$
 (18)

#### 3. Thvenin and Norton equivalent circuits

(a) Find the Thvenin and Norton equivalent circuits seen from the outside the box.

First, calculate the effective resistance seen from the voltage source to find the current supplied by the voltage source. The resistances  $R_3$  and  $R_4$  are in series hence have effective resistance of  $6\Omega$ . They are connected in parallel to a  $R_2$  resistance yielding an effective resistance of

$$(\frac{1}{6} + \frac{1}{3})^{-1} = 2\Omega. (19)$$

This resistance is in series to  $R_1$ , yielding a total effective resistance of

$$R_{eq} = 3\Omega + 2\Omega = 5\Omega. \tag{20}$$

Hence the current supplied by the voltage source is

$$I = \frac{10V}{5\Omega} = 2A \tag{21}$$

Now set up these KCL / KVL equations:

$$-v_2 + v_3 + v_4 = 0 (22)$$

$$v_2 = 3I_2 \tag{23}$$

$$v_3 = 4.5I_3 \tag{24}$$

$$v_4 = 1.5I_3 \tag{25}$$

$$I = I_2 + I_3 = 2A (26)$$

We combine equations (4) through (7) to get

$$\implies -3I_2 + 4.5I_3 + 1.5I_3 = 0 \tag{27}$$

Solving equations (8) and (9) for  $I_3$ , we get

$$3I_3 + 6I_3 = 6A \implies I_3 = \frac{2}{3}A$$
 (28)

Thus  $V_{thvenin} = 4.5I_3 = 3$  Volts. The Norton equivalent is given by

$$I_{norton} = \frac{V_{thvenin}}{R_{thvenin}} = \frac{3}{\frac{9}{4}} = \frac{4}{3}A \tag{29}$$

(b) Find the Threnin and Norton equivalent circuits seen from the outside the box.

$$V_{thevenin} = IR = (2A)(1.5\Omega) \implies \boxed{V_{th} = 3V}$$
 (30)

$$I_{sc} = \frac{V_{th}}{(R_1||R_3 + R_5)} \Longrightarrow \boxed{I_{no} = 2.8A}$$

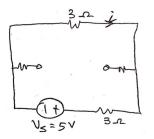
$$(31)$$

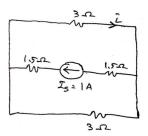
$$I_{sc} = \frac{V_{th}}{(R_1||R_3 + R_5)} \Longrightarrow \boxed{I_{no} = 2.8A}$$

$$R_{thevenin} = \frac{V_{th}}{I_{sc}} = \frac{3V}{2.8A} \Longrightarrow \boxed{R_{th} = 1.0714\Omega}$$
(31)

4. Nodal Analysis Or Superposition? Solve for the current through the  $3\Omega$  resistor, marked as i, using superposition. Verify using nodal analysis. You can use IPython to solve the system of equations if you wish. Where did you place your ground, and why?

Using superposition: We look at one independent source at a time, and in this case,  $V_s$  then  $I_s$ :





From the left superposition, we can easily see that

$$I = \frac{V}{R_{eq}} = \frac{5V}{3\Omega + 3\Omega} = \frac{5}{6}A\tag{33}$$

and since i is just in the opposing direction of the same current,

$$i = -I = -\frac{5}{6}A\tag{34}$$

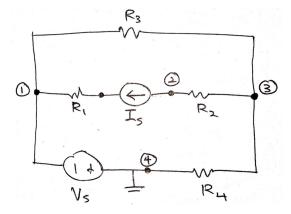
From the right superposition, we notice the symmetry so it is easy to see that the current source splits evenly:

$$i = \frac{1}{2}I_s = \frac{1}{2}A\tag{35}$$

Thus by superposition,

$$i = -\frac{5}{6}A + \frac{1}{2}A \implies \boxed{i = -\frac{1}{3}A} \tag{36}$$

Verify using nodal analysis: From all the nodes that exist in this circuit, we label nodes 1, 2, 3, and 4, and recognizing that we cannot solve for all of these potentials, we place a ground node to set the potential of  $V_4 = 0$ :



It is easy to see that  $V_1$  (potential at node 1) is

$$V_1 = -V_s \tag{37}$$

Now, proceed with nodal analysis on nodes 2 and 3:

For  $V_2$ , we have:

$$I_s + G_2(V_3 - V_4) = 0 (38)$$

For  $V_3$ , we have:

$$G_3(V_4 - V_1) + G_2(V_4 - V_3) + G_4(V_4 - 0) = 0 (39)$$

Substituting in  $V_1$  in equation (36) then rearranging into the matrix-vector form  $(Av = b, \text{ where } v = \begin{bmatrix} V_2 \\ V_3 \end{bmatrix})$  then solving through iPython(code in the back), we get

$$V_2 = -5.5V (40)$$

$$V_3 = -4V \tag{41}$$

Finally, to solve for current i through  $R_3$ ,

$$i = \frac{\Delta V}{R_3} = \frac{V_1 - V_3}{R_3} = \frac{-5V - (-4V)}{3\Omega} \implies i = -\frac{1}{3}A$$
 (42)

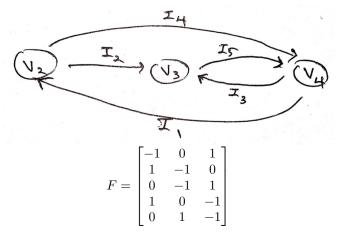
- 5. Optional
- 6. Solving Circuits with Voltage Sources

(a) What relationship does the voltage source enforce between  $v_1$  and  $v_4$ ?

$$\boxed{v_1 - v_4 = V_s} \tag{43}$$

The voltage source fixes the nodes to be a constant offset from each other.

(b) Draw the graph for the circuit where  $v_1$  and  $v_4$  are combined into one node. Specify a new incidence matrix for this graph.



(c) Find R and  $\vec{b}$  so that Ohms law is written  $F\vec{v} + \vec{b} = R\vec{i}$ .

$$R = \begin{bmatrix} R_1 & 0 & 0 & 0 & 0 \\ 0 & R_2 & 0 & 0 & 0 \\ 0 & 0 & R_3 & 0 & 0 \\ 0 & 0 & 0 & R_4 & 0 \\ 0 & 0 & 0 & 0 & R_5 \end{bmatrix}$$

$$b = \begin{bmatrix} V_s \\ 0 \\ V_s \\ 0 \\ 0 \end{bmatrix}$$

(d) What is  $\vec{f}$  in this circuit? write  $\vec{v}$  in terms of known quantities  $(\vec{f}, \vec{b}, G, F, R)$ . You may need to modify several of the members of the derived equation by grounding a node and dropping a row or a column in order to give the problem a unique solution.

First let us compute the product  $F^T\vec{i}$ :

$$\begin{bmatrix} -1 & 1 & 0 & 1 & 0 \\ 0 & -1 & -1 & 0 & 1 \\ 1 & 0 & 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \\ i_4 \\ i_5 \end{bmatrix} = \begin{bmatrix} -i_1 + i_2 + i_4 \\ -i_2 - i_3 + i_5 \\ i_1 + i_3 - i_4 - i_5 \end{bmatrix}$$

From this, we know the vector  $\vec{f}$  has 3 elements in it. Furthermore, we know we combined the nodes 1 and 4 into a supernode. Therefore:

Solving the Ohms law equation for  $\vec{i}$ ,

$$\vec{i} = G(F\vec{v} + \vec{b}).$$

Now plugging this expression into KCL we see

$$F^TG(F\vec{v}+\vec{b})=-\vec{f}$$

Does this equation have a unique solution? Let us first go back to the matrix F, row-reducing we see F has a linearly dependent column.

$$F = \begin{bmatrix} -1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} - > \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

This implies that the system is underdetermined. In order to make this system determined, we can drop one column of the F matrix, and ignore one potential in  $\vec{v}$ . We will assign this node a potential of 0. This is equivalent to grounding a node in a circuit  $(\vec{v}_{qr})$ .

Call the new matrix  $F_{gr}$  and the new  $\vec{f}$  as  $\vec{f}_{gr}$ . Then  $F_{gr}$  has no null space and:

$$\vec{i} = GF_{gr}\vec{v}_{gr} + G\vec{b} \tag{45}$$

Plugging this into KCL again, we see

$$F_{gr}^T G F_{gr} \vec{v}_{gr} + F_{gr}^T G \vec{b} = -\vec{f}_{gr}$$

$$\tag{46}$$

Thus,

$$\boxed{F_{gr}^T G F_{gr} \vec{v}_{gr} = -\vec{f}_{gr} - F_{gr}^T G \vec{b}}$$
(47)

(e) write  $\vec{i}$  in terms of known quantities

$$\vec{i} = G(F_{gr}\vec{v}_{gr} + \vec{b})$$
(48)

(f) See iPython Notebook in the end of PDF

# prob6

## October 11, 2016

# 1 HW6

1.0.1 EECS 16A: Designing Information Devices and Systems I, Fall 2016

## 1.1 Numpy Calculations

```
2)
     a)
In [3]: import numpy as np
        A = np.array([[3/20, -1/20]],
                     [1/20, -7/100]])
        b = np.array([[1],[2]])
        v = np.linalg.solve(A,b)
        print (v)
[[-3.75]
 [-31.25]]
  2) b)
In [4]: import numpy as np
        A = np.array([[1/10 + 1/20 + 1/50, -10, -1/50],
                      [0, 1/60 + 1/55, -1/55],
                      [-1/50, -1/55, 1/50 + 1/55]])
        b = np.array([[1/10 + 1/5],[0],[-1/5]])
        v = np.linalg.solve(A,b)
        print(v)
[[ 10.40226382]
 [ 0.14627775]
 [ 0.28036569]]
  4) Verifying with Nodal Analysis
In [5]: import numpy as np
        A = np.array([[1/1.5, -1/1.5],
                      [-1/1.5, 1/3 + 1/1.5 + 1/3]])
        b = np.array([[-1], [-5/3]])
        v = np.linalg.solve(A,b)
        print(v)
[[-5.5]]
 [-4.]]
```

## 1.2 Q6 Circuit solver

In this question we will write a program that solves circuits methodically, able to include both voltage and current souces.

```
In [6]: import numpy as np
        from numpy import linalg
        from __future__ import print_function
  (i) Write the incidence matrix F for the graph, considering v_1 and v_4 as a combined "supernode".
In [7]: F = np.array([[-1,0,1],
                        [1,-1,0],
                        [0,-1,1],
                        [1,0,-1],
                        [0,1,-1]]
        print('\nF:\n',F)
F:
 [[-1 0 1]
 [ 1 -1 0]
 [ 0 -1 1]
 [1 0 -1]
 [ 0 1 -1]]
 (ii) Specify the resistance matrix R and the vector of voltage sources \vec{b}.
In [8]: R1,R2,R3,R4,R5 = 100000, 200, 100, 100000, 100
        Rvec = np.array([R1,R2,R3,R4,R5])
        R = np.eye(5)*Rvec
        Vs = 10
        b = np.array([[Vs],[0],[Vs],[0],[0]])
        # For convenience, we will define the conductance matrix G as the inverse of R.
        G = np.linalg.inv(R)
        print('\nR:\n',R)
        print('\nb:\n',b)
R:
 [[ 100000.
                                      0.
                                                0.1
                   0.
                             0.
        0.
                200.
                            0.
                                               0.]
 0.
 0.
                  0.
                          100.
                                      0.
                                               0.]
 0.
                  0.
                            0.
                                100000.
                                               0.]
 0.
                  0.
                            0.
                                     0.
                                             100.]]
b:
 [[10]
 [ 0]
 [10]
 [ 0]
 [ 0]]
(iii) Write down the vector f so that KCL is satisfied as: F^{T}i + f = 0
In [9]: f = np.array([[0],[0],[0]])
        print('\nf:\n', f)
```

```
[[0]]
 [0]
 [0]]
(iii) What is the rank of F? Does it have a null space? If so, what is it?
   Row-reducing F, we see F has a linearly dependent column (see Problem 6 Part d). Therefore, rank(F)
is 2.
   Since it's not a full rank, F does have a null space.
   The null space is spanned by [[1],[1],[1]].
In [10]: # any code you write to help you answer above
          from sympy import Matrix
          Fm = Matrix(F)
          # Frr = row-reduced F matrix
          Frr = Fm.rref()
          print(Frr)
          \# Fns = null space of F
          Fns = Fm.nullspace()
          print(Fns)
(Matrix([
[1.0,
        0, -1.0],
[0, 1.0, -1.0],
[ 0,
        0,
               0],
[ 0,
        0,
               0],
               0]]), [0, 1])
[ 0,
        0,
[Matrix([
[1.0],
[1.0],
[ 1]])]
(iv) Setting a potential in v to 0 corresponds to deleting a column of F. Let v_4 = 0, and write down our
     new "grounded" matrix F: F_grounded
In [11]: F_grounded = F[:, :2]
          print('\nF_grounded:\n', F_grounded)
F_grounded:
 [[-1 0]
 [1-1]
 [ 0 -1]
 [ 1 0]
 [ 0 1]]
 (v) Implement your algebraic solution to compute v in terms of F, G, \vec{f}, and \vec{b}. You may also have to slice
     \vec{f} and \vec{b}.
In [12]: A = np.dot(F_grounded.T,np.dot(G,F_grounded))
          print('\nA:\n', A)
          B = np.linalg.inv(A)
```

f:

```
print('\nB:\n', B)
         f_gr = f[0:2]
         v_gr = - B.dot(f_gr + np.dot(F_grounded.T,np.dot(G,b)))
         print('\nv:\n', v_gr)
A:
 [[ 0.00502 -0.005 ]
 [-0.005 0.025 ]]
B:
 [[ 248.75621891 49.75124378]
 [ 49.75124378 49.95024876]]
v:
 [[ 5.]
 [ 5.]]
(vi) Compute \vec{i} with your solution of \vec{v}.
In [13]: i = G.dot(np.dot(F_grounded, v_gr) + b)
         print('\ni:\n', i)
i:
[[ 5.0000000e-05]
 [ 8.88178420e-18]
 [ 5.00000000e-02]
 [ 5.0000000e-05]
 [ 5.0000000e-02]]
In []:
```