

src/Manual_ObsAv.cpp

```
graph TD; A[src/Manual_ObsAv.cpp] --> B[ros/ros.h]; A --> C[geometry_msgs/Twist.h]; A --> D[sensor_msgs/LaserScan.h]; A --> E[termios.h];
```

A diagram illustrating the dependencies of the source file `src/Manual_ObsAv.cpp`. The source file is represented by a gray box at the top. Four blue arrows point from it to four white boxes below, representing the header files it includes: `ros/ros.h`, `geometry_msgs/Twist.h`, `sensor_msgs/LaserScan.h`, and `termios.h`.

ros/ros.h

geometry_msgs/Twist.h

sensor_msgs/LaserScan.h

termios.h