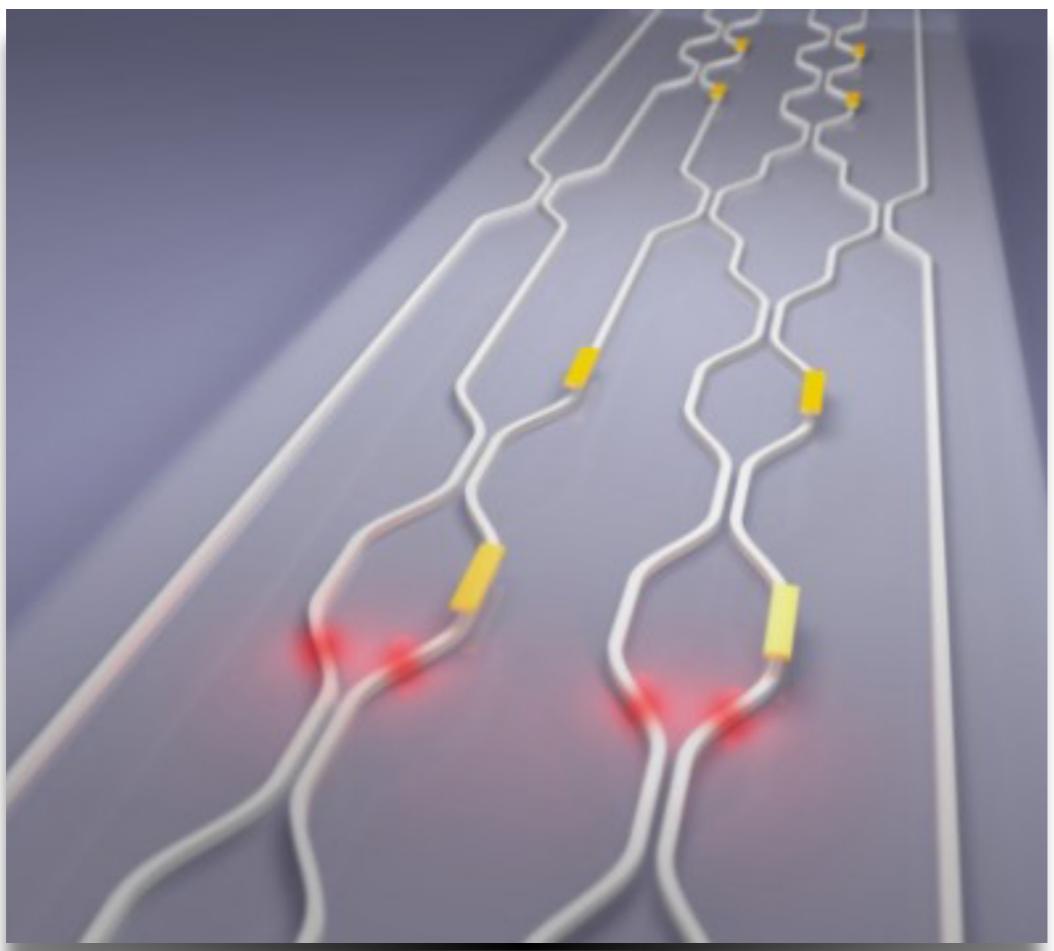


# Characterisation of Linear-Optical Devices via PhaseLift

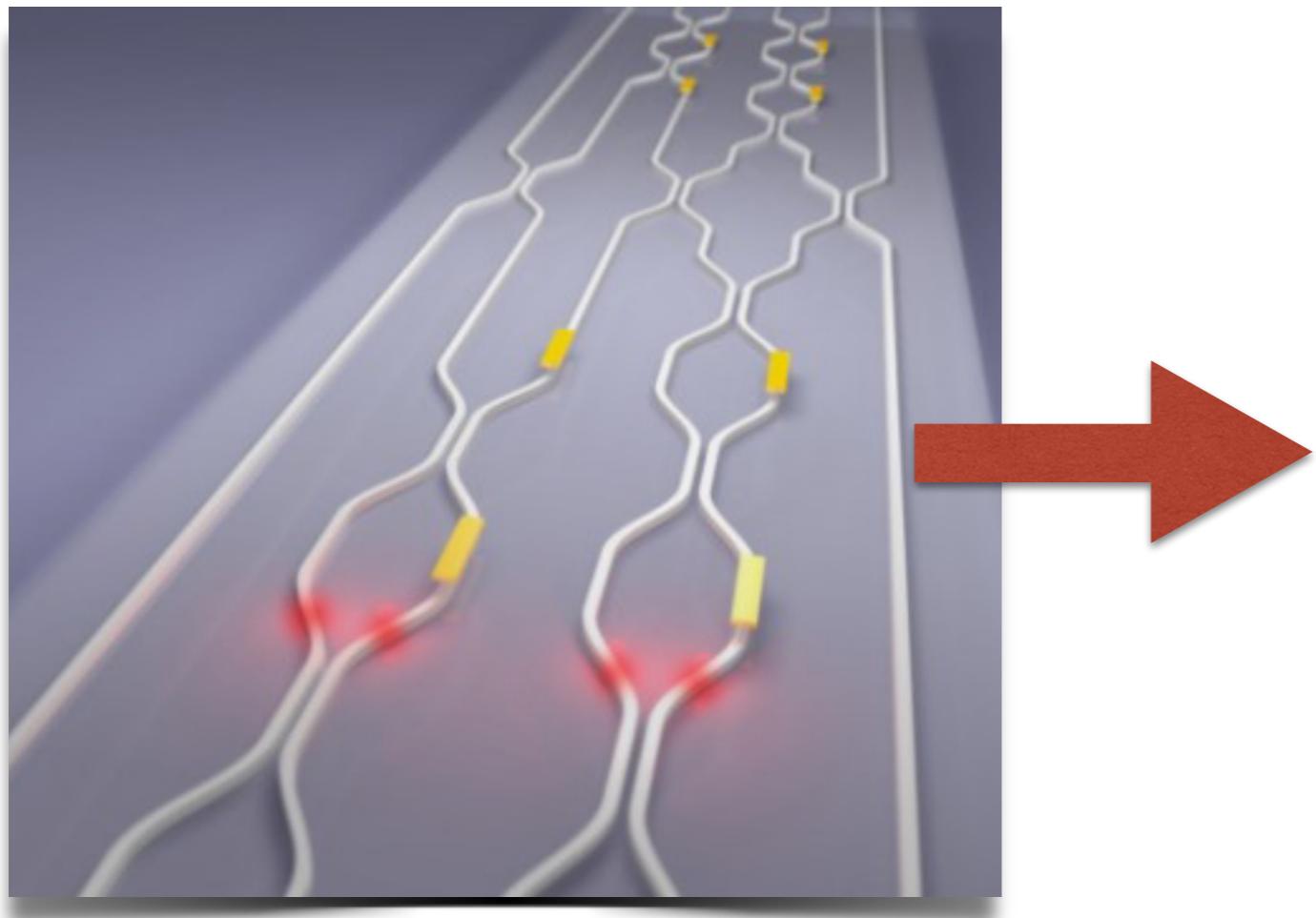
R. Kueng, **D. Suess**, and D. Gross

University of Freiburg

# The Question is...

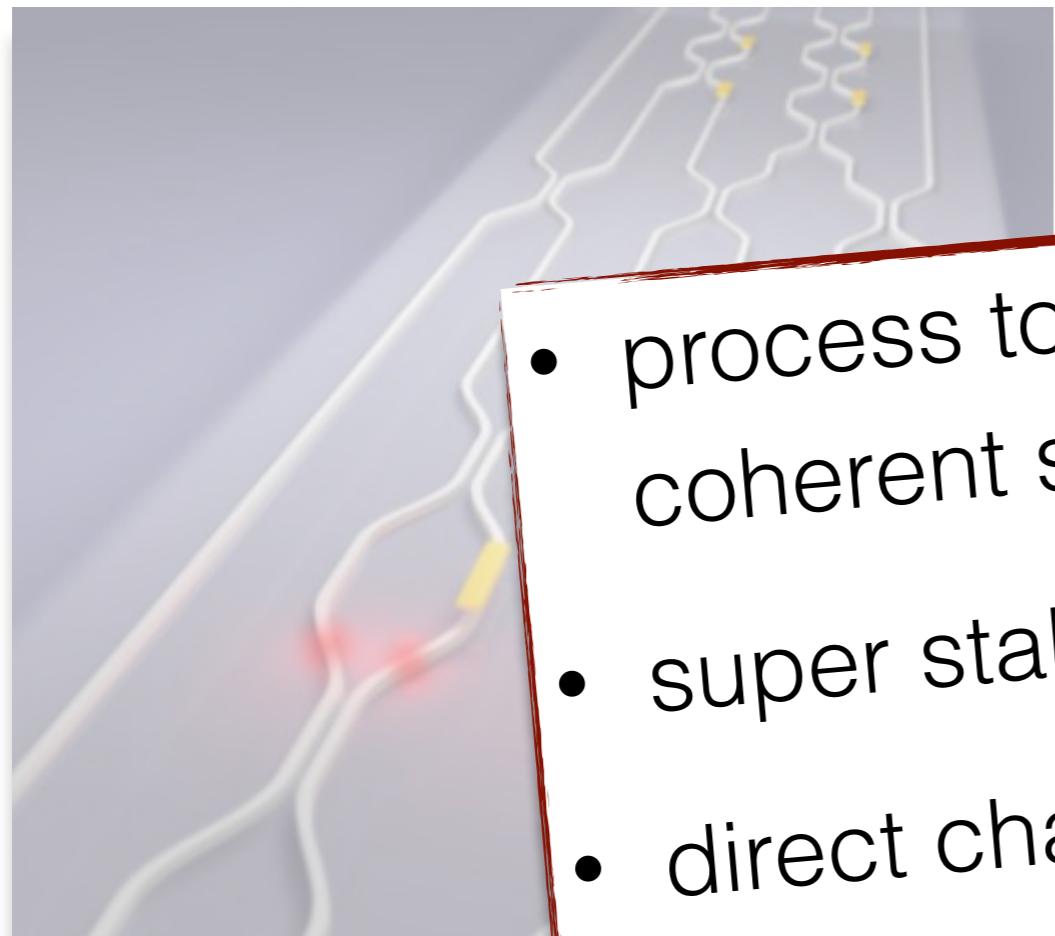


# The Question is...



$$\begin{pmatrix} M_{1,1} & \cdots & M_{1,n} \\ M_{2,1} & \cdots & M_{2,n} \\ \vdots & \ddots & \vdots \\ M_{n,1} & \cdots & M_{n,n} \end{pmatrix}$$

# The Question is...

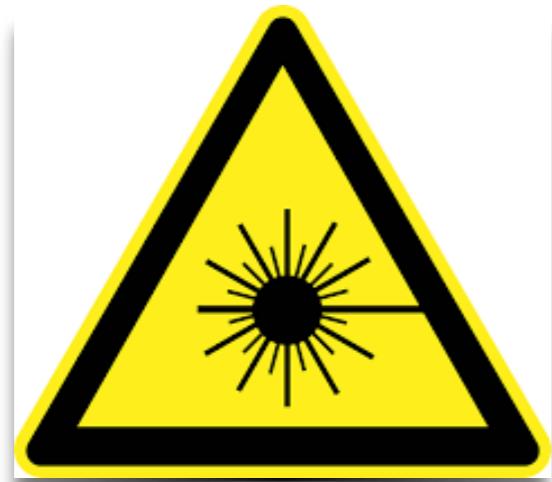


- process tomography with coherent states
- super stable tomography
- direct characterisation
- ...

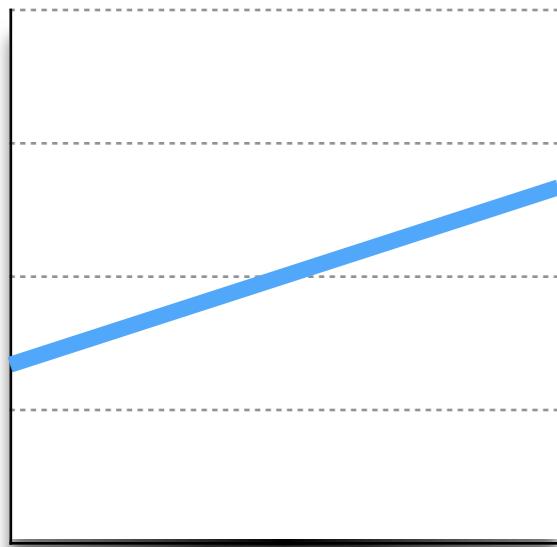
...  
...  
...  
...

$M_{1,n}$   
 $M_{2,n}$   
⋮  
 $M_{n,n}$

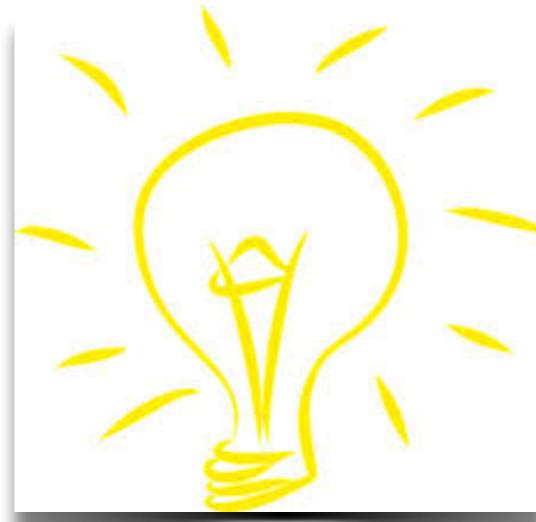
# PhaseLift Characterisation



laser source &  
photo diodes



nr. of measurements  
scale linear in size



conceptually  
simple

Handwritten mathematical equations on a blue chalkboard:

$$(4\alpha_i - 2\rho) \gamma_i^l = (2\alpha_i - \omega) \gamma_{i+1}^l$$
$$\left(2 - \frac{4\alpha_i}{\rho}\right) \gamma_i^l + \left(\frac{2\alpha_{i+1} + \omega}{\rho}\right) \gamma_{i+1}^l = b_i$$
$$c_i$$

rigorous recovery  
guarantees



robust to noise

# Outline

- What is PhaseLift?
- Setup for Device Characterisation
- Characterisation via PhaseLift
- Numerical Results
- Conclusions & Outlook

# What is PhaseLift?

**PhaseLift: Exact and Stable Signal Recovery  
from Magnitude Measurements via Convex Programming**

EMMANUEL J. CANDÈS  
*Stanford University*

THOMAS STROHMER  
*University of California at Davis*

AND

VLADISLAV VORONINSKI  
*University of California at Berkeley*

# What is PhaseLift?

**PhaseLift: Exact and Stable Signal Recovery  
from Magnitude Measurements via Convex Programming**

EMMANUEL J. CANDÈS  
*Stanford University*

THOMAS STROHMER  
*University of California at Davis*

AND

VLADISLAV VORONINSKI  
*University of California at Berkeley*

$$I(a) = |\langle x, a \rangle|^2 \quad \rightarrow \quad x = ?$$

# What is PhaseLift?

$$y_i = |\langle \mathbf{x}, \mathbf{a}_i \rangle|^2 = \text{Tr} (\lvert \mathbf{x} \rangle \langle \mathbf{x} \rvert \lvert \mathbf{a}_i \rangle \langle \mathbf{a}_i \rvert) \quad (*)$$

D. Gross: “Recovering Low-Rank Matrices From Few Coefficients in Any Basis.”  
R. Kueng, H. Rauhut, U. Terstiege: “Low Rank Matrix Recovery from Rank One Measurements.”

# What is PhaseLift?

$$y_i = |\langle \mathbf{x}, \mathbf{a}_i \rangle|^2 = \text{Tr}(|\mathbf{x}\rangle\langle \mathbf{x}| |\mathbf{a}_i\rangle\langle \mathbf{a}_i|) \quad (*)$$

$= Z$

# What is PhaseLift?

$$y_i = |\langle \mathbf{x}, \mathbf{a}_i \rangle|^2 = \text{Tr}(|\mathbf{x}\rangle\langle \mathbf{x}| |\mathbf{a}_i\rangle\langle \mathbf{a}_i|) \quad (*)$$

$= \mathbf{Z}$

minimize  
 $\mathbf{Z} \in \mathbb{H}^n$  rank ( $\mathbf{Z}$ )

subject to     $\text{Tr} (\mathbf{Z} |\mathbf{a}_i\rangle\langle \mathbf{a}_i|) = y_i \quad 1 \leq i \leq m$

$\mathbf{Z} \geq 0$

D. Gross: "Recovering Low-Rank Matrices From Few Coefficients in Any Basis."

R. Kueng, H. Rauhut, U. Terstiege: "Low Rank Matrix Recovery from Rank One Measurements."

# What is PhaseLift?

$$y_i = |\langle \mathbf{x}, \mathbf{a}_i \rangle|^2 = \text{Tr}(|\mathbf{x}\rangle\langle \mathbf{x}| |\mathbf{a}_i\rangle\langle \mathbf{a}_i|) \quad (*)$$

$= \mathbf{Z}$

$$\underset{\mathbf{Z} \in \mathbb{H}^n}{\text{minimize}} \quad \cancel{\text{rank}(\mathbf{Z})} \quad \text{Tr } \mathbf{Z}$$

$$\text{subject to} \quad \text{Tr} (\mathbf{Z} |\mathbf{a}_i\rangle\langle \mathbf{a}_i|) = y_i \quad 1 \leq i \leq m$$

$$\mathbf{Z} \geq 0$$

D. Gross: “Recovering Low-Rank Matrices From Few Coefficients in Any Basis.”

R. Kueng, H. Rauhut, U. Terstiege: “Low Rank Matrix Recovery from Rank One Measurements.”

# What is PhaseLift?

$$y_i = |\langle \mathbf{x}, \mathbf{a}_i \rangle|^2 = \text{Tr}(|\mathbf{x}\rangle\langle \mathbf{x}| |\mathbf{a}_i\rangle\langle \mathbf{a}_i|) \quad (*)$$

$= \mathbf{Z}$

minimize  
 $\mathbf{Z} \in H^n$

$$\cancel{\text{rank}(\mathbf{Z})} \quad \text{Tr } \mathbf{Z}$$

subject to       $\text{Tr}(\mathbf{Z} |\mathbf{a}_i\rangle\langle \mathbf{a}_i|) = y_i \quad 1 \leq i \leq m$

$$\mathbf{Z} \geq 0$$

where       $\mathbf{a}_i$  uniformly sampled from  $\mathcal{S}^{n-1} \subset \mathbb{C}^n$

$$m = Cn$$

D. Gross: "Recovering Low-Rank Matrices From Few Coefficients in Any Basis."

R. Kueng, H. Rauhut, U. Terstiege: "Low Rank Matrix Recovery from Rank One Measurements."

# What is PhaseLift?

- Denote by  $\mathbf{Z}^\#$  the solution of the convex program,  
then with high probability:

$$\mathbf{Z}^\# = |\mathbf{x}\rangle\langle\mathbf{x}|$$

# What is PhaseLift?

- Denote by  $\mathbf{Z}^\#$  the solution of the convex program,  
then with high probability:

$$\mathbf{Z}^\# = |\mathbf{x}\rangle\langle\mathbf{x}|$$

- Numerically, recover  $\mathbf{x}^\#$  by eigenvalue expansion:

$$Z^\# = \sum_i \lambda_i |\mathbf{x}_i\rangle\langle\mathbf{x}_i| \quad (\lambda_i \geq \lambda_{i+1}) \quad \Rightarrow \quad \mathbf{x}^\# = \sqrt{\lambda_1} \mathbf{x}_1$$

# What is PhaseLift?

- Denote by  $\mathbf{Z}^\#$  the solution of the convex program,  
then with high probability:

$$\mathbf{Z}^\# = |\mathbf{x}\rangle\langle\mathbf{x}|$$

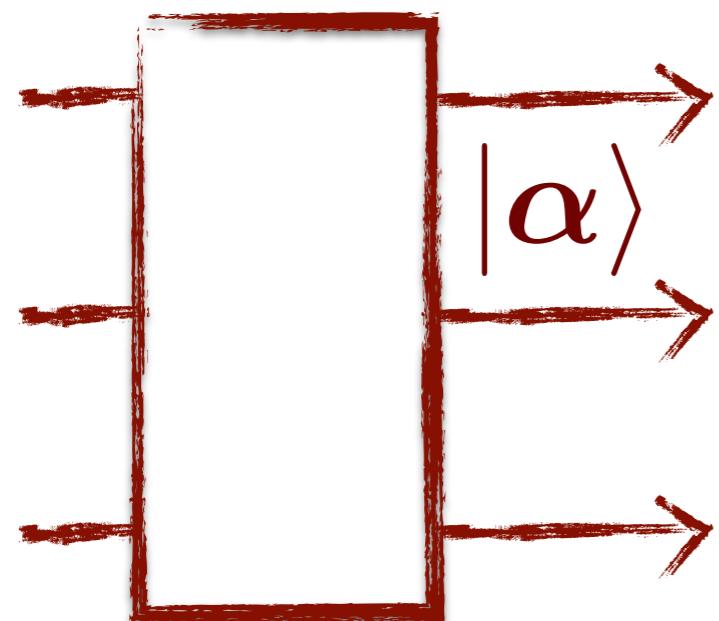
- Numerically, recover  $\mathbf{x}^\#$  by eigenvalue expansion:

$$Z^\# = \sum_i \lambda_i |\mathbf{x}_i\rangle\langle\mathbf{x}_i| \quad (\lambda_i \geq \lambda_{i+1}) \quad \Rightarrow \quad \mathbf{x}^\# = \sqrt{\lambda_1} \mathbf{x}_1$$

- up to a global phase of  $\mathbf{x}$  (lost in measurement)

# Device Characterisation

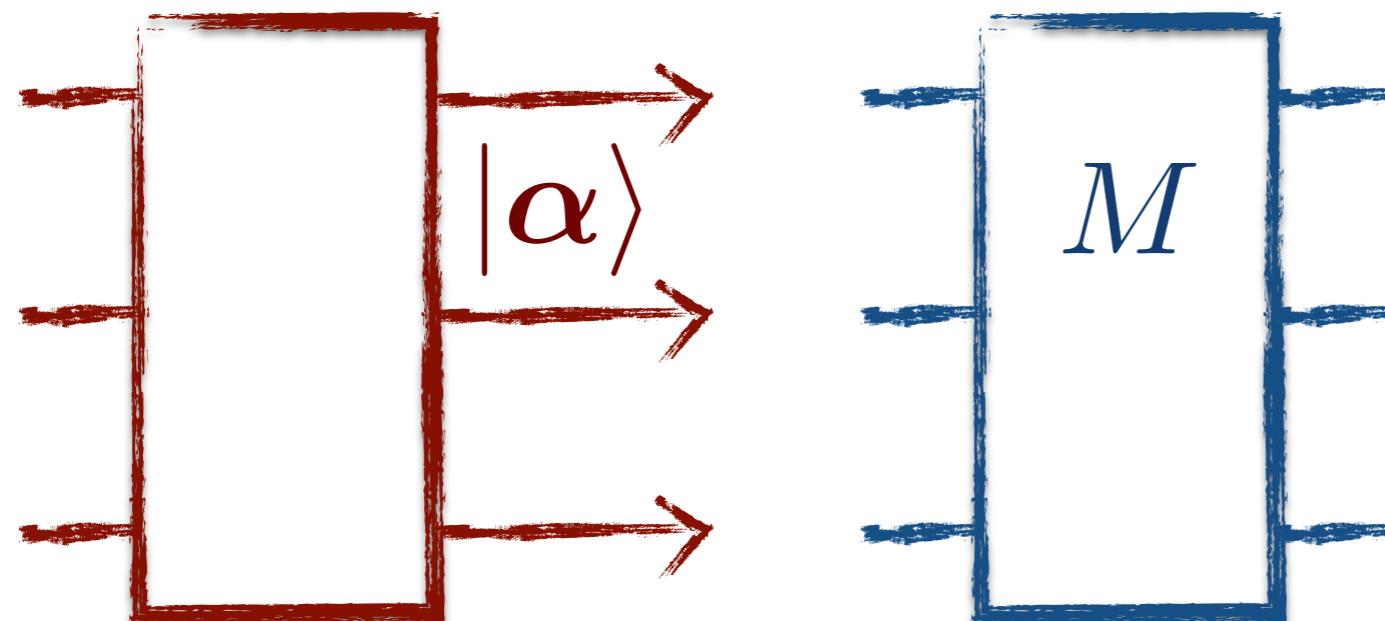
## Preparation



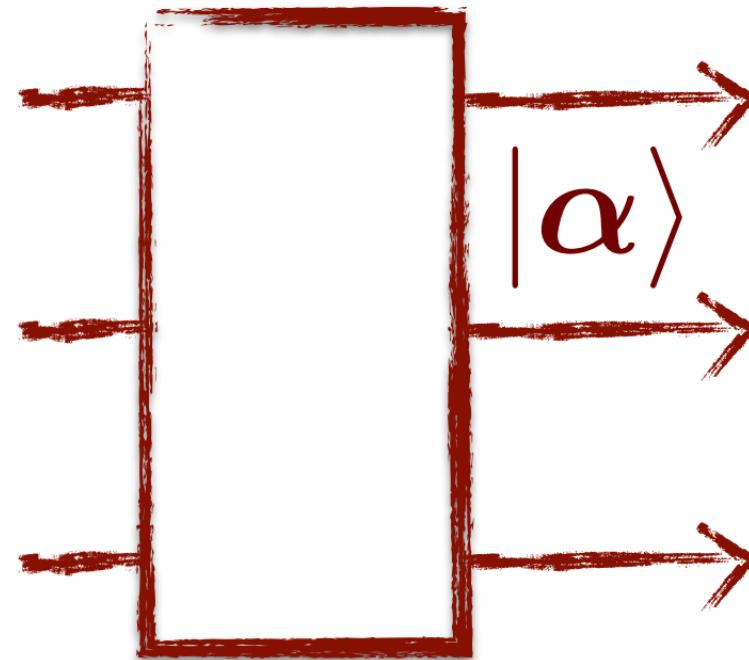
# Device Characterisation

Preparation

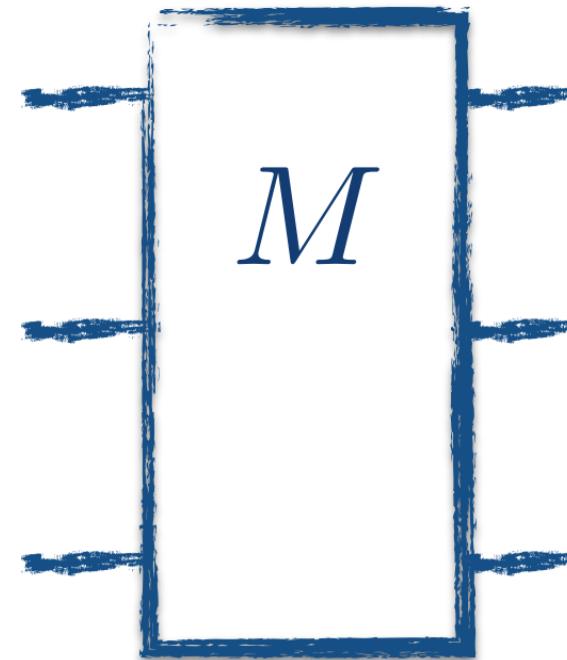
Lin. Optical Circuit



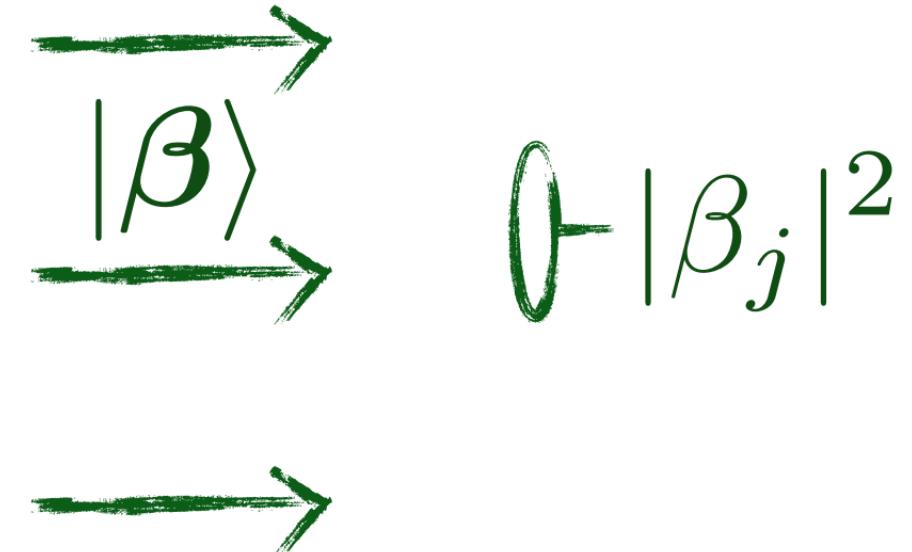
# Preparation



# Lin. Optical Circuit



# Intensity Meas.



Characterisation via aapl

# Characterisation via PL

$$I_j(\alpha) = \left| \sum_k M_{j,k} \alpha_k \right|^2 = |\langle M_j, \alpha \rangle|^2,$$

where  $M_j = (M_{j,1}^*, \dots, M_{j,n}^*)$

1. input coherent states sampled uniformly from complex unit sphere

# Characterisation via PL

$$I_j(\alpha) = \left| \sum_k M_{j,k} \alpha_k \right|^2 = |\langle M_j, \alpha \rangle|^2,$$

where  $M_j = (M_{j,1}^*, \dots, M_{j,n}^*)$

1. input coherent states sampled uniformly from complex unit sphere
2. measure intensities on each output mode

# Characterisation via PL

$$I_j(\alpha) = \left| \sum_k M_{j,k} \alpha_k \right|^2 = |\langle \mathbf{M}_j, \alpha \rangle|^2,$$

where  $\mathbf{M}_j = (M_{j,1}^*, \dots, M_{j,n}^*)$

1. input coherent states sampled uniformly from complex unit sphere
2. measure intensities on each output mode
3. run PhaseLift to recover rows of  $\mathbf{M}$  up to global phases

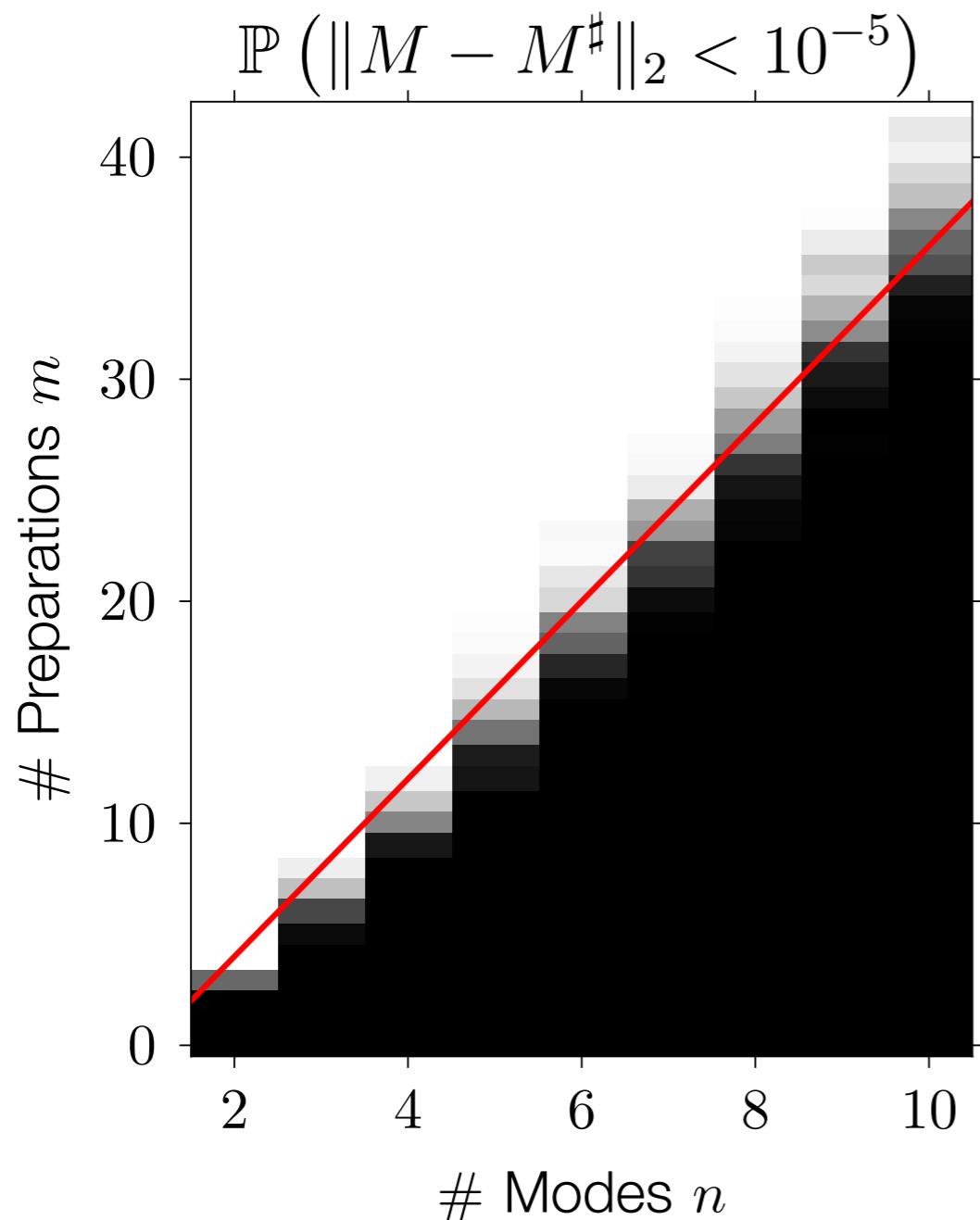
# Characterisation via PL

$$I_j(\alpha) = \left| \sum_k M_{j,k} \alpha_k \right|^2 = |\langle M_j, \alpha \rangle|^2,$$

where  $M_j = (M_{j,1}^*, \dots, M_{j,n}^*)$

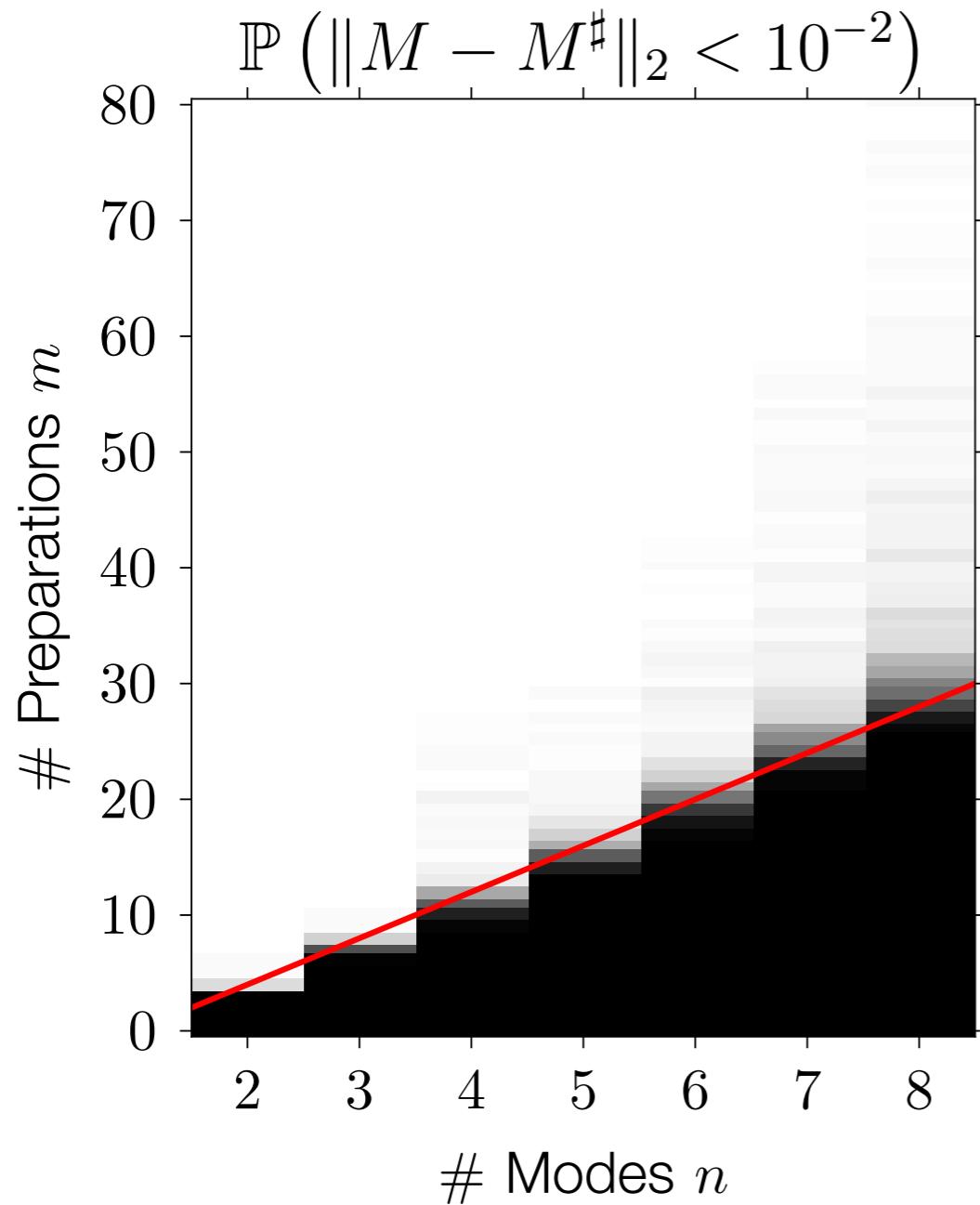
1. ~~input coherence~~ Perfect reconstruction – i.e.  $M^\sharp = M$  – by means of this Protocol holds with probability at least  $1 - O(e^{-\gamma m})$ ,
2. random sampling with probability at least  $1 - O(e^{-\gamma m})$ , provided that the number of randomly chosen input states obeys  $m \geq Cn$ . Here,  $C, \gamma$  are absolute constants.

# Numerical Results



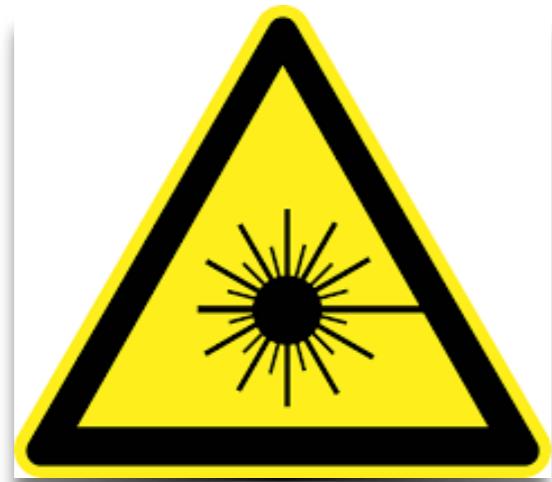
- 100 samples from GUE
- finite precision due to numerical accuracy
- red line: conjectured phase transition at  $m = 4n - 4$

# Numerical Results

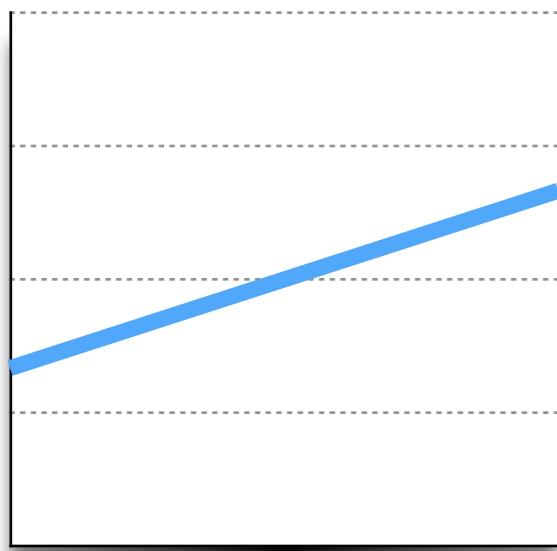


- noisy measurements:
$$I_j(\boldsymbol{\alpha}) = |\langle \mathbf{M}_j, \boldsymbol{\alpha} \rangle|^2 + \epsilon_j$$
- several convex programs robust to additive noise
- recovery guarantees depend on  $n$  and strength of noise

# Conclusion



laser source &  
photo diodes



nr. of measurements  
scale linear in size



conceptually  
simple

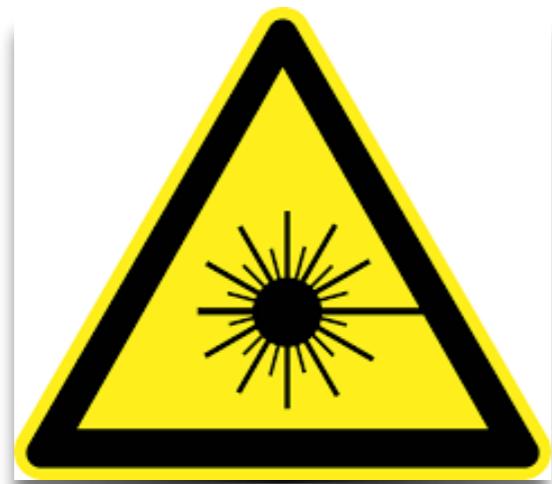
A photograph of handwritten mathematical equations on a blue surface. The equations involve variables like  $\gamma_i^l$ ,  $\alpha$ ,  $\beta$ ,  $b_i$ , and  $c_i$ . One equation shows a subtraction of terms involving  $\alpha$  and  $\beta$ , and another shows a sum involving  $b_i$  and  $c_i$ .

rigorous recovery  
guarantees

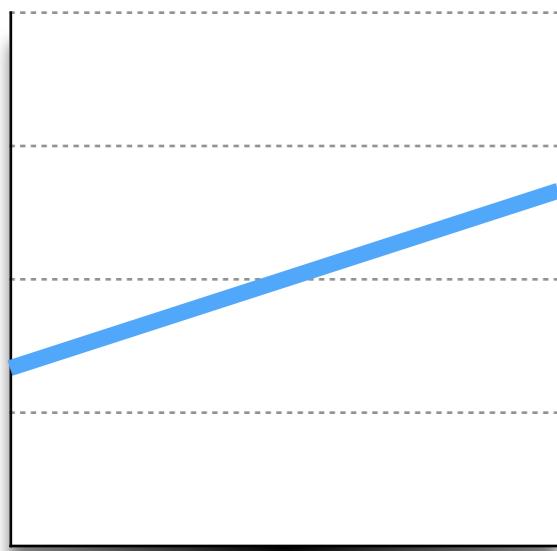


robust to noise

# Conclusion



laser source &  
photo diodes



nr. of measurements  
scale linear in size



conceptually  
simple

A photograph of handwritten mathematical equations on a blue chalkboard. The equations involve variables like  $\gamma_i^l$ ,  $\alpha$ ,  $\beta$ ,  $b_i$ , and  $c_i$ . One equation shows a term  $(4\alpha_i - 2\beta) \gamma_i^l = (2\alpha_i - \alpha) \gamma_{i+1}^l$ .

rigorous recovery  
guarantees

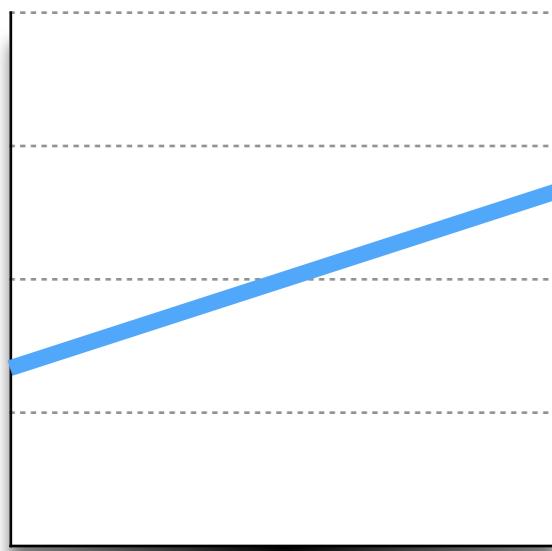


robust to noise

# Conclusion



laser source &  
photo diodes



nr. of measurements  
scale linear in size



conceptually  
simple

A photograph of handwritten mathematical equations on a blue surface. The equations involve variables like  $\gamma_i^l$ ,  $\alpha$ ,  $\beta$ ,  $b_i$ , and  $c_i$ . One equation shows a subtraction of terms involving  $\alpha$  and  $\beta$ , and another shows a sum of terms involving  $b_i$  and  $c_i$ .

rigorous recovery  
guarantees



robust to noise

# Conclusion



laser source &  
photo diodes



nr. of measurements  
scale linear in size



conceptually  
simple

A photograph of a chalkboard with handwritten mathematical equations. The equations involve variables like  $\gamma_i^l$ ,  $\alpha$ ,  $\beta$ ,  $b_i$ , and  $c_i$ . The equations appear to be related to a system of linear equations or a similar mathematical model.

rigorous recovery  
guarantees



robust to noise

# Conclusion



laser source &  
photo diodes



nr. of measurements  
scale linear in size



conceptually  
simple



rigorous recovery  
guarantees



robust to noise

# Conclusion



laser source &  
photo diodes



nr. of measurements  
scale linear in size



conceptually  
simple



rigorous recovery  
guarantees



robust to noise

# Outlook & Open Questions

- Experimental Implementation
- Comparison to established protocols
- Which program works best for the particular experimental setting?
- How scalable is the PhaseLift approach?

# Thank you!

Richard Kueng



David Gross





$$\|A\|_p := \left( \sum_k \sigma_k(A)^p \right)^{\frac{1}{p}}$$

