Towards Generalized Fiducial Inference for Finite Mixtures

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Outline of Topics

The Fiducial Paradigm

Gaussian Mixture Models (GMMs)

Sketch of Topics Under Consideration



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Some History

- ▶ Origins of fiducial inference can be traced back to Fisher (1922), who introduced a fiducial distribution for a parameter in place of the Bayesian posterior for interval estimation of said parameter
- Single-parameter families of distributions: Fiducial intervals coincide with classical confidence intervals
- ▶ Multi-parameter families of distributions: Fiducial approach yields confidence sets with frequentist coverage probabilities close to the nominal level, but are not exact in the repeated sampling frequentist sense
- Mid-20th century: Prominent statisticians penned many critical discussions about the fiducial argument
- Late-20th century: Infrequent publications on the topic, with it seemingly becoming a topic of mere historical interest
- ► Early-21st century: A revival of interest in modern modifications of fiducial inference
- ► See Hannig et al. (2016) for a contemporary review on the topic, including key references traversing the timeline stated above



Generalized Fiducial Inference (Hannig, 2009)

- ► **Generalized fiducial inference (GFI)** aims to define a distribution for parameters of interest that contains all the information from data
 - ► The paradigm carefully uses an inverse of a deterministic data-generating equation without the use of Bayes' theorem
- ► Inference for the parameters can therefore be made from this (generalized) fiducial distribution, which can further be interpreted as a posterior distribution without assuming a prior distribution (Efron, 1998)
- ► The random variable having a derived fiducial distribution is called a **generalized fiducial quantity (GFQ)**
- ► The tenet of the GFI framework is to switch the role of the parameters and the data
- ▶ Unfortunately, there is typically no unique way to define a fiducial distribution



Brief Mathematical Setup

- Suppose the data **X** are generated through the structural equation $\mathbf{X} = G(\boldsymbol{\xi}, U)$
 - ▶ $\xi \in \Xi$ is a vector of parameters
 - ightharpoonup U is some random variable with a known distribution independent of ξ
 - ▶ The structural equation can be regarded as a data generation process where the noise process U=u and the signal $\boldsymbol{\xi}$ will produce observed data $\mathbf{X}=\mathbf{x}$
- lacktriangle Hence, the distribution of f X can be determined via the structural equation given a fixed parameter $m \xi$ and the distribution U
- After the data **X** are observed, switch the position of the data and parameters by solving the structural equation (conditioned on the existence of the solution)
- ▶ Thus, we get $\boldsymbol{\xi} = Q(\mathbf{X}, U)$, where $Q(\mathbf{X}, U)$ is the inverse function used to define the following generalized fiducial distribution on $\boldsymbol{\Xi}$: $V(Q(\mathbf{x}, U^*))|\{Q(\mathbf{x}, U^*) \neq \emptyset\}$, where U^* is an independent copy of U
- ightharpoonup A random element generated from this fiducial distribution, say $\mathcal{R}_{\varepsilon}(\mathbf{x})$, is a GFQ



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Model and Notation

- ► Hannig (2009) considered the generalized fiducial distribution for the parameters of a two-component GMM
- Let X_1, \ldots, X_n be independent random variables drawn from a classic five-parameter, two-component GMM:

$$(1-\pi)\mathcal{N}(\mu_1,\sigma_1^2) + \pi\mathcal{N}(\mu_2,\sigma_2^2)$$

- ► Assumptions:
 - $\mu_1 < \mu_2$ (identifiability constraint)
 - ▶ We observe at least two data points from each distribution
- ▶ Goal: Find the generalized fiducial distribution of $\boldsymbol{\xi} = (\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \pi)^T$



Structural Equations

 \blacktriangleright We can write a set of structural equations for X_1, \ldots, X_n as

$$X_i = (\mu_1 + \sigma_1 Z_i) \operatorname{I}_{\{(0,\pi)\}}(U_i) + (\mu_2 + \sigma_2 Z_i) \operatorname{I}_{\{(\pi,1)\}}(U_i), \quad i = 1, \dots, n,$$

where $Z_i \stackrel{iid}{\sim} \mathcal{N}(0,1)$ and $U_i \stackrel{iid}{\sim} \mathcal{U}(0,1)$

- \blacktriangleright When finding the inverse (set-valued) function Q, this inversion will be stratified based on the possible assignment of the observed x_i to one of the two components
- ▶ The Q function, which is omitted for brevity (see p. 528 of Hannig (2009)), is an extension to the framework for finding the generalized fiducial distribution of (μ, σ^2) in the $\mathcal{N}(\mu, \sigma^2)$ setting
- ▶ The sums in the generalized fiducial distribution have a total of $2^n 2 2n n(n-1)$ terms, so we are unable to get a closed-form generalized fiducial density
- ► Turn to a Metropolis-Hastings algorithm to simulate observations from the derived generalized fiducial distribution to perform inference



k-Component GMMs

Now let X_1, \ldots, X_n be independent random variables drawn from a k-component (k > 2) GMM:

$$X_i \sim \mathcal{N}(\mu_j, \sigma_j^2)$$
 with probability $P\{W_i = j\} = \pi_j$,

where the W_i is a membership variable

- ► Assumptions:
 - $\blacktriangleright \mu_1 < \mu_2 < \cdots < \mu_k$ (identifiability constraint)
 - ► We observe at least two data points from each distribution
- ▶ The number of occurrences of the outcome j among W_1, \ldots, W_n is denoted by n_j ; i.e., $\sum_{i=1}^n \mathbb{I}\{W_i=j\}=n_j$, such that $\sum_{j=1}^k n_j=n$
- ▶ We can apply the recipe used in Hannig (2009) for the k=2 setting to the above k>2 setting



GFQ for π_j

lacktriangle The $W_i,\ i=1,\ldots,n$, can be treated as outcomes from the following data-generating equation:

$$W_i = \sum_{j=0}^k \mathbf{I} \left\{ U_i \in \left[\sum_{l=0}^j \pi_l, 1 \right] \right\},\,$$

where $U_i \stackrel{iid}{\sim} \mathcal{U}(0,1)$ and $\pi_0 = 0$

▶ A GFQ for π_j can be expressed as

$$\mathcal{R}_{\pi_j} = \begin{cases} U_{(r_j)} + D_j [U_{(r_j+1)} - U_{(r_j)}] & j = 1; \\ U_{(r_j)} + D_j [U_{(r_j+1)} - U_{(r_j)}] - \mathcal{R}_{\pi_{j-1}} & j = 2, \dots, k-1; \\ 1 - \sum_{l=1}^{k-1} \mathcal{R}_{\pi_l} & j = k, \end{cases}$$

where $U_{(1)}, \ldots, U_{(n)}$ are the order statistics of U_1, \ldots, U_n , $r_j = \sum_{l=1}^j n_l$, and $D_j \stackrel{iid}{\sim} \mathcal{U}(0,1)$

▶ In the formula for \mathcal{R}_{π_j} , we set $U_{(0)} = 0$ and $U_{(n+1)} = 1$



GFQs for μ_j and σ_j^2

- \blacktriangleright We extend the set of structural equations for X_1, \ldots, X_n used in the two-component setting to the k-component setting
- ▶ A GFQ for σ_j^2 can be expressed as

$$\mathcal{R}_{\sigma_j^2} = \frac{(n_j - 1)s_j^2}{V_j},$$

where s_j^2 denotes the sample variance and $V_j \sim \chi_{n_j-1}^2$

▶ A GFQ for μ_j can be expressed as

$$\mathcal{R}_{\mu_j} = \bar{x}_j - Z_j \sqrt{\frac{\mathcal{R}_{\sigma_j^2}}{n_j}},$$

where $ar{x}_j$ denotes the sample mean and $Z_j \sim \mathcal{N}(0,1)$



Sketch of MCMC Sampler

- Initialize the sampler by determining an arbitrary assignment to the k components, say, $\mathbf{w}^{(0)}=(w_1^{(0)},\dots,w_n^{(0)})^{\mathrm{T}}$
- @ Generate a proposal configuration by taking the previous assignment, randomly choose one data point, and switch it to another component (accept/reject based on usual Metropolis-Hastings rule)
- **3** Based on the current assignment, $\mathbf{w}^{(t)}$, generate realizations of \mathcal{R}_{μ_j} , $\mathcal{R}_{\sigma_j^2}$, and \mathcal{R}_{π_j} , $j=1,\ldots,k$
- The stationary distribution of the assignment-valued Markov chain is the generalized fiducial distribution of the assignment



Using the Results

- ► Since a generalized fiducial distribution provides us with a distribution on the parameter space, its use is similar to the practical use of a Bayesian posterior
- After a burn-in period, we can take, for example, the mean to get a point estimator of the full parameter vector $\boldsymbol{\xi} = (\mu_1, \dots, \mu_k, \sigma_1^2, \dots, \sigma_k^2, \pi_1, \dots, \pi_{k-1})^T$
 - ► Posterior membership probabilities can then be calculated for doing model-based clustering
- ▶ We can find $C(\mathbf{x})$ with fiducial probability $P\left\{\mathcal{R}_{\boldsymbol{\xi}}(\mathbf{x}) \in C(\mathbf{x})\right\} = 1 \alpha$ to get approximate $100 \times (1 \alpha)\%$ fiducial confidence sets
 - ► These confidence sets, though not exact, often have very good coverages and expected length properties in small sample simulations, but can be exact asymptotically



Example: Simulated Data

- ightharpoonup k = 3 components
- $\xi = (\mu_1, \mu_2, \mu_3, \sigma_1^2, \sigma_2^2, \sigma_3^2, \pi_1, \pi_2)^{\mathrm{T}} = (0, 6, 12, 1, 1, 1, 0.50, 0.25)^{\mathrm{T}}$
- ightharpoonup n = 100
- lacktriangle Generated M=5000 fiducial samples after dropping 5000 for burn-in
- ► Computed point estimates based on the fiducial approach and compared with the maximum likelihood solutions using EM
- ► Code is available at my GitHub repo: https://github.com/dsy109/ Supplemental/blob/main/WGMBC/MixNormFid.R



Example: Simulated Data (ctd.)

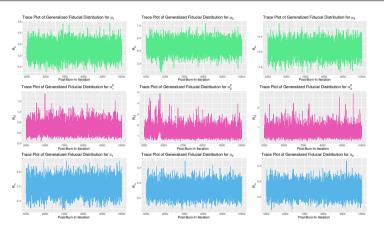


Figure 1: Trace plots of the generalized fiducial distributions



Example: Simulated Data (ctd.)

Parameter	Fiducial	EM
μ_1	0.0980	0.1004
μ_2	6.1604	6.1657
μ_3	12.0699	12.0693
σ_1^2	0.7236	0.6774
σ_2^2	1.3740	1.1749
σ_3^2	0.7533	0.6626
π_1	0.4998	0.5000
π_2	0.2530	0.2500

Table 1: Fiducial and EM estimates of ξ for the simulated data



Example: 1872 Hidalgo Stamp Data

- Analyzed the famous 1872 Hidalgo stamp data (n=485) assuming k=4 components (Izenman & Sommer, 1988)
- ightharpoonup Generated M=50000 fiducial samples after dropping 50000 for burn-in
- ► Trace plots indicate convergence

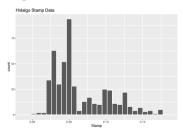


Figure 2: Histogram of Hidalgo stamp data



Example: 1872 Hidalgo Stamp Data (ctd.)

Parameter	Fiducial	EM
μ_1	0.0729	0.0712
μ_2	0.0790	0.0786
μ_3	0.0935	0.0980
μ_4	0.1021	0.1034
σ_1	0.0028	0.0013
σ_2	0.0031	0.0024
σ_3	0.0143	0.0151
σ_4	0.0131	0.0054
π_1	0.0789	0.1926
π_2	0.4620	0.3722
π_3	0.2278	0.3613

Table 2: Fiducial and EM estimates of ξ for the Hidalgo stamp data



Example: 1872 Hidalgo Stamp Data (ctd.)

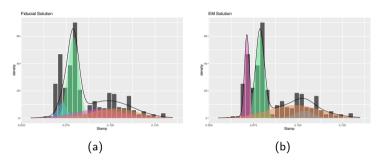


Figure 3: (a) Fiducial fits and (b) EM fits for GMM with k=4 components



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Model Selection

- lacktriangle Consider a finite collection of models ${\mathcal M}$
- ▶ Data-generating equation is $\mathbf{X} = G(M, \boldsymbol{\xi}_M, U), M \in \mathcal{M}, \boldsymbol{\xi}_M \in \boldsymbol{\Xi}_M$, where M is the model considered and $\boldsymbol{\xi}_M$ are the parameters associated with model M
- ► Similar to maximum likelihood estimation, GFI tends to favor models with more parameters over ones with fewer parameters
- ► Therefore, an outside penalty accounting for our preference toward parsimony (e.g., in terms of number of components) needs to be incorporated in the model
- ► Hannig and Lee (2009) developed model selection in the GFI paradigm for wavelet regression and Lai et al. (2015) did it for ultra-high dimensional regression
- ► A fiducial factor is available, akin to a Bayes factor
- ► An outside penalty tailored towards mixture distributions could be derived, and, perhaps, some notion like a BIC difference (Raftery, 1995) can give us an indication of strength of a particular model



Determining the Number of Components

- A generalized fiducial model selection criterion could be used to determine the number of components, k
- We might include k in the parameter vector and find that generalized fiducial distribution
- Big challenge with this is that we are looking at deriving generalized fiducial quantities for parameters of varying dimensions
- ▶ A possibility is to use an extension of a Bernoulli factory (Latuszyński et al., 2011), which uses martingale approaches to simulate a Bernoulli variable with success probability f(p) from independent Bernoulli variables with success probability p
- ▶ Here, $p \in \mathcal{P} \subseteq [0,1]$ is unknown, but $f : \mathcal{P} \to [0,1]$ is known
- ▶ A Bernoulli factory could be used in an algorithm where f(p) is the probability that a component is "born" or "dies", or we might consider developing something along the lines of a "multinoulli factory," where we simulate a multinoulli variable with success probability $f(\mathbf{p})$ from independent multinoulli variables with success probability \mathbf{p}



Computing

- ▶ Quick search of all R packages on CRAN yields only four packages with "fiducial" in the package name, each of which is focused on a specific class of models (e.g., logistic regression or normal linear mixed models), although other packages have some limited fiducial capabilities
- ► A realistic goal is to develop flexible, fiducial-based mixture functions for which we could employ S3 methods
 - ► A pipe dream is to develop a comprehensive fiducial modeling architecture akin to Stan
- Generating observations from generalized fiducial distributions for conducting GFI is often computationally intensive, so efficiency in computational routines will be important



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