# FRA 331: Basic Control Theory

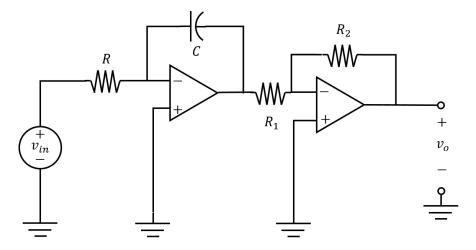
Homework Assignment 1: Modelling

## Written

#### 1: Integrator Circuit

The following circuit is an integrator. Using Krichoff's Voltage and Current laws, derive the expression of  $v_o$  in term of t, R,  $R_1$ ,  $R_2$ , C, and  $v_i n$ .

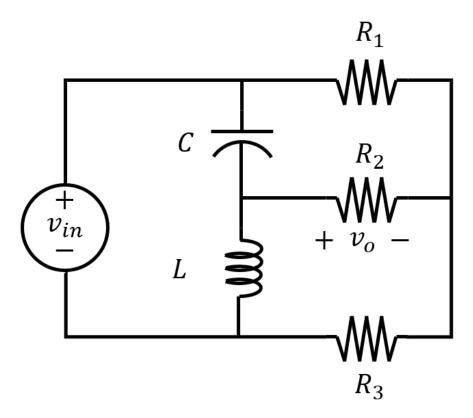
In order to receive full credits, determine the condition of  $R_1$  and  $R_2$  such that the circuit is a direct integrator without any gain.



Problem 1

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### 2: second-order circuit



Problem 2

Using Kirchoff's Voltage and Current laws, show that the dynamics of the circuit is the following. You do not need to box the answer for this problem.

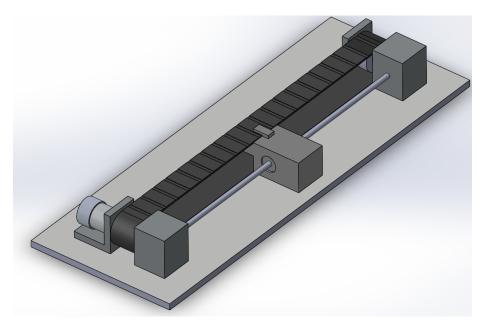
$$v_{in} = v_c + L \frac{di_L}{dt}$$

$$C \frac{dv_c}{dt} = i_L + \left(\frac{1}{R_1 R_2 + R_1 R_3 + R_2 R_3}\right) \left(R_1 v_{in} - (R_1 + R_3) v_c\right)$$

$$v_o = \left(\frac{R_2}{R_1 R_2 + R_1 R_3 + R_2 R_3}\right) \left(R_1 v_{in} - (R_1 + R_3) v_c\right)$$

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#### 3: Belt-Driven Mechanism



Problem 3

The given belt-driven mechanism consists of a brushless DC motor with the following specification.

- R: internal resistance  $[\Omega]$
- L: internal inductance [H]
- $K_m$  : motor-torque constant  $[\frac{N \cdot m}{A}]$
- $K_b$  : internal inductance  $[\frac{V\cdots}{rad}]$
- r: gearbox ratio []
- $J_m$  : total motor inertia  $[kg \cdot m^2]$
- $B_m$  : total motor mechanical damping  $[\frac{kg \cdot m^2}{s}]$

Given an input voltage of  $v_{in}$  and external load the output shaft  $\tau_l$ , the current of the motor  $i_a$  and the angular displacement of output shaft  $\theta_s$  change due to its dynamics.

The belt mechanism can be modeled as a mass-damper-spring system with a mass of m, mechanical damping of b, and a stiffness of k. The radius of the pulley is c. Let the linear displacement z of the belt mechanism.

Derive the equation which describes the dynamics of the entire system, where  $v_{in}$  is the input. DO NOT LEAVE THE ANSWER IN TERM OF  $\theta$  (Note: the transmission formula for belt is  $\tau_l=cf$ , where f is the transmitted force by the belt. And  $z=c\theta$ , where  $\theta$  is the angular displacement of the output shaft at the pulley)

