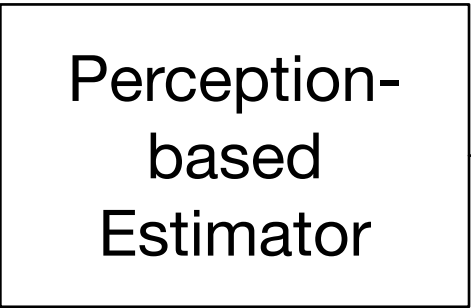
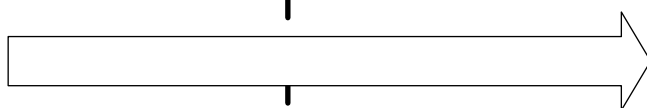
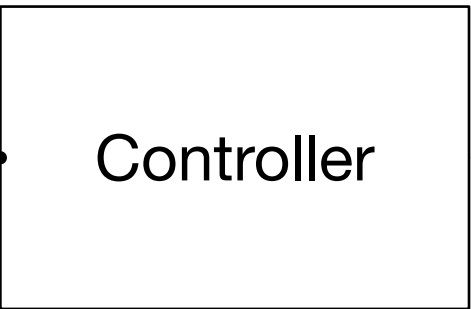


Measurement from Sensors

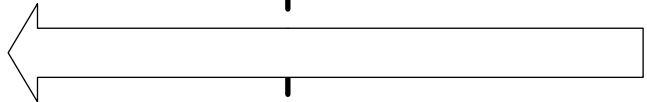


(Delay, Error)
Contract



State Estimate
(e.g. Robot Position)

Control Action
to Physical System
(e.g. Motor Thrust)



Physical System
(e.g. Autonomous Robot)

Estimation and Control