

Negotiation

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The setting

What is a good
outcome?

Protocols

- ▶ Lecture I: **Bilateral** Negotiation
- ▶ Lecture II (tomorrow am): **Multilateral** Negotiation
- ▶ Lecture III (tomorrow pm): **Argument-based** Negotiation

Negotiation is a huge topic, it has been studied in many fields for many years.

Raiffa. *The art and science of negotiation*. 1982.

These are some general AI/MAS books, notes, with nice chapters on negotiation:

Wooldridge. *An Introduction to Multiagent Systems*. MIT Press-2004.

Vidal. *Fundamentals of Multiagent Systems*. 2007.

And these are two classic books on the subject:

Rosenschein & Zlotkin. *Rules of Encounter: Designing Conventions for Automated Negotiation among Agents*. 1994.

Kraus. *Strategic Negotiation in Multiagent Environments*. 2001.

It is also common to find the following distinction:

- ▶ **Game-theoretic**—use of mathematical tools, as developed in game-theory, to analyze strategical interaction. Provable properties, strong assumptions.
- ▶ **Heuristic-based**—design of good strategies in practice, in specific domains of negotiation. More realistic assumptions, more difficult to guarantee properties.
- ▶ **Argument-based**—allows the exchange of arguments during negotiation.

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We first describe the **outcome set** \mathcal{O} . This set may have different characteristics.

Compare the following scenario:

1. we must decide on the next location for the summer school.

$$o_1 = \langle \text{bali} \rangle$$

2. we must divide a chocolate-vanilla cake
division of a continuous resource.

$$o_1 = \langle 1/3, 2/3 \rangle$$

3. there are 4 candies, we must decide on a complete allocation of resources to children.
allocation of indivisible resources.

$$o_1 = \langle \{c_1, c_4\}, \{c_2, c_3\} \rangle$$

The outcome set may be very large, even in the discrete case:

- ▶ allocations of indivisible resources
 g goods, so $|\mathcal{O}| = |\mathcal{A}|^g$ outcomes
- ▶ choice in a multi-issue domain
 p issues, with D_i the domain of the issue i , so $|\mathcal{O}| = \prod_i |D_i|$

Example: Choosing the next holiday package:

- ▶ $D_d = \{1\text{week}, 2\text{weeks}\}$
- ▶ $D_c = \{\text{bali}, \text{lisboa}, \text{moscow}, \text{dakar}\}$
- ▶ $D_h = \{\text{pension}, \text{hotel1}, \text{hotel2}, \text{hotel3}, \text{hotel4}\}$
- ▶ $D_t = \{\text{plane}, \text{bike}, \text{car}\}$

This yields $2 \times 4 \times 5 \times 3 = 120$ outcomes.

Next we have discuss how agents express their preferences.

A **preference structure** represents an agent's preference over the set of outcomes \mathcal{O} . There are different types of preference structures:

Roughly speaking, preferences can be **ordinal** or **cardinal**.

- an **ordinal** preference structure is a binary relation over the outcomes \mathcal{O} , which is reflexive, transitive (and often complete).

$$o_1 \succeq o_2$$

" o_1 is at least as good as o_2 "

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- ▶ a **cardinal** preference structure is expressed as a valuation function

$$v : \mathcal{O} \mapsto Val$$

where Val can be a totally ordered scale of **qualitative** values ("very good", "good", ...), or some **quantitative** values.

Very often quantitative values are used. But beware of the exact interpretation of this “value”.

Following (Luce and Raiffa, 1957), make sure to distinguish:

1. values are in **utility** terms, no interpersonal comparison of utility are permitted, and no side payments are allowed
2. values are in **utility** terms, interpersonal comparison is meaningful, and no side payment are allowed
3. values are in **monetary** terms, utility is linear in money, interpersonal comparisons are meaningful, and monetary side payments are allowed.

From now, we denote by $u_i(o)$ the utility of agent i for the outcome o .

Luce & Raiffa. *Games and Decisions*. 1957.

In the context where agents seek to agree on an allocation of indivisible resources (or tasks), the following distinction is useful:

- ▶ **task-oriented domains**—the utility function is common to all agents (and commonly sub-additive), and agents are only concerned with the tasks its gets
- ▶ **state-oriented domains**—the utility function is common to all agents, but agents can value the state in general (not only its bundle of resources)
- ▶ **worth-oriented domains**—the utility function may be different for the different agents

Rosenschein & Zlotkin. *Rules of Encounter*. 1994.

Negotiation Domain: Convex Outcome Sets

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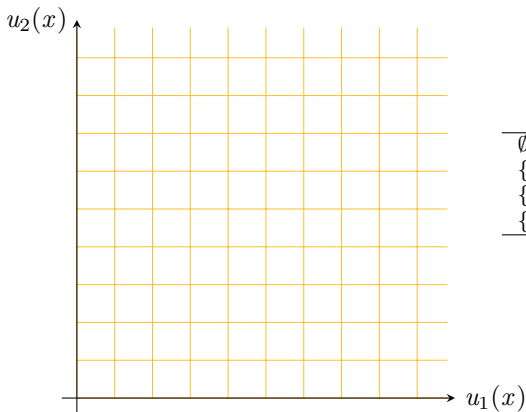
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	u_1	u_2
\emptyset	0	0
$\{r_1\}$	1	3
$\{r_2\}$	3	3
$\{r_1, r_2\}$	7	8

What are the outcomes? Can you place them on this figure?

Negotiation Domain: Convex Outcome Sets

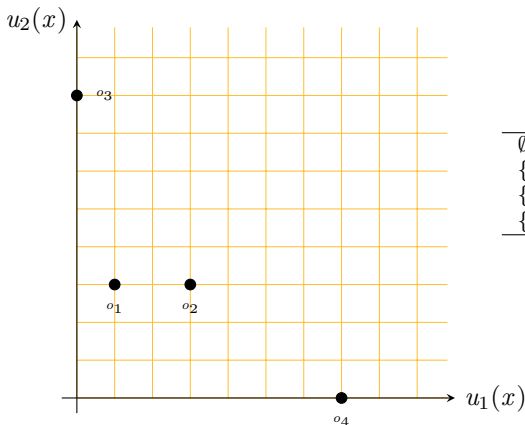
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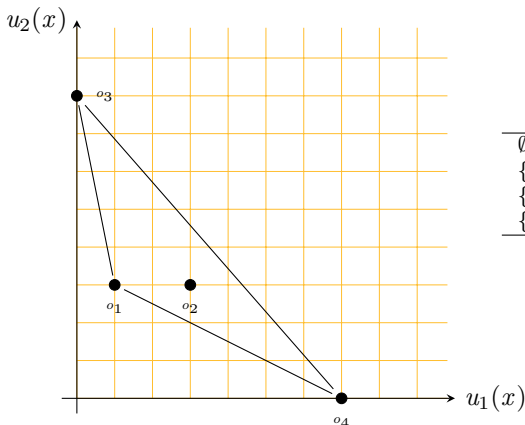
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Randomization between possible outcomes defines a new outcome. For instance, any point on the segment $o_3 - o_4$ is a randomized outcome of the form $\langle p \cdot u_1 + (1 - p) \cdot u_1, p \cdot u_2 + (1 - p) \cdot u_2 \rangle$. But then the outcome set becomes a **convex region**.

The following remarks are useful:

1. ordinal preferences do not allow interpersonal comparison
2. ordinal preferences cannot represent intensities, cardinal preferences can
3. ordinal preferences can handle incomparabilities, but cardinal preferences cannot
4. explicit representation of cardinal and ordinal preferences require space complexity of $O(|\mathcal{O}|)$ and $O(|\mathcal{O}|^2)$

In the following, we make some assumptions:

1. preferences of agents are **common knowledge** among all agents (we come back to this later)
2. agents can provide **explicit representation** of their preferences (more **compact** way of representing preferences are possible)

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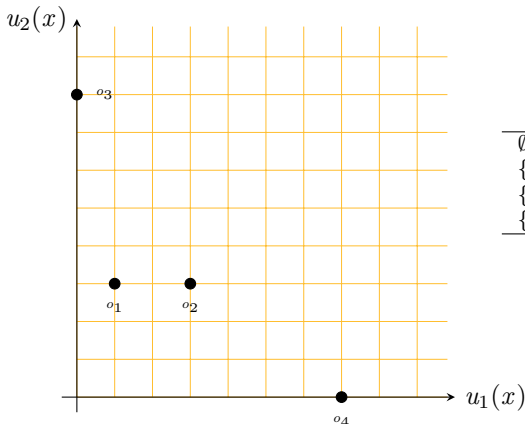
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- ▶ An outcome o_1 **Pareto-dominates** another outcome o_2 if o_1 is at least as good as o_2 for all agents, and strictly better for at least one.
- ▶ An outcome is **Pareto-optimal** if no other outcome dominates it.



	u_1	u_2
\emptyset	0	0
$\{r_1\}$	1	3
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There may be many Pareto-optimal outcomes. Outcomes may also maximize some measure of social welfare:

- ▶ **utilitarian**— maximizes $\sum_i u_i(o)$
- ▶ **egalitarian**— maximizes $\min_i u_i(o)$
- ▶ **Nash product**— maximizes $\prod_i u_i(o)$

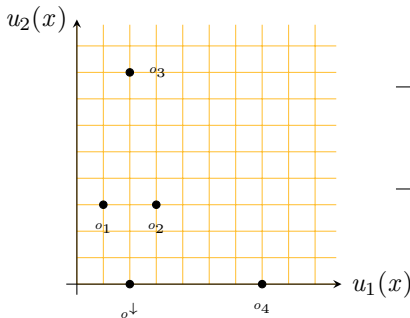
Example:

	u_1	u_2
\emptyset	0	0
$\{r_1\}$	1	3
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- ▶ Which outcome maximizes the utilitarian social welfare, the egalitarian social welfare, and the Nash product?
- ▶ Which of these notions imply Pareto-optimality?

- We denote by o^\downarrow the **disagreement** (or conflict) point. It indicates the utility that each player gets if the negotiation fails. This needs not be the same for both agents.
- **Individual rationality**: agents should be better off engaging in the negotiation, that is, for all i , the outcome of the negotiation o must be such that:

$$u_i(o) \geq u_i(o^\downarrow)$$



	u_1	u_2
\emptyset	2	0
$\{r_1\}$	1	3
$\{r_2\}$	3	3
$\{r_1, r_2\}$	7	8

IR plus **Pareto** brings the **negotiation set** (Luce and Raiffa, 1957). However, this set contains many possible solutions. Can we restrict further the set of intuitively “fair” outcomes?

Nash (1950) takes an axiomatic approach, and under some assumptions (in particular that the outcome set is convex), shows that the unique solution to a bargaining problem must be the Nash product, provided we accept some “intuitive” axioms.

A **bargaining problem** is described as a pair $\langle \mathcal{O}, o^\downarrow \rangle$.
We write $o^* = NBS(\langle \mathcal{O}, o^\downarrow \rangle)$ for the outcome selected.

Basic axioms:

- ▶ **Pareto** the solution should be on the Pareto-frontier
- ▶ **IR** the outcome should be individually rational

Additional axioms:

- ▶ **Symmetry**
- ▶ **Linear Invariance**
- ▶ **Independance of Irrelevant Alternatives**

We discuss them in more details now.

Intuitively, **symmetry** says that agents should be treated the same when their initial situation is equivalent. So,

1. if $u_1(o^\downarrow) = u_2(o^\downarrow)$, and
2. if $\forall o \in \mathcal{O}: \exists o' \in \mathcal{O}$ such that $u_1(o) = u_2(o')$ and $u_2(o) = u_1(o')$

then the outcome o^* must be such that $u_1(o^*) = u_2(o^*)$

Intuitively, linear invariance says two things:

- ▶ **independence of scale**—the outcome does not depend on the scale used by the agent to represent its utility.
Suppose agent 1 uses a scale $[0,10]$ to represent its utility, while agent 2 uses a scale $[0,100]$. The fact that agent 1 enjoys utility 9 and agent 2 utility 50 does not mean that agent 2 is more “happy”.
- ▶ **independence of zero**—a translation of the scale of utilities does not affect the outcome.
Suppose agent 1 uses a scale $[0,9]$, while agent 2 uses a scale $[1,10]$. The scale of agent 2 can be translated to $[0,9]$ without any consequence on the outcome.

Intuitively, **Independence of Irrelevant Alternatives** (IIA) says that if the outcome o^* of the negotiation lies in some sub-region of the outcome set, then the negotiation should still select o^* if we restrict the outcome set to this sub-region.

So, removing “irrelevant outcomes” should not affect the result.

More precisely, for any $O \subseteq \mathcal{O}$,
if $NBS(\langle \mathcal{O}, o^\downarrow \rangle) = o^* \in O$ then $NBS(\langle O, o^\downarrow \rangle) = o^*$.

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Which axioms do you find controversial?

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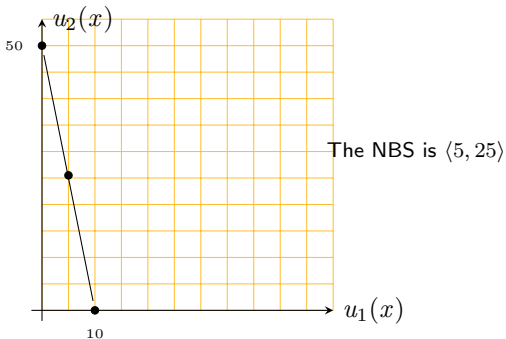
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Which axioms do you find controversial?

Interestingly, we will see that discussing these axioms sometimes unveils interesting links to argumentation...

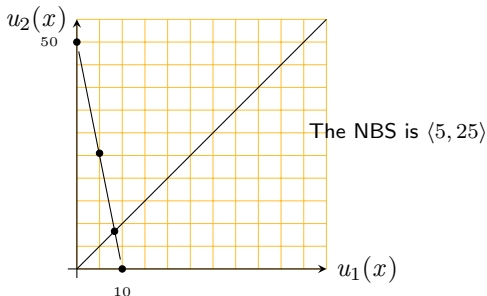
We follow the exposition of (Luce and Raiffa).
Consider the following bargaining problem.



Agent 1 can put forward the following argument:

"The solution should be $o^* = \langle 8.33, 8.33 \rangle$ " because

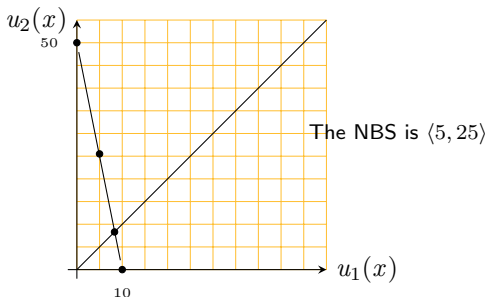
1. if you go for $\langle 5, 25 \rangle$, it will simply refuse it (threat)
(I will only lose 5, you will lose 25...)
2. the reference point should be $\langle 0, 0 \rangle$, so we should gain the same.



Agent 2 can then put forward the following argument:

“No, we must chose $\langle 8.33, 8.33 \rangle$ ”, because

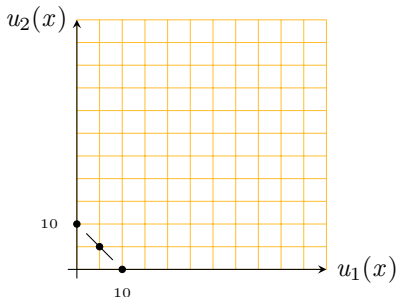
If we chose $o^* = \langle 8.33, 8.33 \rangle$ instead of $\langle 5, 25 \rangle$, I give up more than 16, while you only gain a bit more than 3...”



Agent 1 may then say:

“Come on. Suppose there is this other game. I prefer to play in our game” because I expect to get more from our game. I am fine to let you have more in our game than in this one, as long as I get something in return...

“Such an argument implicitly assumes an interpersonal comparison of utility. Nash feels that such comparisons are not meaningful and that such an argument cannot be made sound” (Luce & Raiffa)



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A **protocol** specifies the rules of interaction (who can say what?).
For instance, we may allow **simultaneous** moves, or **sequential** moves.

A **strategy** specifies the behavior of the agent (which move to select among all the legal ones?)

We usually require the following properties of protocols+strategies:

- ▶ **termination**—the negotiation will terminate
- ▶ **guaranteed agreement**—the negotiation will end on an agreement (not on the conflict point)
- ▶ **efficiency**—upon termination, the negotiation provides an efficient (eg. Pareto-optimal) outcome
- ▶ **equilibrium**—captures a notion of stability. In particular:
 - **symmetric Nash equilibrium**: assuming agent 1 uses strategy s , agent 2 cannot be better off using a different strategy than s .
 - **subgame perfect equilibrium**: in the case of sequential protocol.

The protocol proceeds in rounds where agents make **simultaneous** offers. Let o_i^t and o_j^t be the offers made by agent i and agent j , at round t . In the initial round, agents make the offer they like, then in the following rounds, each agent must either:

- ▶ **stick** to their previous offer, or
- ▶ make a **concession** (an offer which gives the other more utility)

An **agreement** is found when, for at least an agent, the offer made by the other agent is at least as good as its own current offer. That is:

$$u_i(o_j^t) \geq u_i(o_i^t) \text{ or } u_j(o_i^t) \geq u_j(o_j^t)$$

(Flip a coin if both agents agree).

A **disagreement** occurs when both agents stick to their current offer.

How should agents play this game? Zeuthen proposes the following:

The willingness to risk conflict (denoted Z_i^t), intuitively captures “how bad” would be a conflict for agent i at round t . It is given by the following formula (assuming $(0, 0)$ for the conflict):

$$Z_i^t = \begin{cases} 1 & \text{if } u_i(o_i^t) = 0 \\ \frac{u_i(o_i^t) - u_i(o_j^t)}{u_i(o_i^t)} & \text{otherwise} \end{cases}$$

From this, the Zeuthen strategy is specified as follows, for agent i :

- compute your willingness to risk conflict Z_i^t and that of your partner
- the one with the smallest value should concede
- make the **minimal concession** making Z_j^t become smaller than Z_i^t

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[Too lazy to do a nice picture here]

Monotonic Concession Protocol: Example

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round	offer a_1	offer a_2	$u_1(o_{a_1}^t), u_1(o_{a_2}^t)$	$u_2(o_{a_1}^t), u_2(o_{a_2}^t)$	Z_1	Z_2
1	$\langle \emptyset, \{a, b, c\} \rangle$	$\langle \{a, b, c\}, \emptyset \rangle$	9,0	0,9	1	1
2	$\langle \{a\}, \{b, c\} \rangle$	$\langle \{a, c\}, \{b\} \rangle$	7,4	3,7	$\frac{3}{7}$	$\frac{4}{7}$
3	$\langle \{a, c\}, \{b\} \rangle$	$\langle \{a, c\}, \{b\} \rangle$	4,4	7,7	stop	stop

The properties of the MCP + Zeuthen strategy are as follows:

- ▶ **termination** is guaranteed, as well as **agreement upon termination** (there is always at least an agent willing to concede)
- ▶ because the offers considered are in the Negotiation Set to start with, Pareto-optimality is obvious

Now a stronger result:

- ▶ The outcome **maximizes the Nash product**.

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Explanation: The problem comes from the last step of the protocol. If both agents have the same Z , both are willing to concede, and so one agent can exploit this and deviate to get a better outcome.

Some final remarks on MCP.

- ▶ it is possible to extend the Zeuthen strategy (by allowing a mixed strategy in the last step) to retrieve stability
- ▶ a more simple one-step protocol is possible!

The one-step protocol is as follows:

- ▶ agents simultaneously make a single offer
- ▶ select the one maximizing the product of utilities

What is the best strategy for an agent given this protocol?

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Given this protocol, the strategy for an agent is to select, among the outcomes maximizing, the one giving him the best utility.

Rosenschein & Zlotkin. *Rules of Encounter*. 1993.

We now discuss a **sequential** protocol.

- ▶ an agent starts by making an offer. In the next round, the other agent can either **accept** or make a **counter-offer**.
- ▶ the protocol integrates a **discount factor** λ_i to capture the fact that negotiation is time constrained. An offer accepted at round t by agent i brings utility $u_i(o^t) \times (\lambda_i)^t$.

The sequential nature of this protocol allows backward induction solving.

Rubinstein. *Perfect equilibrium in a bargaining model*. Econometrica-1982.

Set $\lambda = 1$ for agents (they are patient).

- suppose the number of rounds **is known in advance**. But then the last agent to make an offer gets all the “power”. What is his best strategy?

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Always refuse the offers of the other, then make an offer $\langle 1 - \epsilon, \epsilon \rangle$ in the last round (this last step is actually an ultimatum game: more on this later)

- suppose the number of rounds **is not known in advance**
Suppose a_1 uses this strategy: Always propose $(1 - \epsilon, \epsilon)$, and always refuse the offer of the other. What is a_2 best response to this?

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- suppose the number of rounds **is not known in advance**
Suppose a_1 uses this strategy: Always propose $\langle 1 - \epsilon, \epsilon \rangle$, and always refuse the offer of the other. What is a_2 best response to this? Always refusing yields the conflict outcome. So a_2 must accept at some point, no reason to postpone: accept in the first round.
Immediate acceptance of any offer is a Nash equilibrium, given that a_2 knows a_1 's strategy.

Alternating Offers: Example

Take $\mathcal{O} = \{o_2, o_3, o_6\}$, with $o_2 = \langle 7, 3 \rangle$, $o_3 = \langle 5, 4 \rangle$, and $o_6 = \langle 4, 7 \rangle$.

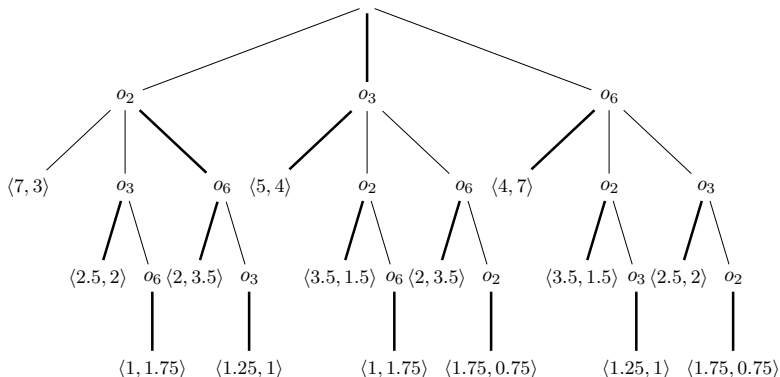


Figure: Backward Induction with the alternating-offer protocol

Back to the **ultimatum game**.

Remember: One agent proposes an offer (say a division of a pie), the offer may either accept or reject. If it accepts the offer is chosen outcome, otherwise the conflict outcome.

What do you a human agent will propose in real life?

Back to the **ultimatum game**.

Remember: One agent proposes an offer (say a division of a pie), the offer may either accept or reject. If it accepts the offer is chosen outcome, otherwise the conflict outcome.

What do you a human agent will propose in real life?

- ▶ many studies in economics
- ▶ usually offers more around a 60/40 division
- ▶ importance of social context, reputation, etc.

Now consider the following game, known as the **centipede** game.

There are 100 candies to share, and two agents. The protocol for negotiation is as follows. In each round:

- ▶ player i can either take 1 or 2 candies
- ▶ if he takes 2 candies, the protocol terminates, and agents keep the candies they have collected so far (the rest is wasted)
- ▶ if he takes 1 candy, the protocol continues, by giving the turn to the other agent, and so on.

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Can you analyze this game?

Often, agents have not an exact knowledge about the preferences of others. It is possible to conceive general **profiles of agents**, specifying high-level behavior.

- ▶ **boulware** agents—very slow concession until we get close to the deadline, then exponential increase
- ▶ **conceder** agents—prone to concede in the first rounds of negotiation and get close to reserve price, then slow increase

But how can we make sure that a move is indeed a concession in the first place?

Faratin et al.. *Negotiation decision functions for autonomous agents*. Robotics and Autonomous Systems-1998.

Consider a multi-issue domain.

Suppose agents' utilities are given as **weighted sums**. Agents give different importance to different criteria.

$$u_i(o) = \sum_c w_i^c u_i^c(o)$$

Note: note necessarily zero-sum, nor negatively correlated utilities.

Faratin et al. distinguish:

- ▶ **response strategies**—concession operate on a single issue
- ▶ **compensation strategies**—concede on a single issue but ask more on other issues (trade-offs), so that the new offer has the same utility for itself, but a higher utility for the other one.

Faratin et al.. *Using similarity criteria to make issue trade-offs in automated negotiations*. AIJ-2002.

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But trying to guess/approximate an agent preference structure based on its negotiation behavior is very challenging!

Idea: seek the offer which is the “closest” from the other agent offer in the preceding move. To do this, compute similarity among offers.

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Example:

$\mathcal{D}_c = \{\text{yellow, violet, magenta, green...}\}$

Choose criteria to assess how similar colors are (eg. warmness, perception,...)

$h_w = \{(\text{yellow}, 0.9), (\text{violet}, 0.1), (\text{magenta}, 0.1), (\text{green}, 0.3), \dots\}$

$h_p = \{(\text{yellow}, 1), (\text{violet}, 0.5), (\text{magenta}, 0.4), (\text{green}, 0.1), \dots\}$

By giving to similarity criteria (eg. 0.7 and 0.3) , we can compute eg.

$$\text{sim}(\text{magenta, green}) =$$

$$0.7 \times (1 - |h_w(\text{magenta}) - h_t(\text{green})|) + 0.3 \times (1 - |h_p(\text{magenta}) - h_t(\text{green})|)$$

But trying to guess/approximate an agent preference structure based on its negotiation behavior is very challenging!

Idea: seek the offer which is the “closest” from the other agent offer in the preceding move. To do this, compute similarity among offers.

Example:

$\mathcal{D}_c = \{\text{yellow, violet, magenta, green...}\}$

Choose criteria to assess how similar colors are (eg. warmth, perception,...)

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- ▶ we can then compute similarity among offers (by summing similarity, taking weights into account)
- ▶ finally the agent seeks among all offers giving her the same utility the one which is most similar to the other agent's previous offer.

In recent years, competitions involving negotiating agents have emerged, allowing to test and compare various strategies on different problems.

- ▶ ANAC Competition: Automated Negotiating Agents Competition
- ▶ TAC: Trading Agent Competition (auctions, etc.)
- ▶ Genius platform (negotiation problems, library of agents' strategies)
<http://mmi.tudelft.nl/negotiation/index.php/Genius>
- ▶ many papers and even books on analysis of the best strategies

Wellmann, Greenwald, & Stone. *Autonomous Bidding Agents: Strategies and Lessons from the TAC competition*. 2007.

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London 2013

The setting

What is a good
outcome?

Protocols

Outline of this morning's lecture.

- ▶ multilateral negotiation with mediator
- ▶ a multilateral protocol for agents with ordinal preferences
- ▶ extension of monotonic concession protocol
- ▶ contract-based multilateral negotiation
- ▶ negotiation on networks

A first possible approach is to use a **mediator**.
The protocol is as follows (K is fixed a priori):

```
for t:=1 to K do  
begin  
  the mediator proposes an offer o ;  
  agents votes on o (accept/refuse);  
  if all agents accept, then current := o;  
end;
```

So the protocol returns the latest unanimously accepted offer.
Essentially, the protocol starts from an offer, and performs Pareto improvements.

- ▶ Is the protocol guaranteed to reach a Pareto-optimal outcome?
- ▶ Is the protocol guaranteed to stop when having reached a Pareto optimal outcome?

Single Text Mediated Agent: Example

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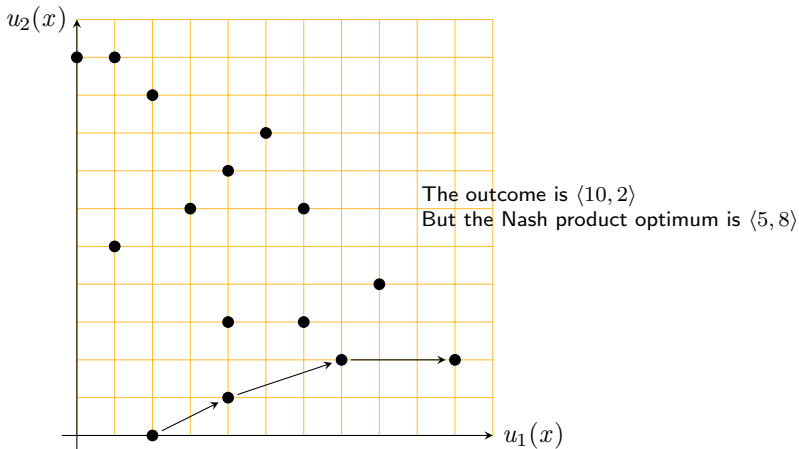
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This protocol may be problematic in some contexts:

- ▶ it requires a mediator (not always possible)
- ▶ requires many rounds of communication from all agents to the mediator
- ▶ it can reach outcomes with very low social welfare

Some extensions have been proposed to try to address some of these limitations:

- ▶ use of meta-heuristic techniques to avoid local optima (eg. simulated annealing)
- ▶ learning of agents preferences to guide the offer proposal from the mediator

Klein et al.. *Protocols for negotiating complex contracts*. IEEE Intelligent Systems.

Now we discuss a purely **ordinal** bargaining procedure.

Each agent ranks her preferred options. Let $top_i(k)$ be the ranking up to k for agent i .

The procedure is as follows:

- while no option is in *all* $top(k)$ rankings, do $k \leftarrow k + 1$

The **compromise set** (CS) is the output of this procedure.

Example:

agent 1: $o_1 \succ o_2 \succ o_3 \succ o_4$

agent 2: $o_2 \succ o_4 \succ o_1 \succ o_3$

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What is the compromise set? $CS = \{o_2\}$, a compromise of level 2.

Brams & Kilgour. *Fallback Bargaining*. Group Decision and Negotiation 2001.

What are the properties of the compromise set?

agent 1: $o_1 \succ o_2 \succ o_3 \succ o_4$

agent 2: $o_1 \succ o_2 \succ o_3 \succ o_4$

agent 3: $o_1 \succ o_4 \succ o_2 \succ o_3$

agent 4: $o_4 \succ o_3 \succ o_2 \succ o_1$

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What is the compromise set?

Does it seem a fair compromise? For most (if not all) voting rule, the chosen option would be a . (a is a Condorcet winner, in particular).

“(....) as unanimous consent is required in a bargaining situation, the choice of b seems (...) appropriate”

- Are the options from CS Pareto-optimal?

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- Are Pareto-optimal options necessarily in CS ?

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- Are Pareto-optimal options necessarily in CS ? No.

CS selects Pareto-optimal options maximizing the min ranking of agents.

Brams & Kilgour. *Fallback Bargaining*. Group Decision and Negotiation 2001.

Is it possible to simply extend the protocols used in the bilateral case?
Let us consider the case of the **monotonic concession protocols**.

Remember:

- ▶ An **agreement** is reached iff one agent makes an offer that is at least as good for each other agent as their own proposal.

But for the notion of concession we run into trouble...

Endriss. *Monotonic Concession Protocols for Multilateral Negotiation*. AAMAS-06.

For what it means to concede to **many** agents?

- ▶ **Strong/Weak concession**: make an offer strictly better for all / at least one other agent(s).
- ▶ **Pareto concession**: make an offer at least as good for all other agents and strictly better for at least one of them.
- ▶ **Egalitarian/Utilitarian/Nash concession**: make an offer such that the min/sum/product of utilities increases
- ▶ **Egocentric concession**: make an offer that is worse for yourself.

Termination is guaranteed (except for weak concessions)

Endriss. *Monotonic Concession Protocols for Multilateral Negotiation*. AAMAS-06.

- A concession criterion is **deadlock-free** iff it guarantees that at least one agent can make a concession satisfying the criterion at any stage during negotiation, until an agreement has been reached.

Example: Assume Pareto concessions are used.

Three possible outcomes.

round 1: $o_1 = \langle 3, 2, 1 \rangle$, $o_2 = \langle 1, 3, 2 \rangle$, $o_3 = \langle 2, 1, 3 \rangle$.

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Three possible outcomes.

round 1: $o_1 = \langle 3, 2, 1 \rangle$, $o_2 = \langle 1, 3, 2 \rangle$, $o_3 = \langle 2, 1, 3 \rangle$.

round 2: $o_1 = \langle 1, 3, 2 \rangle$, $o_2 = \langle 2, 1, 3 \rangle$, $o_3 = \langle 3, 2, 1 \rangle$.

No more concessions are possible. An agreement is reached (all agents enjoy utility 1 in their current offer, so any other offer is better).

- A concession criterion is **deadlock-free** iff it guarantees that at least one agent can make a concession satisfying the criterion at any stage during negotiation, until an agreement has been reached.

Example: Assume Pareto concessions are used.

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round 1: $o_1 = \langle 2, 1, 3 \rangle$, $o_2 = \langle 3, 2, 1 \rangle$, $o_3 = \langle 1, 3, 2 \rangle$.

No more concessions are possible. No agreement is reached!

(all agents enjoy utility 2 in their current offer, so any other makes one of them worse off).

Instead of trying to deal with multilateral encounters, let us try to build on simple building blocks. We take inspiration from **Contract-Net protocols**.

- ▶ negotiation starts with an **initial allocation**
- ▶ agents asynchronously **negotiate** resources
- ▶ **deals** to move from one allocation to another, ie $\delta = (A, A')$
- ▶ deals can involve **payments** (utility transfer);
- ▶ agents accept deals on the basis of a **rationality criterion**, we assume myopic IR: $v_i(A') - v_i(A) > p(i)$

Different **types of deals** can be considered
“natural” restrictions on the type of exchanges allowed between agents,
in particular:

- ▶ **1-deals**: exchange of a single resource
- ▶ **bilateral deal**: exchange involving two agents
- ▶ **clique deal**: exchange among agents in a clique of neighbours

Different assumptions on the **preference structures**
“natural” restrictions/assumptions to be made on the preferences of **all**
the agents of the system, in particular:

- ▶ **monotonicity**: $v_i(B_1) \leq v_i(B_2)$ when $B_1 \subseteq B_2$
- ▶ **modularity**: $v(S_1 \cup S_2) = v(S_1) + v(S_2) - v(S_1 \cap S_2)$

Some known results:

- ▶ a deal is IR (with money) iff it increases utilitarian social welfare (thus generates a **surplus**).
- ▶ allows to show that **any** sequence of IR deals converges to an allocation maximizing utilitarian social welfare
- ▶ however, may require **very complex** deals to be implemented during the negotiation (in fact, for any conceivable deal we may construct a scenario requiring exactly that deal).
- ▶ for **modular** domains, convergence is guaranteed for negotiations involving 1-deals only

Sandholm. *Contract types for satisficing task allocation*. IEEE Symposium-1998.

Endriss et al.. *Negotiating socially optimal allocation of resources*. JAIR-2006.

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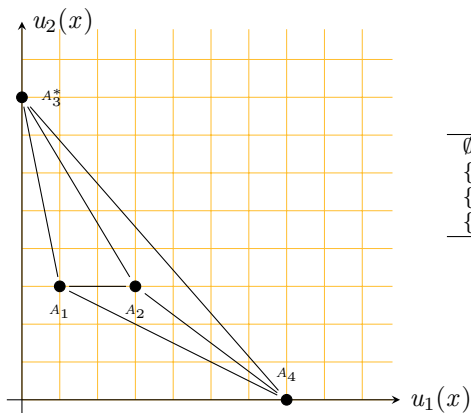
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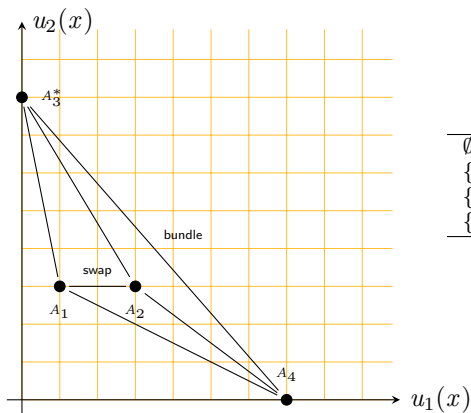
The setting

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	u_1	u_2
\emptyset	0	0
$\{r_1\}$	1	3
$\{r_2\}$	3	3
$\{r_1, r_2\}$	7	8



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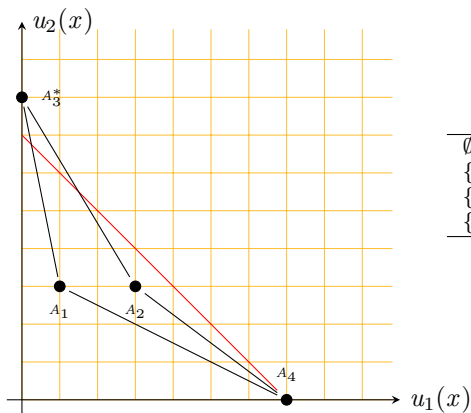
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How far can we get with bilateral deals?

Assume (at least) 3 agents, and take an arbitrary non-modular valuation function:

$$v_1 = a + b.r_1 + c.r_2 + d.r_1.r_2$$

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Assume (at least) 3 agents, and take an arbitrary non-modular valuation function:

$$v_1 = a + b.r_1 + c.r_2 + d.r_1.r_2$$

We need to show that it is possible to construct two **modular** functions and select an initial allocation such that no bilateral deals would lead to optimal sw. Assuming $d > 0$ here, take:

$$v_2 = v_3 = (b + \frac{1}{3}d).r_1 + (c + \frac{1}{3}d).r_2$$

Initially (A_0), we allocate r_1 to agent 2 and r_2 to agent 3.

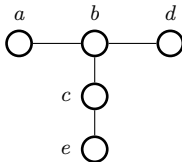
Hence, $sw(A_0) = a + b + c + \frac{2}{3}d < sw(A^*)$, where A^* is the allocation where agent 1 receives both objects.

Chevaleyre et al.. *Simple Negotiation Schemes for Agents with Simple Preferences*. JAAMAS-2010.

Network Exchange Theory: agents can only negotiate with neighbours.

- ▶ agents are now located on a **graph** G
- ▶ each agent can reach an agreement with **at most one** neighbour
- ▶ each pair of agents negotiate over the division of 1 euro

Example:

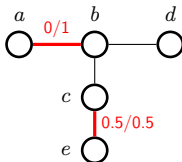


Can you guess how the negotiation will unfold?
Which agreements are met, how the money is divided?

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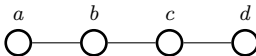
Intuition: b uses his “power” to have two potential agreements (a/d). c sees that b would not deal with him, so focus on e .

More precisely, we can define:

- ▶ an **outcome** is a pair $\langle M, \alpha \rangle$, where M is a matching (which agents agree on a deal), and values α_x for each agent x , with:
 - $\alpha_x + \alpha_y = 1$ when $(x, y) \in M$,
 - $\alpha_x = 0$ when $x \notin M$.

Let β_x be the **best alternative** for x , that is, $\max\{1 - \alpha_y \mid (x, y) \in G\}$

- ▶ an outcome is **stable** if $\alpha_x \geq \beta_x$, for all x .

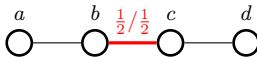


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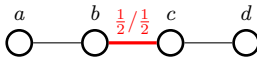
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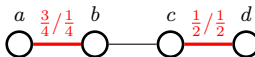
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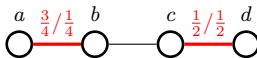
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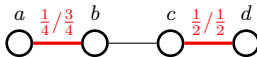
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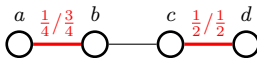
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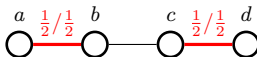
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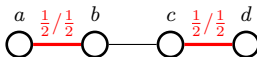
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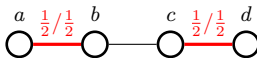


Is this multi-outcome stable? Yes!

But contradicted by experiments (b and c have more negotiation power)

The idea is to strengthen the notion of stability.

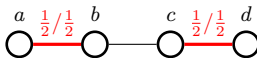
- A **balanced outcome** is an outcome such that, for all $(x, y) \in M$, (α_x, α_y) constitutes a Nash Bargaining Solution **considering** (β_x, β_y) as the disagreement outcome.



This is not a balanced outcome.

The idea is to strengthen the notion of stability.

- A **balanced outcome** is an outcome such that, for all $(x, y) \in M$, (α_x, α_y) constitutes a Nash Bargaining Solution **considering** (β_x, β_y) as the disagreement outcome.



This is not a balanced outcome. Indeed take $(\alpha_a, \alpha_b) = (0.5, 0.5)$.

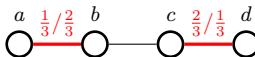
Given $(\beta_a, \beta_b) = (0, 0.5)$, the surplus $1 - 0.5$ should be evenly divided, yielding $(\alpha_a, \alpha_b) = (0.25, 0.75)$.

But now **given** $(\beta_c, \beta_d) = (0.25, 0)$, the values of (α_c, α_d) should be modified... \Rightarrow **fixed-point definition**

- Can you guess the balanced outcome here?

The idea is to strengthen the notion of stability.

- ▶ A **balanced outcome** is an outcome such that, for all $(x, y) \in M$, (α_x, α_y) constitutes a Nash Bargaining Solution **considering** (β_x, β_y) **as the disagreement outcome**.



Gives rise to many questions:

- ▶ are balanced outcomes guaranteed to exist? (if not, when?)
- ▶ are these values rational?
- ▶ is it easy to compute these values?
- ▶ etc.

seminar DESIR

Nicolas Maudet
UPMC

ACAI Simmer School,
London 2013

The setting

What is a good
outcome?

Protocols

Outline of this afternoon lecture.

- ▶ What is the role of argumentation in negotiation?
- ▶ What kind of arguments are valid in negotiation?
- ▶ How to integrate argumentation in negotiation?

In a nutshell, argumentation-based negotiation allows an agent to convey additional information with its own offers, or responses to offers made by others.

Intuitively, argumentation-based negotiation can (in principle):

1. facilitate convergence to efficient outcomes, by adding arguments justifying why the current offer is refused (or accepted);
"I can't accept this offer, because I really need both resources."
2. make an outcome acceptable to the partner, by adding arguments likely to modify its preferences.
"My proposal is 100 for this bike, because it was rated A in the recent survey."*

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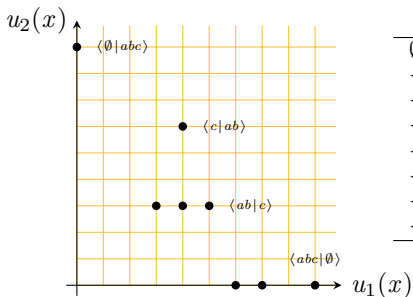
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Some remarks:

1. only make sense if agents do not know the preferences of others
2. raises many very challenging questions:
 - what kind of arguments are allowed?
 - how are preferences of agents modified?



	u_1	u_2
\emptyset	0	0
$\{a\}$	2	0
$\{b\}$	3	0
$\{c\}$	4	3
$\{a, b\}$	5	6
$\{b, c\}$	7	3
$\{a, c\}$	6	3
$\{a, b, c\}$	9	9

Agents do not know the preferences of others, so (assuming monotonicity) they only “see” the following ranking for the other agents.

$$\{a, b, c\} \succeq \{\{a, b\}, \{b, c\}, \{a, c\}\} \succeq \{\{a\}, \{b\}, \{c\}\} \succeq \emptyset$$

$$\{a, b, c\} \succ \{\{a, b\}, \{b, c\}, \{a, c\}\} \succ \{\{a\}, \{b\}, \{c\}\} \succ \emptyset$$

Take a MCP-like protocol.

We denote by C_i the potential minimal concessions (noted as the set of objects offered to the partner), given his current knowledge.

round	offer r_1	offer r_2	u_1	u_2	C_1	C_2
1	$\langle \{a, b, c\}, \emptyset \rangle$	$\langle \emptyset, \{a, b, c\} \rangle$	9,0	0,9	$\{a\}, \{b\}, \{c\}$	$\{a\}, \{b\}, \{c\}$
2	$\langle \{b, c\}, \{a\} \rangle$	$\langle \{c\}, \{a, b\} \rangle$	7,4	0,6	$\{b\}, \{c\}$	$\{a\}, \{b\}$

$$\{a, b, c\} \succ \{\{a, b\}, \{b, c\}, \{a, c\}\} \succ \{\{a\}, \{b\}, \{c\}\} \succ \emptyset$$

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2	$\langle \{b, c\}, \{a\} \rangle$	$\langle \{c\}, \{a, b\} \rangle$	7,4	0,6	$\{b\}, \{c\}$	$\{a\}, \{b\}$

"This is not a concession because a and b are only valuable together to me!"
This discards b as a potential concession for agent 1.

3	$\langle \{a, b\}, \{c\} \rangle$	$\langle \{c\}, \{a, b\} \rangle$	5,4	3,6	$\{a, b\}$	$\{a\}, \{b\}$
4	$\langle \{c\}, \{a, b\} \rangle$	$\langle \{c\}, \{a, b\} \rangle$	4,4	6,6	$\{b\}$	$\{a\}, \{b\}$

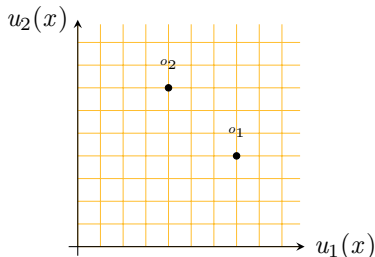
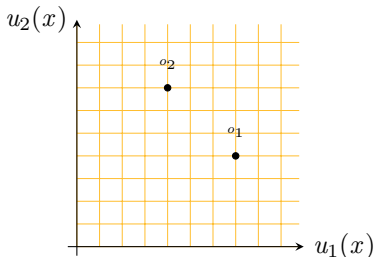
Not that the same argument also discards $\{a, c\}$ and $\{b, c\}$ after round 3.
Agent 2 can perform this reasoning and sticks to his proposal.

Abstractly, an argument will be “some information” conveyed during the negotiation, potentially modifying the preferences of other agents

- ▶ information referring to the outcomes from the outcome set
- ▶ information referring to underlying goals of agents
- ▶ information referring to underlying goals, beliefs, etc. (eg. BDI)
- ▶ information referring to the overall context of the negotiation

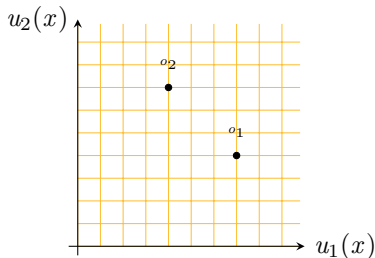
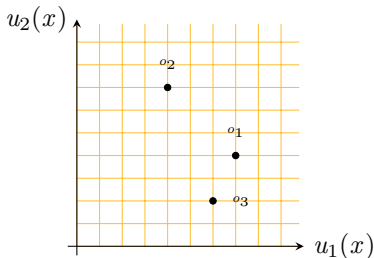
So the granularity of the representation of agents' **mental states** allows to express arguments of different nature.

There is evidence from economics that agents decide based on **reasons** they have at their disposal. It is possible to construct such justifications from the structure of the option set only.



Shafir, Simonson, & Tversky. *Reason-based Choice*. Cognition-1993.

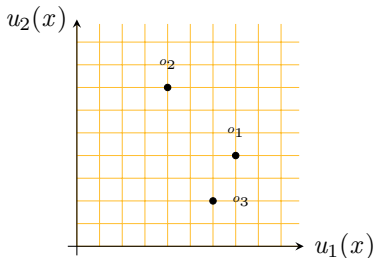
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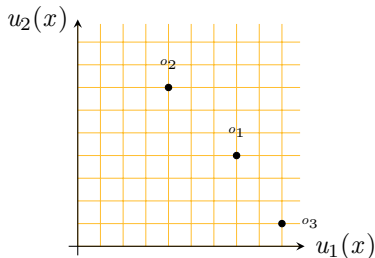
Dominance effect

Shafir, Simonson, & Tversky. *Reason-based Choice*. Cognition-1993.

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Dominance effect



Compromise effect

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Note that this violates some (variant of) independence axioms discussed in the first lecture! Do you see why?

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- ▶ for the **dominance effect**, the argument is of the form:
“I prefer o_1 , because at least it dominates o_3 ”.
- ▶ for the **compromise effect**, the argument is of the form:
“I prefer o_1 because it is a compromise between o_2 and o_3 ”

In argumentation we often conceive arguments as referring to various elements of the context, including mental states of agents.

For instance, in (Kraus, 1998), the following types of arguments are considered, from weakest to strongest:

- ▶ appeal to prevailing practice
- ▶ counter-example
- ▶ appeal to past promise
- ▶ appeal to self-interest
- ▶ promise of future reward
- ▶ threat

Agents are equipped with mental states, and are able to derive intentions and communicative acts (like requests). So the request is justified by a sequence of derivations concluding on the underlying intention

$$I_a(\textit{give}(b, a, \textit{nail}))$$

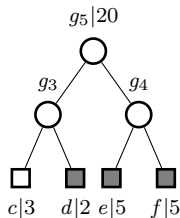
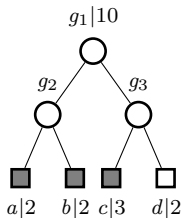
The request may be rejected because :

1. a conflicting intention can be build (e.g. b does not intend to give the nail, because it needs it for some other matter, like hanging a mirror)
2. an undercutting argument for one of premises justifying the request can be put forward (e.g. b may explain that a actually does not need the nail to hang the picture).

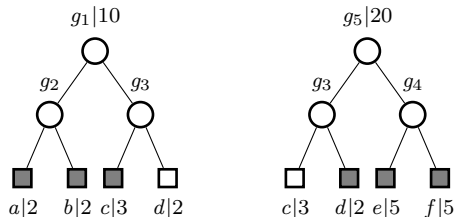
Parsons, Sierra, Jennings. *Agents that reason and negotiate by arguing*. JLC-1998.

Rahwan et al.. *Argumentation-based Negotiation*. KER-2004.

- ▶ preferences of agents are based on **goals** they would like to satisfy
- ▶ agents can exchange information about their underlying goals
- ▶ doing so, they can profit from common goals, or propose new plans



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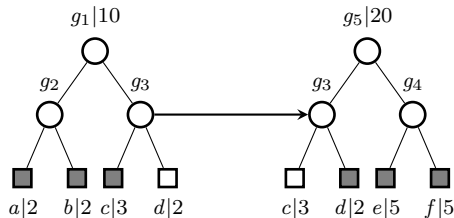


agent 1: "I would like to buy d for 2 euros"

agent 2: "Sorry. I can't accept this deal. **What do you need d for?**"

agent 1: "I would like to complete g_3 "

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agent 1: "I would like to buy d for 2 euros"

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agent 1: "I would like to complete g_3 "

Rahwan et al.. *On the benefits of using underlying goals in interest-based negotiation*. AAAI-2007.

Can we use abstract argumentation to support moves in negotiations?

We first distinguish:

- ▶ **practical arguments**: arguments supporting choices, decisions, offers
- ▶ **epistemic arguments**: arguments supporting beliefs

A common assumption is that practical arguments cannot attack epistemic arguments (to avoid “wishful thinking”).

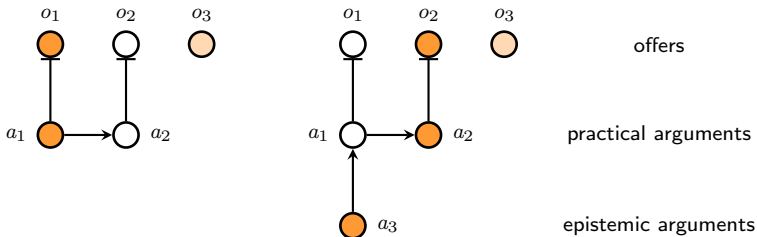
A key ingredient is the function \mathcal{F} which returns, for an offer o , the (practical) arguments supporting it. These arguments “highlight positive features of the options they support”.

Amgoud, Dimopoulos, Moraitis. *A unified and general framework for argumentation-based negotiation*. AAMAS-07.

It is then possible to relate the status of offers to the status of its supporting arguments. More precisely:

- ▶ an offer o is **acceptable** iff there exists an argument $a \in \mathcal{F}(o)$ such that a is accepted.
- ▶ an offer o is **rejected** iff for all argument $a \in \mathcal{F}(o)$ such that a is accepted.
- ▶ an offer o is **non-supported** iff $\mathcal{F}(o) = \emptyset$.

A natural ordering is provided: acceptable \succ non-supported \succ rejected. However note that this only distinguishes 3 classes of offers...



For agent 1, the set of accepted arguments is $\{a_1\}$.
Thus, o_1 is acceptable while o_2 is rejected, and o_3 is unsupported.

$$o_1 \succ o_3 \succ o_2$$

For agent 2, the set of accepted arguments is $\{a_3, a_2\}$.
Thus, o_2 is acceptable while o_1 is rejected, , and o_3 is unsupported.

$$o_2 \succ o_3 \succ o_1$$

- ▶ to account for the dynamics, protocols allow the exchange of arguments.
- ▶ new arguments are integrated by the other agent in its theory (hypothesis of trust or verifiability of arguments)
- ▶ this in turn may affect the acceptability status of offers

In (Amgoud et al.), the notion of concession is defined as follows:

- ▶ o is a concession at round t iff there exists $o' \succ^t o$.

Amgoud, Dimopoulos, Moraitis. *A unified and general framework for argumentation-based negotiation*. AAMAS-07.

Now argumentative moves are allowed in the negotiation (see also Simon's course). Often as a subprotocol embedded in negotiation.

Take for instance the alternating-offers protocols. Now the possible moves become:

- ▶ propose, accept, refuse (counter-offer)
- ▶ **argue**, **agree**

Where, in short, argue allows to present arguments defending his own offer, or to counter-attack by putting forward arguments against the offer of the other agent. It is also possible to argue about rejections.

Amgoud et al.. *Arguments, dialogue, and negotiation*. ECAI-00.

Hadidi et al.. *Argumentative Alternating-Offers*. AAMAS-07.

Veenen, Prakken. *A protocol for arguing about rejections in negotiation*. COMMA-06.

Note that since the preferences of agents are now **dynamic**, we often assess the quality of an outcome given the information exchanged so far.

- ▶ an outcome is **t-acceptable** iff it is acceptable to both agents given their theories at round t
- ▶ an outcome is **t-Pareto** iff it is Pareto-optimal given the theories of agents at round t
- ▶ an outcome is **ideal** iff the outcome is acceptable to both agents, were those agents merging their theories.

Amgoud and Vesic. *A formal analysis of the role of argumentation in negotiation dialogues*. JLC-2012.

Quality of Outcomes: Example

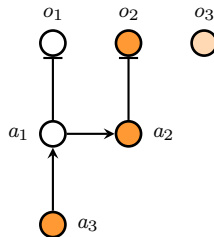
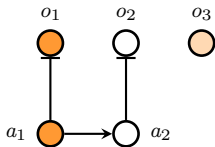
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offers

practical arguments

epistemic arguments

$t = 0$: $o_1 \succ o_3 \succ o_2$ and $o_2 \succ o_3 \succ o_1$
No offer is 0-acceptable, but o_3 is 0-Pareto.

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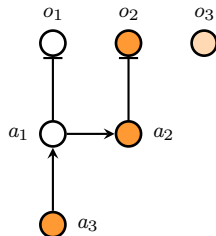
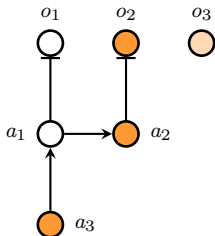
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No offer is 0-acceptable, but o_3 is 0-Pareto.

If agent 2 utters argument a_3 : $t = 1$: $o_2 \succ o_3 \succ o_1$ and $o_2 \succ o_3 \succ o_1$
Now offer o_2 is 1-acceptable (and so 1-Pareto).

This course was certainly not exhaustive but tried to convey some fundamental ideas...

- ▶ in particular: much richer representations (logic-based) give a much finer understanding of the type of arguments, goals, etc. which can be involved in negotiation

Many things remain to do...

- ▶ the added-value of argumentation in negotiation remains somewhat theoretical
- ▶ experimental results start to emerge, raises questions of strategies

Thanks!