**Test Objective/Description:** Collision Correction

**Location:** Flemming Test Space

**Date:**

**Hardware Needed:** Onboard computer

**Procedure:**

Run (On computer) path planning algorithm to regenerate a path once obstacle information has been added to map

* Check that path traverses remainder (\_\_%) of space
* Check that path eventually leads to target identification

Upon successful completion on PC, run (on flight computer) path planning algorithm to regenerate a path

* Check that path traverses remainder (\_\_%) of space
* Check that path eventually leads to target identification

**Requirements Met**

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| **1.2.1** |  |
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**Test Anomalies**

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**Test Results:**