**Test Objective/Description:** Controls Subsystem

**Location:** RECUV VICON Cage

**Date:** December 2015

**Hardware Needed:**

**Procedure:**

.

**Requirements Met**

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| **1.2** |  |
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**Test Anomalies**

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**Test Results:**

Test flights were successful after integrating with Mechanical subsystem.

We were able to perform simple trajectories and nonzero yaw pointing.

Integrated with planning via passing text files of waypoints.