

Presentation Title

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International Workshop of Couch Potatoes, Munich, 11/16/2012





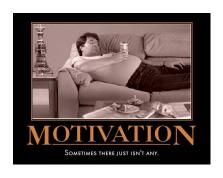
Motivation



Why are we addressing this problem?

- Aaa
- Bbb
- Ccc

Introduction







Motivation



Why are we addressing this problem?

- Aaa
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This is why!





Overview



Introduction

Approach Definition

Results

Summary







Problem Formulation



Problem

$$x^* = \operatorname*{arg\,min}_{x \in \mathcal{X}} \int J(x, t) \, \mathrm{d}t$$

Challenges:

- Curse of dimensionality
- Non-linear model/constraints
- No analytical solution
- Noisy Measurements
- Real-time capability

Solution

Solve Problem





Related Work



Normal cite: [Molin and Hirche 2012] Bigger cite: [Molin and Hirche 2012]

Variable number of authors:

Introduction

■ 2 authors: [Lawitzky, Hernandez, et al. 2012]

■ 3 authors: [Lawitzky, Hernandez, and Hirche 2012]





Approach



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Introduction









Results



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Introduction





Summary















Summary



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Introduction









References





Martin Lawitzky, JM Hernandez, and Sandra Hirche.

Rapid prototyping of planning, learning and control in physical human-robot interaction. In: 13th International Symposium on Experimental Robotics (ISER). 2012, pp. 819–824.



Adam Molin and Sandra Hirche.

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This work was supported by:



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