Fundamental Concepts in Computational and Applied Mathematics

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Recap

- Beware catastrophic cancellation know the limits of precision
- Learn about the conditioning of your problem
- Choose algorithms known to be stable so as to not introduce any more loss of precision than necessary
 - Conditioning is fundamentally a characteristic of the problem while
 - Stability is related to algorithms

Dense Linear Algebra methods

Let
$$x, y \in R^N$$
 and $A \in R^{N \times N}$

- Basic Linear Algebra
 - dot products: $x^T y$
 - matvec: Ax
 - saxpy: ax + y
 - Solve Ax = b
 - Solve $Ax = \lambda x$

Rule of Thumb

We cannot solve anything except linear systems

Warning

Never (EVER) solve a linear system by calculating the inverse of the matrix and multiplying!

Linear Algebra methods

- Various standard methods
 - LU
 - Cholesky
 - QR
 - SVD
- All have advantages and disadvantages learn about them!
- Your choice will depend on the application, software availability, and time constraints

Some Useful Definitions

Definition (Condition Number)

The condition number of a matrix A is given by: $\kappa(A) = ||A|| \cdot ||A^{-1}||$

Definition (Residual)

The residual of linear system is given by b - Ax

Definition (Machine Precisions)

The machine precision is denoted by μ

Definition

A problem is said to be ill-conditioned if $\mu \kappa_{\infty}(A) \approx 1$

Fun Facts

- Gaussian elimination always produces solutions with relatively small residuals (minor caveats)
- Best possible error bound for solving a system of linear equations can be given by

$$\frac{||x - \hat{x}||_{\infty}}{||x||_{\infty}} \le 4\mu\kappa_{\infty}(A) \tag{1}$$

where μ is machine precision of the computer.

Stable or Unstable? Well conditioned or ill-conditioned?

Consider Ax = b where

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

Comparison of algorithms

Table: Number of iterations to reduce error by 10^{-3} .

| $\overline{\kappa(A)}$ | Value | iter |
|------------------------|--------|--------|
| 1 | 0.0 | 1 |
| 10^{2} | 0.82 | 15 |
| 10^{4} | 0.98 | 150 |
| 10^{8} | 0.9998 | 15,000 |

LU with Partial Pivoting

• Can show that LU/PP generates the exact solution to a perturbed problem (A+E)x=b, such that

$$||E||_{\infty} \le 8n^3 \rho ||A||_{\infty} \mu \tag{2}$$

- ullet The growth factor ho can grow exponentially, but in practice is usually of order 10
- Consider the residual, b Ax:

Summary

- A
- B
- C

References

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