

# Maximizing Linear Functions Subject to Linear Inequalities- The Simplex Method

Mario Banelos

University of California, Merced

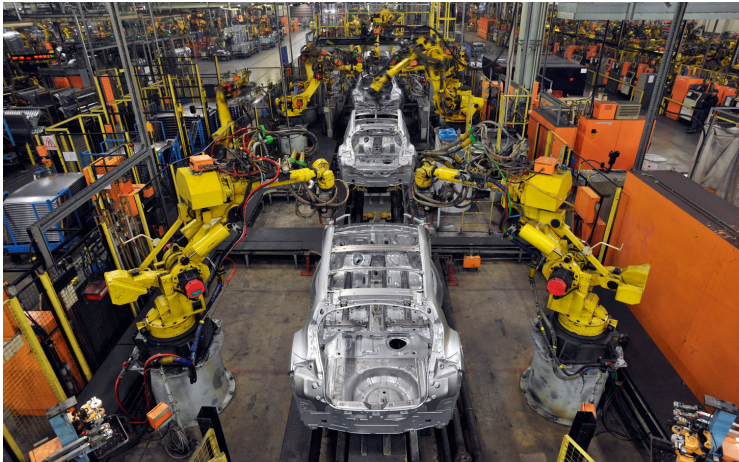
*[mbanelos4@ucmerced.edu](mailto:mbanelos4@ucmerced.edu)*

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# Motivation and Background

- George Dantzig invented the Simplex Method in 1947, and it is still used in many applications of linear programming.
- How do we maximize or minimize given linear restrictions?
- Applications of the simplex method include: economics, industry, and transportation problems.

# Applications



# Standard form

- For a given linear program, we can convert it to the following form:

$$\max \quad z = c_1x_1 + c_2x_2 + \dots + c_nx_n$$

subject to

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n} = b_1$$

$$\dots \quad \dots \quad \dots \quad \dots = \vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn} = b_m$$

for nonnegative  $x_i$  ( $i = 1, 2 \dots n$ ).

# Rewriting LP

We want to maximize

$$\mathbf{c} \cdot \mathbf{x}$$

with

$$\mathbf{Ax} = \mathbf{b}, \mathbf{x} \geq \mathbf{0}$$

We can write the LP as

- $$\begin{bmatrix} 1 & -\mathbf{c}^T & 0 \\ 0 & \mathbf{A} & \mathbf{b} \end{bmatrix} \begin{matrix} \text{Row } 0 \\ \text{Row } i \end{matrix}$$
- $i = 1, 2, \dots, m$

# Definitions

## Feasible Solution

A solution which meets all constraints but may or may not be optimal.

## Basic Feasible Solution

A feasible solution with  $m$  number of nonzero  $x_i$ .

## Theorem

If one feasible solution exists, then there exists a basic feasible solution.

# Simplex Algorithm

- **Step 1:** If  $\mathbf{c}^T \geq 0$  in Row 0, the current basic solution is optimal.

⇒ Otherwise, pick a variable  $x_j$  with a negative coefficient in Row 0.

- **Step 2:** For each Row  $i, i \geq 1$ , where there is strictly positive "entering variable coefficient", choose the pivot row with

$$\theta = \min (b_i / A_{ij}) \quad A_{ij} > 0.$$

# Maximization Example

Maximize  $z = 4x_1 + 6x_2$ , subject to

$$-x_1 + x_2 \leq 11$$

$$x_1 + x_2 \leq 27$$

$$2x_1 + 5x_2 \leq 90$$

with  $x_1, x_2 \geq 0$



# Maximization Example

Rewriting the LP, we introduce **slack variables**  $s_1, s_2$ , and  $s_3$

$$-x_1 + x_2 + s_1 = 11$$

$$x_1 + x_2 + s_2 = 27$$

$$2x_1 + 5x_2 + s_3 = 90$$

with  $x_1, x_2, s_1, s_2, s_3 \geq 0$ .

# Maximization Example

Our tableau becomes

$$\begin{bmatrix} 1 & -4 & -6 & 0 & 0 & 0 & 0 \\ 0 & -1 & 1 & 1 & 0 & 0 & 11 \\ 0 & 1 & 1 & 0 & 1 & 0 & 27 \\ 0 & 2 & 5 & 0 & 0 & 1 & 90 \end{bmatrix}$$

with the basic feasible solution  $(x_1, x_2, s_1, s_2, s_3) = (0, 0, 11, 27, 90)$ .  
Then,

$$z = 4(0) + 6(0) + 0(11) + 0(27) + 0(90) = 0$$

## Maximization Example

We choose  $x_2$  as "entering variable" and  $s_1$  as "exiting variable" since  $\theta = 11$ . After pivoting, our tableau becomes

$$\begin{bmatrix} 1 & -10 & 0 & 6 & 0 & 0 & 66 \\ 0 & -1 & 1 & 1 & 0 & 0 & 11 \\ 0 & 2 & 0 & -1 & 1 & 0 & 16 \\ 0 & 7 & 0 & -5 & 0 & 1 & 35 \end{bmatrix}$$

with the basic feasible solution  $(x_1, x_2, s_1, s_2, s_3) = (0, 11, 0, 16, 35)$ . Then,

$$z = 4(0) + 6(11) + 0(0) + 0(16) + 0(35) = 66$$

## Maximization Example

After carrying out the Simplex Method two more times, we have

$$\begin{bmatrix} 1 & 0 & 0 & 0 & \frac{8}{3} & \frac{2}{3} & 132 \\ 0 & 0 & 1 & 0 & -\frac{2}{3} & \frac{1}{3} & 12 \\ 0 & 0 & 0 & 1 & \frac{7}{3} & -\frac{2}{3} & 14 \\ 0 & 1 & 0 & 0 & \frac{5}{3} & -\frac{1}{3} & 15 \end{bmatrix}$$

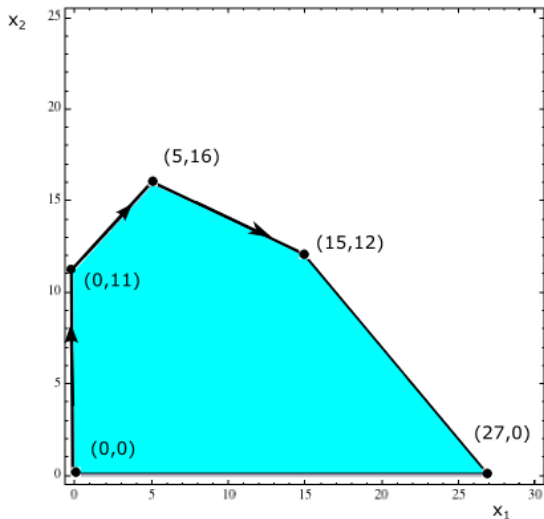
with the basic feasible solution  $(x_1, x_2, s_1, s_2, s_3) = (15, 12, 14, 0, 0)$ .  
Then,

$$z = 4(15) + 6(12) + 0(14) + 0(0) + 0(0) = 132$$

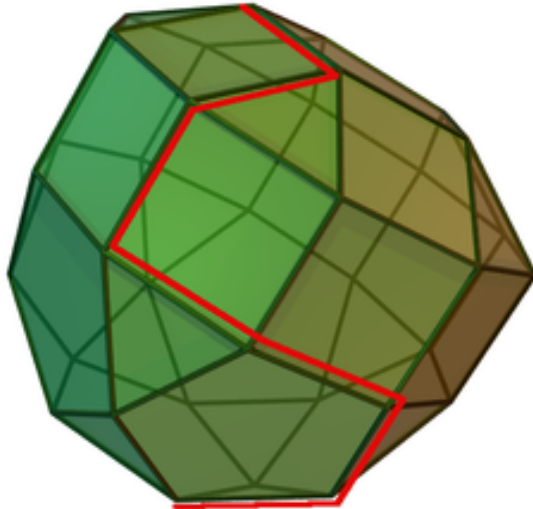
# Graphing the Simplex Method

- We can consider the simplex algorithm as moving from one vertex  $v$  to another adjacent vertex  $w$  of a polytope
- Each step increases the objective function.

# Graphical Example: $\max z = 4x_1 + 6x_2$



# Higher dimensions



## Disadvantages of the Method

- The method works well for non-degenerate matrix **A**.
- A basic feasible solution is needed as a starting point.
- Other methods (i.e. interior point) may be more efficient with large  $m$ .



## Concluding Remarks

- Introduced the Simplex Method with a specific maximization example.
- Provided intuition for the graphical representation of the method.
- Highlighted a few applications and shortcomings.

# References



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