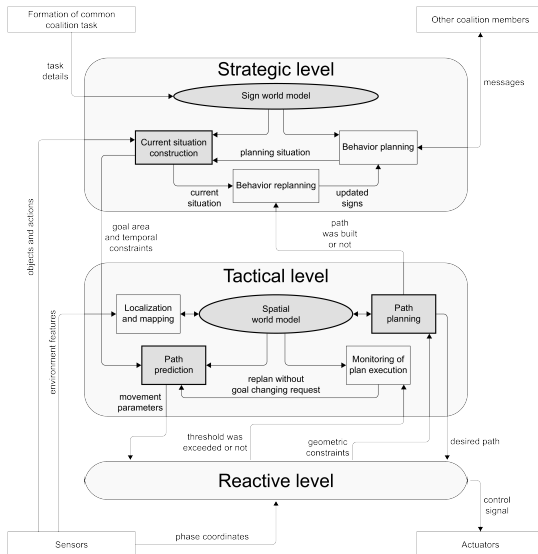# Behavior and path planning for the coalition of cognitive robots in smart relocation tasks

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STRL architecture

Movie

Thank you for attention!

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