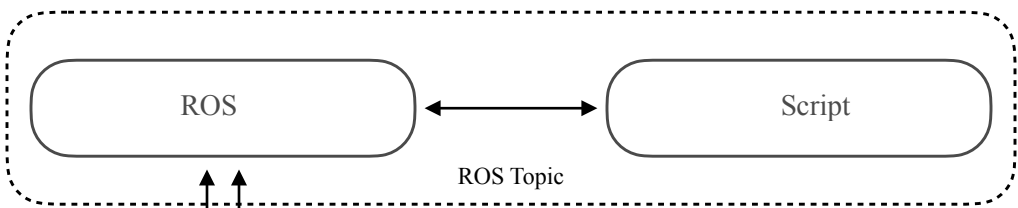


# Ground Control Station



ROS Topic

## MAVLink Message (Radio Telemetry)

Subscribe: State, Position, Attitude

Publish: Arm/Disarm, Mode Switch, Desired Position/Velocity

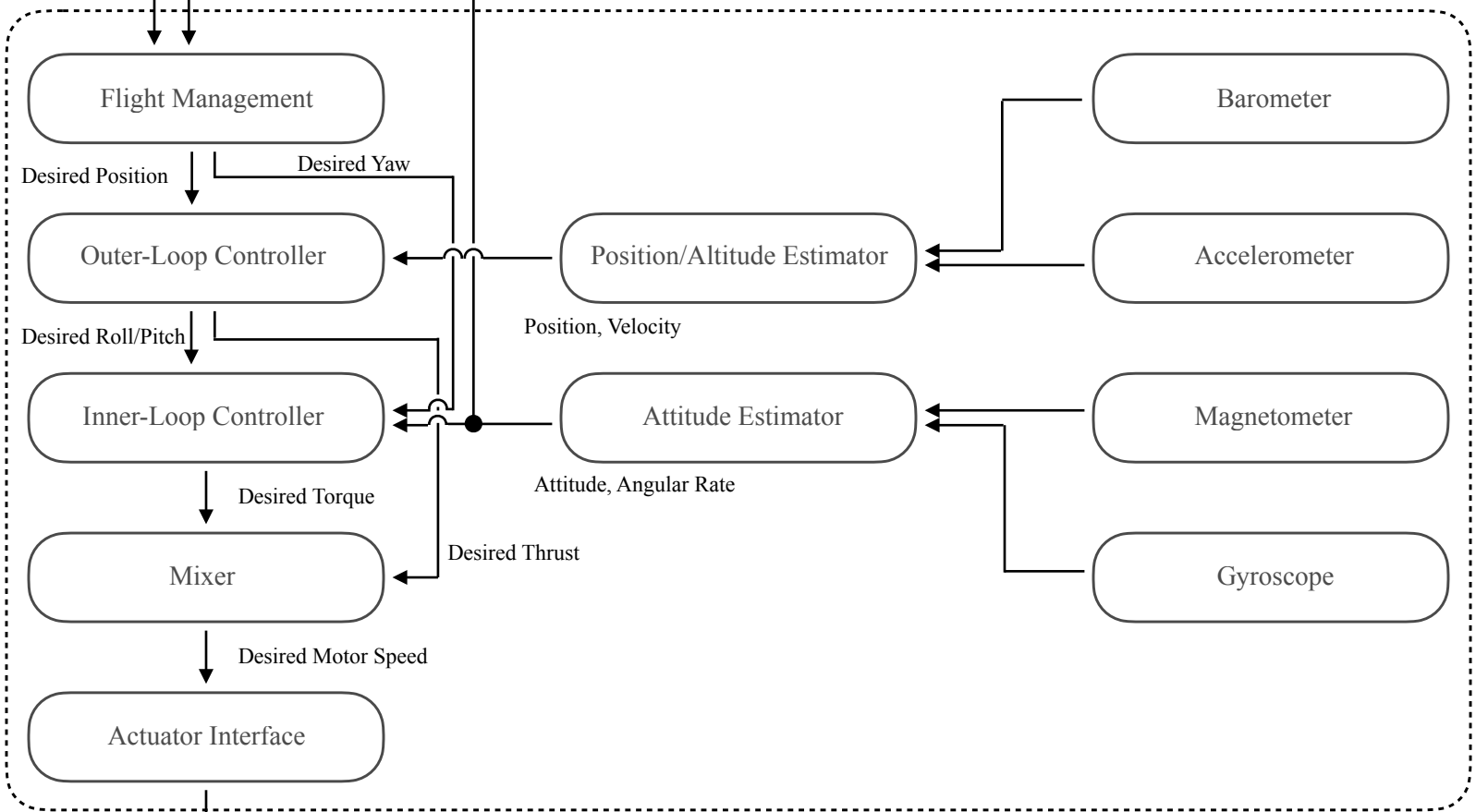


Arm/Disarm

Mode Switch

Desired Position/Velocity

# Autopilot (Pixhawk)



Motor Voltage

