PROPOSAL:
HUMAN GUIDED ITERATIVE TRAINING OF DYNAMIC MOTOR SKILLS

A Thesis Proposal
Presented to
The Academic Faculty

by

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PROPOSAL:
HUMAN GUIDED ITERATIVE TRAINING OF DYNAMIC MOTOR SKILLS

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SUMMARY

We propose a set of techniques for training a dynamic controller

CHAPTER I

INTRODUCTION

Every dissertation should have an introduction. You might not realize it, but the introduction should introduce the concepts, backgrouand, and goals of the dissertation.

1.1 Structure

haha

CHAPTER II

ITERATIVE CONTROLLER DESIGN

Resembles learning by demonstration,

2.1 *System Overview*

coaching and training

2.2 *Controller*

Our controller produces a torque

2.3 *Instruction*

our instruction are following:

REFERENCES