```
?
                          Scipy pyOpt \min_{x} f(x)
                            x_{k+1}
                            (t_{final}, C_0, C_{d+n_{knot}-2})\min J = (t_{final} - t_{initial})^2
                             \begin{array}{l} \forall k \in \\ \{0,,N_s - 1\} \end{array}
                                     \begin{cases} \varphi_1(z(t_{initial}), z^{(l-1)}(t_{initial})) = q_{initial} \\ \varphi_1(z(t_{final}), z^{(l-1)}(t_{final})) = q_{final} \end{cases}
                                \begin{cases} \varphi_2(z(t_{initial}), z^{(l)}(t_{initial})) \\ \varphi_2(z(t_{final}), z^{(l)}(t_{final})) \\ \varphi_2(z(t_{final}), z^{(l)}(t_{final})) \\ \varphi_2(z(t_k), z^{(l)}(t_k)) \\ d_{O_m}(t_k) \end{cases}
                                                                                                                                                                                                                                    =u_{initial}
                                                                                                                                                                                                                                        =u_{final}
                                                                                                                                                                                                                                           \geq \rho + r_m, \forall O_m \in \mathcal{Q}_{occupied}
           (2)
                             \begin{bmatrix} \dot{v}\dot{\omega} \end{bmatrix}
                            \varphi_3(z(t_k), z^{(l)}(t_k)) \in \mathcal{A}
                          \begin{array}{l} {\mathcal{A}} \\ {\varphi}_3 \\ {\varphi}_3(z(t_k),\underline{z}^{(3)}(t_k)) = \end{array}
                            \begin{split} & \varphi_{3}(z(t_{k}),z^{-1}(t_{k})) = \\ & = \begin{bmatrix} \dot{v} \\ \omega \end{bmatrix} = \begin{bmatrix} \frac{\partial}{\partial t} \|\dot{z}\| \\ \frac{\partial}{\partial t} \frac{(\dot{z}_{1}\ddot{z}_{2} - \dot{z}_{2}\ddot{z}_{1})}{\|\ddot{z}\|^{2}} \end{bmatrix} = \begin{bmatrix} \frac{\dot{z}_{1}\ddot{z}_{1} + \dot{z}_{2}\ddot{z}_{2}}{\|\ddot{z}\|} \\ \frac{(\ddot{z}_{1}\ddot{z}_{2} + z_{2}^{(3)}\dot{z}_{1} - (\ddot{z}_{2}\ddot{z}_{1} + z_{1}^{(3)}\dot{z}_{2}))\|\dot{z}\|^{2} - 2(\dot{z}_{1}\ddot{z}_{2} - \dot{z}_{2}\ddot{z}_{1})\|\dot{z}\|\dot{v}} \end{bmatrix} \end{split}
                            T_p
                             \tau_k = t_{initial} {+} k T_c k \in
                          \begin{array}{l} 2m \\ (\tau_{k-1},\tau_k)(k \in \\ ) \\ \tau_k \\ \tau_k + \\ T_p \end{array} 
                            (C_{(0,\tau_k)}, C_{(d+n_{knot}-2,\tau_k)})\min J_{\tau_k} = \|\varphi_1(z(\tau_k + T_p, \tau_k), z^{(l-1)}(\tau_k + T_p, \tau_k)) - q_{final}\|^2
(3) \forall t \in [\tau_k, \tau_k + T_p]
                                \begin{cases} \varphi_{1}(z(\tau_{k},\tau_{k}),,z^{(l-1)}(\tau_{k},\tau_{k})) = q_{ref}(\tau_{k},\tau_{k-1}) \\ \varphi_{2}(z(\tau_{k},\tau_{k}),,z^{(l)}(\tau_{k},\tau_{k})) &= u_{ref}(\tau_{k},\tau_{k-1}) \\ \varphi_{2}(z(t,\tau_{k}),,z^{(l)}(t,\tau_{k})) &\in \mathcal{U} \\ d_{O_{m}}(t,\tau_{k}) &\geq \rho + r_{m}, \forall O_{m} \in \mathcal{U} \end{cases}
                                                                                                                                                                                                                           \geq \rho + r_m, \forall O_m \in \mathcal{O}(\tau_k)
           (4)
                               [\tau_{-1}, \tau_0)
                             q_{ref}(\tau_0, \tau_{-1}) = q_{initial}
                             u_{ref}(\tau_0, \tau_{-1}) = u_{initial}
                        u_{ref}(\tau_{0}, \tau_{-1})
q \in^{n}
N_{s}
n+
m
N_{k}
N_{s}(m+
\operatorname{card}(\mathcal{O}(\tau_{k})))
X_{s}
```