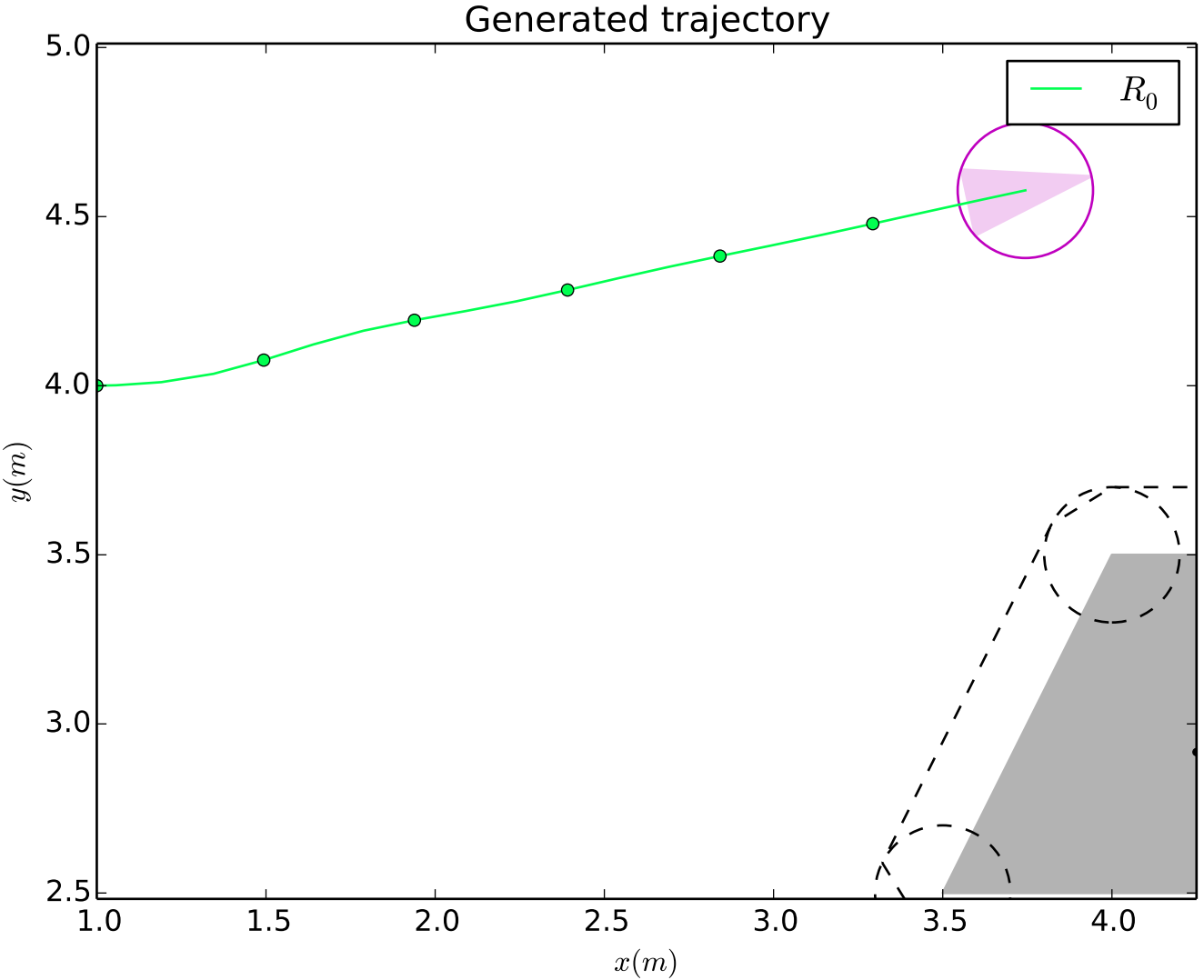
Generated trajectory
R_0
5.0
4.5
4.0
3.5
3.0
2.5
1.0
1.5
2.0
2.5
3.0
3.5
4.0
$y(m)$
$x(m)$