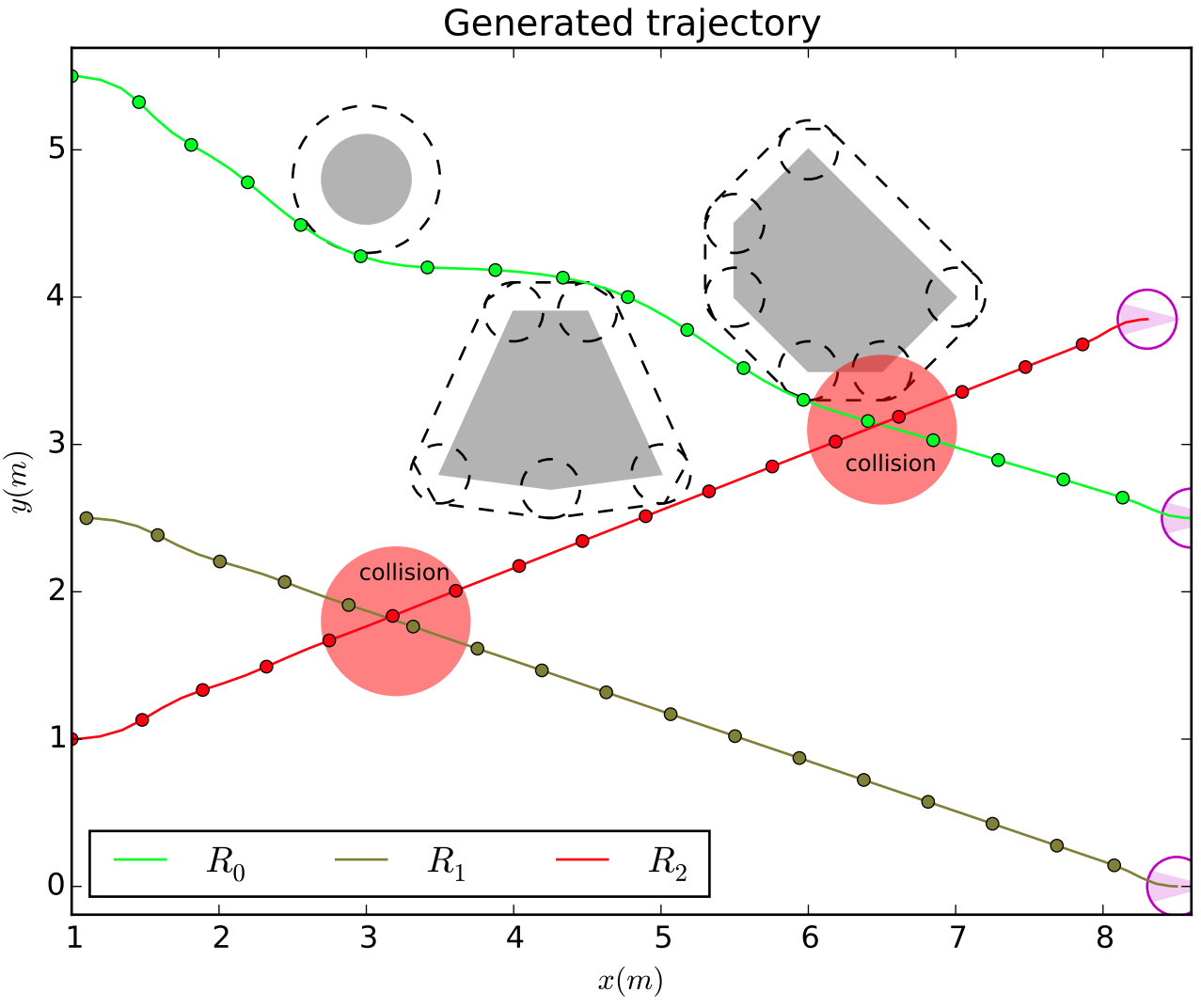
Generated trajectory
collision
collision
R_0
R_1
R_2
$y(m)$
$x(m)$
0
1
2
3
4
5
1
2
3
4
5
6
7
8