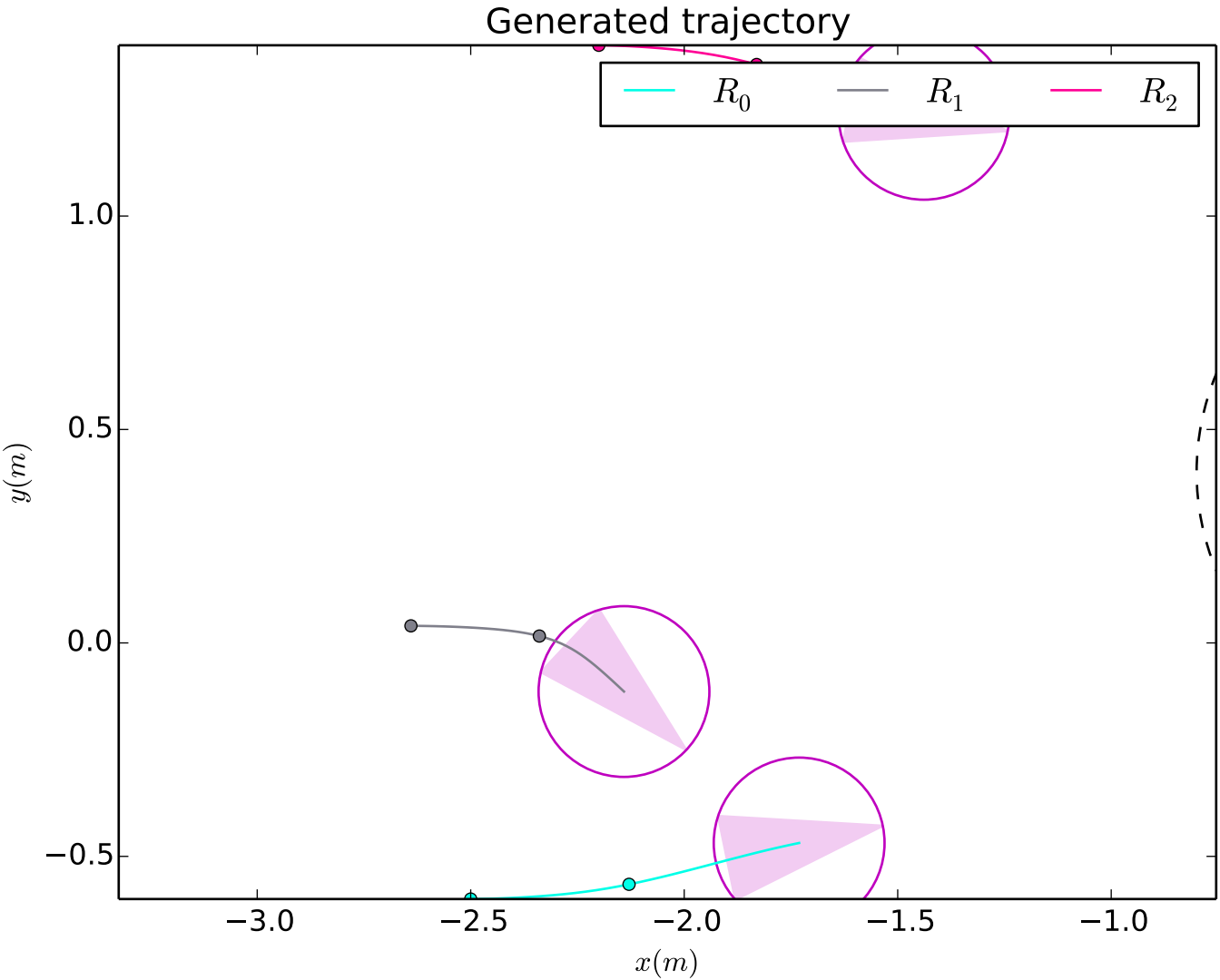
Generated trajectory
R_0
R_1
R_2
1.0
0.5
0.0
−0.5
$y(m)$
−3.0
−2.5
−2.0
−1.5
−1.0
$x(m)$