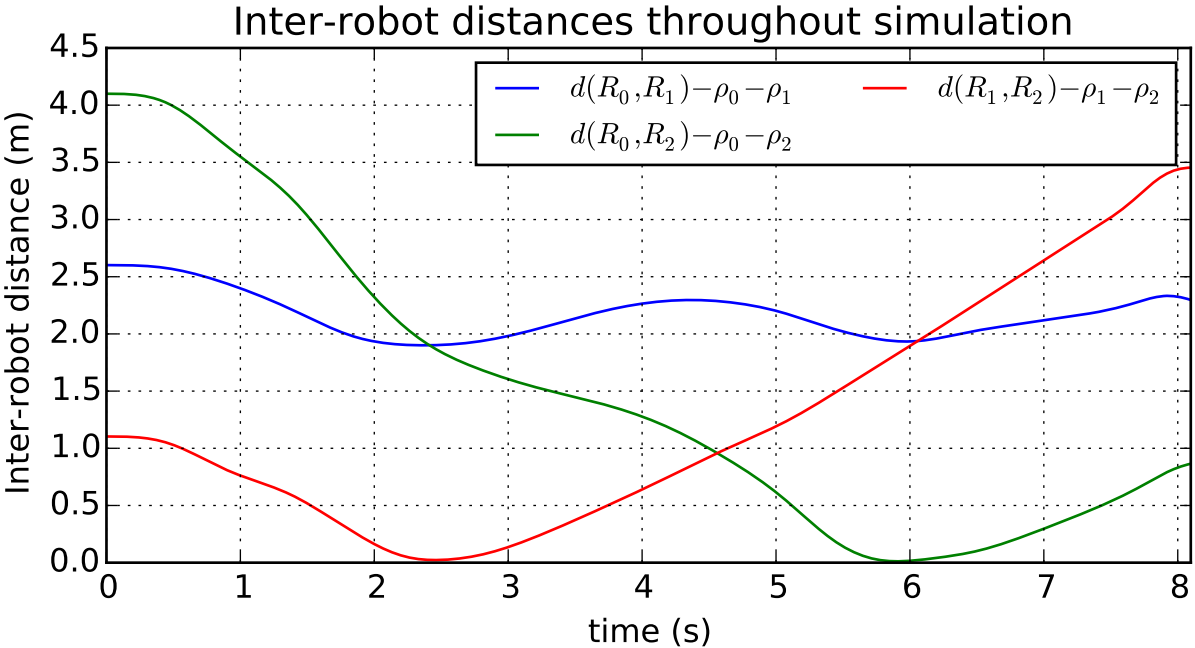
Inter-robot distances throughout simulation
Inter-robot distance (m)
time (s)
$d(R_0,R_1)-\rho_0-\rho_1$
$d(R_0,R_2)-\rho_0-\rho_2$
$d(R_1,R_2)-\rho_1-\rho_2$
0.0
0.5
1.0
1.5
2.0
2.5
3.0
3.5
4.0
4.5
0
1
2
3
4
5
6
7
8