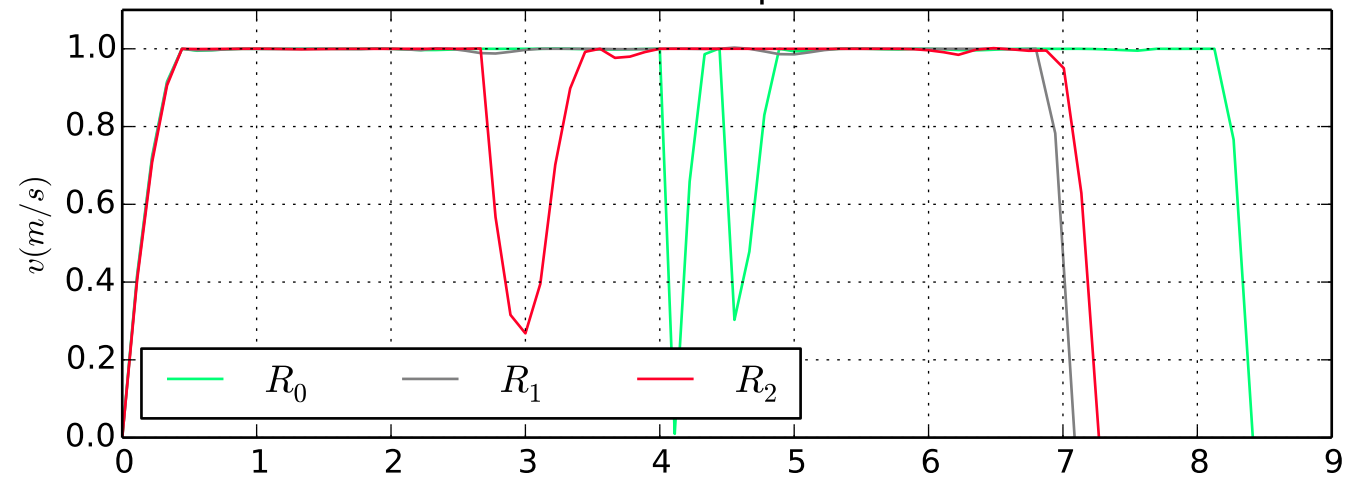


Linear speed



Angular speed

