EE-384 Classwork-1

Problem 1: Common sequence (turn in your codes)

1.1) Create a 'unit_impulse' **function** that creates a unit impulse sequence y(n). The function should accepts input arguments of n_p, n1, and n2 where n1 and n2 are the start and the end of the sequence; n_p is the position of the pulse. Note that for each value of n:

$$y(n) = \begin{cases} 1 \text{ when } n = n_p \\ 0 \text{ when } n \neq n_p \end{cases}$$

1.2) Create a 'unit_step' **function** that creates a unit step sequence y(n). The function should accepts input arguments of n_s, n1, and n2 where n1 and n2 are the start and the end of the sequence; n_s is the step position. Note that for each value of n:

$$y(n) = \begin{cases} 1 \text{ when } n \ge n_s \\ 0 \text{ when } n < n \text{ s} \end{cases}$$

Problem 2: Time-shift and Time-reversal (turn in your codes and plots)

- 2.1) Create a 'time_shift' **function** that create an output sequence y(n) as a delayed version of the input sequence x(n). The function should accept input arguments of x, n, and n_d where n_d is the number of samples delayed.
- 2.2) Let x(n) = 2n + 3, where n = -10:10.
 - a. Plot x(n).
 - b. Plot a time delayed version of x(n) delayed by 3 samples.
 - c. Plot the time-reversal of x(n)
- 2.3) Plot $y(n) = 5*\delta(n+4) 2*\delta(n-2); n = -10:10$
- 2.4) Plot z(n) = u(n) u(n-4); n = -10:10

where $\delta(n)$ is the unit impulse sequence and u(n) is the unit step sequence.

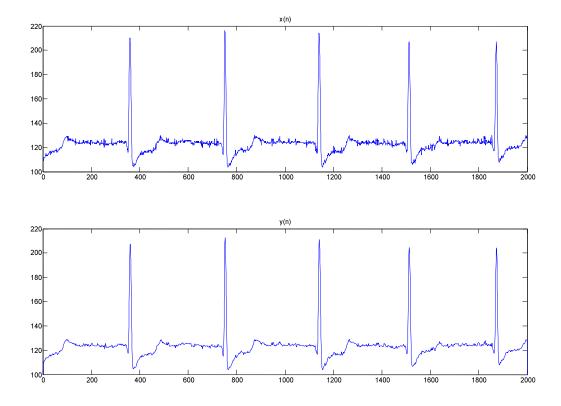
Problem 3: Systems (turn in your codes and plots)

The additional file 'SAMPLE_ECG.mat' stores a sequence of Electrocardiography, an interpretation of the electrical activity of the heart over a period of time.

- 3.1) Load and Plot the signal. Call this signal x(n)
- 3.2) Using for loop, write a program that creates an output y(n) where

$$y(n) = \frac{x(n) + x(n+1) + x(n+2)}{3}$$

3.3) Plot both x(n) and y(n) in a same figure using the subplot command. The vertical axis varies from 100 to 200 and the horizontal axis varies from 0 to 2000 for both plots. Hint: use the command axis([0 2000 100 220]). Your figure should look similar to the following: (remember to put titles for each plots)



3.4) Does y(n) look smoother than x(n)? You have just filtered the original signal using a low-pass filter. The filter is supposed to remove high frequency components of the signal.

Read:

- a) Direct form-II implementation of a standard difference equation.
- b) Convolution of two discrete-time signals.
- c) Nyquist theorem