

Dissertation Work for supervision 25th November

AUTHOR

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For my dissertation, I have been working on different ways that acquisition functions could be implemented alongside Bayesian History Matching to speed up management strategy evaluation in fisheries.

I have based my work on the paper “Using history matching to speed up management strategy evaluation grid searches”.

Currently, I am focusing on three files on my Github that are looped versions of [the original code from this paper](#) with acquisition functions added in. I will show the outputs from these files below and try to provide some explanation.

Looped version of case_study8.R with Expected Improvement

This is the [case_study8.R](#) file but now looped and with an expected improvement acquisition function added, which can be found [here](#) in my repo.

I will now add some of the outputs of this file. The number of rounds can be changed using the `max_rounds` variable which is how I have made the different plots.

```
Attaching package: 'dplyr'
```

```
The following objects are masked from 'package:stats':
```

```
filter, lag
```

```
The following objects are masked from 'package:base':
```

```
intersect, setdiff, setequal, union
```

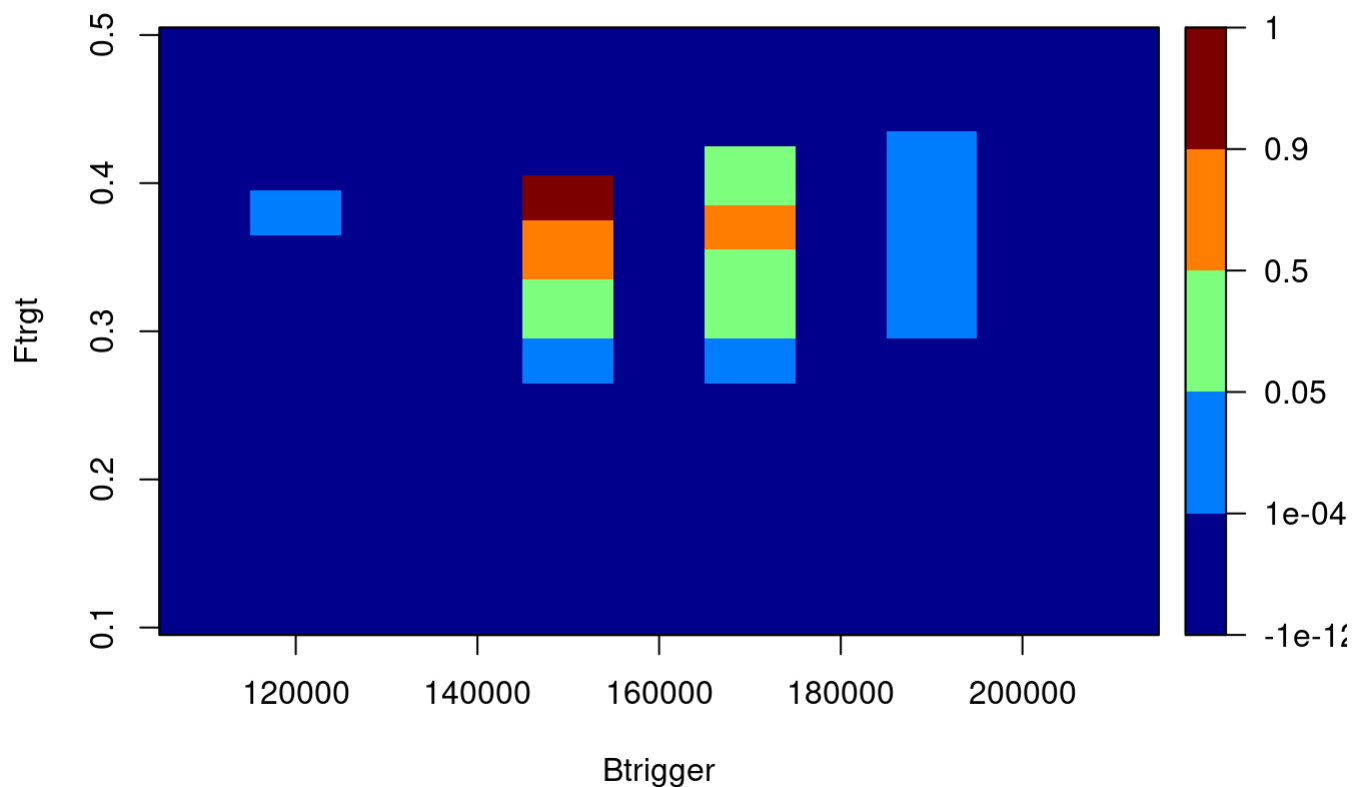
```
Joining with `by = join_by(Ftrgt, Btrigger)`
```

```
Plausible points remaining: 258
```

```
Current maximum 54596.5
```

```
Round 2
```

```
Unevaluated candidates with EI > 0: 257
```



Plausible points remaining: 47
 Best catch so far: 54596.5

OPTIMIZATION COMPLETE

Completed 2 rounds

Total evaluations: 16

Optimal parameters:

The plot above presents the plausible points remaining in Round 2. For the points that are still plausible, it shows the probability that their median catch is higher than the current best median catch. We then use the expected improvement acquisition function to determine which points will be the best to sample at next.

First we use Bayesian History Matching to determine which points are still plausible. Then, we use the function below:

```
#' @param xi is a scalar for exploration/exploitation trade off
expected_improvement <- function(mu, sigma, y_best, xi = 0.05, task = "max", pred_risk,
{
  ei <- numeric(length(mu))
  safe_points <- pred_risk >= eps

  # Only calculate EI for safe points
```

```

if (any(safe_points)) {
  if (task == "min")
    imp <- y_best - mu[safe_points] - xi
  if (task == "max")
    imp <- mu[safe_points] - y_best - xi
  else
    stop('task must be "min" or "max"')

  Z <- imp / sigma[safe_points]
  ei[safe_points] <- imp * pnorm(Z) + sigma[safe_points] * dnorm(Z)
  ei[safe_points][sigma[safe_points] == 0.0] <- 0.0
}

return(ei)
}

```

where you can see that we remove any points that have a probability less than $\text{eps} = 1e-4$ of having $\text{prisk} \leq 0.05$ removing any points with $\text{pred_risk} < \text{eps}$. Then, we only calculate EI for these safe_points . This saves us some computation time, especially as we move into later rounds. The calculation is done using the standard formula for EI.

If we let $f_{\max} = \max(y_1, \dots, y_n)$ be the current best value, as we are maximising, and sample next at some point x_{n+1} with the emulator as \hat{f} , then we have:

$$EI[(x)] = (f_{\min} - \hat{f})\Phi\left(\frac{f_{\min} - \hat{f}}{s}\right) + s\phi\left(\frac{f_{\min} - \hat{f}}{s}\right)$$

where s is the standard deviation of \hat{f} at x and Φ is the standard normal distribution function and ϕ is the standard normal density function.

We then repeat the code until we resolve to one point:

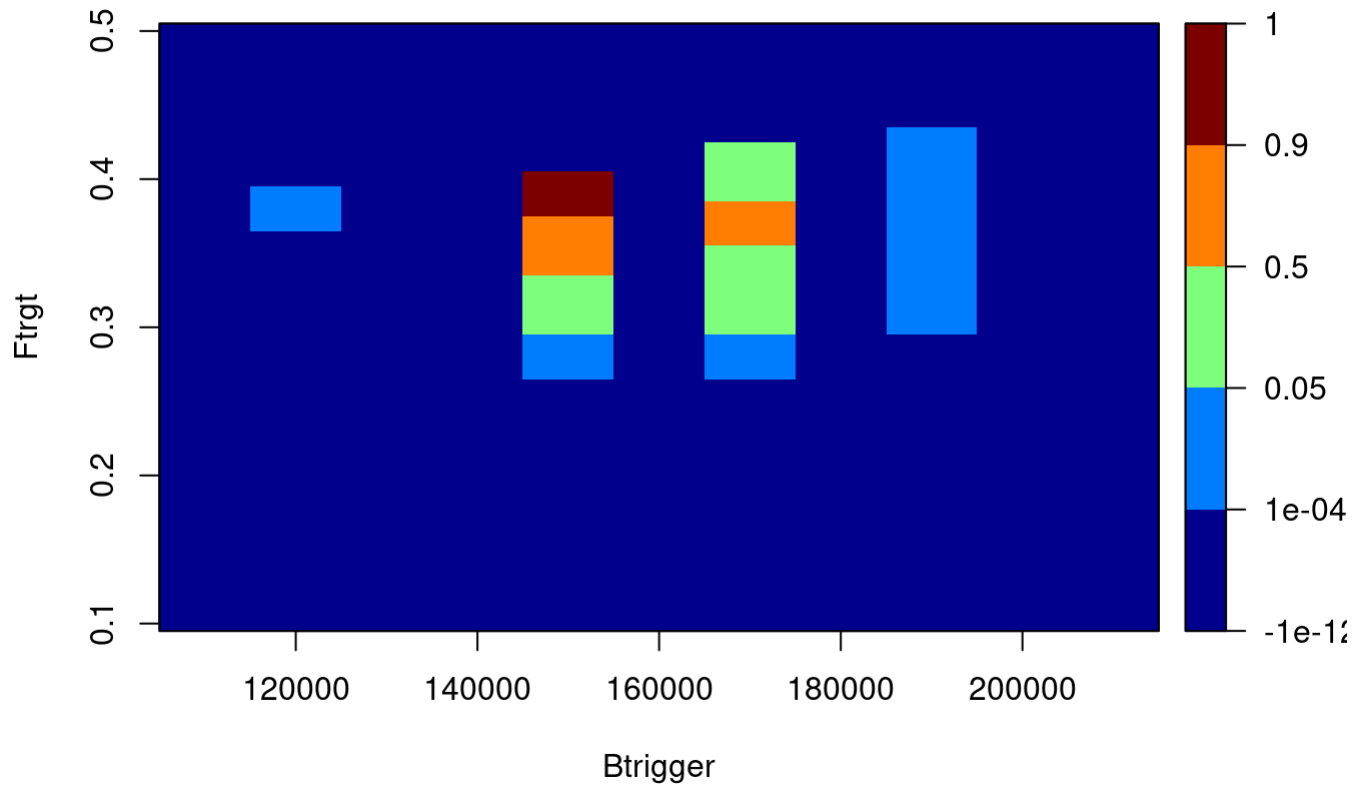
```
Joining with `by = join_by(Ftrgt, Btrigger)`
```

Plausible points remaining: 258

Current maximum 54596.5

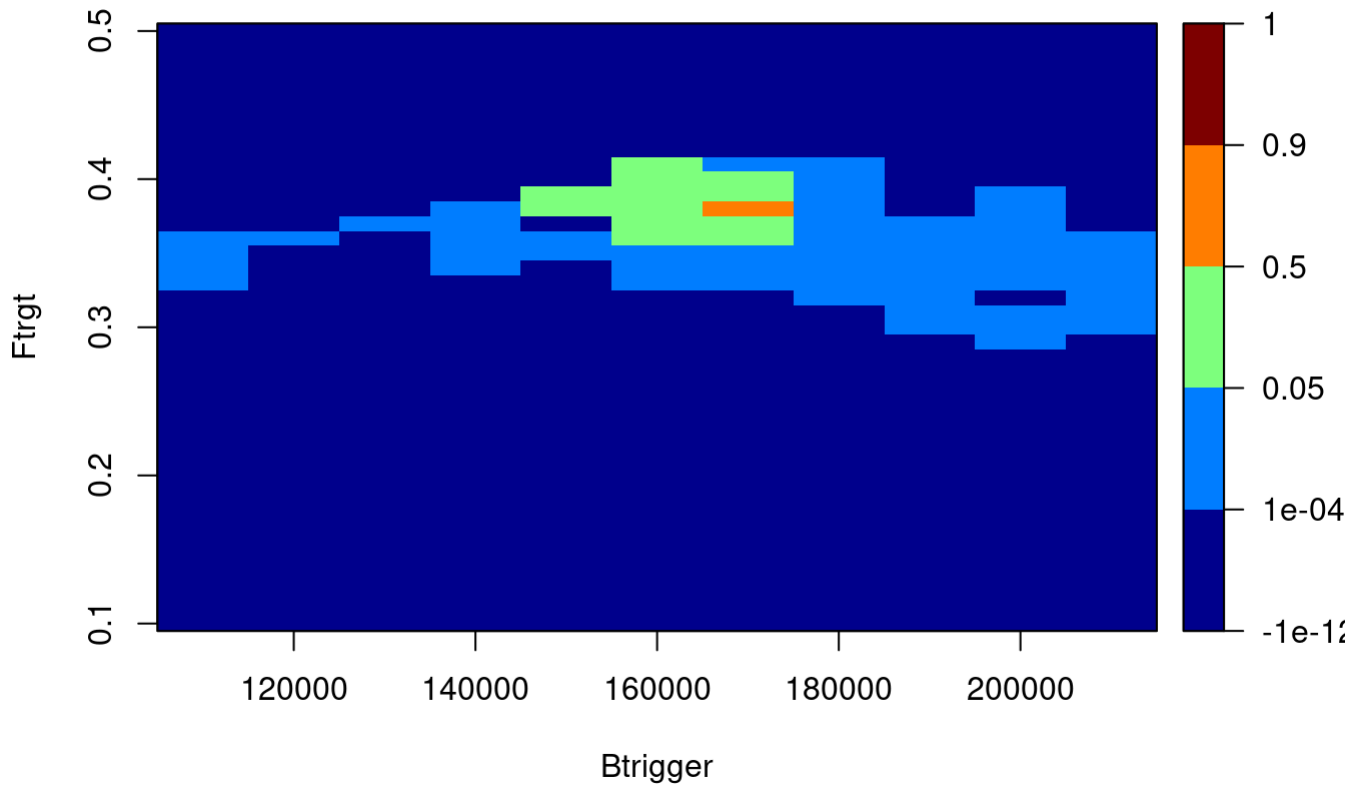
Round 2

Unevaluated candidates with EI > 0: 257



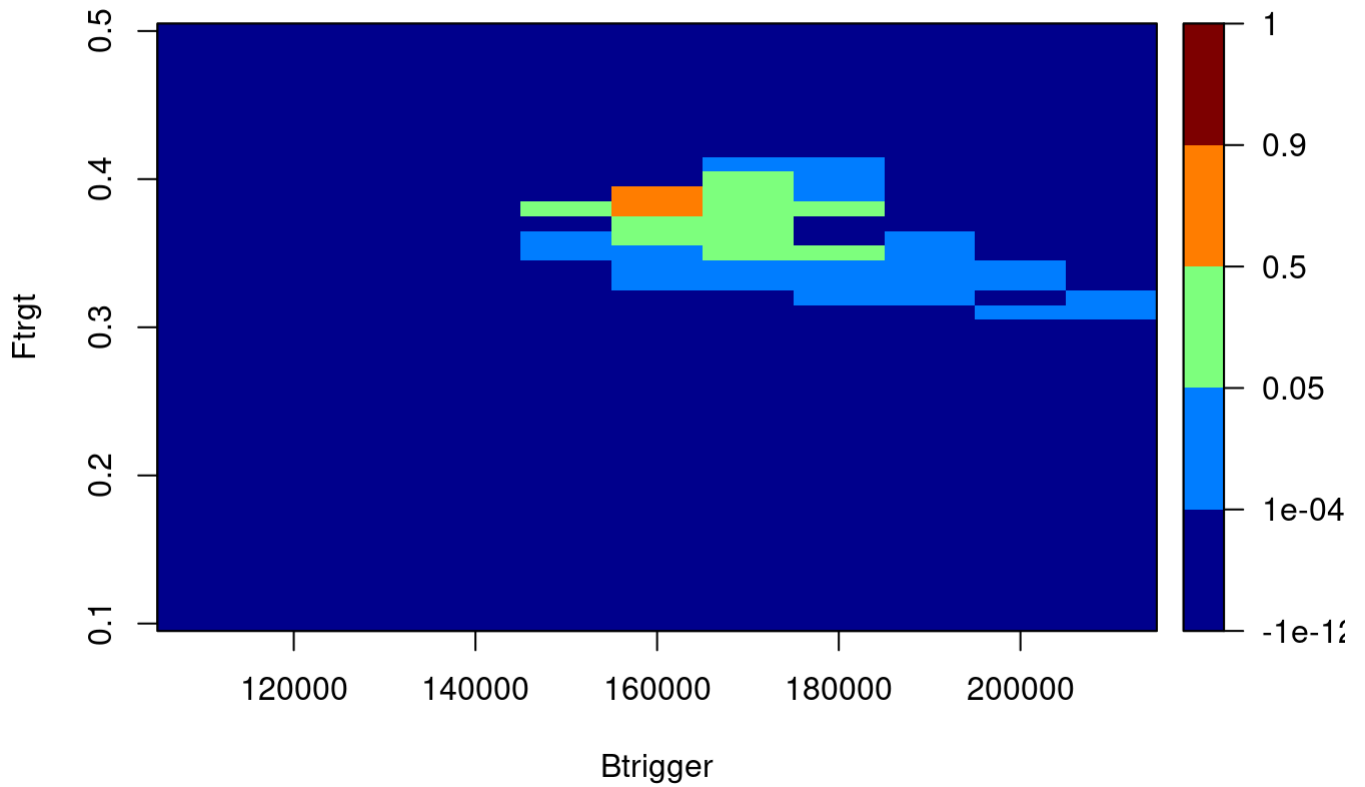
Plausible points remaining: 47
Best catch so far: 54596.5

Round 3
Unevaluated candidates with $EI > 0$: 46



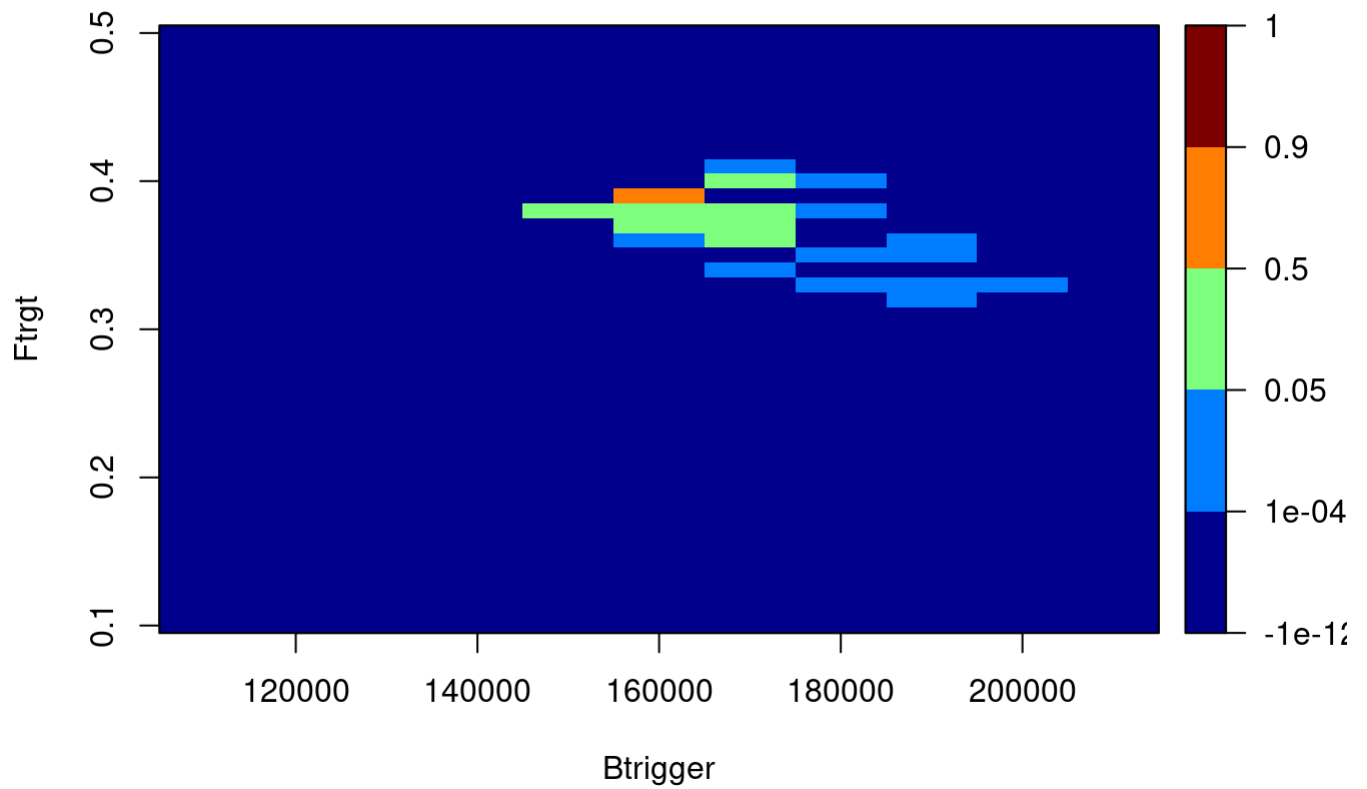
Plausible points remaining: 68
Best catch so far: 54596.5

Round 4
Unevaluated candidates with $EI > 0$: 67



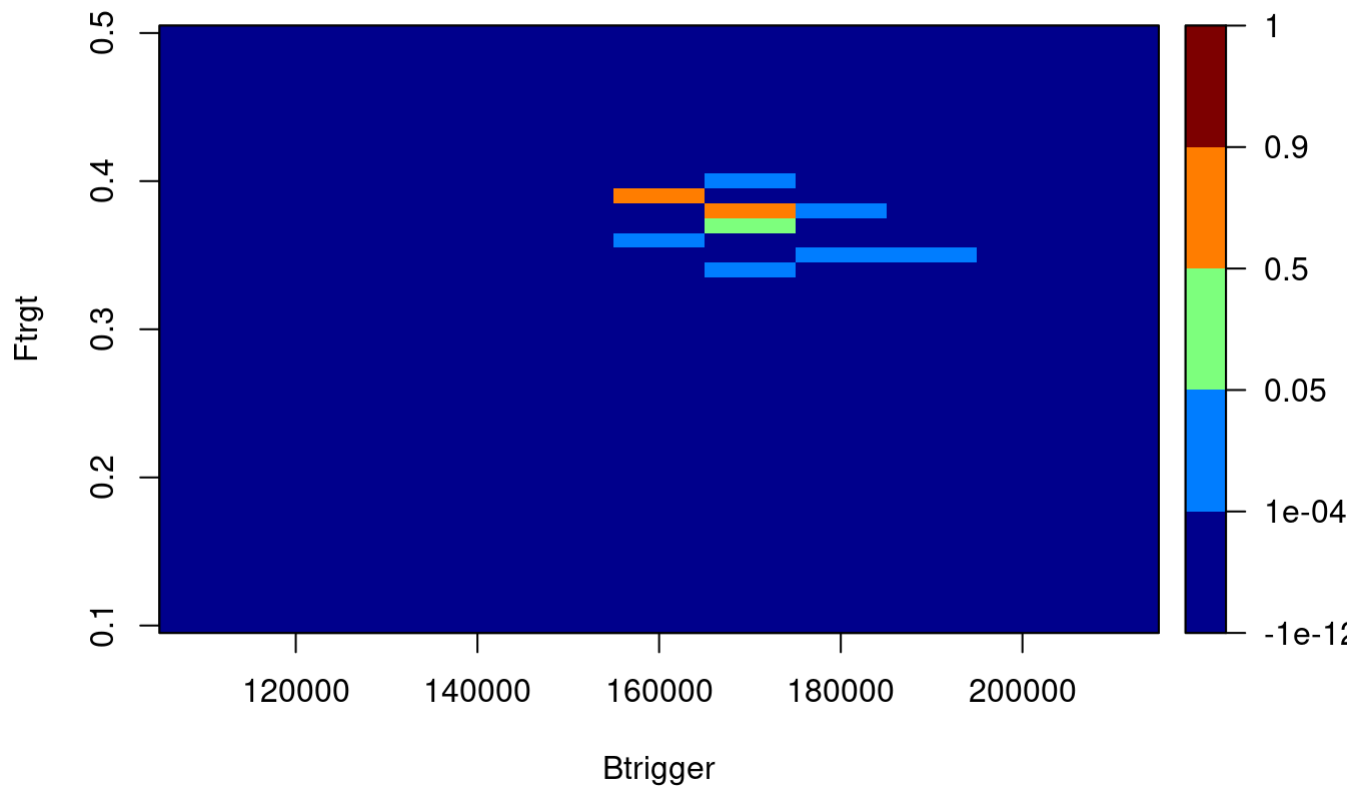
Plausible points remaining: 37
Best catch so far: 54596.5

Round 5
Unevaluated candidates with $EI > 0$: 36



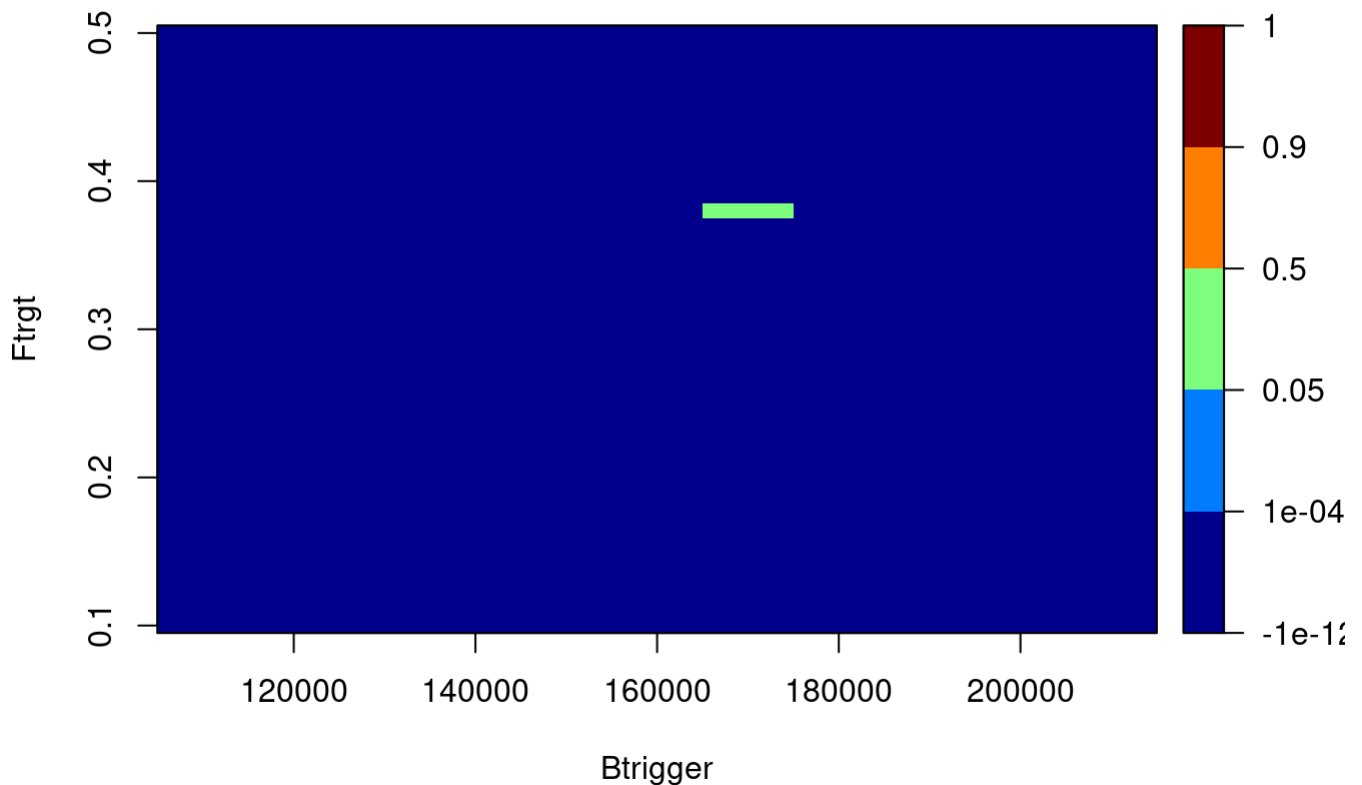
Plausible points remaining: 20
Best catch so far: 54596.5

Round 6
Unevaluated candidates with EI > 0: 19



Plausible points remaining: 9
Best catch so far: 54596.5

Round 7
Unevaluated candidates with $EI > 0$: 8



Plausible points remaining: 1
Best catch so far: 54596.5

Round 8
No unevaluated candidates with positive EI. Stopping at round 8

OPTIMIZATION COMPLETE

Completed 7 rounds

Total evaluations: 56

Optimal parameters:
Ftarget Btrigger
275 0.38 170000

Looped version of case_study8.R with Augmented Expected Improvement

This is very similar to EI and the only change we make is to add an augmentation factor to help deal with very noisy observations:

```
{r}  
# Augmentation factor to handle noise
```

Then we get the whole augmented expected improvement function as:

Looped ver of case_study8.R with Knowledge Gradient

```
dat <- data.frame(
  Ftrgt =c(0.1,0.1,0.1,0.1,0.1,0.1,0.1,0.1,0.1,0.1,0.1,0.11,0.11,0.11,0.11,0.11,0.11,0
  Btrigger =c(110000,120000,130000,140000,150000,160000,170000,180000,190000,210000,2e
  catch_median_long =c(34965,34973,34989.5,34990.5,35005,35005.5,35015,35019,35047.5,3
  risk1_full =c(0.01035,0.01025,0.01015,0.01015,0.0101,0.01005,0.01005,0.01,0.00995,0.
)

rescale_Her <- function(runs,dat){
  # Rescale Ftarget and Btrigger to [0,1] using ranges from `dat`.
```

```

# This makes optimisation / GP fitting numerically more stable.
ret <- runs
minF <- min(dat$Ftarget)
rangeF <- diff(range(dat$Ftarget))
ret$Ftarget <- (ret$Ftarget - minF)/rangeF
minB <- min(dat$Btrigger)
rangeB <- diff(range(dat$Btrigger))
ret$Btrigger <- (ret$Btrigger - minB)/rangeB
return(ret)
}

unrescale_Her <- function(runs, dat){
  # Undo the rescaling performed by `rescale_Her` to recover original units.
  ret <- runs
  minF <- min(dat$Ftarget)
  rangeF <- diff(range(dat$Ftarget))
  ret$Ftarget <- ret$Ftarget*rangeF + minF
  minB <- min(dat$Btrigger)
  rangeB <- diff(range(dat$Btrigger))
  ret$Btrigger <- ret$Btrigger*rangeB + minB
  return(ret)
}

library(DiceKriging)
library(dplyr)
library(plot3D)

cov_exp <- function(X1, X2, theta, sigma2) {
  n1 <- nrow(X1)
  n2 <- nrow(X2)
  # pairwise difference weighted by theta
  D <- array(0, dim = c(n1, n2))
  for (j in seq_along(theta)) {
    D <- D + theta[j] * abs(outer(X1[, j], X2[, j], "-"))
  }
  sigma2 * exp(-D)
}

knowledge_gradient_sim <- function(mu, sigma, model, obs_noise_var = 0, nsim = 100, pro
{
  X_pred <- dat[, c("Ftrgt", "Btrigger")]
  cov_grid <- cov_exp(X_pred, X_pred, theta = model@covariance@range.val, sigma2 = m
  m <- length(mu)
  var <- sigma^2
  # Current best mean catch
  mu_best <- max(mu)
  kg <- numeric(m)

  # Loop over candidate points
  for (i in seq_len(m)) {
    # set knowledge gradient to 0 for any points with a predicted risk that is
    if (pred_risk[i] < eps) {

```

```

        kg[i] <- 0
      next
    }

    mu_i <- mu[i]
    sigma_i <- sqrt(var[i] + obs_noise_var)
    # nsim simulated observations - using rnorm to sample from a normal distribution
    # to model the catch, which is assumed to be normally distributed
    y_sim <- rnorm(nsim, mu_i, sigma_i)
    # the covariance between every point in the grid and the point x_i
    cov_xp_xi <- cov_grid[, i]
    # denominator term in the KG update formula
    denom <- var[i] + obs_noise_var
    # For each simulated y, compute updated max(mu)
    max_after <- numeric(nsim)
    for (s in seq_len(nsim)) {
      # says what would the new maximum mu be if we observed this simulated y
      # by implementing the standard formula for this in GP posterior updating
      # This evaluates the posterior mean for every point in the space, updated
      # to the evaluated point by using the cov matrix
      mu_new <- mu + cov_xp_xi * (y_sim[s] - mu_i) / denom
      # takes this new maximum mu into a vector for later averaging
      max_after[s] <- max(mu_new)
    }
    # Computes expected increase in the maximum posterior mean, mu
    # higher values mean we're getting better knowledge as to where and what the target is
    kg[i] <- mean(max_after - mu_best)
  }

  # Returns the vector of knowledge gradient values for each point in the design space
  kg
}

# Objective function - takes candidate points and returns their evaluated metrics
objective_func <- function(cand_points, lookup_data = dat) {
  # cand_points should have columns: Ftrgt, Btrigger
  # Returns: data frame with Ftrgt, Btrigger, catch_median_long, risk1_full

  evaluated <- left_join(cand_points, lookup_data, by = c("Ftrgt", "Btrigger"))

  # Select and rename to standard output format
  result <- data.frame(
    Ftarget = evaluated$Ftrgt,
    Btrigger = evaluated$Btrigger,
    C_long = evaluated$catch_median_long,
    risk3_long = evaluated$risk1_full
  )

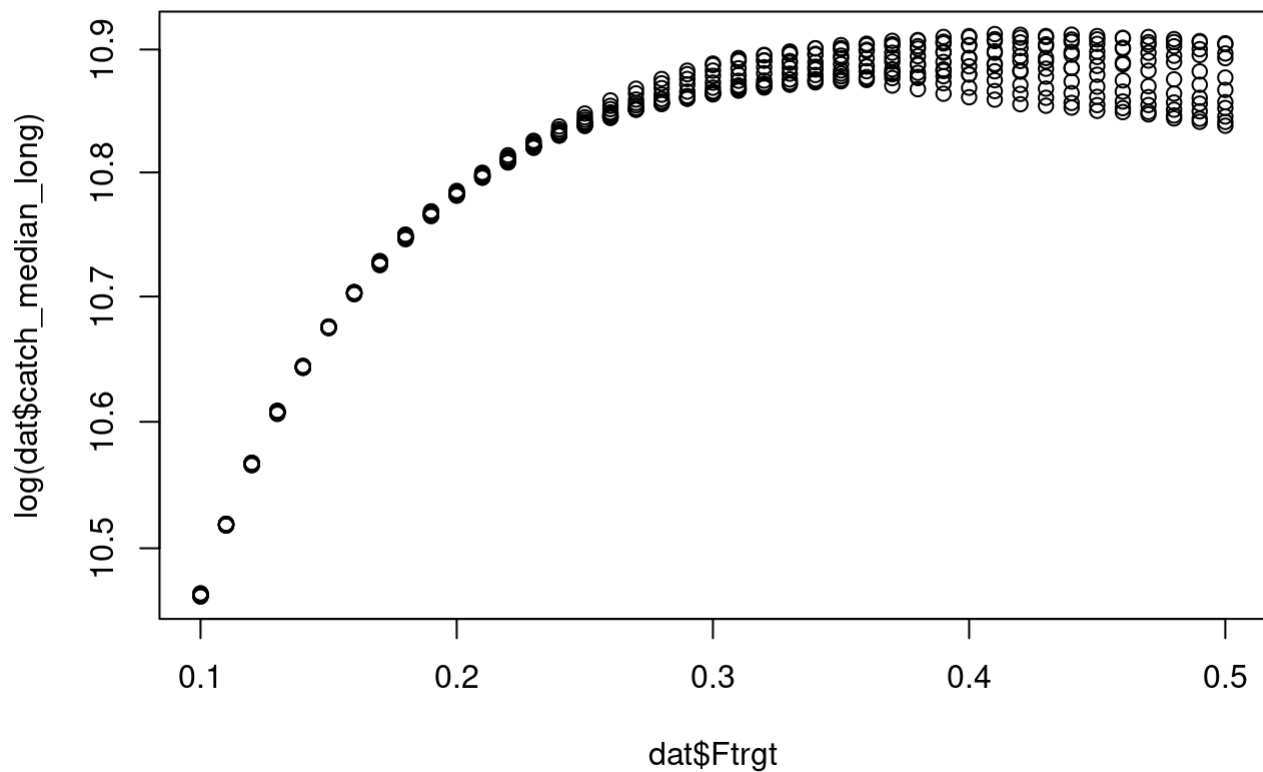
  names(result) <- c("Ftarget", "Btrigger", "C_long", "risk3_long")

  return(result)
}

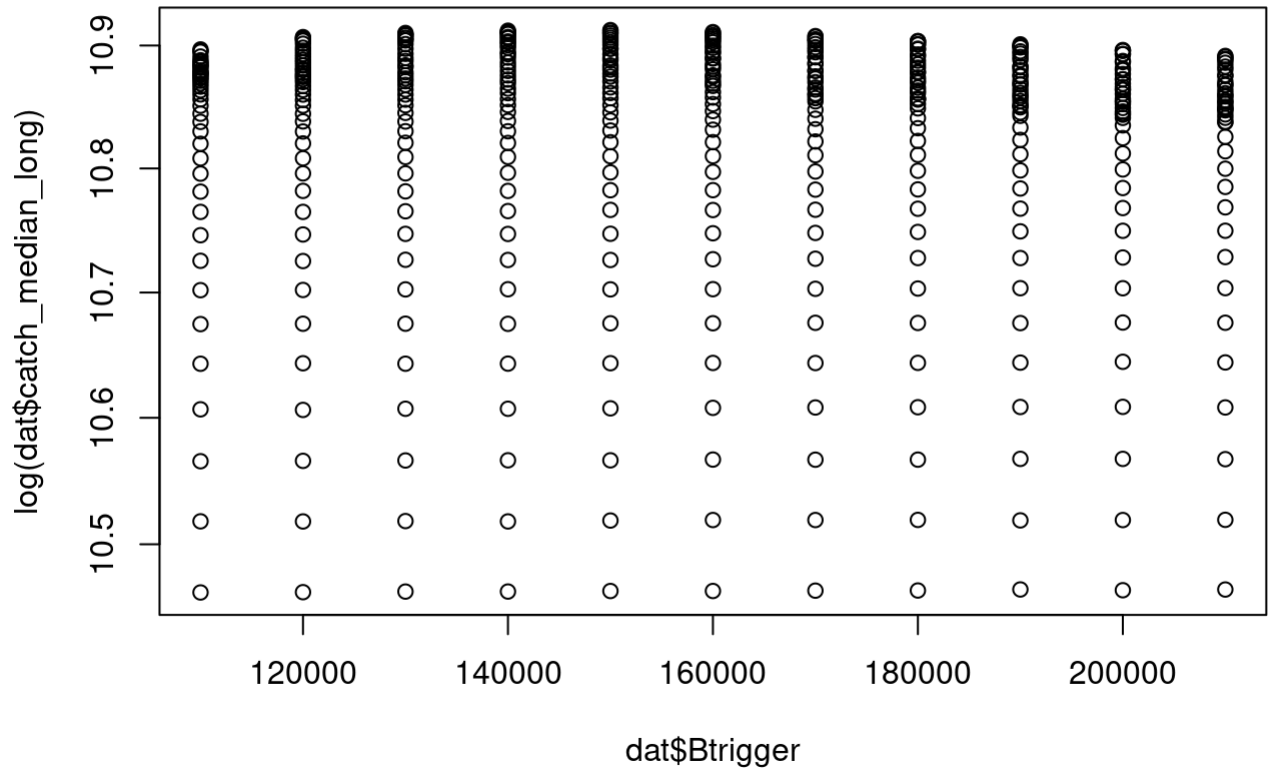
# Use a logarithmic y-axis for the plot, i.e. log="y" tells the plot to display the y-axis on a log scale

```

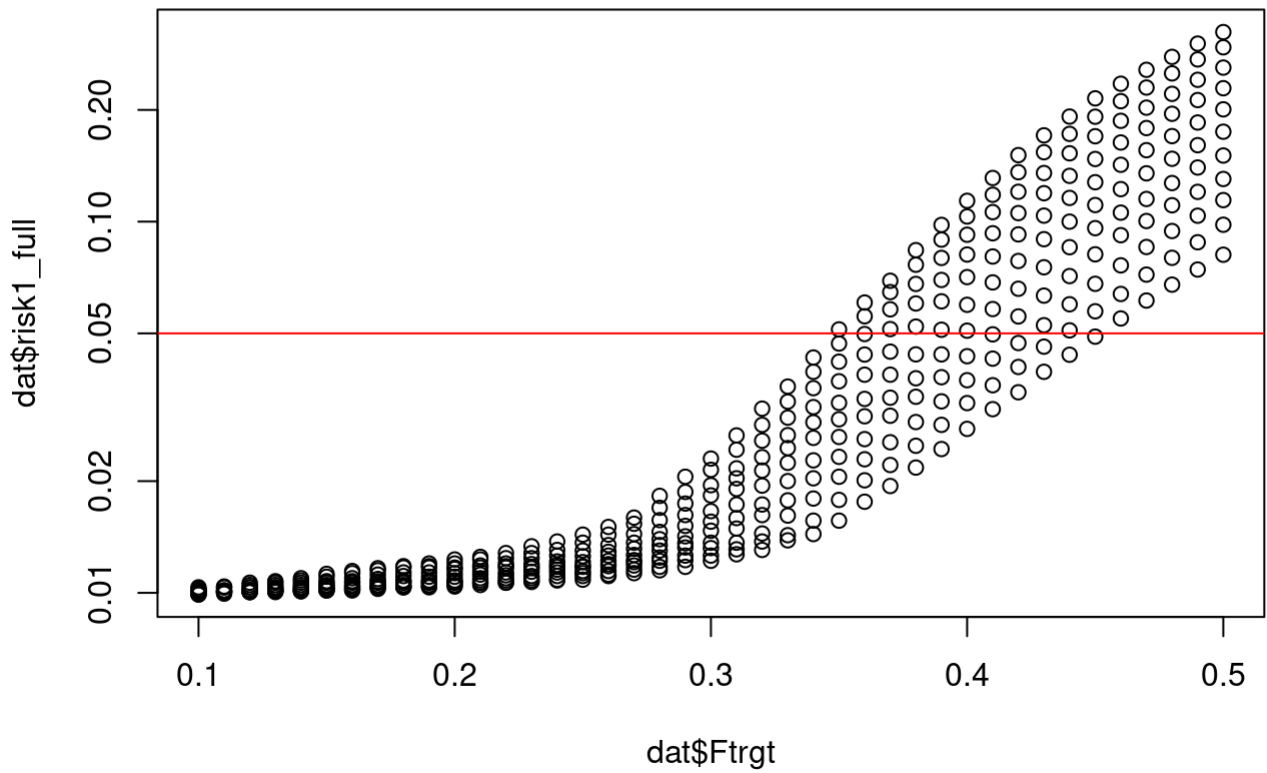
```
#CoPilot suggested this could result in a double transformation in lines 62 and 63, wh:  
plot(dat$Ftrgt, log(dat$catch_median_long), log="y")
```



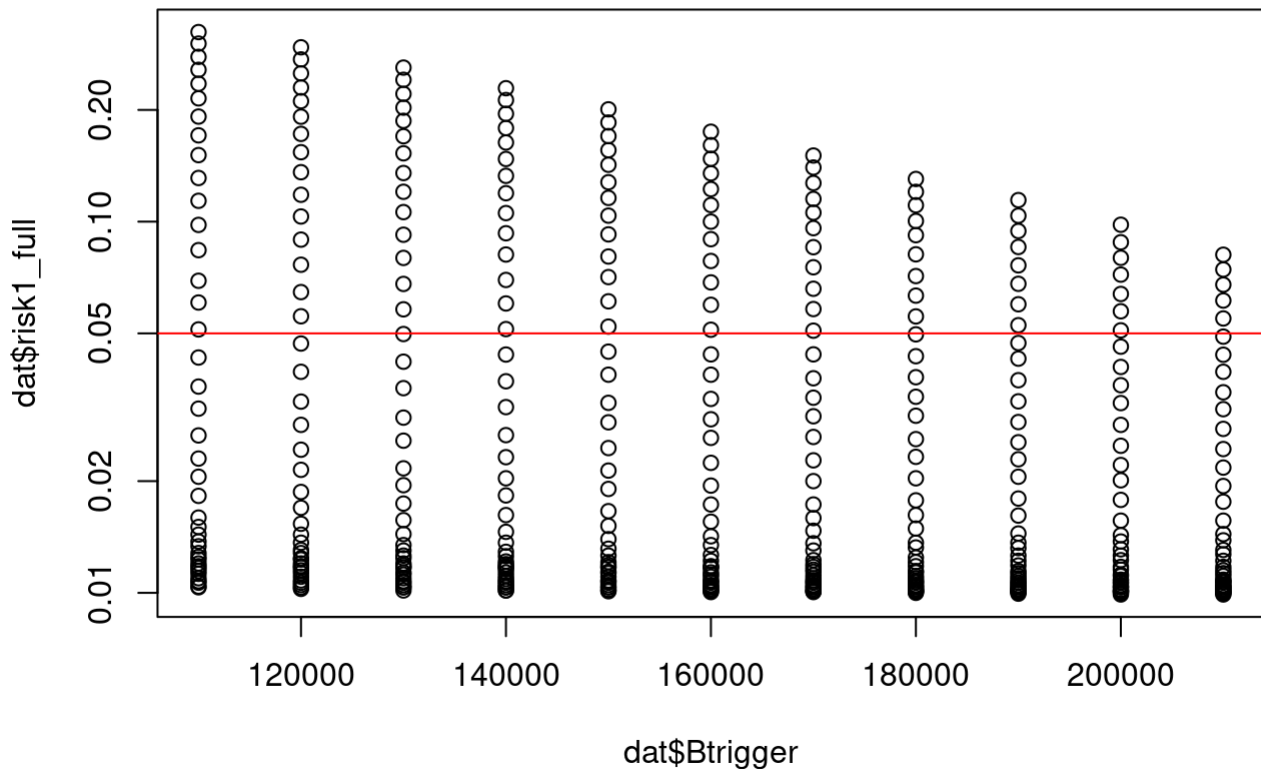
```
plot(dat$Btrigger, log(dat$catch_median_long), log="y")
```



```
plot(dat$Ftrgt, dat$risk1_full, log="y")  
abline(h=0.05, col="red")
```



```
plot(dat$Btrigger, dat$risk1_full, log="y")  
abline(h=0.05, col="red")
```



```
# Checks length of Ftrgt and Btrigger sets
length(unique(dat$Ftrgt))
```

```
[1] 41
```

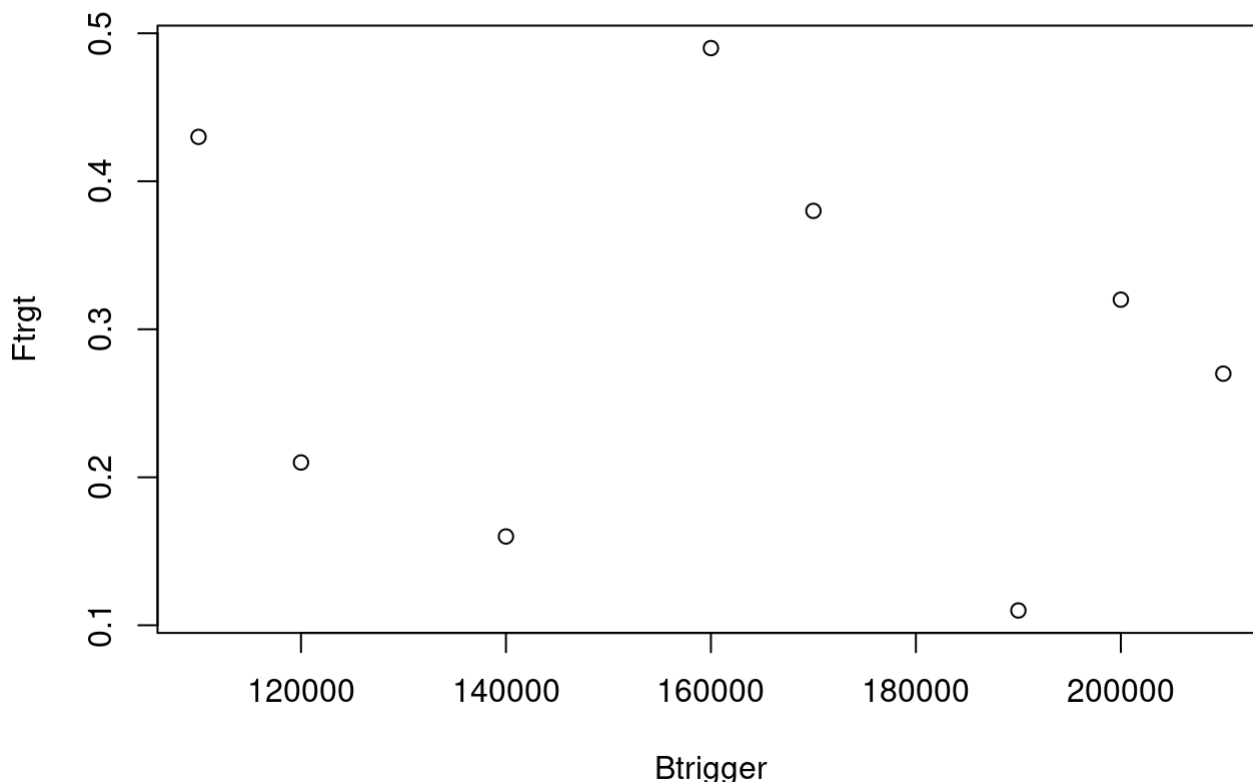
```
length(unique(dat$Btrigger))
```

```
[1] 11
```

```
# Set Random Number Generator seed for reproducible random sampling.
# Copilot says I could change this to explore sensitivity of the process to the initial
set.seed(18)
```

```
#Round 1
```

```
# A space filling algorithm (seems simply chooses evenly spaced points) is used in the
# as detailed in Section 3 Case Study in the paper
round1 <- data.frame(Ftrgt=sample(unique(dat$Ftrgt)[floor(seq(2,40,l=8))]),Btrigger=sample(unique(dat$Btrigger)),
plot(round1[,2:1])
```

```
# Choose an initial small set of design points and fit GP emulators for log-catch and
Ftarget <- sort(unique(dat$Ftrgt))
Btrigger <- sort(unique(dat$Btrigger))
dat1 <- data.frame(expand.grid(Ftarget,Btrigger))
names(dat1) <- c("Ftarget","Btrigger")

gridd <- dat1[,c("Ftarget","Btrigger")]
gridd<- rescale_Her(gridd[order(gridd$Ftarget,gridd$Btrigger),],dat=dat1)

dat_run <- left_join(round1,dat)
```

Joining with `by = join_by(Ftrgt, Btrigger)`

```
names(dat_run) <- c("Ftarget","Btrigger","C_long","risk3_long")
runs <- rescale_Her(dat_run,dat=dat1)

# build the emulator for median catch

# res_cat is the log of observed median catch at the design runs. The GP
# on line 109 models this response using polynomial terms in the formula.
res_cat <- log(runs$C_long)

# Looks like it is using maximum likelihood estimation below and mentions this nugget
# CoPilot says "nugget: a tiny diagonal noise term for numerical stability."

# CoPilot also said "covtype = "exp": exponential correlation function (gives a less s
```

```
# which could maybe be something to follow up on

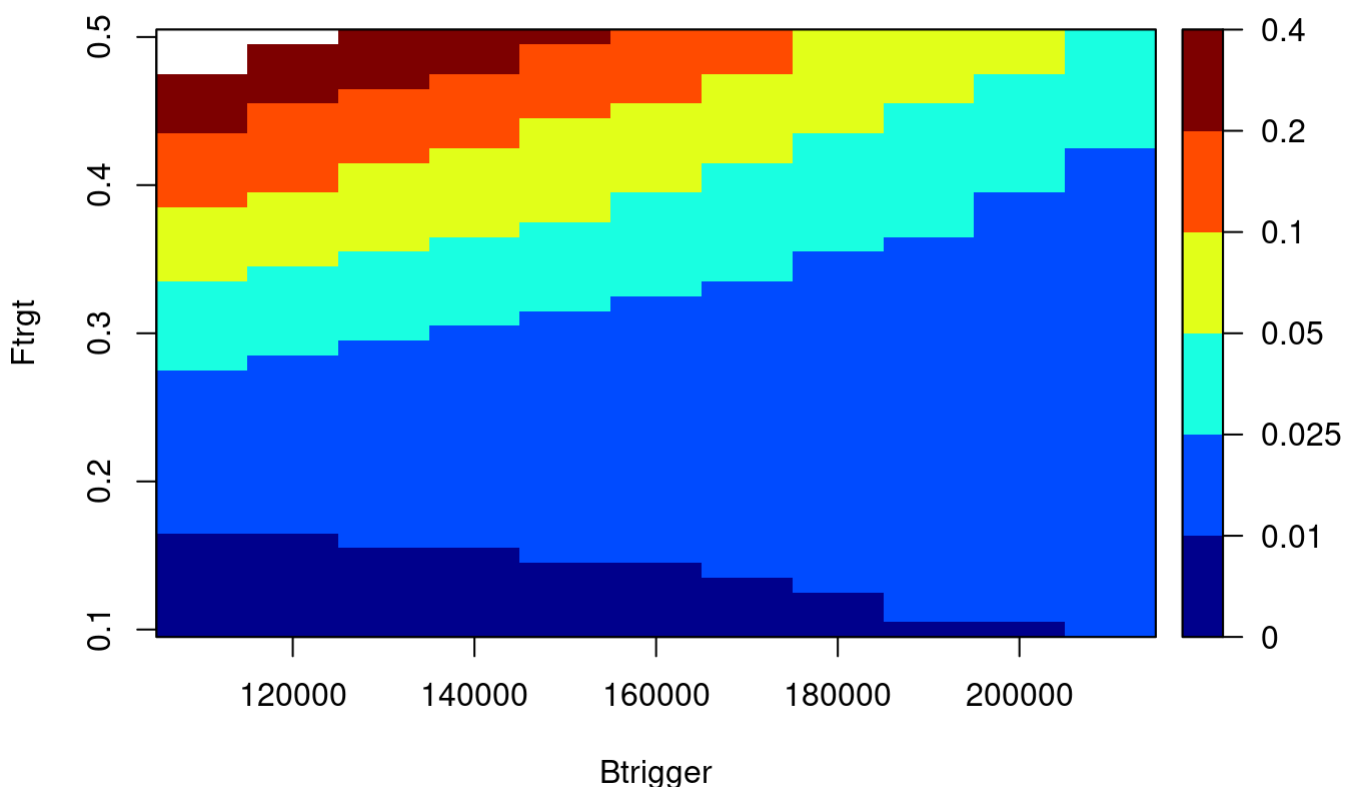
# Also has covariance type which is important for Gaussian Processes

# Below carries out the Kriging process for the two separate emulators, as detailed in
invisible(capture.output(
gp_cat <- km(~.^2,design=runs[,c("Ftarget", "Btrigger")],estim.method="MLE",response = 1
))
res_risk <- log(runs$risk3_long)

invisible(capture.output(
gp_risk <- km(~.^2,design=runs[,c("Ftarget", "Btrigger")],estim.method="MLE",response = 1
))

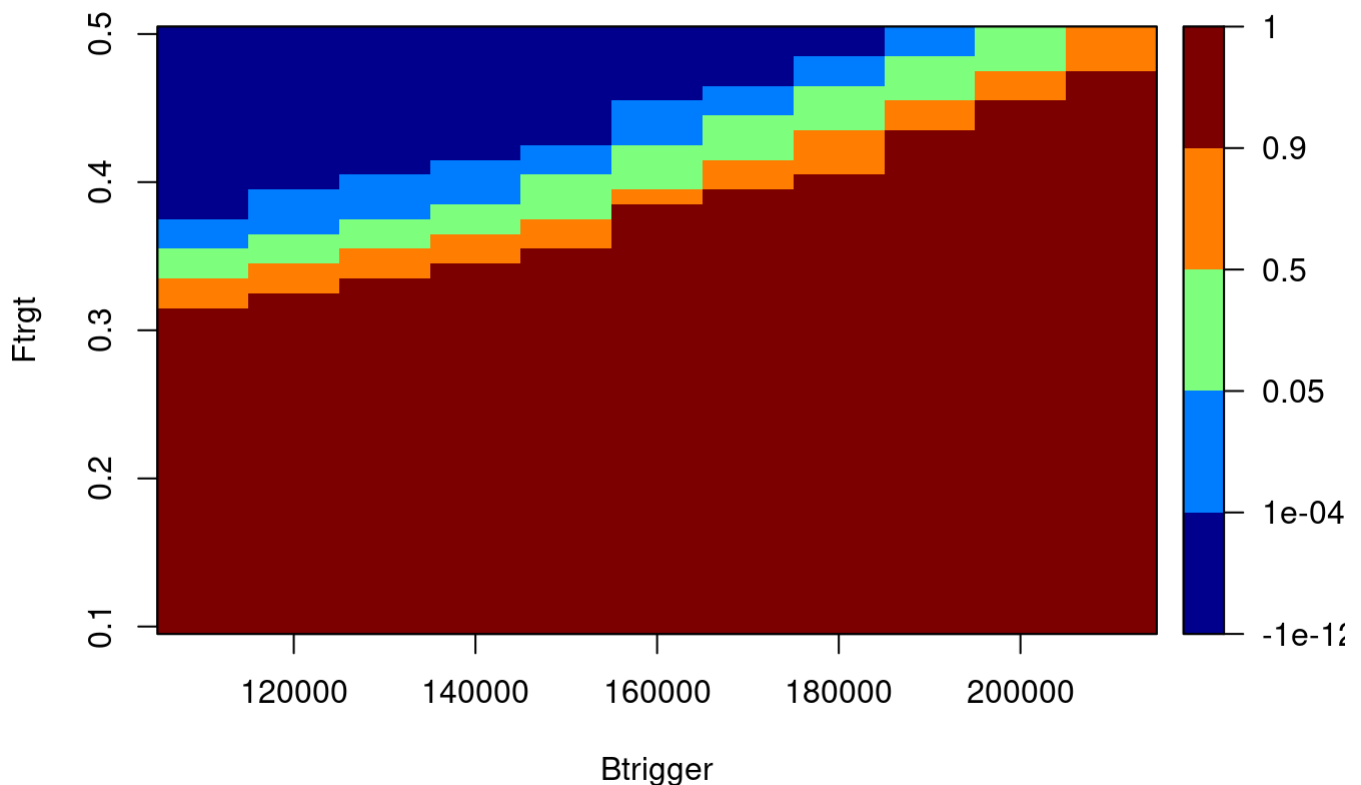
# Gets the Gaussian Process to produce a prediction for risk at every point in gridd
# gridd is the rescaled grid of Ftrgt and Btrigger
#This has a mean and standard deviation as we are unsure of the exact risk
pred_risk1_g <- predict(gp_risk,newdata=gridd,type="SK")

# Estimate median predicted risk
med_risk1 <- exp(pred_risk1_g$mean)
# plot it
image2D(matrix(med_risk1,nrow=11),breaks=c(0,0.01,0.025,0.05,0.1,0.2,0.4),y=sort(unique(runs$Ftarget)),x=sort(unique(runs$Btrigger))))
```



```
# now lets look at the probability that the risk is less than or equal to 0.05
prisk <- pnorm(log(0.05),pred_risk1_g$mean,pred_risk1_g$sd+1e-12)
```

```
# plot it
image2D(matrix(prisk,nrow=11),y=sort(unique(dat$Ftrgt)),x=sort(unique(dat$Btrigger)),x.lim=range(Btrigger),y.lim=range(Ftrgt))
```



```
# Predicts mean and uncertainty for log(catch) at each parameter combination in gridd
# SK means simple kriging
pred_cat_g <- predict(gp_cat,newdata=gridd,type="SK")

# Best catch observed so far where risk is below 0.05
current_max <- max(runs$C_long[runs$risk3_long < 0.05])

#Convert to max1 log scale as emulator trained on log(catch)
# pcat1 is the probability that the catch is less than or equal to max1 (the best safe
pcat1 <- pnorm(log(current_max),pred_cat_g$mean,pred_cat_g$sd+1e-12)

# mark which points in gridd are still good candidates
eps <- 1e-4
possible <- (apply(cbind((1-pcat1) , prisk),1,min) > eps)

# collect final points - this is so we know what to do in round 2
pot_points1 <- gridd[possible,]

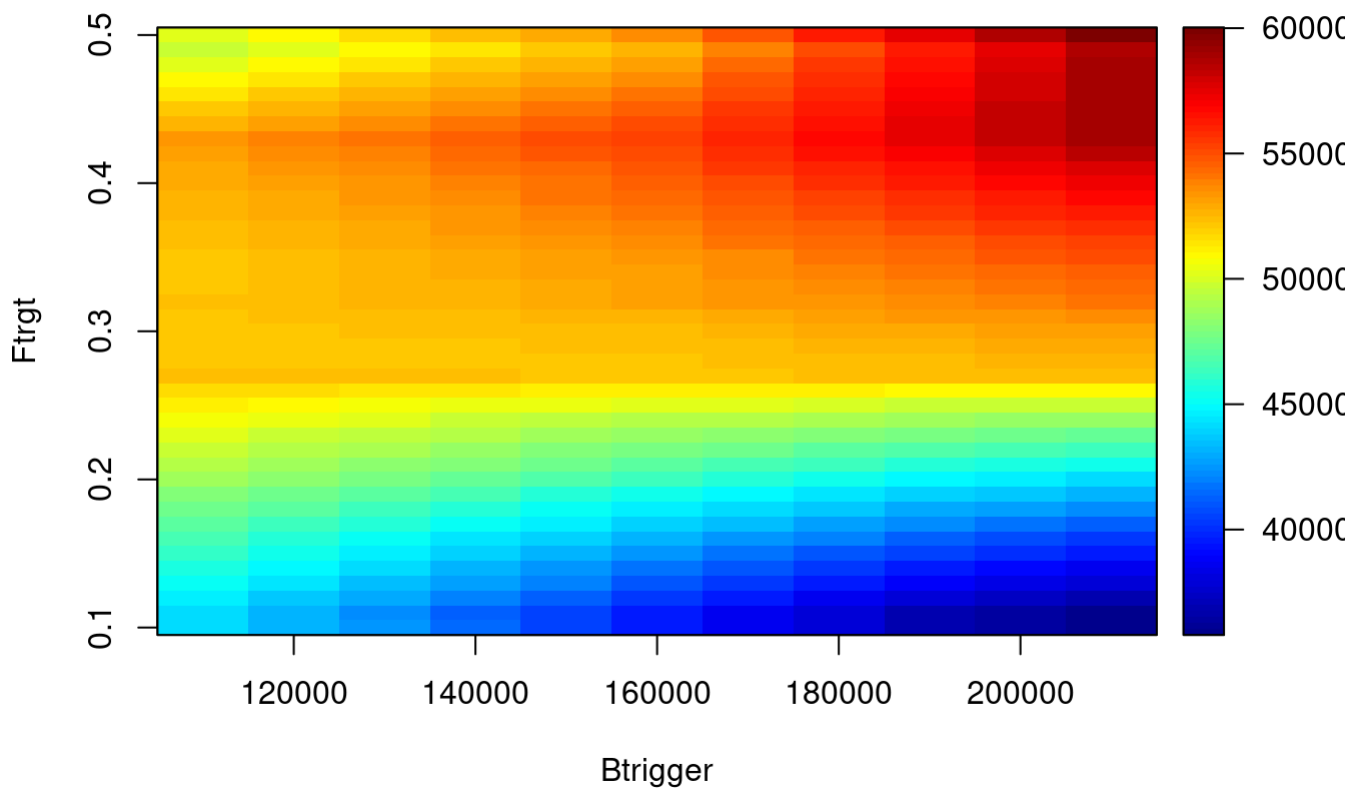
#Removes already evaluated points from those that are still possible so don't evaluate
tmp <- setdiff(pot_points1,runs[,1:2])
pot_points1 <- tmp

# getting catch out of log(catch) for each point in gridd
```

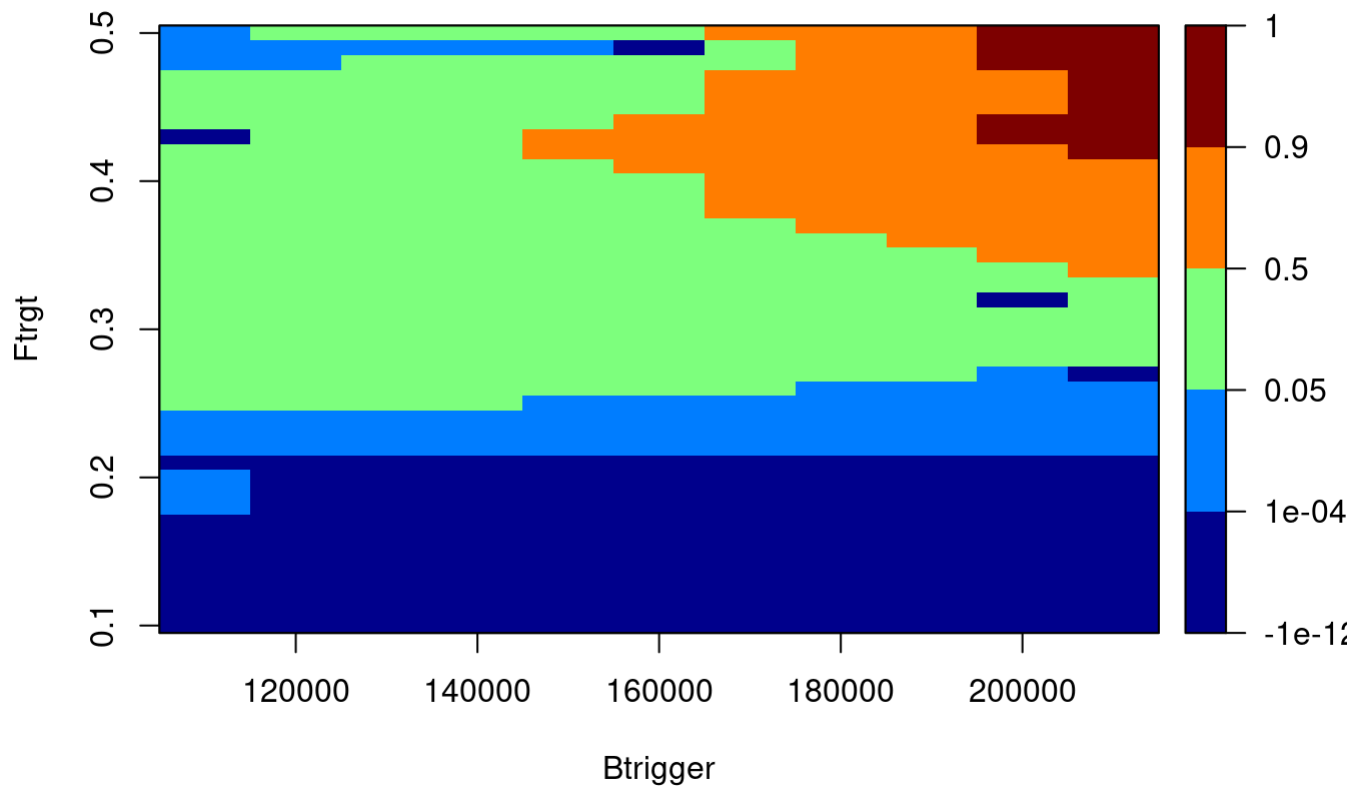
```
med_cat1 <- exp(pred_cat_g$mean)
```

```
# Below produces heat maps for round 1
```

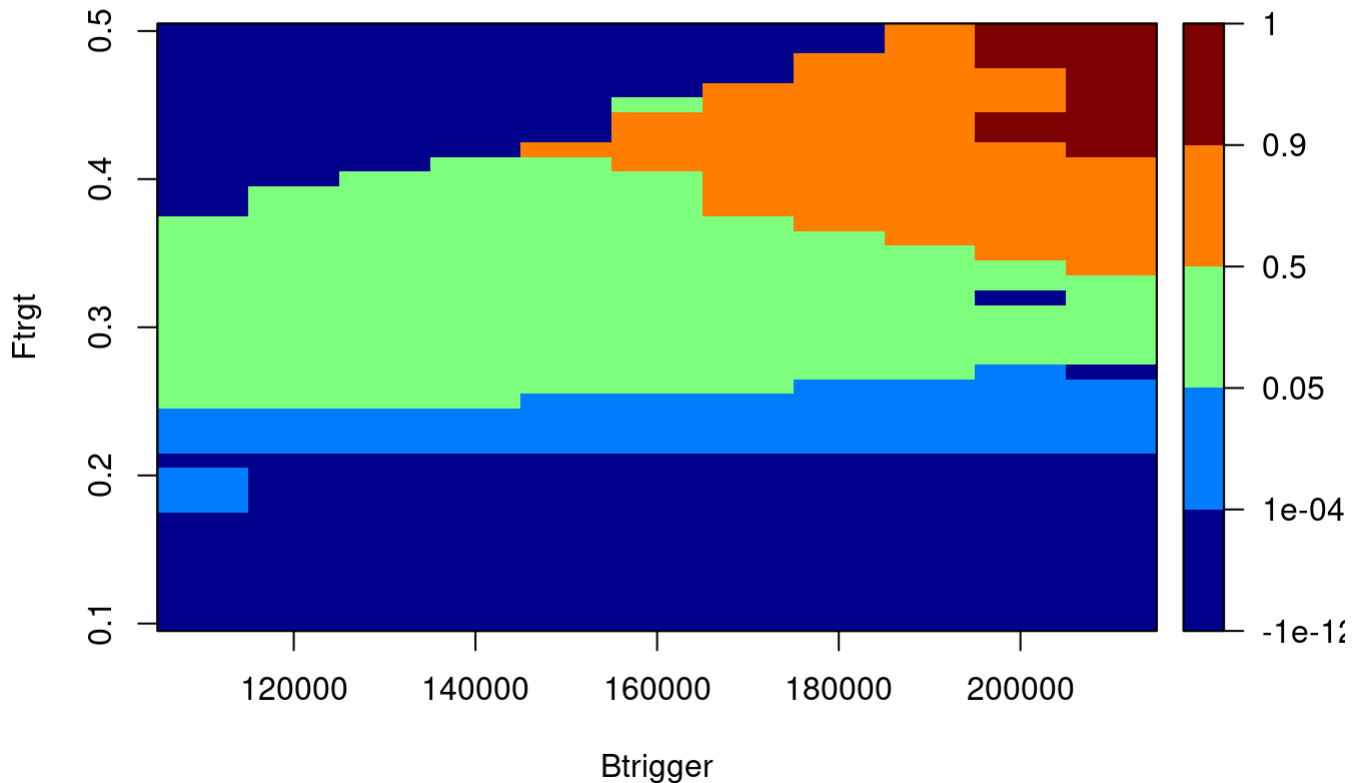
```
image2D(matrix(med_cat1,nrow=11),y=sort(unique(dat$Ftrgt)),x=sort(unique(dat$Btrigger))
```



```
image2D(matrix(1-pcat1,nrow=11),y=sort(unique(dat$Ftrgt)),x=sort(unique(dat$Btrigger)))
```



```
# Visualises region that has risk <0.05 and better catch than best evaluated so far  
image2D(matrix(possible * (1-pcat1),nrow=11),y=sort(unique(dat$Ftrgt)),x=sort(unique(d
```



```
# If no plausible points remain, stop the process
iteration <- 1
if (sum(possible) == 0) {
  stop("No plausible points remaining at round", iteration, "\n")
  ans<-unrescale_Her(pot_points1[1,],dat1)
  ans
}

cat("Plausible points remaining:", sum(possible), "\n")
```

Plausible points remaining: 258

```
cat("Current maximum", current_max)
```

Current maximum 54596.5

```
# Store all rounds
all_rounds <- round1
all_rounds$Round <- 1

# ITERATIVE ROUNDS
max_rounds <- 20
round_num <- 1

#TODO: Can I rename the variables in each round so I can clearly see the progression?
```

```

for (iteration in 2:max_rounds) {

  cat("\n Round", iteration, "\n")

  # Calculate KG
  mu <- pred_cat_g$mean
  sigma <- pred_cat_g$sd
  #TDOD: Put in correct X_pred
  ei <- knowledge_gradient_sim(mu, sigma, gp_cat, obs_noise_var = 0, nsim = 100, pred_

  # Create candidate set
  gridd_with_ei <- gridd
  gridd_with_ei$ei <- ei
  gridd_with_ei$possible <- possible

  cand <- subset(gridd_with_ei, possible == TRUE & ei > 0)

  # Create keys for filtering
  cand$key <- paste(cand$Ftarget, cand$Btrigger, sep = "_")
  runs$key <- paste(runs$Ftarget, runs$Btrigger, sep = "_")

  # Remove already evaluated points
  cand <- cand[!(cand$key %in% runs$key), ]

  # Check if candidates exhausted
  if (nrow(cand) == 0) {
    cat("No unevaluated candidates with positive EI. Stopping at round", iteration, "\n")
    break
  }

  cat("Unevaluated candidates with EI > 0:", nrow(cand), "\n")

  # Select next points
  if (nrow(cand) <= 8) {
    next_points <- cand[order(-cand$ei), c("Ftarget", "Btrigger")]
  } else {
    top_candidates <- cand[order(-cand$ei), ][1:nrow(cand), ]
    set.seed(123)
    km_result <- kmeans(top_candidates[, c("Ftarget", "Btrigger")], centers = 8)
    top_candidates$cluster <- km_result$cluster
    next_points <- do.call(rbind, lapply(split(top_candidates, top_candidates$cluster),
      function(x) {
        df[which.max(df$ei), c("Ftarget", "Btrigger", "ei")]
      }
    ))
  }

  # Unrescale and prepare for evaluation
  coords <- next_points[, c("Ftarget", "Btrigger")]
  new_points <- signif(unrescale_Her(coords, dat1), 2)
  names(new_points) <- c("Ftrgt", "Btrigger")
  new_points$Round <- iteration

  all_rounds <- rbind(all_rounds, new_points[, c("Ftrgt", "Btrigger", "Round")])

  new_round <- rbind(

```

```

    all_rounds[all_rounds$Round < iteration, c("Ftrgt", "Btrigger")],
    new_points[, c("Ftrgt", "Btrigger")]
  )

dat_run <- objective_func(new_round, lookup_data = dat)
runs <- rescale_Her(dat_run, dat = dat1)

res_cat <- log(runs$C_long)
invisible(capture.output(
gp_cat <- km(~I(log(Ftarget+0.1)^2) + I(log(Ftarget+0.1)) + I(log(Ftarget+0.1)^3) + I(log(Ftarget+0.1)^4)),
))

res_risk <- log(runs$risk3_long)
invisible(capture.output(
gp_risk <- km(~.^2, design = runs[, c("Ftarget", "Btrigger")], estim.method = "MLE",
))

pred_risk_g <- predict(gp_risk, newdata = gridd, type = "SK")
pred_cat_g <- predict(gp_cat, newdata = gridd, type = "SK")

# PLOTTING
med_risk <- exp(pred_risk_g$mean)
image2D(matrix(med_risk, nrow=11), breaks=c(0,0.01,0.025,0.05,0.1,0.2,0.4), y=sort(unique(dat$Ftrgt)))

prisk <- pnorm(log(0.05), pred_risk_g$mean, pred_risk_g$sd + 1e-12)
image2D(matrix(prisk, nrow=11), y=sort(unique(dat$Ftrgt)), x=sort(unique(dat$Btrigger)))

current_max <- max(runs$C_long[runs$risk3_long < 0.05])
pcat <- pnorm(log(current_max), pred_cat_g$mean, pred_cat_g$sd + 1e-12)

possible <- (apply(cbind((1 - pcat), prisk), 1, min) > eps)

med_cat <- exp(pred_cat_g$mean)
image2D(matrix(med_cat, nrow=11), y=sort(unique(dat$Ftrgt)), x=sort(unique(dat$Btrigger)))
image2D(matrix(1-pcat, nrow=11), y=sort(unique(dat$Ftrgt)), x=sort(unique(dat$Btrigger)))
image2D(matrix(possible * (1-pcat), nrow=11), y=sort(unique(dat$Ftrgt)), x=sort(unique(dat$Btrigger)))

#STOPPING CRITERION
if (sum(possible) == 0) {
  cat("No plausible points remaining. Stopping at round", iteration, "\n")
  break
}

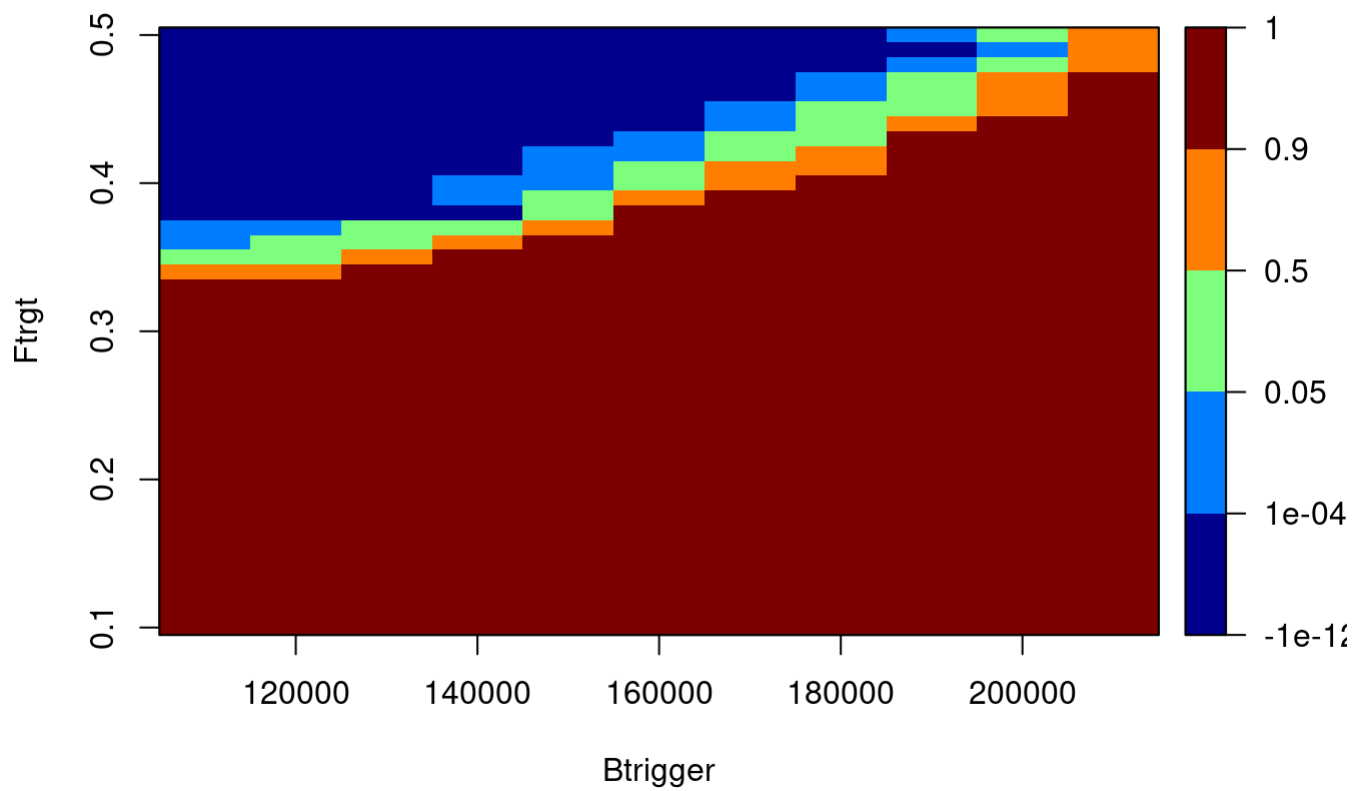
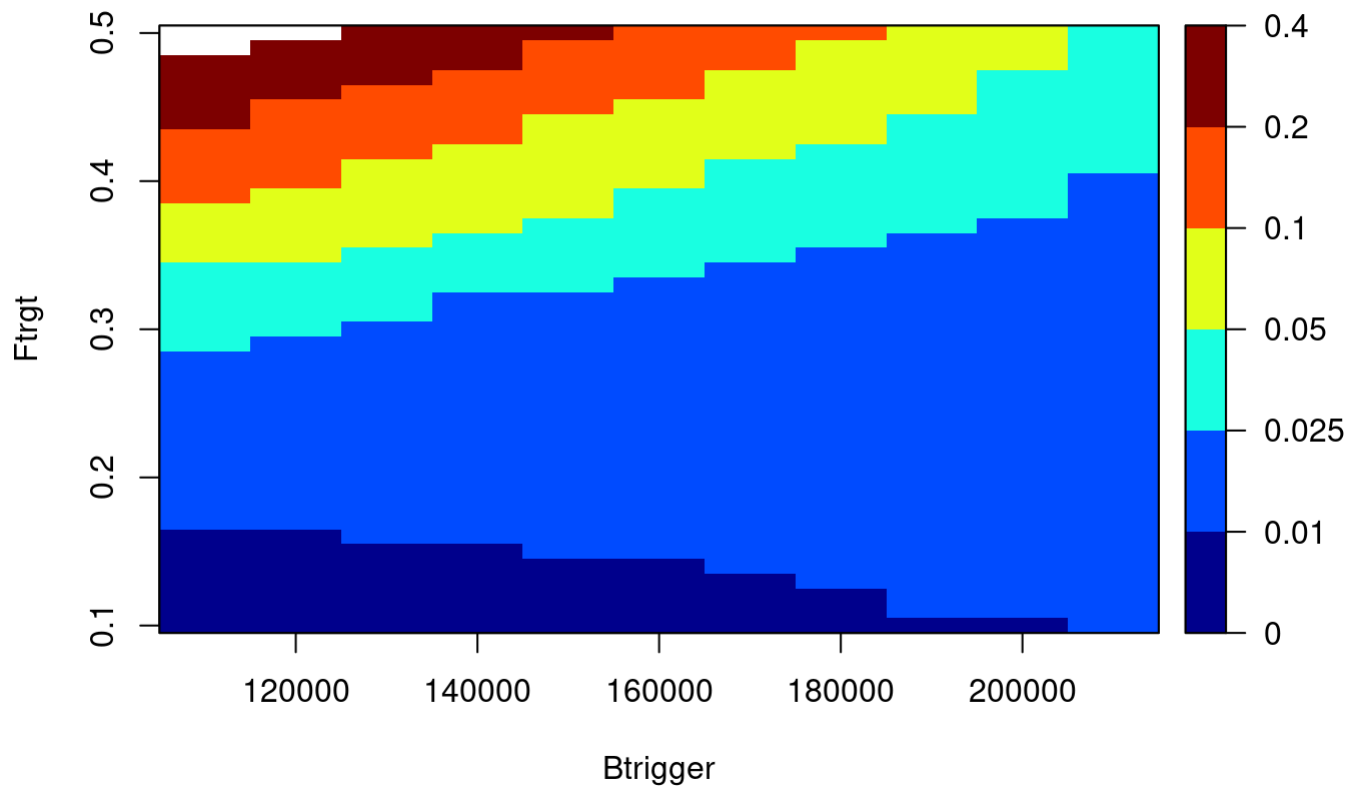
cat("Plausible points remaining:", sum(possible), "\n")
cat("Best catch so far:", current_max, "\n")

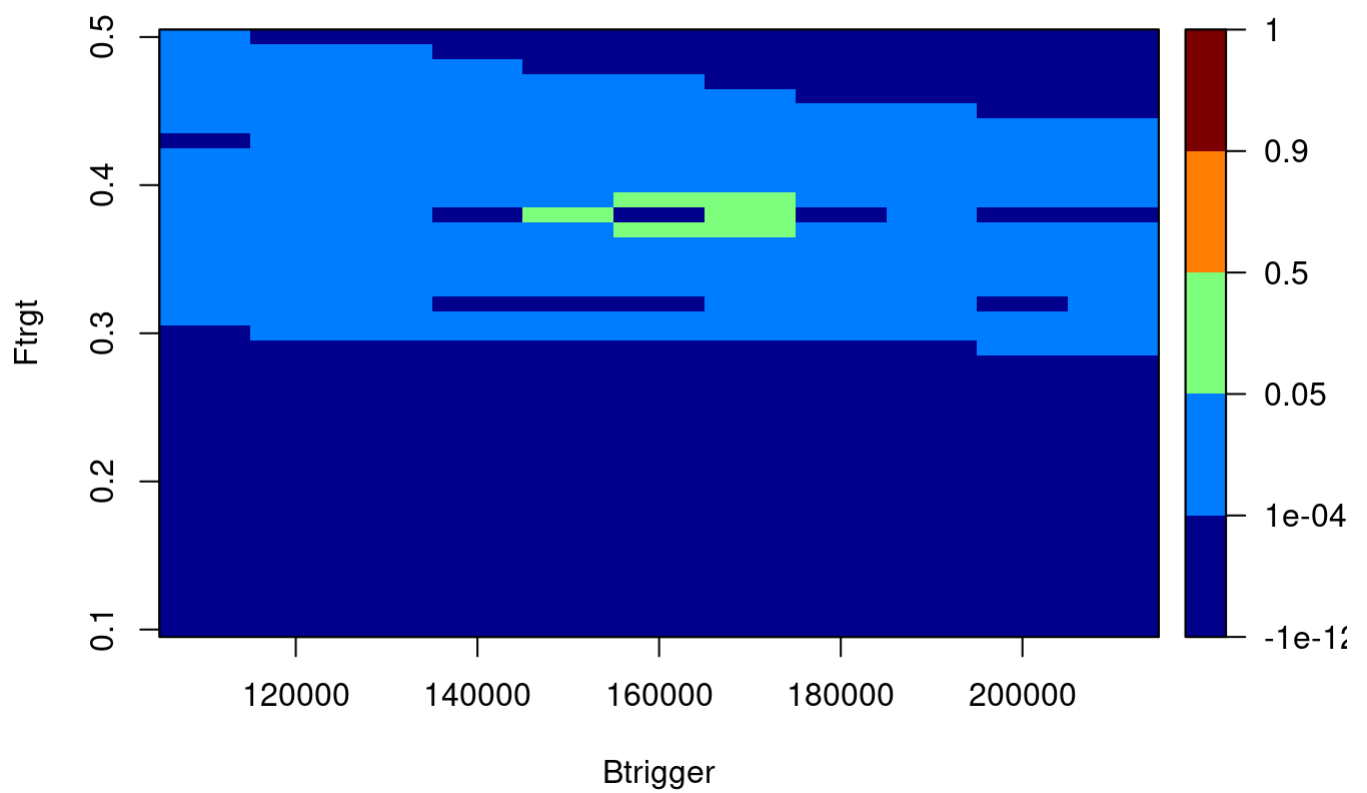
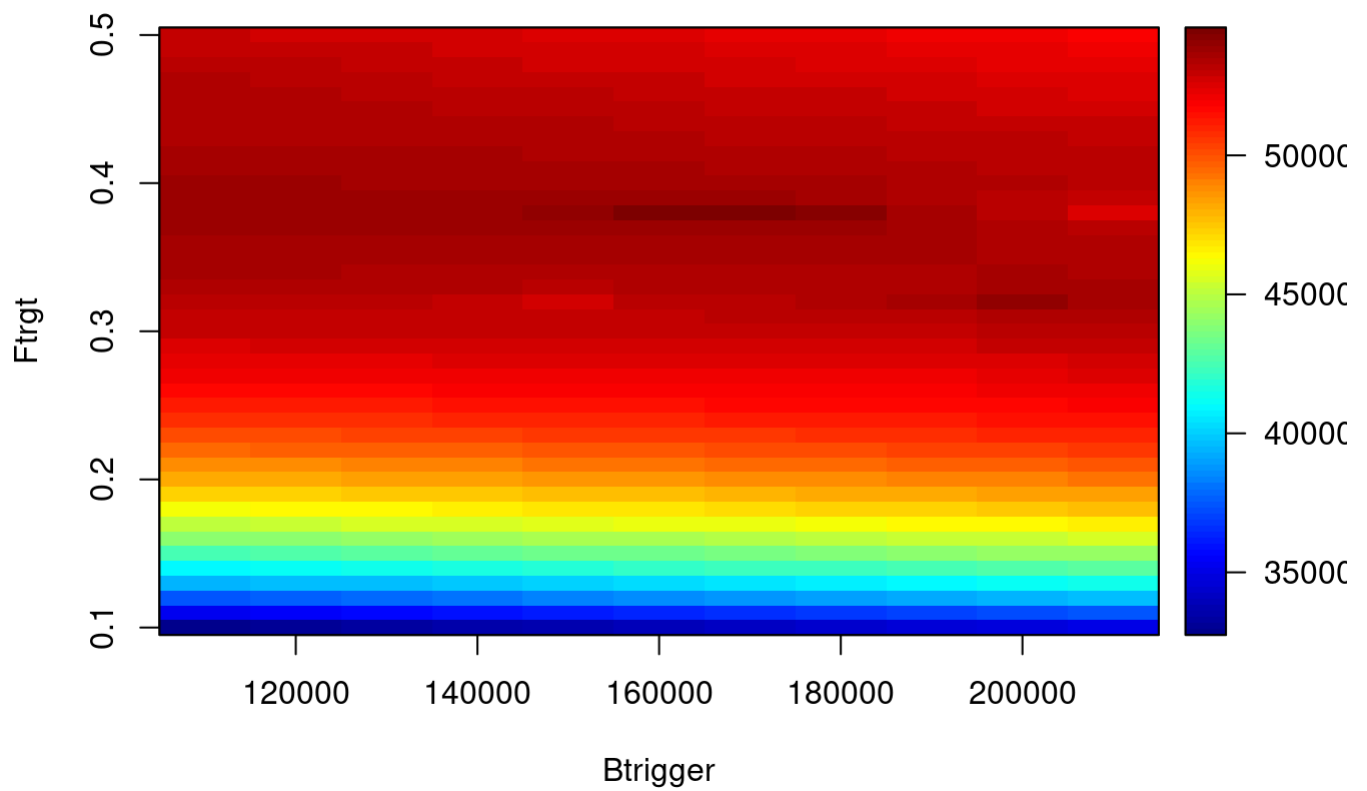
round_num <- iteration
}

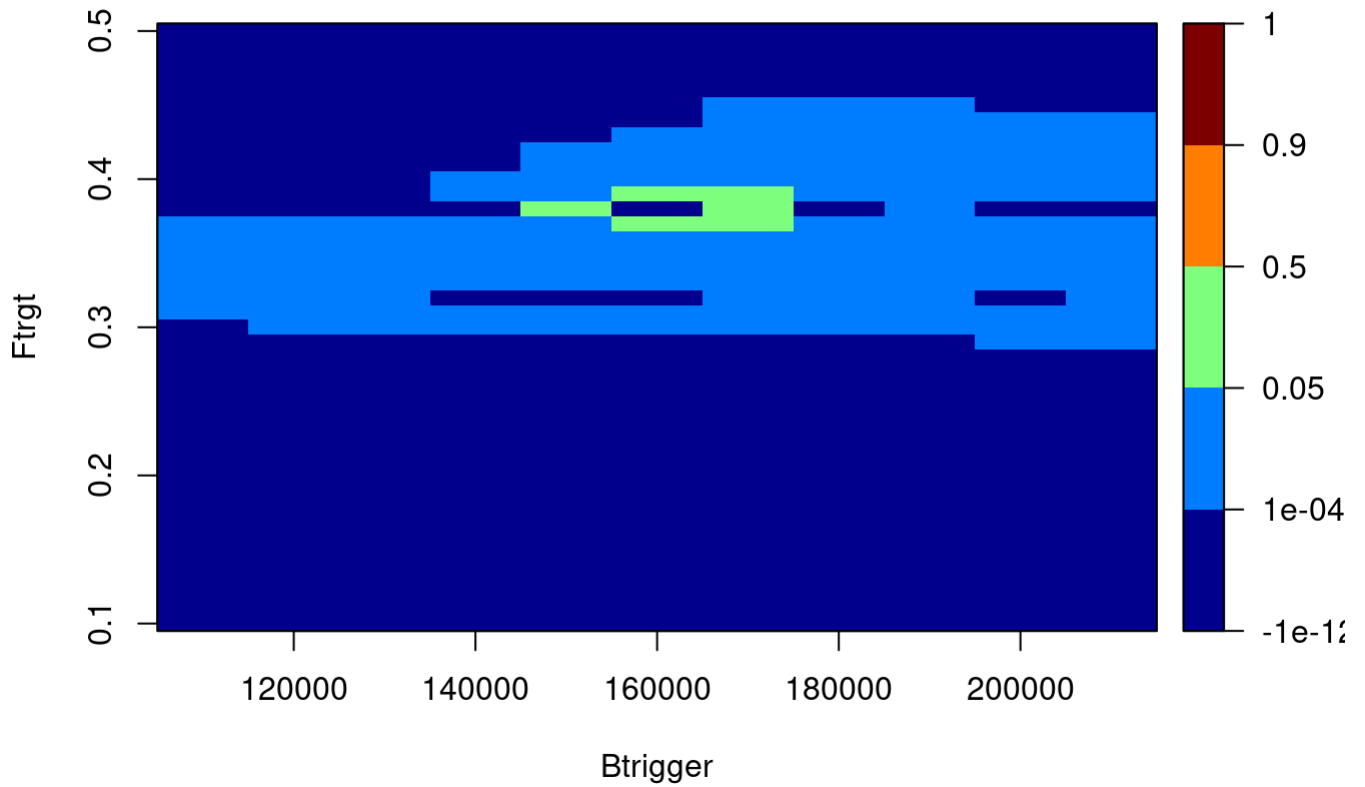
```

Round 2

Unevaluated candidates with EI > 0: 257

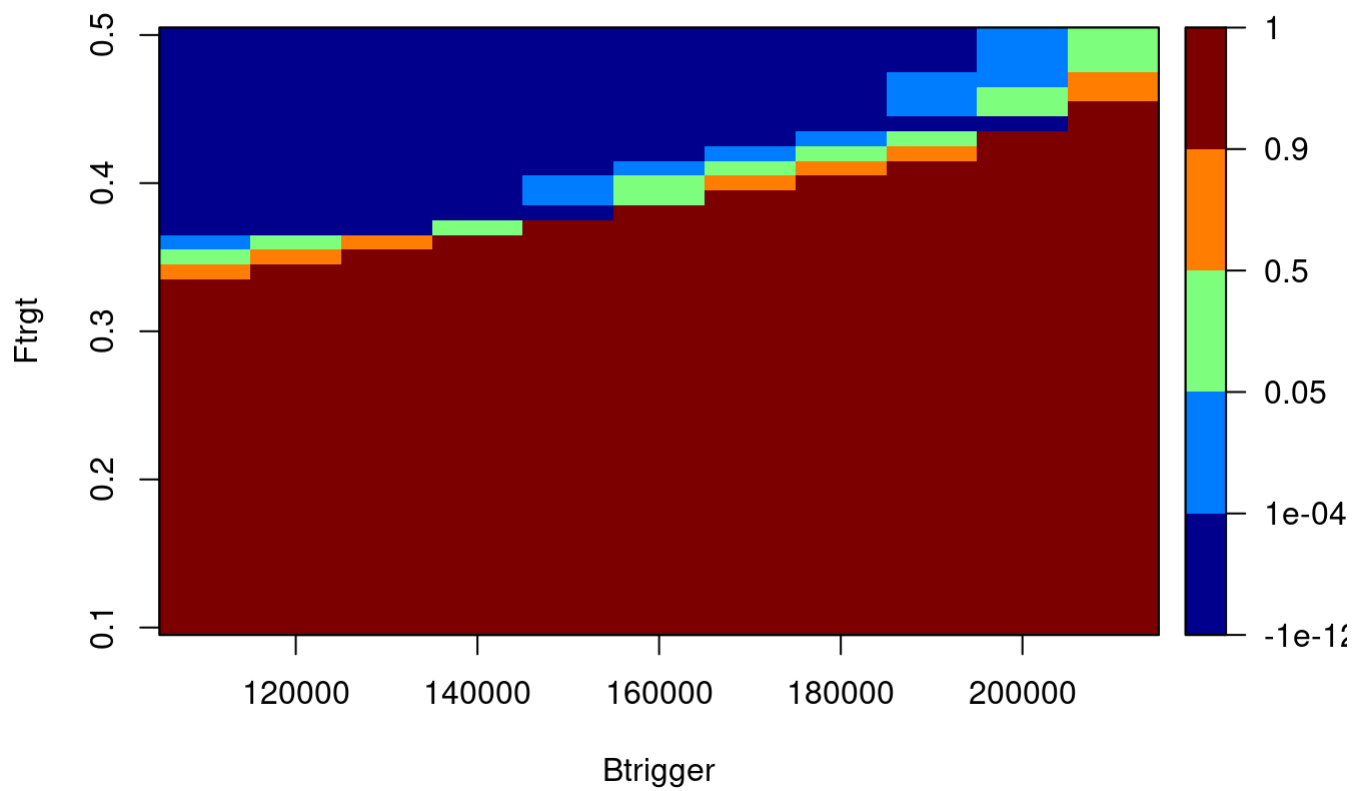
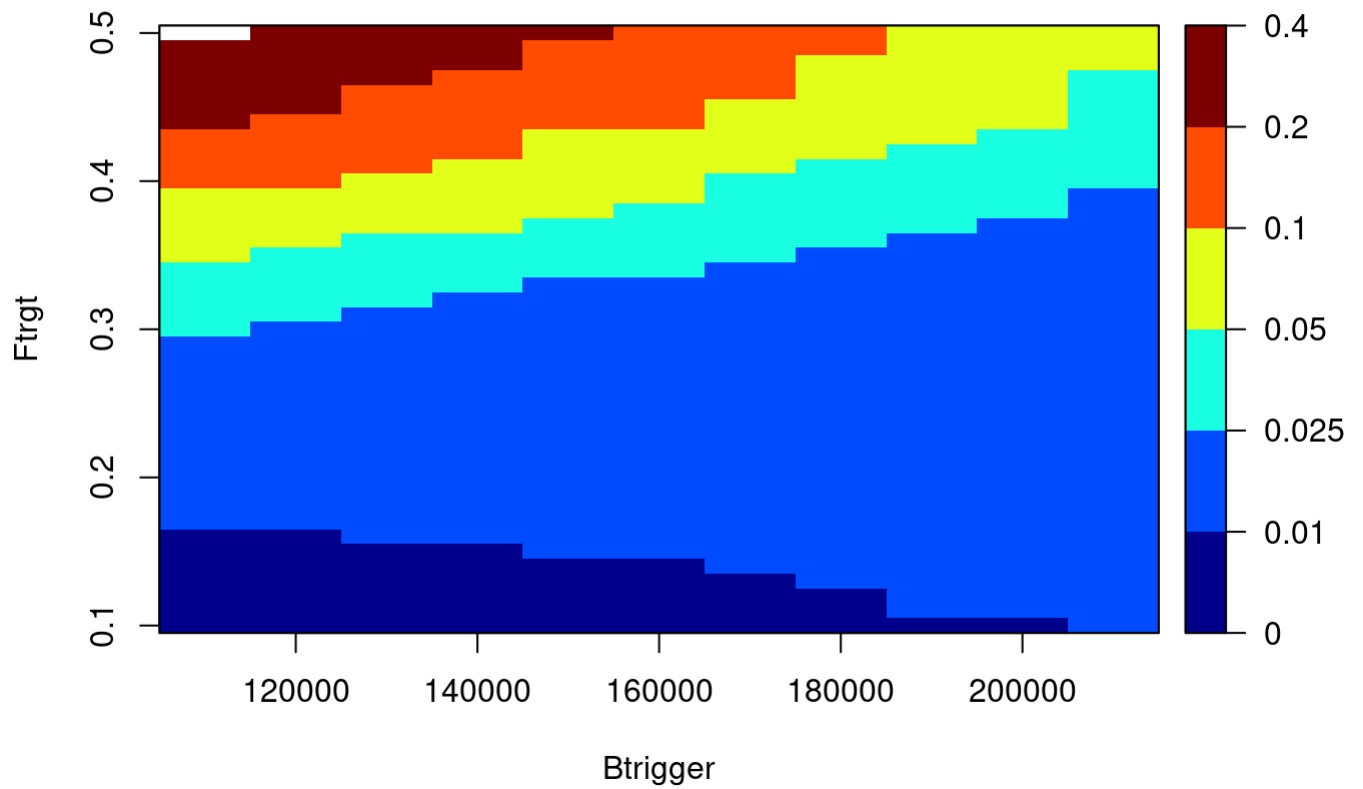


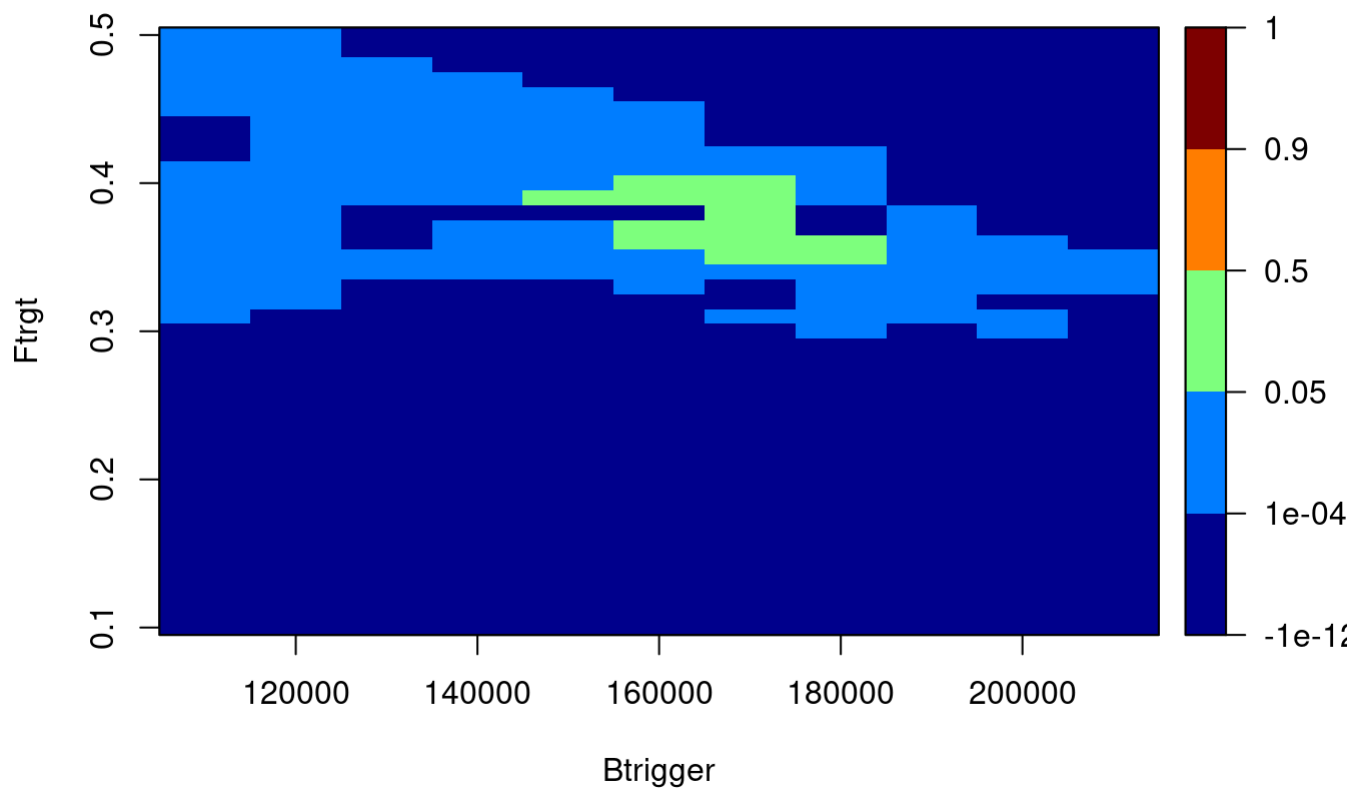
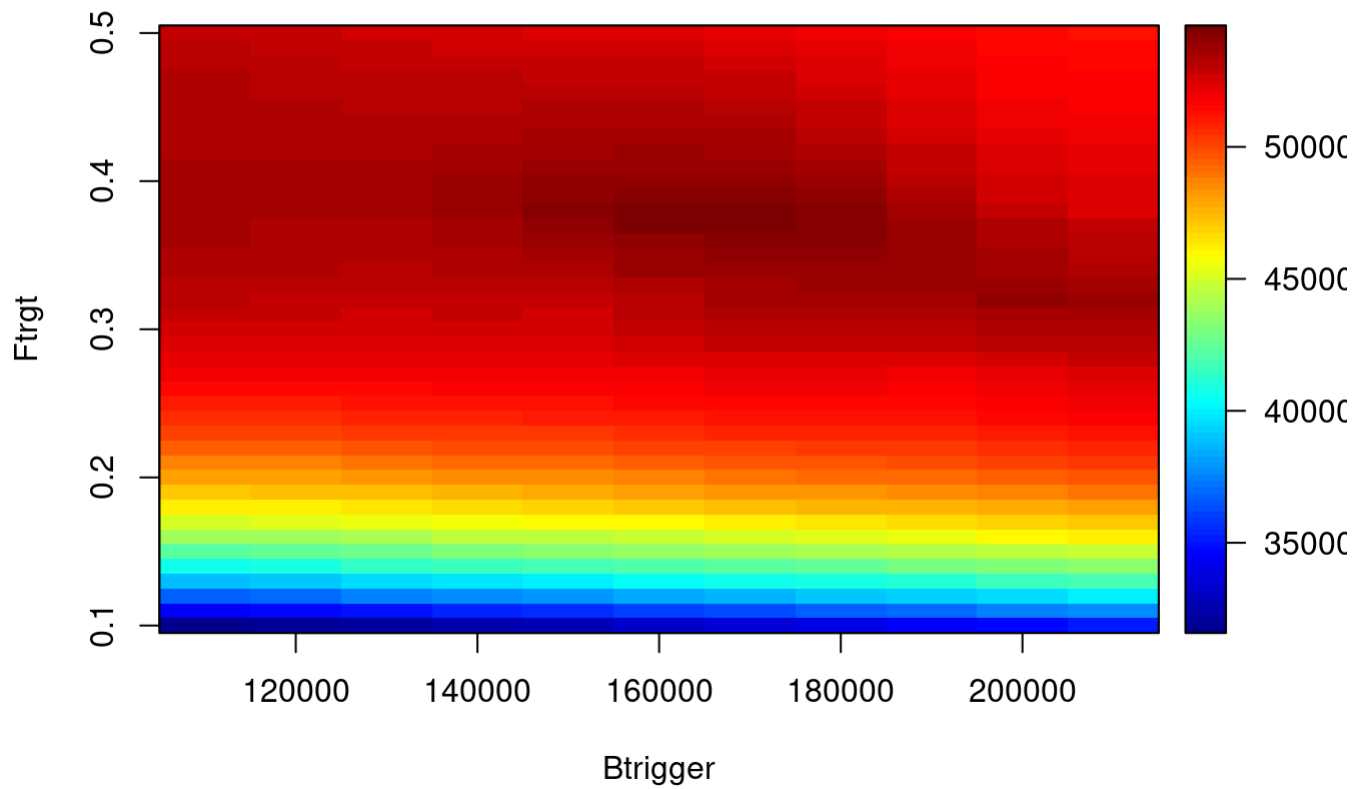


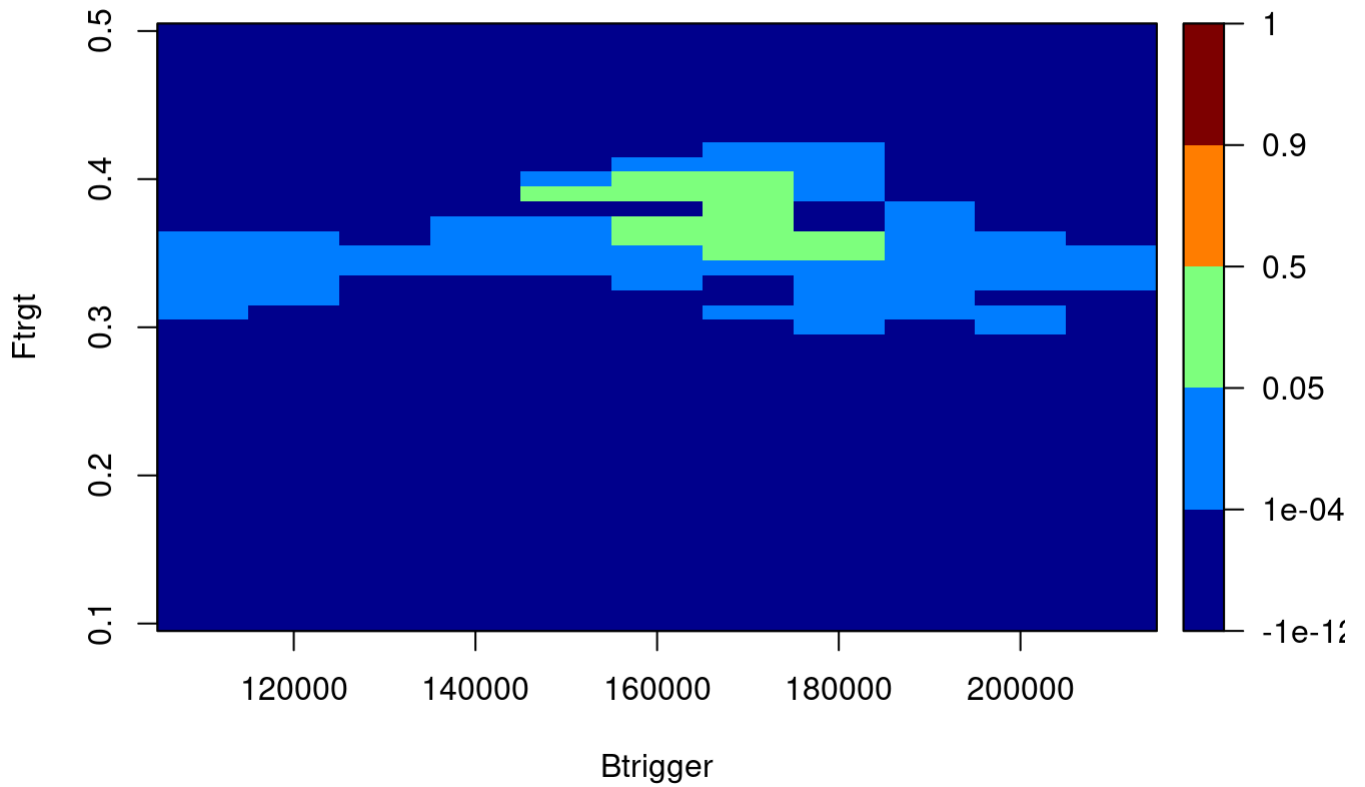


Plausible points remaining: 132
Best catch so far: 54596.5

Round 3
Unevaluated candidates with $EI > 0$: 130

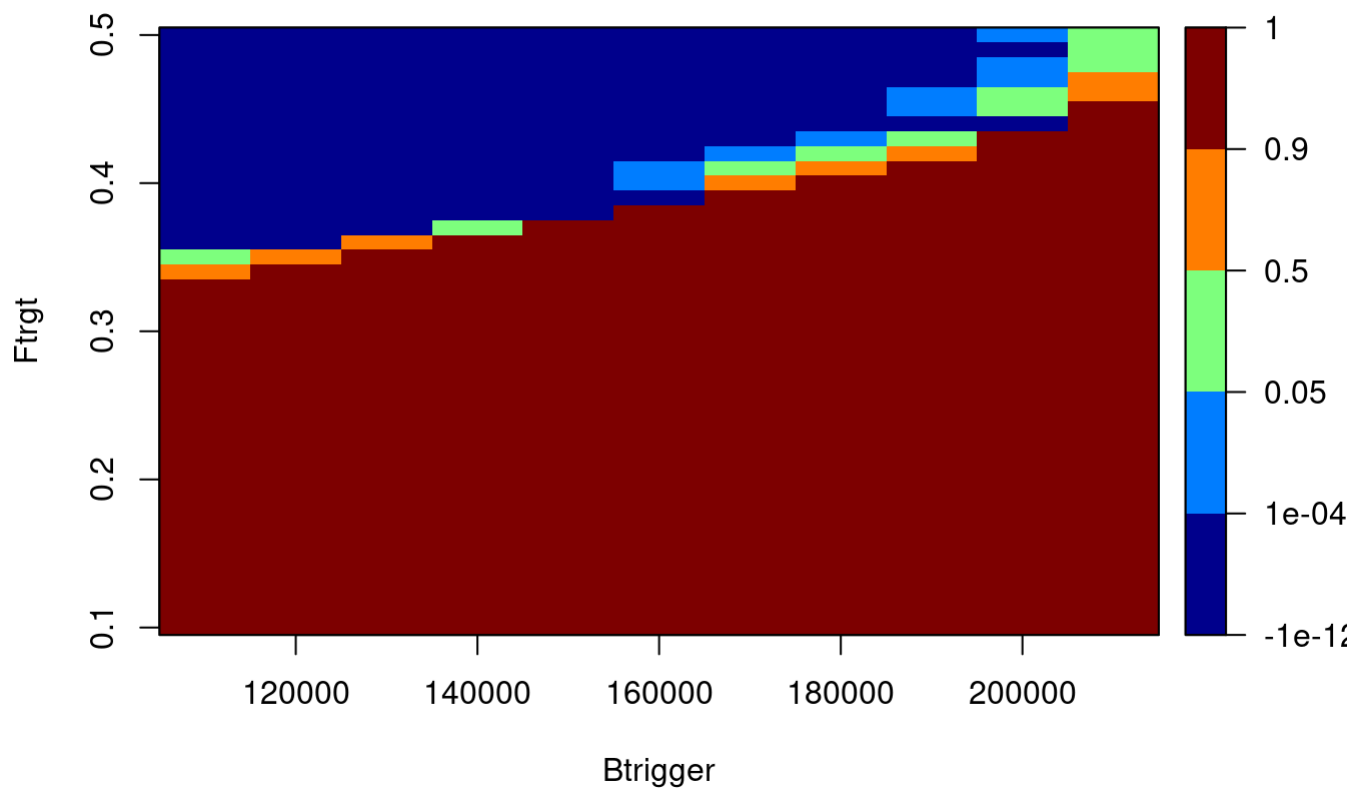
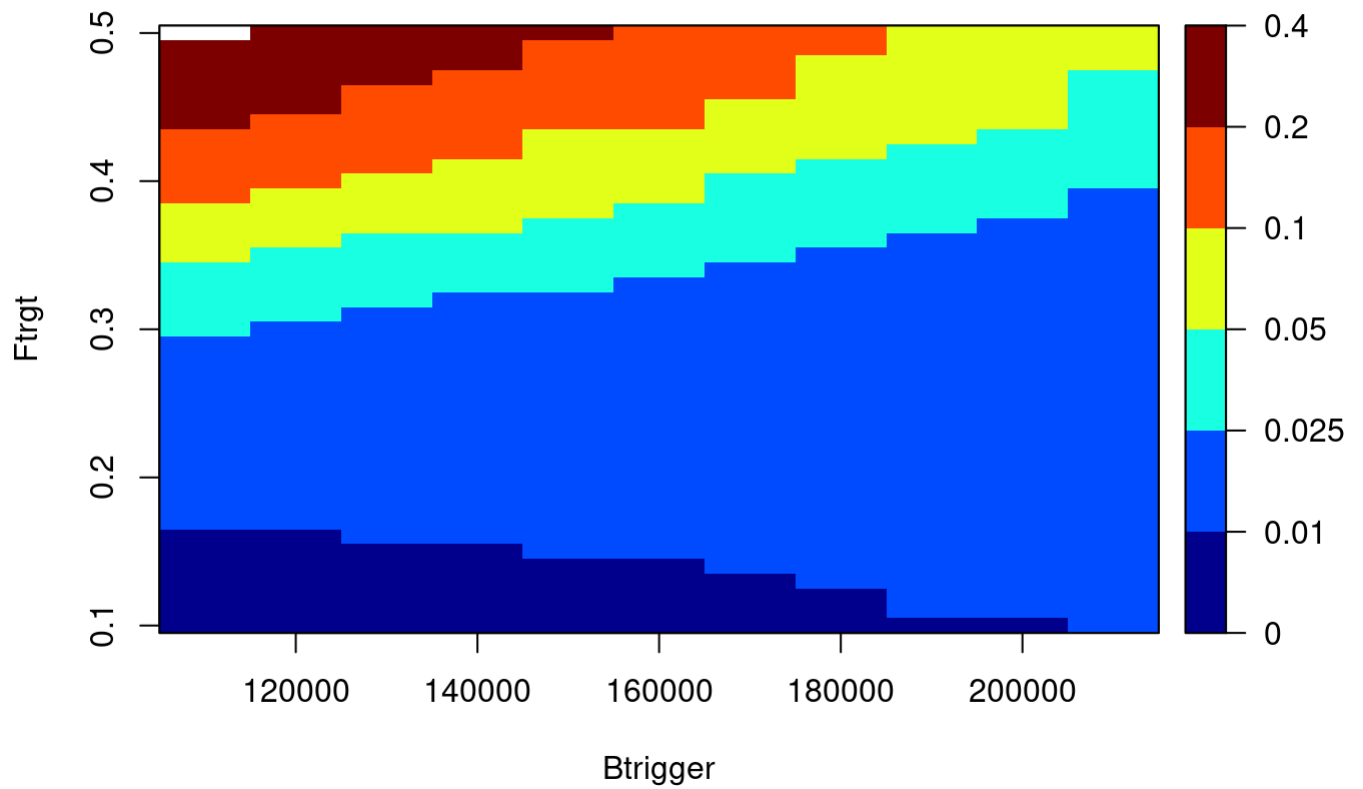


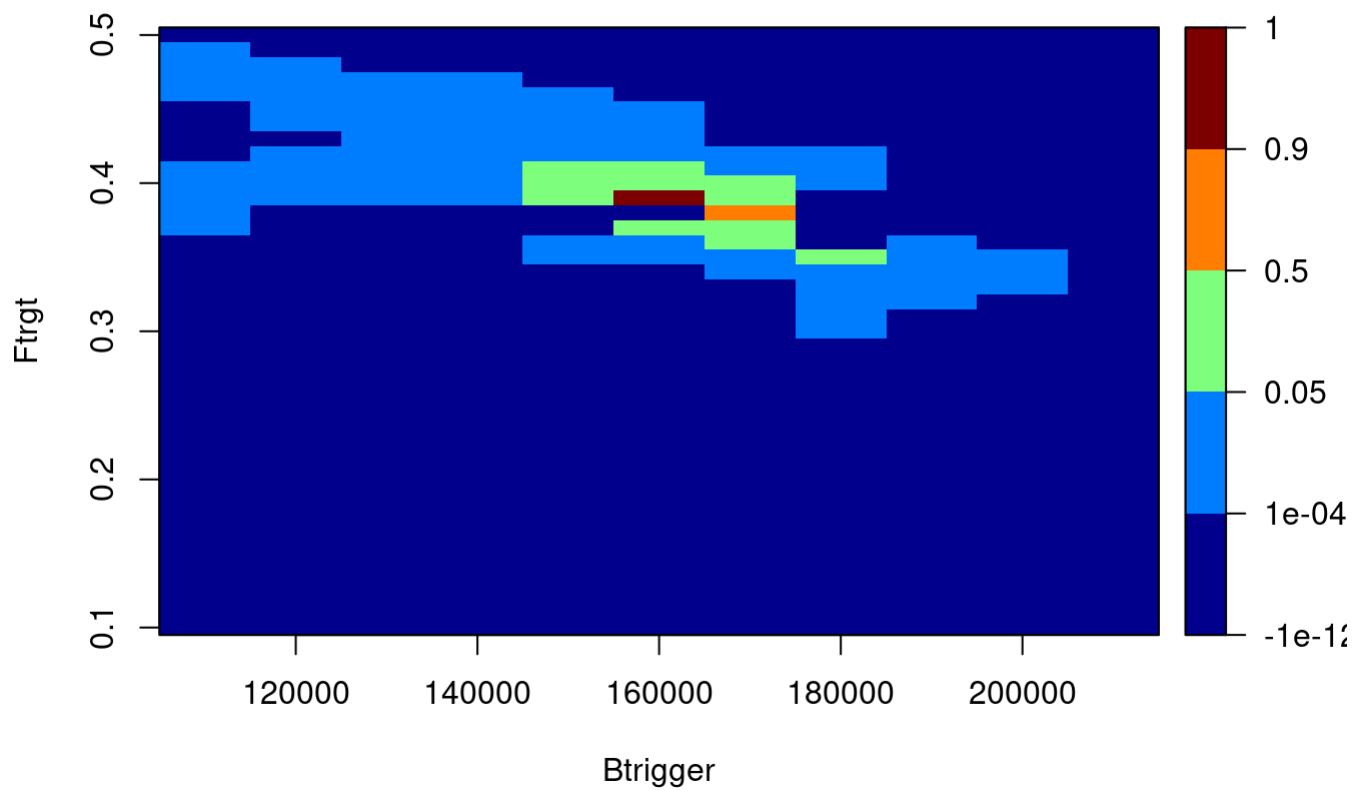
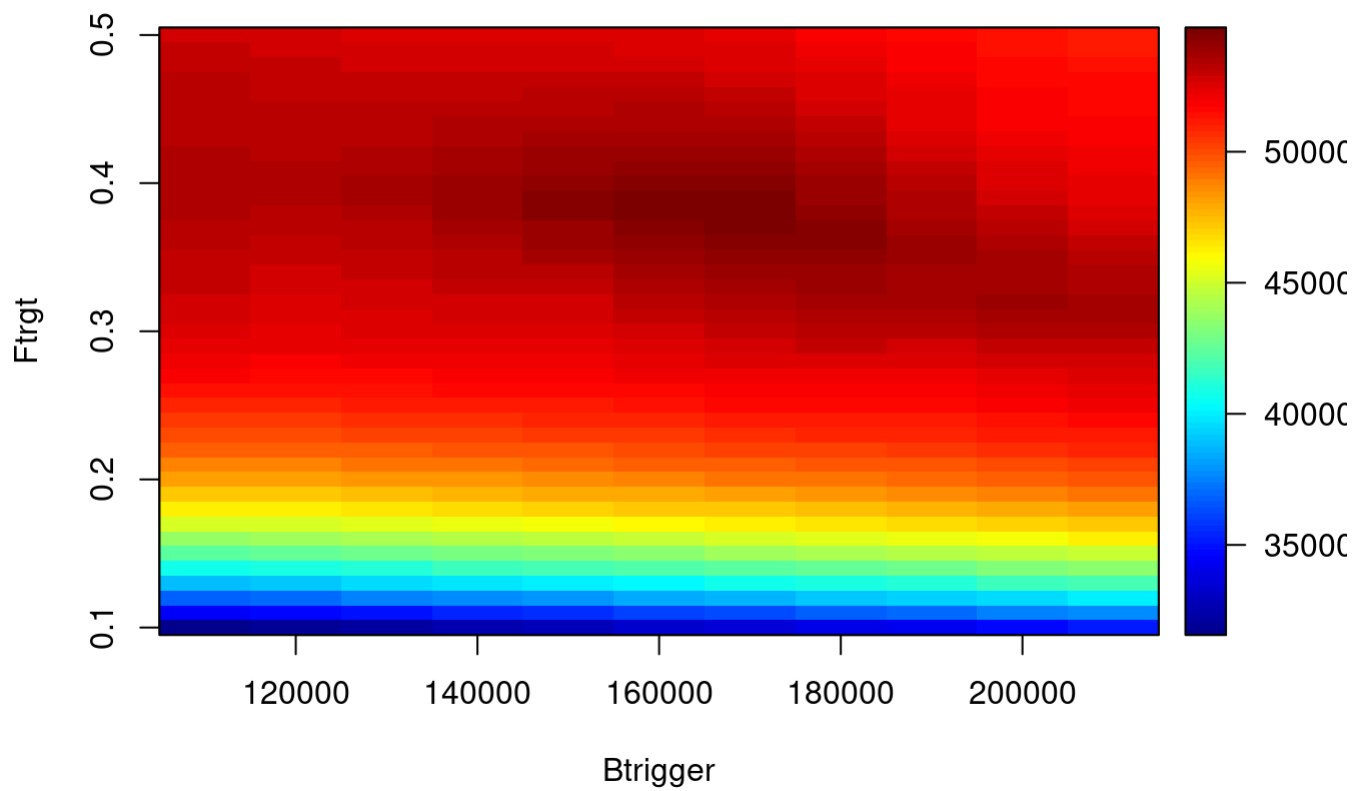


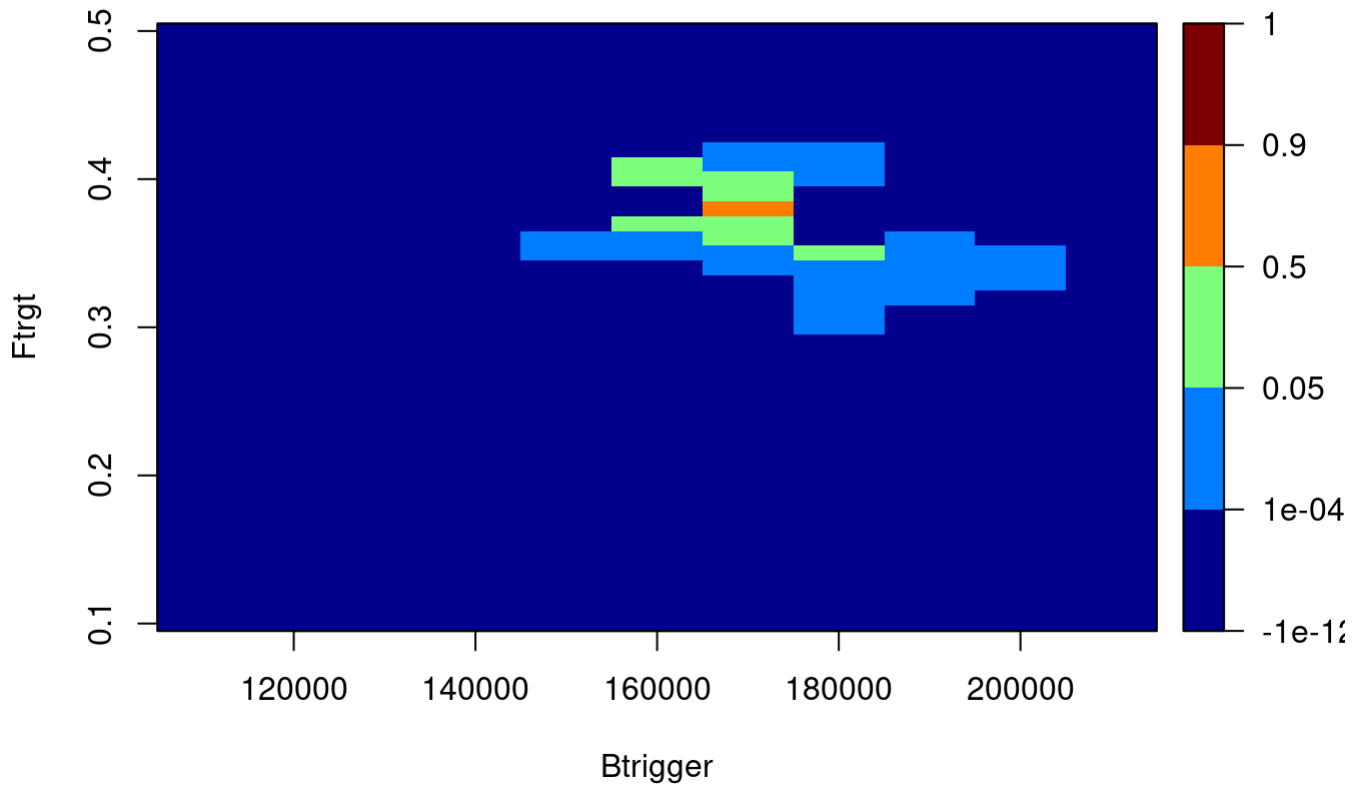


Plausible points remaining: 69
Best catch so far: 54596.5

Round 4
Unevaluated candidates with $EI > 0$: 67

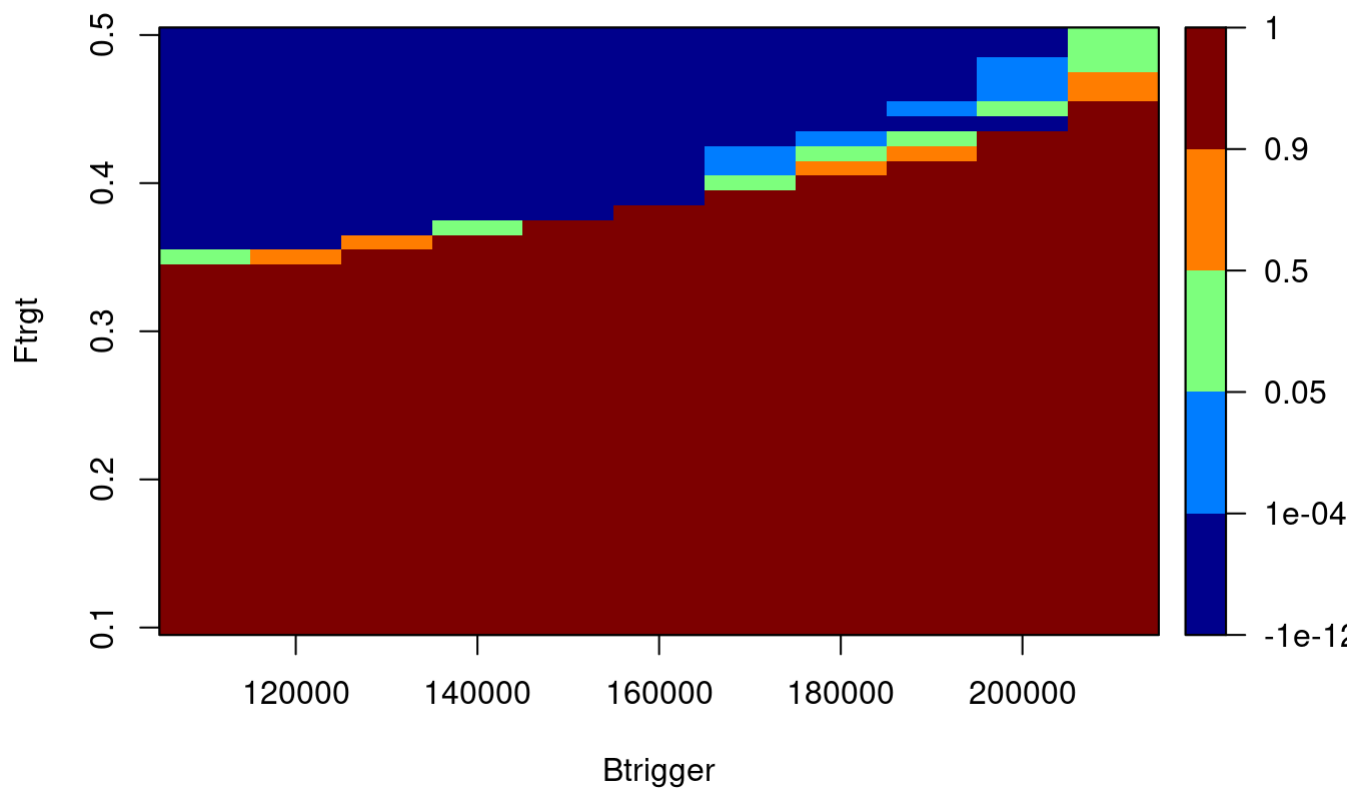
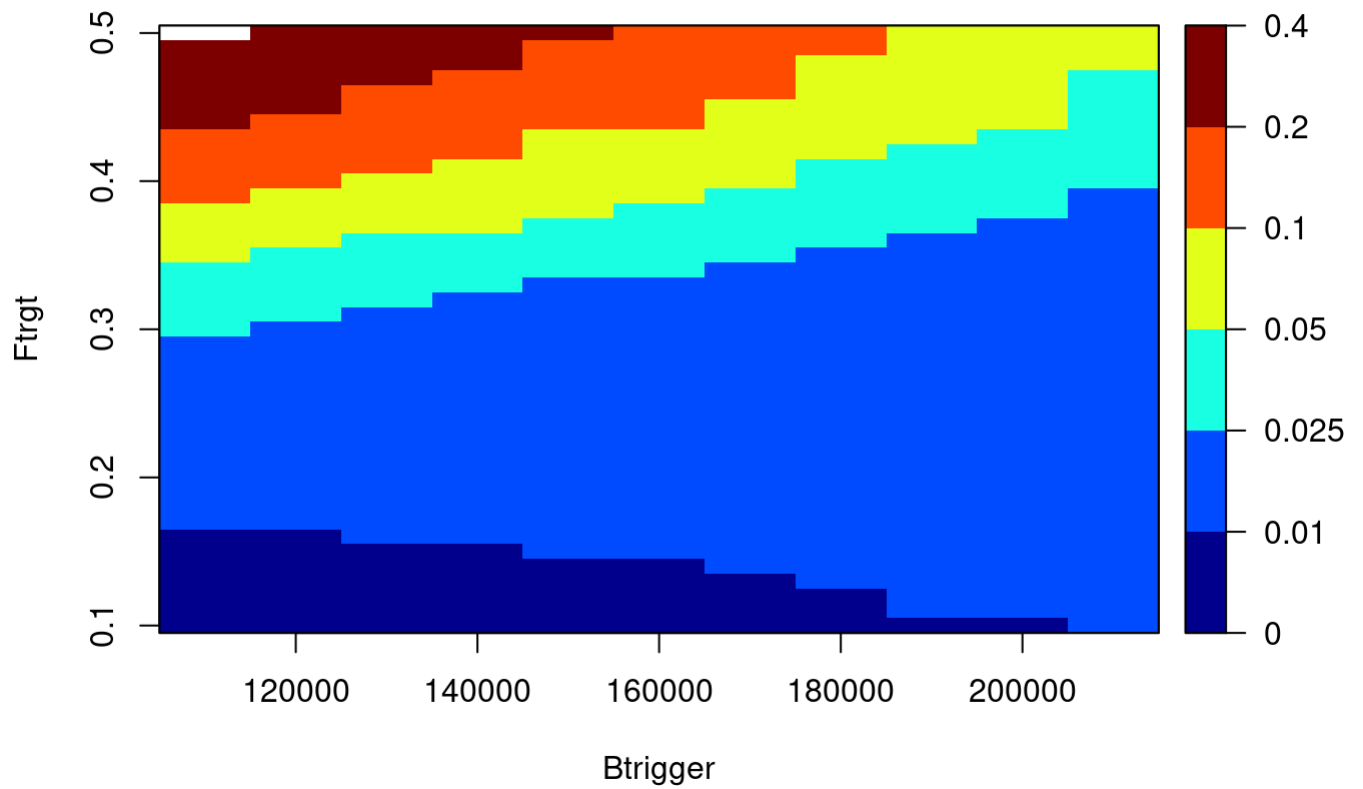


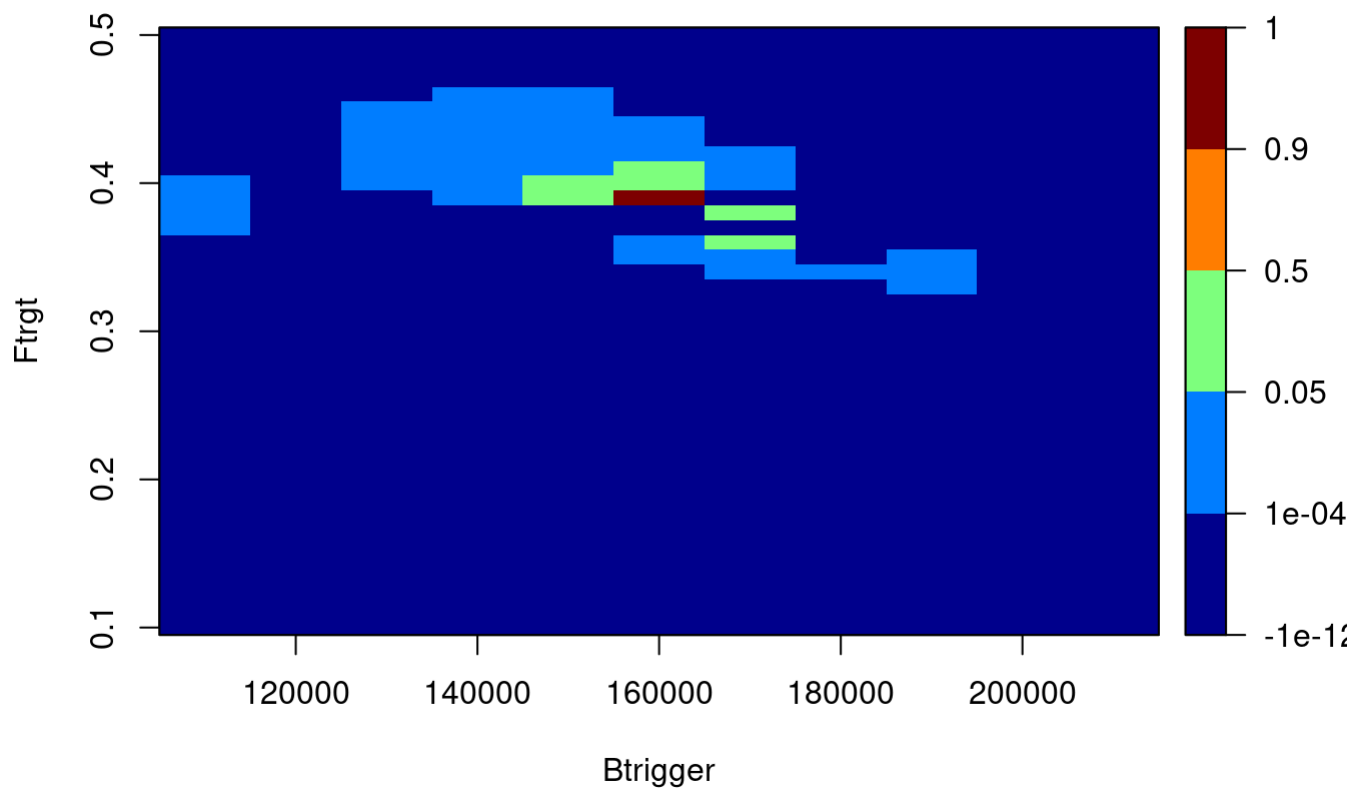
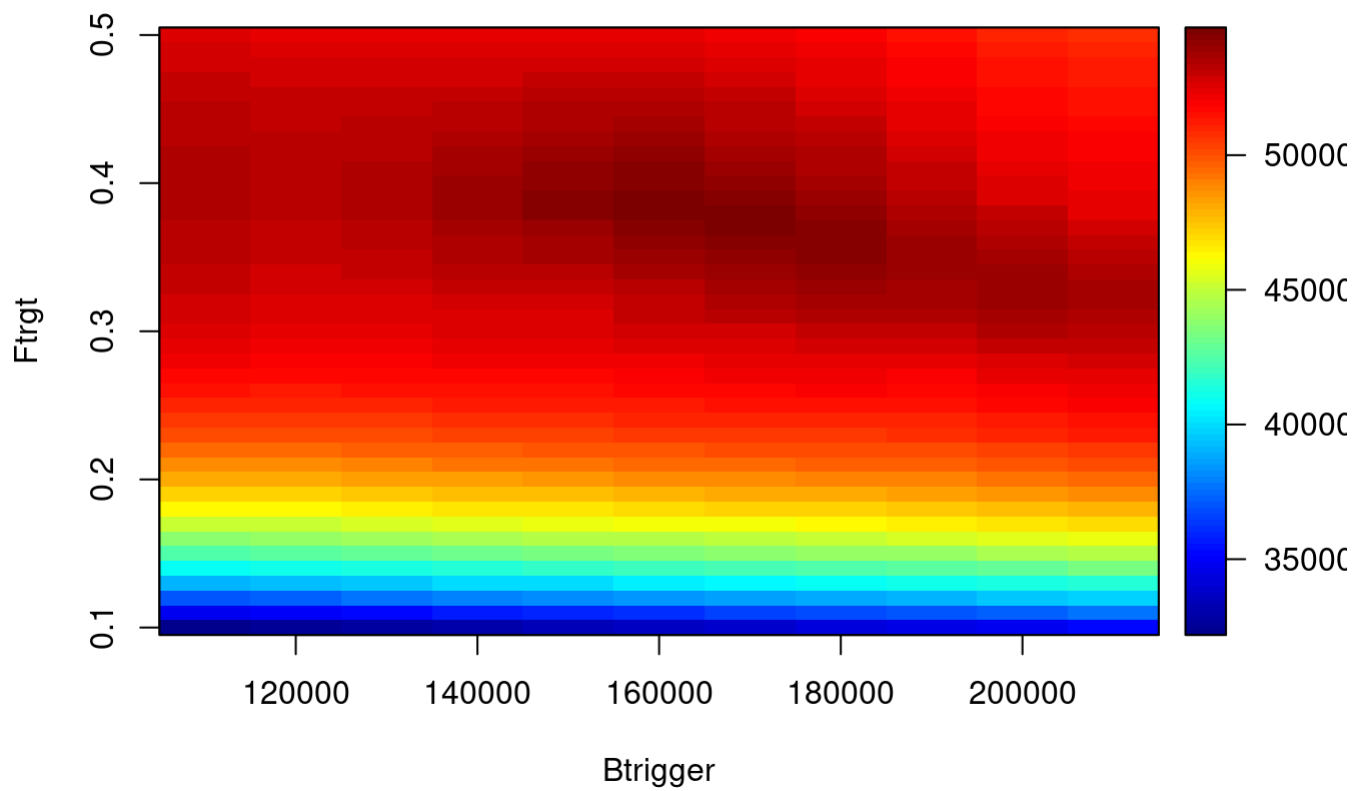


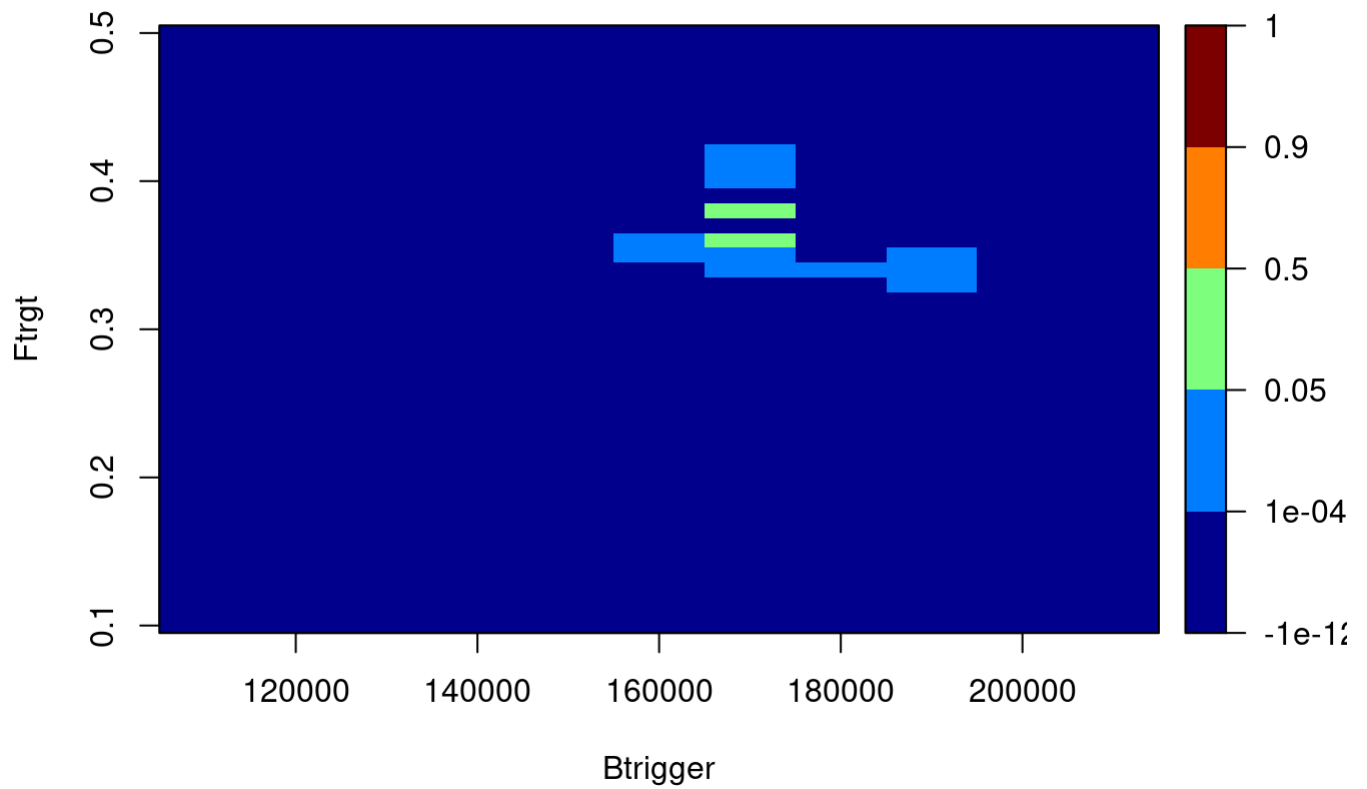


Plausible points remaining: 33
Best catch so far: 54596.5

Round 5
Unevaluated candidates with $EI > 0$: 32

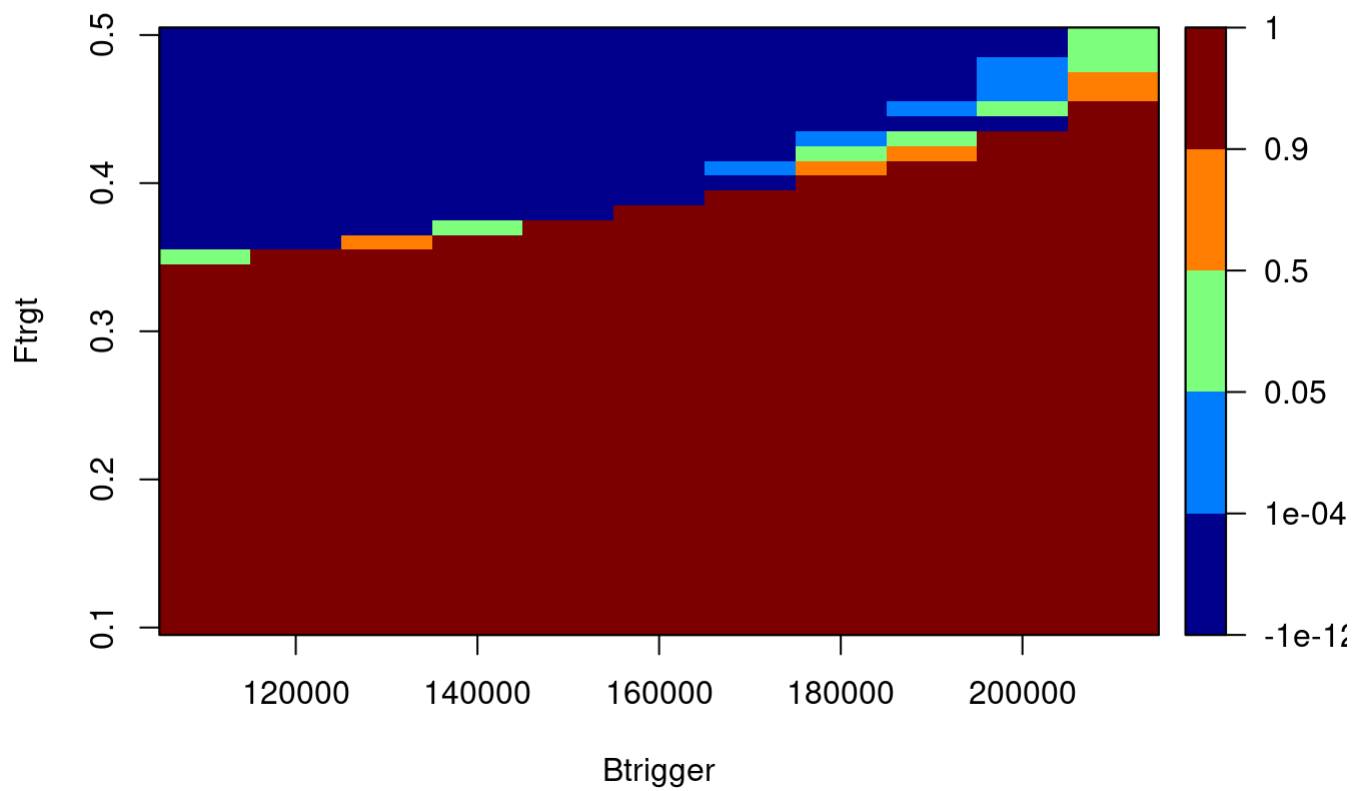
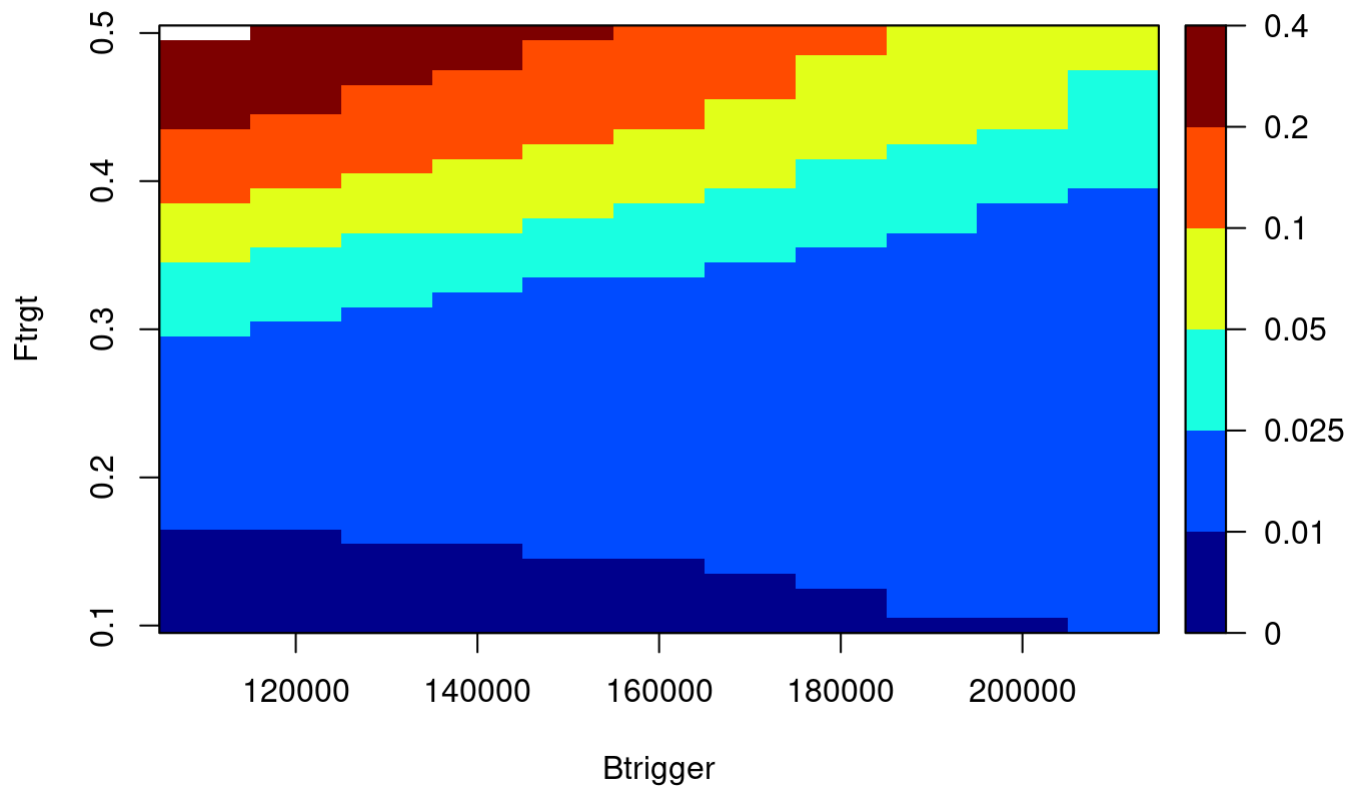


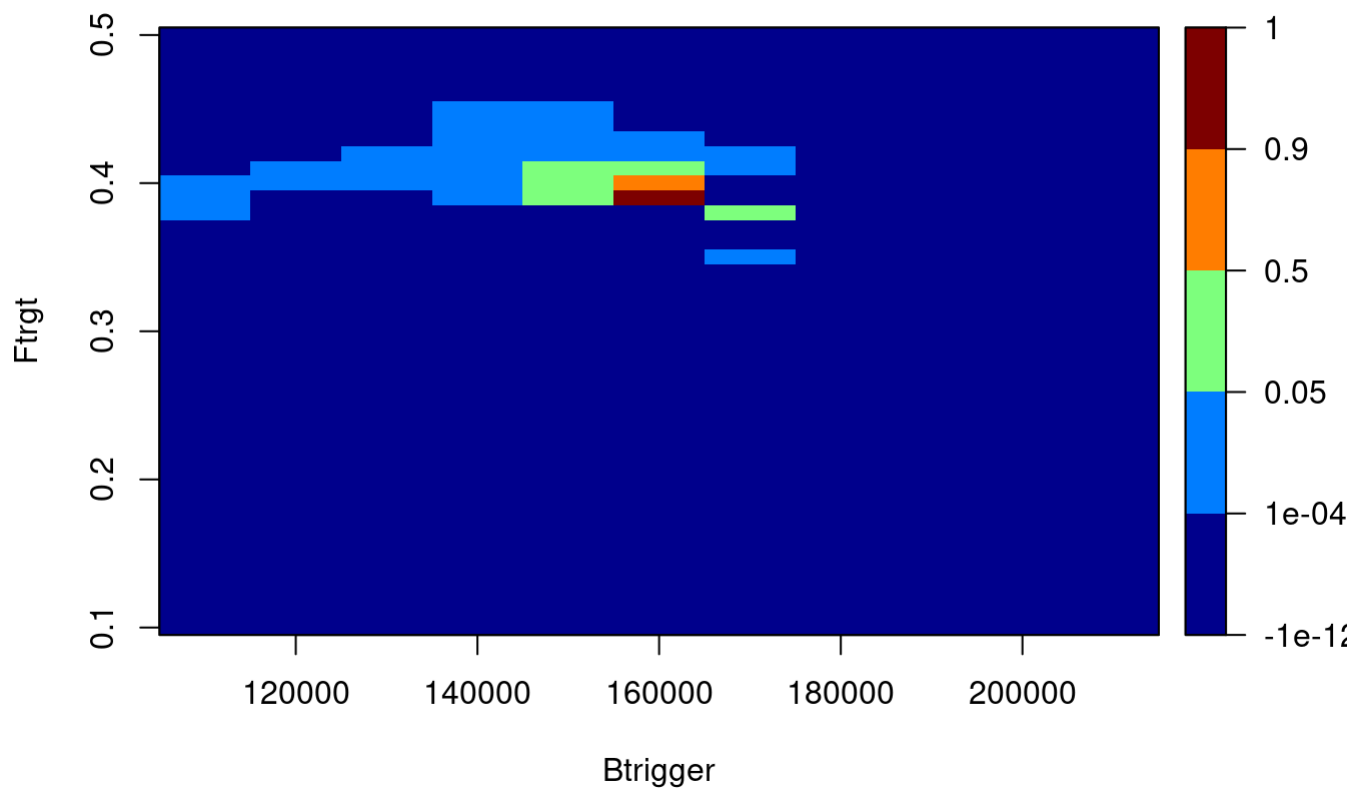
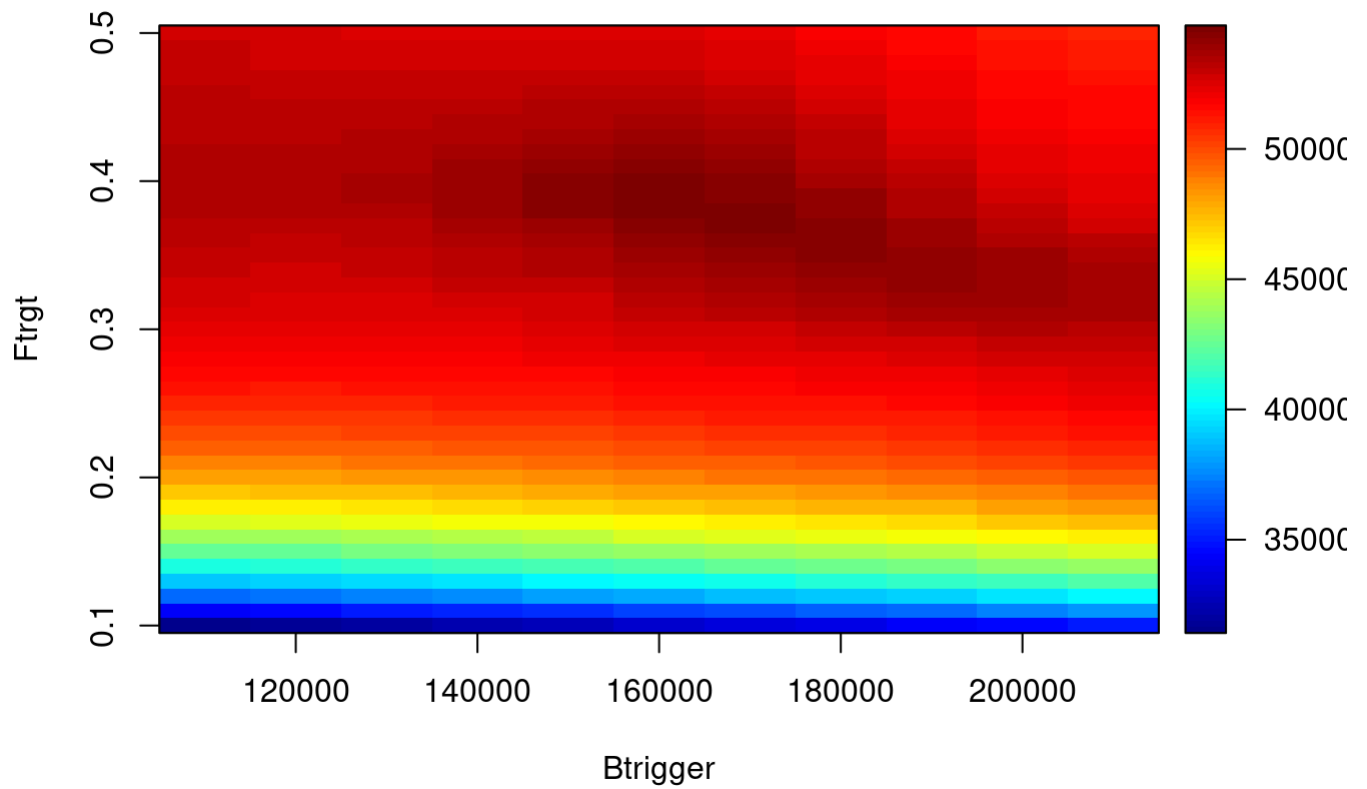


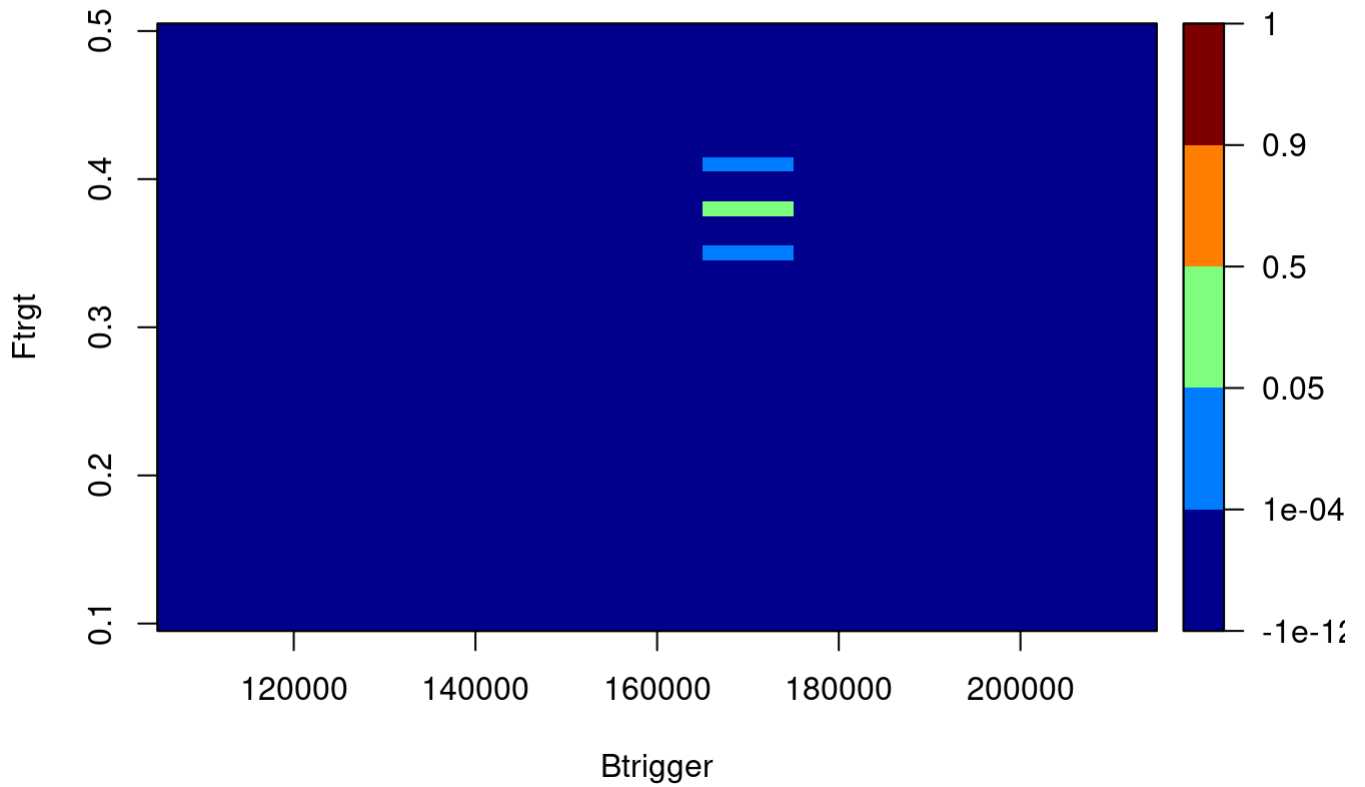


Plausible points remaining: 13
Best catch so far: 54596.5

Round 6
Unevaluated candidates with $EI > 0$: 12

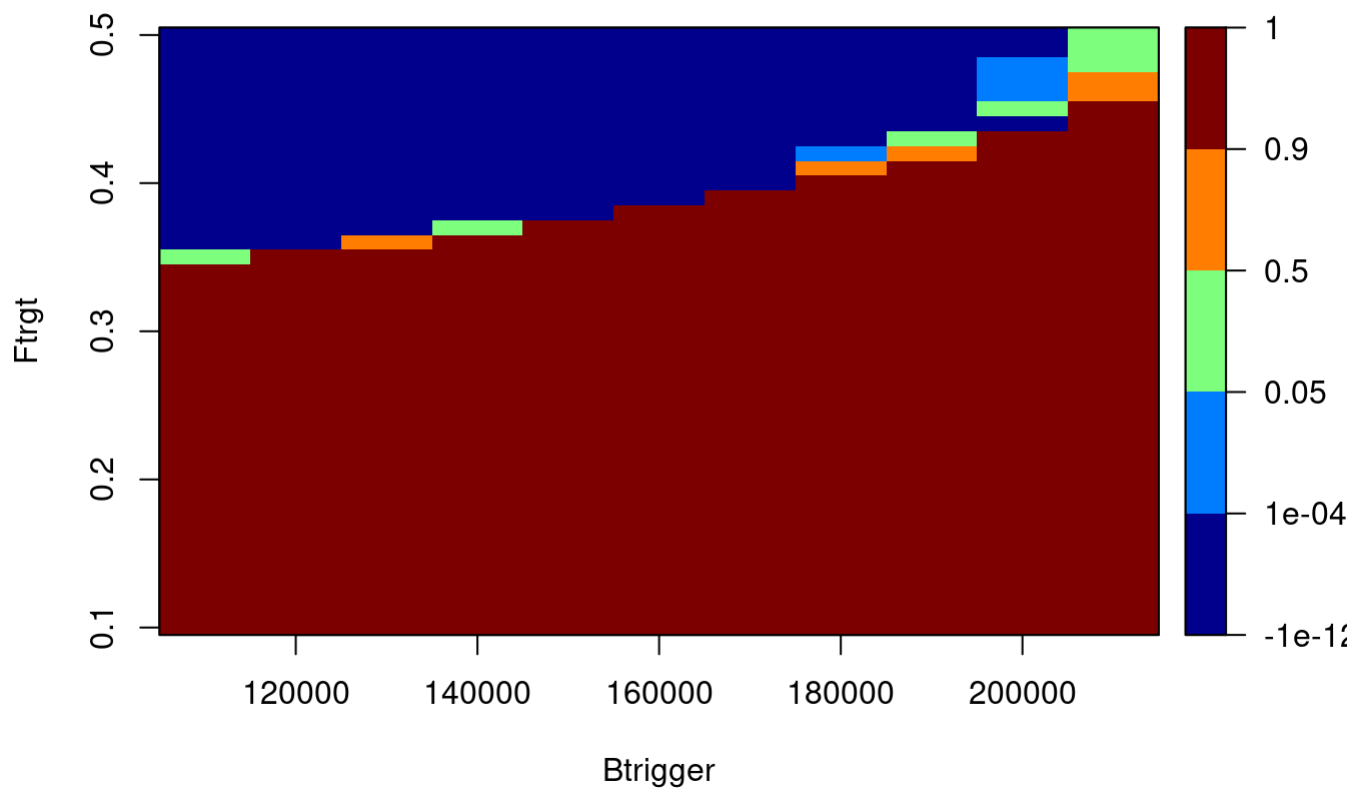
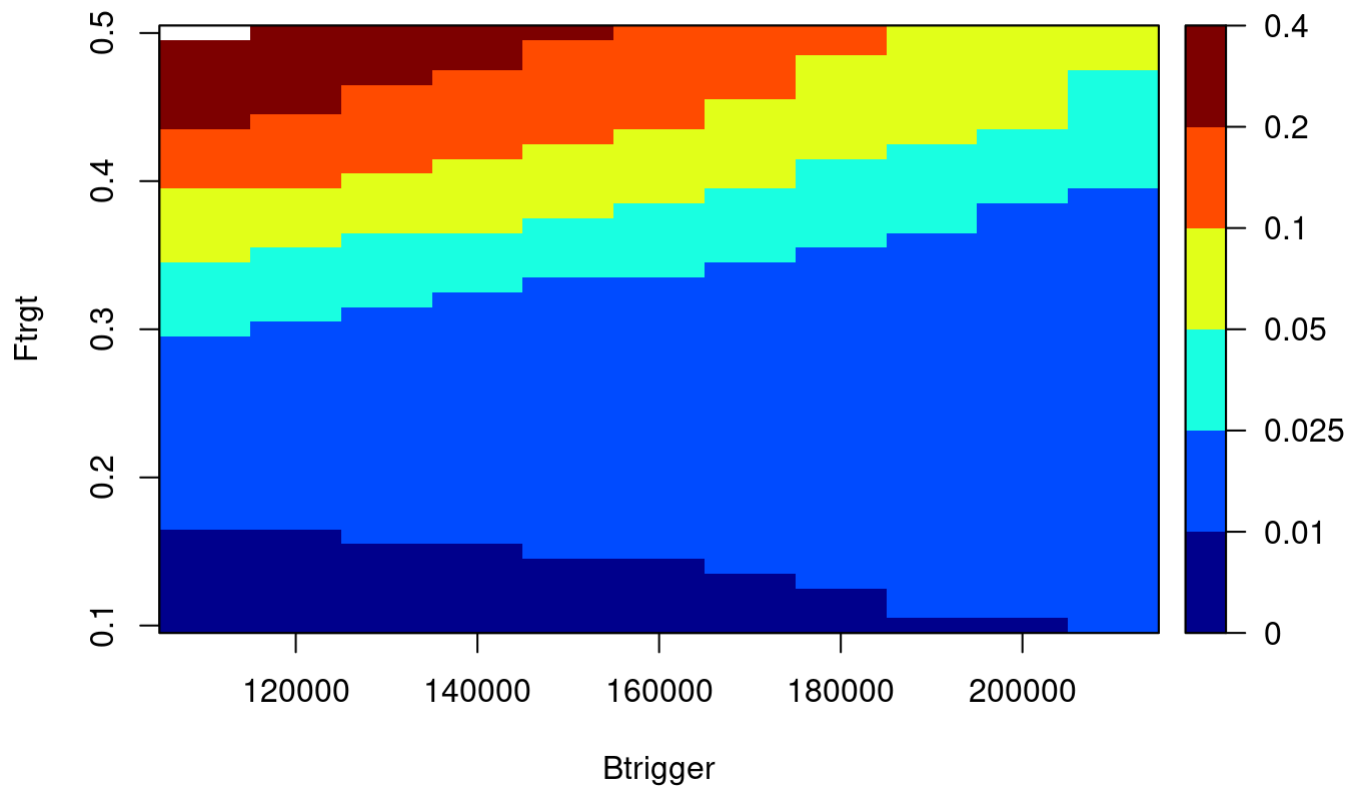


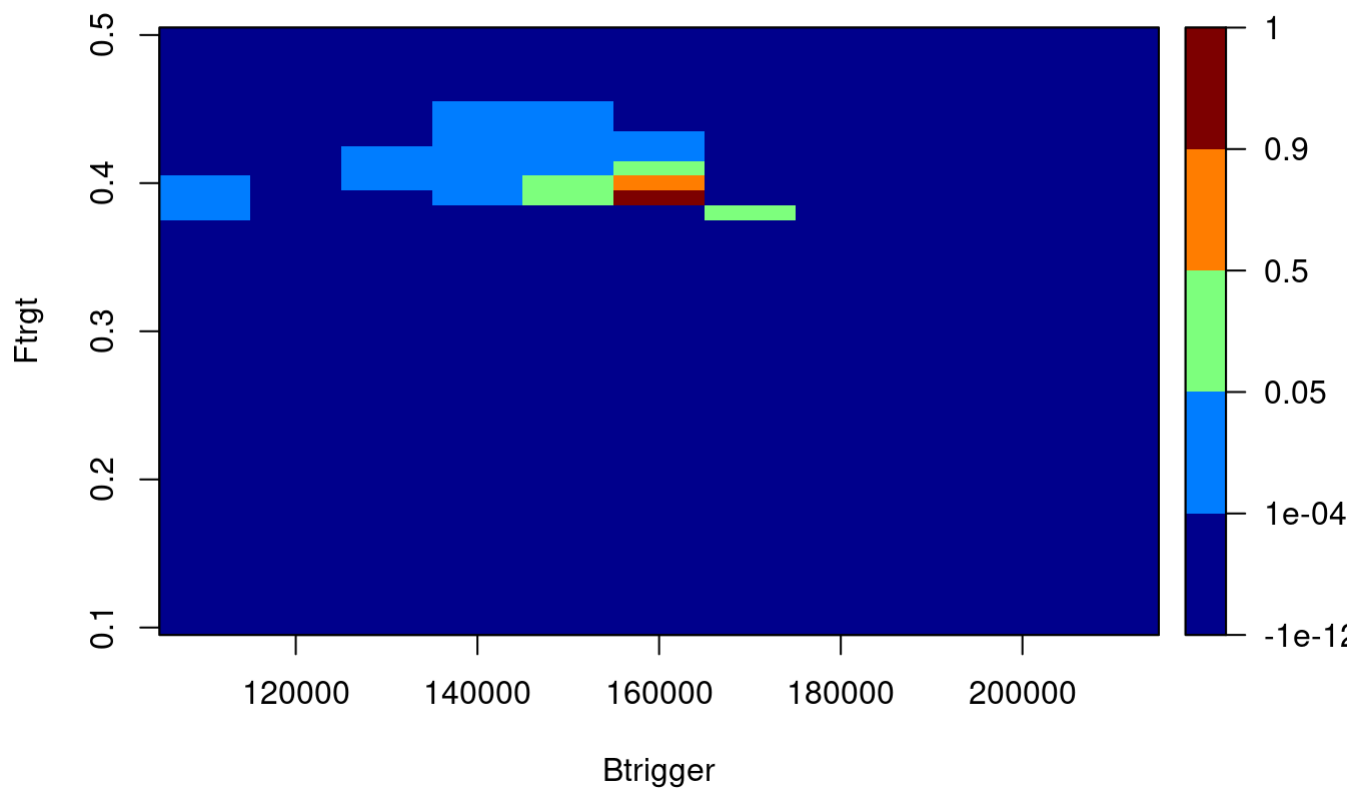
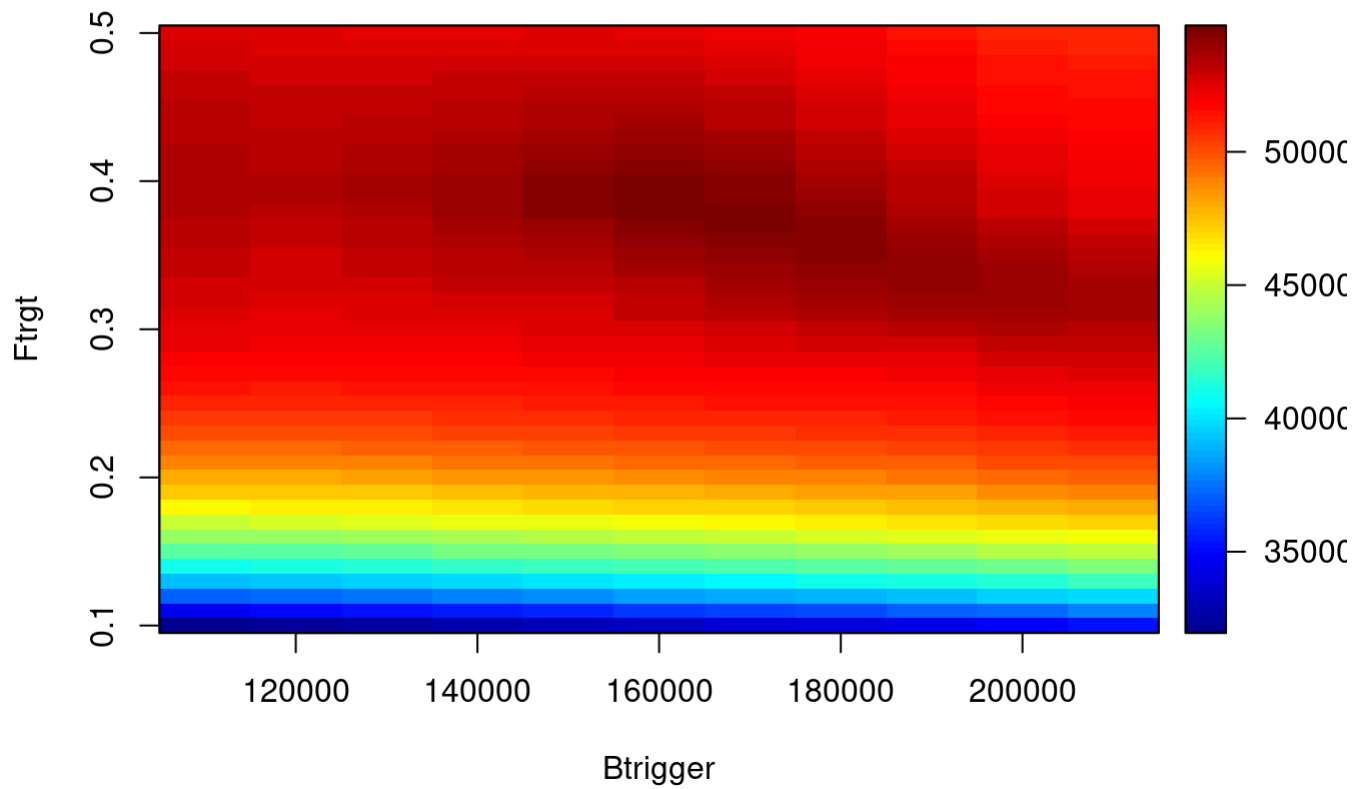


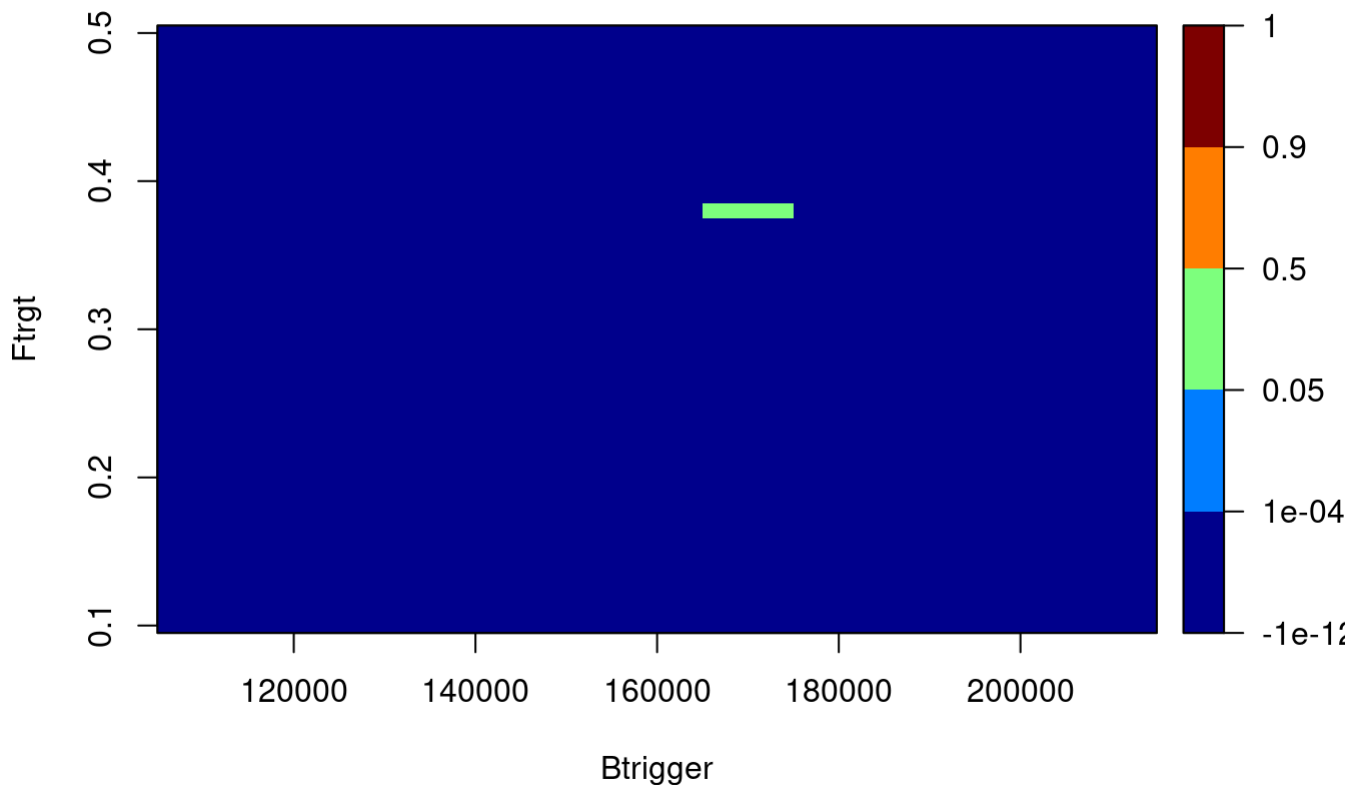


Plausible points remaining: 3
Best catch so far: 54596.5

Round 7
Unevaluated candidates with $EI > 0$: 2







Plausible points remaining: 1
Best catch so far: 54596.5

Round 8

No unevaluated candidates with positive EI. Stopping at round 8

```
#FINAL RESULTS
cat("\n OPTIMIZATION COMPLETE \n")
```

OPTIMIZATION COMPLETE

```
cat("Completed", round_num, "rounds\n")
```

Completed 7 rounds

```
cat("Total evaluations:", nrow(runs), "\n")
```

Total evaluations: 50

```
# Get final answer
pot_points_final <- gridd[possible, ]
if (nrow(pot_points_final) > 0) {
  ans <- unrescale_Her(pot_points_final[1, ], dat1)
  cat("\nOptimal parameters:\n")
  ans
```

```
} else {  
  cat("\nNo feasible points found.\n")  
}
```

Optimal parameters:

	Ftarget	Btrigger
275	0.38	170000

```
# Create final dataset for plotting  
dat_round <- left_join(dat, all_rounds, by = c("Ftrgt", "Btrigger"))  
  
# Color coding  
col_round <- c("white", hcl.colors(max(all_rounds$Round), "viridis", rev = TRUE))
```