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CBE 30356 Transport II

- A second class in transport, w/ emphasis on energy & mass transport.
- Text : BS&L Transport Phenomena
- material for this class is available on the class website: lectures, notes, homework, etc.
- daily quizzes should be completed before and after each session! Best of each (2 tries before, 2 after) count, so don't forget!
- We'll focus on energy transport before break, mass transport after, as well as some separations

Let's start!

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Readings: ch 9, sec. 1-5

Fourier's Law of Energy Conduction:

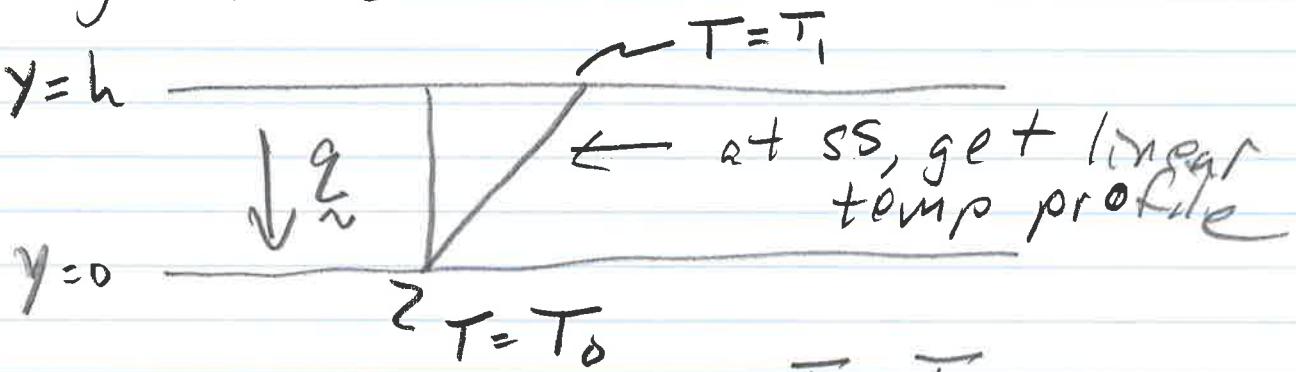
Energy flows from hot to cold!

What is a heat flux \vec{q} ?

$$\vec{q} = \frac{\text{Energy}}{\text{Area} \cdot \text{Time}} + \text{direction}$$

it's a vector!

Thought Problem: Solid Slab



$$\vec{q} = q_y \hat{e}_y = -k \frac{T_1 - T_0}{h} \hat{e}_y$$

magnitude in y direction

Note parallel w/ plane-Couette flow!

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The parallel w/ unidirectional flow
is exact

$$q = \tau \leftarrow \begin{array}{l} \text{shear} \\ \text{stress, mom. flux} \end{array}$$

\nearrow
energy flux

$$\overrightarrow{T} = u_x \leftarrow \begin{array}{l} \text{velocity} \\ \text{temp} \end{array}$$

and $k = \mu$

\nearrow
thermal conductivity \nwarrow
dynamic viscosity

$$\underbrace{q = -k \nabla T}_{\text{Fourier's Law}} \equiv \underbrace{\sum_{ij} = \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)}_{\text{Newton's Law of viscosity}}$$

(Note: BS&L puts a $-$ sign in Newton's Law –
just matches parallel more obvious)

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$$\text{so } \vec{q} = (q_x, q_y, q_z)$$

$$q_x = -k \frac{\partial T}{\partial x}$$

$$q_y = -k \frac{\partial T}{\partial y}$$

$$q_z = -k \frac{\partial T}{\partial z}$$

Note: This is for isotropic materials

Many materials are anisotropic!

In this case:

$$\vec{q} = -k \cdot \nabla T \quad (q_i = -k_{ij} \frac{\partial T}{\partial x_j})$$

↗ matrix!

for wood k is 3x higher along the grain than across it!

Now for units!

$$\vec{q} = -k \frac{\nabla T}{\text{Temp}} \quad \therefore [k] = \frac{\text{Energy}}{\text{L} \cdot \text{Time} \cdot ^\circ \text{K}}$$

$\uparrow E/\text{Area} \cdot \text{Time}$ \downarrow / L

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Units of energy:

$$\text{Joules} : \frac{\text{kg m}^2}{\text{s}^2} \quad (\text{F} \cdot \text{L})$$

$$\text{ergs} : \frac{\text{g cm}^2}{\text{s}^2} \equiv 10^{-7} \text{J}$$

$$\text{cal} : \frac{\text{E to raise 1g water } 1^\circ\text{C}}{} \equiv 4.1868 \text{J}$$

(note: $\text{food cal} \equiv \text{rcal}$)

$$\text{BTU} : \frac{\text{E to raise 1lb water } 1^\circ\text{F}}{} \equiv 1.055 \times 10^3 \text{J}$$

↳ varies a bit dep. on ref.,
still used in nat. gas pricing!

We'll use SI in this class, but
know how to convert! (mostly)

$$[\text{K}] = \frac{\text{kg m}^2}{\text{s}^2} \cdot \frac{1}{\text{m s}^0 \text{K}}$$

$$= \frac{\text{kg m}}{\text{s}^3 \text{K}} \equiv \frac{\text{J}}{\text{m s}^0 \text{K}}, \text{etc.}$$

$$= \frac{\text{W}}{\text{m}^0 \text{K}}$$

What is the magnitude of k_c ? (6)

gases: $k_c \sim 2 \times 10^{-2} \frac{W}{m^\circ K}$

liquids: $k_c \sim 1 \times 10^{-1} \frac{W}{m^\circ K}$ (organics)

$\sim 6 \times 10^{-1} \frac{W}{m^\circ K}$ (water!)

solids: messy! (usually sim to water,
except metals!)

Cu: $k_c \sim 400 \frac{W}{m^\circ K}$

steel: $k_c \sim 45 \frac{W}{m^\circ K}$

Useful to know approx values!

BS&L has several nice tables in sec. 9.1

OK, so where does thermal conductivity
come from? Different mechanisms for
dif. materials!

Look at gases: sec. 9.3

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In low density gases molecules carry mass momentum & energy with them as they bounce around!

The thermal energy of a monatomic gas (say He) is just $\frac{3}{2}kT$

3 degrees of freedom \rightarrow Boltzmann's cst

$$K = 1.38 \times 10^{-23} \frac{\text{J}}{\text{K}}$$

Note: in these notes K looks a lot like K or K . know from context!

The thermal velocity is $\bar{u} = \sqrt{\frac{8kT}{\pi m}}$
where m is molecular wt.

If molecules have number density n then they cross a plane w/ rate per area of $Z = \frac{1}{4}n\bar{u}$ (~~# area*time~~)

and carry mass, mom & E w/ them!

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The net flux depends on the gradient and how far they come from!

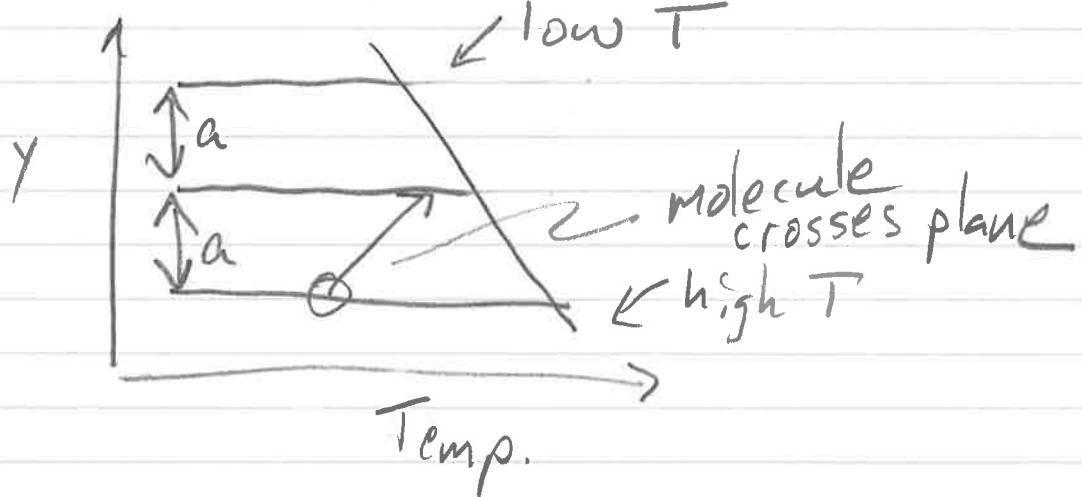
This is determined by mean free path λ between collisions!

$$\lambda = \frac{1}{\sqrt{2} \pi d^2 n}$$

→ collision diameter
(for hard spheres)

on average, last collision would be a distance $a = \frac{2}{3}\lambda$ from plane

So:



What is the energy flux?

$$q_y = Z \left(\frac{3}{2} kT \Big|_{y-a} - \frac{3}{2} kT \Big|_{y+a} \right)$$

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$$\text{Now } T|_{y=a} = T|_y + a \frac{\partial T}{\partial y} = T|_y + \frac{2}{3} \lambda \frac{\partial T}{\partial y}$$

$$\begin{aligned} \text{so } \varrho_y &= -\frac{3}{2} K \left(\frac{4}{3} \lambda \frac{\partial T}{\partial y} \right) \cancel{z} \\ &= -\left(\frac{1}{2} n K \bar{u} \lambda \right) \frac{\partial T}{\partial y} \end{aligned}$$

$$\therefore K = \frac{1}{2} n K \bar{u} \lambda = \frac{\sqrt{m k T / \pi}}{\pi d^2} \frac{K}{m}$$

This shows that for gases K is indep. of n - and hence pressure! It's also a weak function of T (e.g., $T^{1/2}$)

While this works pretty well (& shows where K comes from), usually we use the Chapman-Enskog formula

$$K = \frac{25}{32} \frac{\sqrt{\pi m K T}}{\pi d^2 \sqrt{L_K}} C_V \quad \leftarrow \text{h + cap cst vol}$$

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σ is a Lennard-Jones parameter
and Σ_{μ} is a "collision integral"

This works pretty well for monoatomic gases. You can find values for σ and Σ_{μ} in tables E.1 & E.2

For polyatomic gases this is extended by the Eucken formula

$$\kappa = \left(\hat{C}_p + \frac{5}{4} \frac{\Omega}{M} \right) \mu \xrightarrow[\text{molecular wt}]{\text{gas const.}} \text{viscosity}$$

$$\text{where } \mu = \frac{5}{16} \frac{\sqrt{\pi M k T}}{\pi \sigma^2 \Sigma_{\mu}}$$

from similar arguments. The difference arises because polyatomic gases carry energy via other modes.

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The key thing to remember
is that (for low density gases)

1) K is indep. of pressure (mostly)

2) is a weak $f^{\alpha}(T)$ ($\sim T^{1/2}$)

3) is proportional to the viscosity

because it is produced by the
same mechanism!

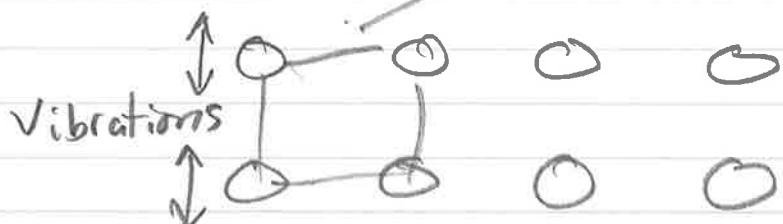
What about liquids? Much messier!

A simple model: (sec. 9.4)

Bridgman: energy is transmitted via

lattice vibrations (molecules don't
trade places)

$$\text{lattice Spacing} = \left(\frac{V}{N}\right)^{1/3}$$



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By analogy w/ low density gases:

$$K \approx \rho \hat{c}_v |\bar{u}_y| a$$

$$a \sim \left(\frac{\tilde{V}}{N}\right)^{1/3} ; \quad |\bar{u}_y| \sim v_s = \sqrt{\frac{C_p}{C_v} \left(\frac{\partial P}{\partial S}\right)_T}$$

$$\hat{c}_v = 3 \frac{K}{m})_{\text{monatomic liquid}}$$

$$\approx \sqrt{\frac{\partial P}{\partial S}}_T$$

$$\text{as } C_p/C_v \approx 1$$

so

$$K \approx 3 \left(\frac{\rho}{m}\right) \left(\frac{\tilde{V}}{N}\right)^{1/3} K v_s$$

$$\hookrightarrow \equiv \frac{\tilde{N}}{\tilde{V}}$$

$$\text{or, empirically, } K \approx 2.80 \left(\frac{\tilde{N}}{\tilde{V}}\right)^{2/3} K v_s$$

$$\text{where } v_s \approx \sqrt{\frac{\partial P}{\partial S}}_T$$

This shows where K comes from for liquids, but usually you just look it up!

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Now for solids: even messier!

Solids are often porous composites

For dry sand conduction occurs through grains, grain contacts, and air matrix — because air is a poor conductor, this is slow!

For wet sand, water is a better conductor, so conductivity goes up!

For metals conduction is via conduction band electrons, so conductivity is much higher!

electrical conductivity of copper >> elec. cond. of steel, \therefore so is thermal conductivity!

They are (mostly) proportional...

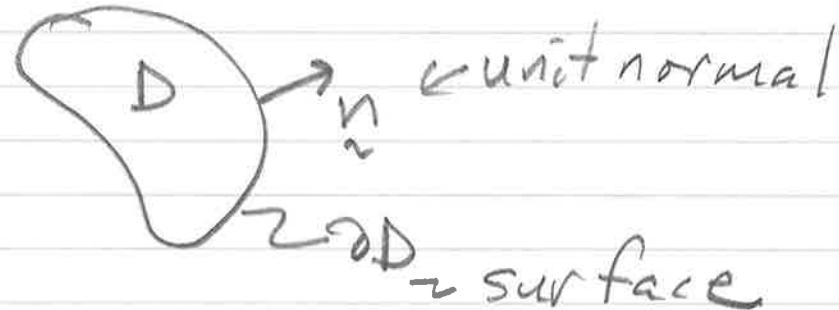
Now let's look at heat conduction
in solids! We need conservation
equation. We'll do a simplified
derivation (for now)

We take thermal energy = $\hat{g} \hat{C}_p T$
 volume volumetric
 conductive ht flux = \hat{q}

$$\frac{\text{energy source}}{\text{volume}} = \dot{S} \quad (\text{rxn, elec. dissip, etc.})$$

(per time, $\frac{\text{watts}}{\text{Vol}}$)

Take arbitrary control volume D



Energy in D is conserved!

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$$\left\{ \begin{array}{l} \text{accum energy} \\ \text{in } D \end{array} \right\} + \left\{ \begin{array}{l} \text{rate energy} \\ \text{out by cond.} \end{array} \right\} = \left\{ \text{sources} \right\}$$

$$\frac{\partial}{\partial t} \int_D \hat{\rho} \hat{C}_p T dV + \int_{\partial D} \vec{q} \cdot \hat{n} dA = \int_D \dot{s} dV$$

$$\int_D \vec{q} \cdot \hat{n} dV \quad \begin{matrix} \text{by divergence} \\ \text{theorem} \end{matrix}$$

If $\hat{\rho} \hat{C}_p$ is constant in time, because D is arbitrary we have the equation valid at every point:

$$\hat{\rho} \hat{C}_p \frac{\partial T}{\partial t} = - \vec{\nabla} \cdot \vec{q} + \dot{s}$$

Now if $\vec{q} = -k \vec{\nabla} T$ and k is indep. of position,

$$\underbrace{\hat{\rho} \hat{C}_p \frac{\partial T}{\partial t}}_{\text{accum of } E} = \underbrace{k \vec{\nabla}^2 T}_{\text{cond/defn of } E} + \underbrace{\dot{s}}_{\text{sources of } E}$$

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Note parallel w/ unidirectional flow!

- for flow in x-dir. only, x-component of Navier-Stokes equations is:

$$\underbrace{g \frac{\partial u_x}{\partial t}}_{\substack{\text{accum of} \\ x\text{-mom}}} = \mu \underbrace{\nabla^2 u_x}_{\substack{\text{dif'n of} \\ x\text{-mom}}} + \underbrace{\left(-\frac{\partial P}{\partial x} + \rho g_x \right)}_{\substack{\text{sources of} \\ x\text{-mom (per vol.)}}}$$

solutions are identical w/ same B.C.'s

plane-Couette flow \equiv cond. through slab

plane-Poiseuille flow \equiv cond. in slab
w/ ht. generation

tube-Pois. flow \equiv cond. in wire w/
ht. generation

There are identical parallels w/ mass transfer too!

Solutions depend on B.C.'s — what kinds are there? 17

- fixed temperature (e.g., $T|_{\partial D} = T_0$)
(equiv. to no-slip condition)
- fixed heat flux (e.g., $\dot{q} \cdot \hat{n}|_{\partial D} = q_0$)
(equiv. to, say, wall shear stress τ_w)
- mixed B.C. (heat transfer coef.)

$$\dot{q} \cdot \hat{n}|_{\partial D} = h (T|_{\partial D} - T_a)$$

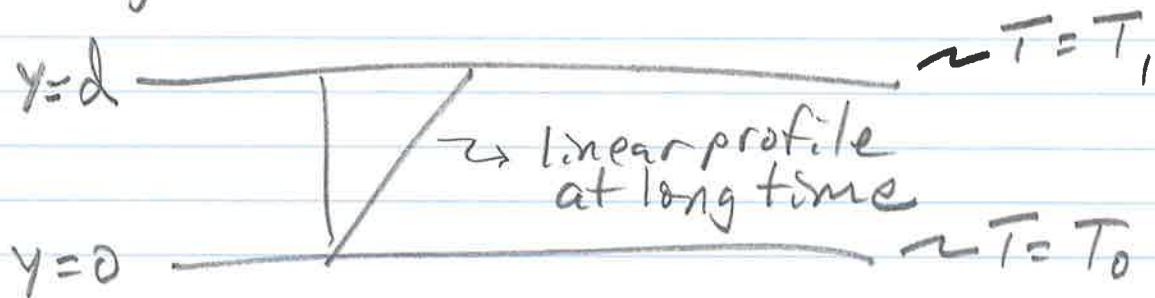
↑ ht. transf. coef.

- we used this BC. for lubricated core-annular flow, actually, but occurs more often in ht transfer

Now let's solve problems! We'll begin w/ 55, then look at start-up transients, Sturm-Liouville theory and boundary layer theory.

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First - the simplest problem! Heat cond.
through a slab!



Assume:

- 1) conduction only in y -direction
- 2) steady-state
- 3) no heat sources (inside!)

$$\hat{q} \leftarrow \frac{\partial T}{\partial t} = K \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right) + \dot{S}$$

0 (ss) 0 0 No source

$$\underline{\text{so}} \quad \frac{\partial^2 T}{\partial y^2} = 0 ; \quad T \Big|_{y=0} = T_0$$

$$T \Big|_{y=d} = T_1$$

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Render dimensionless!

- All dimensionless variables should be of $O(1)$.
- Allow B.C.'s to suggest scaling
(often get some from DE too, but not this time!)

$$T|_{y=0} = T_0 \Rightarrow \text{subtract off ref. temp. } T_0$$

$$\therefore T^* = \frac{T - T_0}{\Delta T_c} \quad T^*|_{y=0} = 0$$

$$T|_{y=\infty} = T_1 \quad \therefore T = T_0 + \Delta T_c T^* \\ \hookrightarrow y^* = \frac{y}{\Delta T_c}$$

$$\therefore \Delta T_c T^*|_{y^*=1} = T_1 - T_0$$

$$T^*|_{y^*=1} = \frac{T_1 - T_0}{\Delta T_c} \\ \checkmark = 1$$

$$\text{so } \Delta T_c = T_1 - T_0$$

$$\therefore \frac{\partial^2 T^*}{\partial y^{*2}} = 0 ; \quad T^* \Big|_{y=0} = 0 \quad T^* \Big|_{y^*=1} = 1 \quad (20)$$

Integ. twice:

$$T^* = A y^* + B$$

$$\begin{aligned} & \downarrow \quad \downarrow \text{since } T^* \Big|_{y^*=0} = 0 \\ & = 1 \text{ from other BC!} \end{aligned}$$

$\therefore T^* = y^*$; same as plane-Couette flow!

What is the heat flux at $y=0$?

$$q_y \Big|_{y=0} = -k \frac{\partial T}{\partial y} \Big|_{y=0} = -k \frac{(T_1 - T_0)}{\Delta} \frac{\partial T^*}{\partial y^*} \Big|_{y^*=0} = 1 !$$

$$\therefore q_y = -k \frac{(T_1 - T_0)}{\Delta}$$

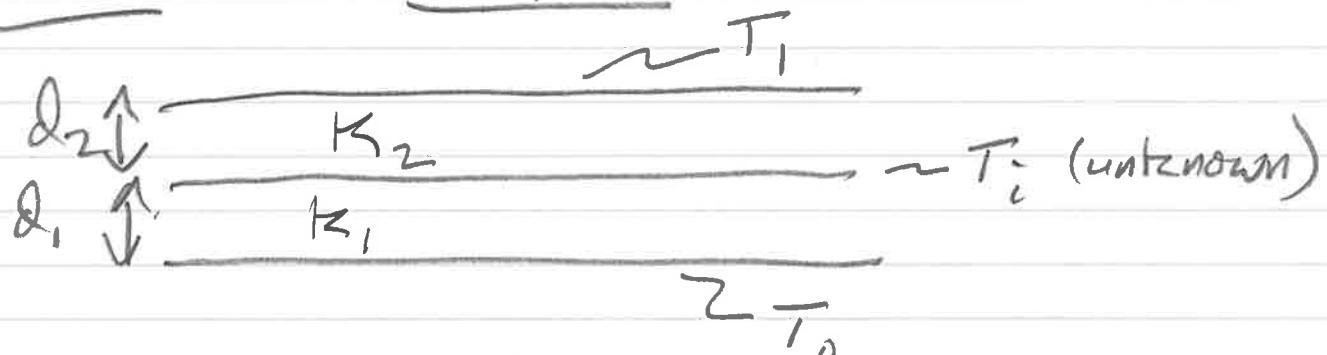
Note that in this geometry q_y is constant:

the same heat flux through every plane!

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Often we have multiple layers w/
different conductivities! (e.g., an insulated wall)

How to solve? Solve in each region and
match at interface!



What are the matching conditions?

At the interface T and $\overset{\sim}{q \cdot n}$ are
continuous! $\overset{\sim}{q \cdot n}$ \hookrightarrow normal ht.
flux

For this geometry q_y is just a constant q_o !
(but it is unknown)

From the last problem

$$q_o = -\frac{k_2}{d_2} (T_1 - T_i) = -\frac{k_1}{d_1} (T_i - T_o)$$

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We can solve these equations to get T_i :

$$T_1 - T_i = \frac{d_2}{d_1} \frac{k_1}{k_2} (T_i - T_0)$$

rearrange:

$$T_i \left(1 + \frac{d_2}{d_1} \frac{k_1}{k_2} \right) = T_1 + T_0 \frac{d_2}{d_1} \frac{k_1}{k_2}$$

$$\text{so } T_i = \frac{T_1 + T_0 \frac{d_2}{d_1} \frac{k_1}{k_2}}{1 + \frac{d_2}{d_1} \frac{k_1}{k_2}}$$

and the flux:

$$\dot{Q}_0 = -k_2 (T_1 - T_i)$$

$$= -\frac{k_2}{d_2} \left(T_1 - \frac{T_1 + T_0 \frac{d_2}{d_1} \frac{k_1}{k_2}}{1 + \frac{d_2}{d_1} \frac{k_1}{k_2}} \right)$$

$$= \frac{-k_2/d_2}{1 + \frac{d_2}{d_1} \frac{k_1}{k_2}} \left(T_1 + T_0 \frac{d_2}{d_1} \frac{k_1}{k_2} - T_1 - T_0 \frac{d_2}{d_1} \frac{k_1}{k_2} \right)$$

$$= \frac{-(T_1 - T_0)}{1 + \frac{d_2}{d_1} \frac{k_1}{k_2}} \frac{k_1/d_1}{}$$

$$= \frac{-(T_1 - T_0)}{\frac{d_1/k_1}{d_1/k_1 + d_2/k_2}}$$

very simple!

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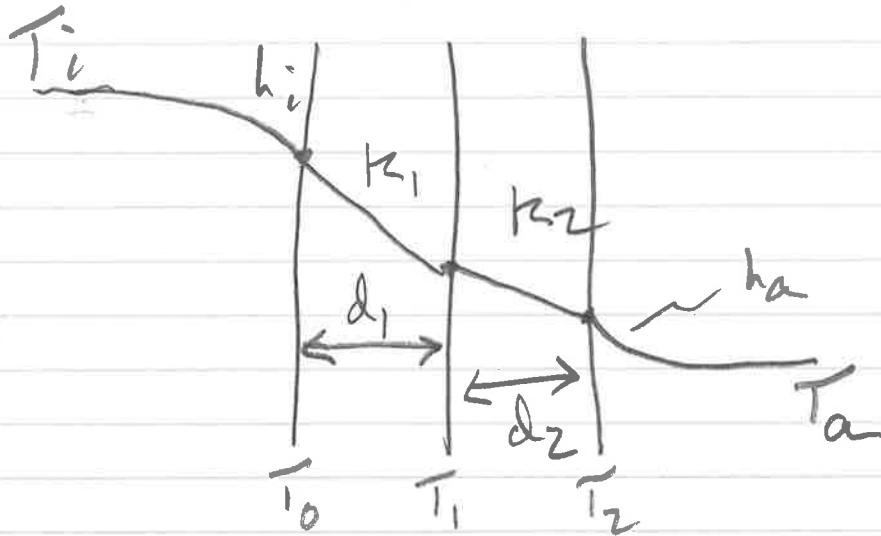
This suggests an analogy w/ electrical circuits:

$$\text{Resistance} \sim \frac{\rho}{k} \leftarrow \begin{matrix} \text{thickness} \\ \text{conductivity} \end{matrix}$$

$$\text{current} \sim q ; \text{voltage} \sim T$$

for resistors in series, total resistance is the sum of resistance of each layer!

We can use this to solve a much messier problem: two layers w/ internal & external heat transfer coefficient!



By definition $q = h_i(T_i - T_0)$ (inside)

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So the resistance of this layer is $\frac{1}{h_i}$!

$$\text{so: } q = \frac{-(T_c - T_a)}{\frac{1}{h_i} + \frac{d_1}{k_1} + \frac{d_2}{k_2} + \frac{1}{h_a}}$$

↑ ↑ ↑ ↑
 inside layer 1 layer 2 outside

$$\text{The quantity } U = \frac{1}{\sum \frac{1}{h}}$$

↓
 sum over all layers

is called the overall ht.
transfer coefficient.

The total flux is

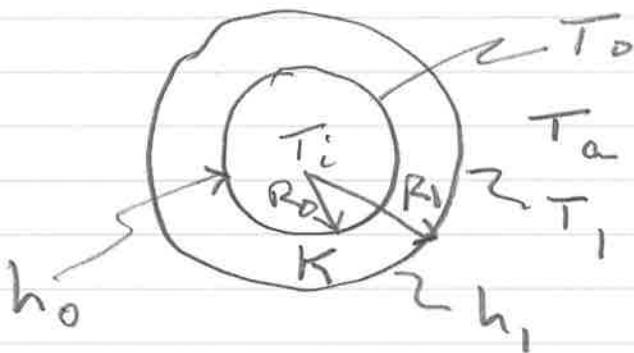
$$q = U \Delta T \quad \downarrow \text{area of wall}$$

and heat loss is $Q = qA = UA\Delta T$

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While insulating walls is important,
often we want to insulate pipes!

We can use the same approach:



Say we have hot water in a pipe
w/ radius R_o , temp T_i

We have a heat transfer coeff. h_o

$$\text{sat. } q_r \Big|_{r=R_o} = h_o (T_i - T_o)$$

We have an external ht transfer
coeff. h_i s.t.

$$q_r \Big|_{r=R_i} = h_i (T_i - T_a)$$

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We don't know T_0 or T_1 !

We need to solve for the temp. dist. in the insulation!

In cyl. coord:

$$K \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) = 0$$

$$\therefore r \frac{\partial T}{\partial r} = A \quad (\text{cst. of integ})$$

$$\therefore T = A \ln r + B$$

$$\text{Now } T \Big|_{r=R_0} = T_0 ; \quad T \Big|_{r=R_1} = T_1$$

$$\therefore T = T_0 + (T_1 - T_0) \frac{\ln \frac{r}{R_0}}{\ln \frac{R_1}{R_0}}$$

We need the flux at R_0 :

$$q_r \Big|_{r=R_0} = -K \frac{\partial T}{\partial r} \Big|_{R_0} = K \frac{(T_0 - T_1)}{R_0 \ln \left(\frac{R_1}{R_0} \right)}$$

The total heat transfer through each cylinder is constant!

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Thus:

$$Q = 2\pi R_0 L q_r \Big|_{r=R_0} = 2\pi R_0 L K \frac{(T_0 - T_i)}{R_0 \ln(\frac{R_1}{R_0})}$$

we also have

$$\begin{aligned} Q &= 2\pi R_0 L h_o (T_i - T_0) \\ &= 2\pi R_1 L h_1 (T_1 - T_a) \end{aligned} \quad \left. \begin{array}{l} \text{other} \\ \text{layers!} \end{array} \right.$$

Rearranging:

$$\frac{Q}{2\pi L} \frac{1}{h_o R_0} = T_i - T_0$$

$$\frac{Q}{2\pi L} \frac{\ln(\frac{R_1}{R_0})}{K} = T_0 - T_1$$

$$\frac{Q}{2\pi L} \frac{1}{h_1 R_1} = T_1 - T_a$$

$$\frac{Q}{2\pi L} \left[\frac{1}{h_o R_0} + \frac{\ln(\frac{R_1}{R_0})}{K} + \frac{1}{h_1 R_1} \right] = T_i - T_a$$

$$\text{or } Q = \frac{2\pi L (T_i - T_a)}{\frac{1}{h_o R_0} + \frac{\ln(\frac{R_1}{R_0})}{K} + \frac{1}{h_1 R_1}}$$

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This has the curious feature that if κ is too large (bad insulation) then increasing R_1 , will increase Q !

Let's look at this:

$$\frac{\partial Q}{\partial R_1} = \frac{-Q}{\frac{1}{h_0 R_0} + \frac{\ln(R_1/R_0)}{\kappa} + \frac{1}{h_1 R_1}} \left(\frac{1}{R_1 \kappa} - \frac{1}{h_1 R_1^2} \right)$$

This is positive if

$$\frac{1}{R_1 \kappa} - \frac{1}{h_1 R_1^2} < 0$$

$$\text{or } \frac{h_1 R_1}{\kappa} < 1$$

$$\text{or } R_1 < \frac{\kappa}{h_1}$$

Now $R_1 > R_0$ so this can only

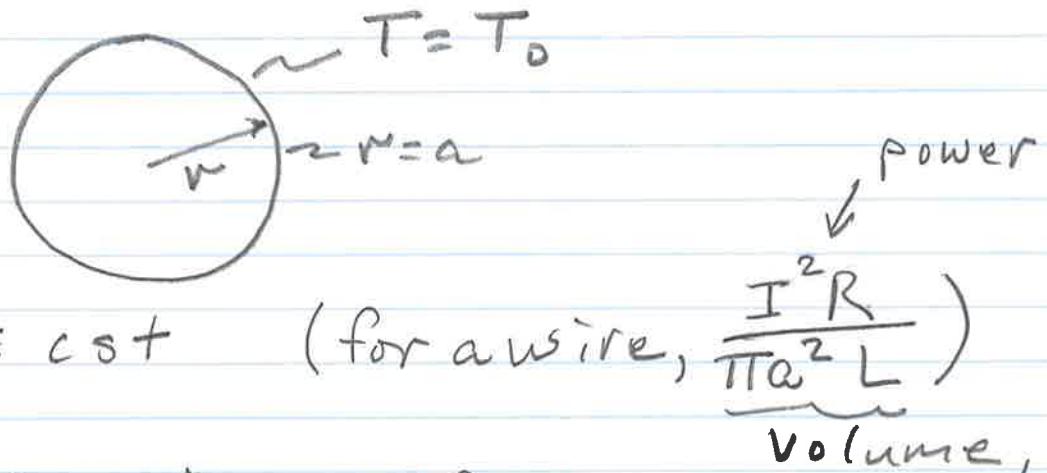
$$\text{occur if } R_0 < \frac{\kappa}{h_1}$$

$$\text{or } \kappa > h_1 R_0$$

If κ is less than $h_1 R_0$, Q always decreases!

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Now let's look at conduction w/
an energy source: electrical dissip.!



$$\dot{S} = \text{const} \quad (\text{for a wire, } \frac{I^2 R}{\pi a^2 L})$$

Volume

This (for DC) is uniform in the wire!

$$\therefore \rho C_p \hat{\nabla} \frac{\partial T}{\partial t} = \kappa \nabla^2 T + \dot{S}$$

- Assume SS : $\frac{\partial T}{\partial t} = 0$

- Diff^u (conduction) only in radial direction

* - Choose coord system in which
boundary has a convenient rep!

\therefore cyl. coords!

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All equations of change, operators,
etc. are in Appendix B! Know
where it is!!

$$\nabla^2 \equiv \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \theta^2} + \frac{\partial^2 T}{\partial z^2}$$

If $a \ll L$ then conduction in z direction is negligible (for this problem)

$$So : \quad 0 = K \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + S$$

$$T|_{r=0} = T_0 \quad T|_{r=0} = \underline{\text{finite}} \quad (\underline{\text{not singular}})$$

Let's render dimensionless:

$$T^* = \frac{T - T_0}{\Delta T_c} \quad r^* = \frac{r}{a} \quad) \text{ suggested by BC's}$$

What's ΔT_c ?

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Plug into D.E.:

$$0 = \frac{K \Delta T_c}{a^2} - \frac{1}{r^*} \frac{\partial}{\partial r^*} \left(r^* \frac{\partial T^*}{\partial r^*} \right) + \dot{s}$$

Divide out:

$$0 = \frac{1}{r^*} \frac{\partial}{\partial r^*} \left(r^* \frac{\partial T^*}{\partial r^*} \right) + \left[\frac{\dot{s} a^2}{K \Delta T_c} \right]$$

$$\therefore \Delta T_c = \frac{\dot{s} a^2}{K} !$$

$$\text{so } \frac{1}{r^*} \frac{\partial}{\partial r^*} \left(r^* \frac{\partial T^*}{\partial r^*} \right) = -1$$

Integrate (mult by r^* first):

$$r^* \frac{\partial T^*}{\partial r^*} = -\frac{1}{2} r^{*2} + A$$

Divide by r^* & integ again:

$$T^* = -\frac{1}{4} r^{*2} + A \ln r^* + B$$

$$T^* \Big|_{r^*=0} = \text{finite}, \text{ so } A=0$$

(note - not true for a hollow pipe!)

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$$T^* \Big|_{r^*=1} = 0 \quad \therefore B = \frac{1}{4}$$

and $T^* = \frac{1}{4} (1 - r^{*2})$

$$\text{or } T = T_0 + \frac{\dot{s}a^2}{K} \frac{1}{4} \left(1 - \frac{r^2}{a^2}\right)$$

This is identical to Poiseuille flow!

What is the energy flux at $r=a$?

$$q \Big|_{r=a} = -k \frac{\partial T}{\partial r} \Big|_{r=a} = -k \frac{\Delta T_c}{a} \frac{\partial T^*}{\partial r^*} \Big|_{r^*=1}$$

$$\text{Now } \frac{\partial T^*}{\partial r^*} \Big|_{r^*=1} = -\frac{1}{2} \quad ! \quad (\text{nice } O(1) !)$$

$$\therefore q \Big|_{r=a} = -k \frac{\dot{s}a^2}{K} \left(-\frac{1}{2}\right) = \frac{1}{2} \dot{s}a$$

indep. of T_c - as it has to be!

We can get it from an energy balance
without knowing T !



$$Q_r \Big|_{r=a} \cdot 2\pi a L = \dot{S} \frac{\pi a^2 L}{\text{volume}}$$

\dot{S} Surface Area

$$\therefore Q_r \Big|_{r=a} = \frac{1}{2} \dot{S} a$$

The same relation was found between the wall shear stress and pressure gradient for Poiseuille flow!

This problem is done w/ shell balances in section 10.2

(34)

We can look at a similar problem in the spherical coord system: a spherical pellet of radioactive material in a solid matrix at const. temp. at infinity: related to nuclear waste storage, for example!

$$T|_{r \rightarrow \infty} = T_\infty \quad (unknown)$$

$$K_\infty \rightarrow T|_{r=a} = T_s \quad (also unknown)$$

$$T|_{r=0} = T_0 \quad (also unknown)$$

We want to calculate the temp. at the center T_0 !

We solve this inside and outside the sphere!

$$\hat{C}_p \frac{\partial T}{\partial t} = K \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial^2 T}{\partial \theta^2} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 T}{\partial \phi^2} \right] + \dot{S}$$

(35)

we're at SS, and all θ & ϕ derivatives are zero (symmetry), so:

$$0 = k \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) + \dot{s}$$

Outside the sphere:

$$k = k_{\infty}, \quad \dot{s} = 0$$

$$T \Big|_{r=a} = T_s \quad (\text{unknown})$$

$$T \Big|_{r \rightarrow \infty} = T_{\infty}$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) = 0 !$$

$$\therefore r^2 \frac{\partial T}{\partial r} = A$$

$$\frac{\partial T}{\partial r} = \frac{A}{r^2}$$

$$T = -\frac{A}{r} + B$$

$$\text{From BC's } T = T_{\infty} + (T_s - T_{\infty}) \frac{a}{r}$$

what is the heat flux? (36)

$$\begin{aligned} Q_r \Big|_{r=a} &= -k_\infty \frac{\partial T}{\partial r} \Big|_{r=a} \\ &= +k_\infty (T_s - T_\infty) \frac{a}{r^2} \Big|_{r=a} \\ &= \frac{k_\infty}{a} (T_s - T_\infty) \end{aligned}$$

so we have a heat transfer coef

$$h = \frac{k_\infty}{a}$$

for external heat transfer!

Now for the inside:

$$k \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) = -\dot{s}$$

$$r^2 \frac{\partial T}{\partial r} = -\frac{\dot{s}}{k} \frac{1}{3} r^3 + A$$

$$\frac{\partial T}{\partial r} = -\frac{\dot{s}}{k} \frac{1}{3} r + \frac{A}{r^2}$$

since $T \Big|_{r=0}$
is finite!

$$\therefore T = -\frac{\dot{s}}{k} \frac{1}{6} r^2 + B$$

(37)

$$\text{Now } T|_{r=a} = T_s$$

$$\therefore T_s = -\frac{\dot{S}}{K} \frac{1}{6} a^2 + B$$

$$B = T_s + \frac{\dot{S}}{K} \frac{1}{6} a^2$$

$$\text{and } T|_{r=0} = B !$$

We still need T_s to finish!

We need to match heat flux at the surface!

$$q_r|_{r=a} = -K \frac{\partial T}{\partial r}|_{r=a} = (-K) \left(-\frac{\dot{S}}{K} \frac{1}{3} a \right)$$

$$= \frac{1}{3} a \dot{S} = \frac{K_a}{a} (T_s - T_\infty)$$

Note that we could also have gotten

$q_r|_{r=a}$ from an energy balance!

$$\frac{4\pi a^2 q_r}{\text{surf. area}}|_{r=a} = \frac{4}{3} \pi a^3 \dot{S}$$

Volume

(38)

Anyway,

$$T_S = T_\infty + \frac{1}{3} \frac{a^2 S}{K_\infty}$$

and so

$$T|_{r=0} = T_0 = T_\infty + \underbrace{\frac{1}{3} \frac{a^2 S}{K_\infty}}_{\text{temp increase from far away}} + \underbrace{\frac{1}{6} \frac{a^2 S}{K}}_{\text{temp inc. from surface}}$$

Interestingly, this doesn't work for exterior temp variation for a cylinder:

$$\text{at } r \rightarrow \infty \quad T_\infty \quad \text{at } r \rightarrow 0 \quad \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) = 0$$

$$\therefore T = A \ln r + B$$

$$\text{or } T - T_S = A \ln \frac{r}{a}$$

The problem is that this blows up as $r \rightarrow \infty$! No solution!

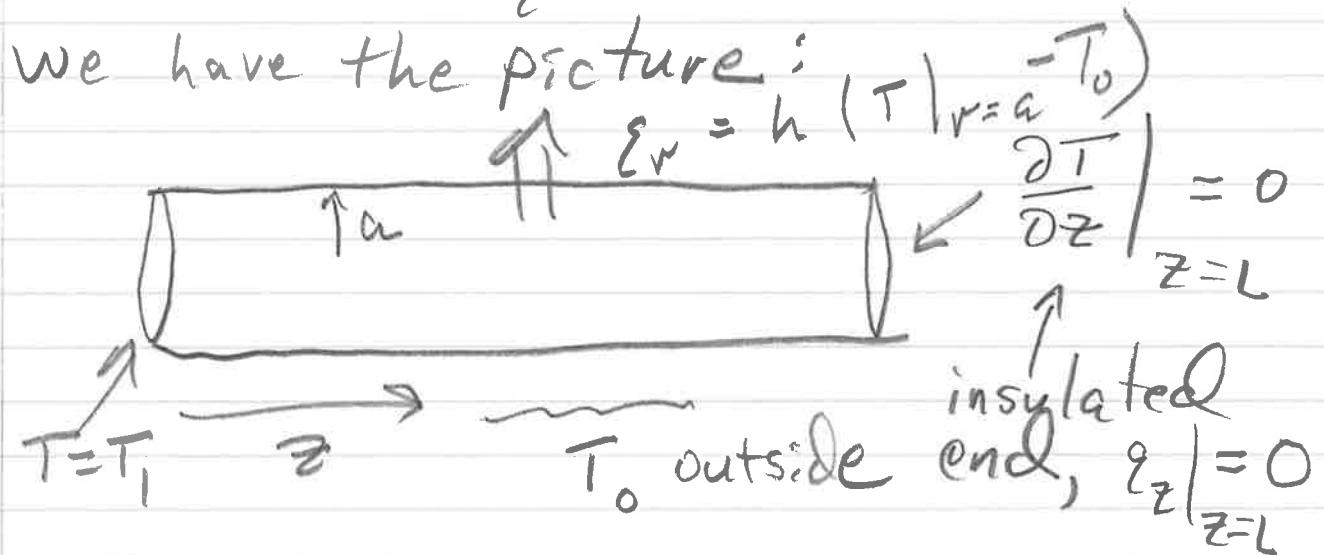
(39)

OK, now for a bit trickier problem:
 the cooling fin (section 10.7). We have
 a rod of length L & radius a
 heated at one end! All along the
 length we lose heat (usually via
 convection). We model this with
 a heat transfer coef.:

$$q_r \Big|_{r=a} = h(T \Big|_{r=a} - T_0)$$

Both q_r and T vary w/ z !

What is the equation for T ?



(40)

We can get the equation from shell balance

Suppose we have some area avg
 temp. $\bar{T} \equiv \frac{1}{\pi a^2} \int_0^a T 2\pi r dr$

Along the rod we get:

$$\begin{aligned}
 -k\pi a^2 \frac{\partial \bar{T}}{\partial z} &\stackrel{z}{=} \left[\int_z^{z+\Delta z} T dr \right] \Rightarrow -k\pi a^2 \frac{\partial \bar{T}}{\partial z} \Big|_{z+\Delta z} \\
 &\quad \xrightarrow{\text{Integration}} \int_z^{z+\Delta z} T dr = \int_z^{z+\Delta z} Q_p \cdot 2\pi a \Delta z \\
 &= 2\pi a \Delta z h (\bar{T} \Big|_{r=a} - \bar{T}_0)
 \end{aligned}$$

Thus we get the balance:

$$0 = -k\pi a^2 \left(\frac{\partial \bar{T}}{\partial z} \Big|_{z+\Delta z} - \frac{\partial \bar{T}}{\partial z} \Big|_z \right) + 2\pi a h \Delta z (\bar{T} \Big|_{r=a} - \bar{T}_0)$$

Divide by Δz and take limit $\Delta z \rightarrow 0$

$$-\kappa \pi a^2 \frac{\partial^2 T}{\partial z^2} + 2\pi a h (T|_{r=a} - T_0) = 0 \quad (41)$$

Let's render dimensionless.

At $z=0$, $T=T_1$ (hot end)

From DE, ref. temp. is T_0

$$\therefore T^* = \frac{T - T_0}{T_1 - T_0} \rightarrow w^* = \frac{r}{a}, z^* = \frac{z}{L}$$

$$\therefore \frac{\partial^2 T^*}{\partial z^{*2}} - \left[\frac{2 h L^2}{\kappa a} \right] T^* \Big|_{r^*=1} = 0$$

$$T^* \Big|_{z^*=0} = 1 \quad \frac{\partial T^*}{\partial z^*} \Big|_{z^*=1} = 0$$

To close, we make the approx.
that $\bar{T}^* \approx T^*|_{r^*=1}$ - negligible
radial temp. gradients!

This works provided $a/L \ll 1$

(42)

We can get the same equation by averaging the ht transfer equation over the rod!

$$\hat{q} \hat{C}_p \frac{\partial \bar{T}}{\partial t} = k \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{\partial^2 T}{\partial z^2} \right]$$

Recall $\bar{T} = \frac{1}{\pi a^2} \int_0^a T 2\pi r dr$

∴ mult by $2\pi r$, integ. over r , divide by πa^2

$$\frac{\hat{q} \hat{C}_p}{\pi a^2} \frac{\partial}{\partial t} \int_0^a T 2\pi r dr = \frac{k}{\pi a^2} \int_0^a \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \bar{T}}{\partial r} \right) 2\pi r dr$$

$$+ \frac{k}{\pi a^2} \frac{\partial^2}{\partial z^2} \int_0^a T 2\pi r dr$$

$$\hat{q} \hat{C}_p \frac{\partial \bar{T}}{\partial t} = \frac{k}{\pi a^2} \left(r \frac{\partial \bar{T}}{\partial r} \right) \Big|_0^a + k \frac{\partial^2 \bar{T}}{\partial z^2}$$

Now $\frac{\partial \bar{T}}{\partial r} \Big|_{r=0} = 0$ (symmetry, finite T , etc.)

and $2 \Big|_{r=a} = -k \frac{\partial \bar{T}}{\partial r} \Big|_{r=a} = h (\bar{T}|_{r=a} - \bar{T}_0)$

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$$\text{So } \kappa \frac{\partial \bar{T}}{\partial r} \Big|_{r=a} = -h (\bar{T} \Big|_{r=a} - T_0)$$

or, plugging back in:

$$\rho \hat{C}_p \frac{\partial \bar{T}}{\partial t} = -\frac{2h}{a} (\bar{T} \Big|_{r=a} - T_0) + \kappa \frac{\partial^2 \bar{T}}{\partial r^2}$$

$$\text{At SS } \frac{\partial \bar{T}}{\partial t} = 0$$

$$\therefore \frac{\partial^2 \bar{T}^*}{\partial r^2} - \left(\frac{2hL^2}{aK} \right) \bar{T}^* \Big|_{r=1} = 0$$

as before!

Again, we take $\bar{T}^* \Big|_{r=1} \approx \bar{T}^*$ by neglecting radial variations!

so how do we solve this? This is a constant coef. ODE! The solutions are exponentials. For this one, the solution is more easily expressed as hyperbolics!

(44)

$$\text{Let } \lambda^2 \equiv \frac{2hL^2}{\alpha k}$$

$$\therefore \frac{\partial^2 \bar{T}^*}{\partial z^*^2} = \lambda^2 \bar{T}^* \quad (\text{neglecting radial var.})$$

$$\therefore \bar{T}^* = A \cosh \lambda z^* + B \sinh \lambda z^*$$

$$\bar{T}^* \Big|_{z^*=0} = 1 \quad \therefore A = 1$$

$$\frac{\partial \bar{T}^*}{\partial z^*} \Big|_{z^*=1} = 0 = \lambda \sinh \lambda + B \lambda \cosh \lambda$$

$$\therefore B = -\frac{\sinh \lambda}{\cosh \lambda}$$

$$\text{and } \bar{T}^* = \cosh \lambda z^* - \frac{\sinh \lambda}{\cosh \lambda} \sinh \lambda z^*$$

We are most interested in the heat loss at $z=0$ (base of fin/rod)

$$Q = -k \frac{\partial \bar{T}}{\partial z} \Big|_{z=0} \cdot \pi a^2 = -k \frac{\pi a^2 (\bar{T}_1 - \bar{T}_0)}{L} \frac{\partial \bar{T}}{\partial z^*} \Big|_{z^*=0}$$

$\overline{q_z} \nearrow$ area scaling

(45)

Now from sol'n:

$$\left. \frac{\partial \bar{T}^*}{\partial z^*} \right|_{z^*=0} = \lambda \sinh \lambda z^* \Big|_{z^*=0} - \lambda \frac{\sinh \lambda}{\cosh \lambda} \cosh \lambda z^* \Big|_{z^*=0}$$

$= 0$!

$$= -\lambda \frac{\sinh \lambda}{\cosh \lambda}$$

$$\therefore Q = \frac{K\pi a^2 (T_1 - T_0)}{L} \left(\frac{2 h L^2}{a k} \right)^{1/2} \frac{\sinh \lambda}{\cosh \lambda}$$

This is a little messy, but it has
2 useful asymptotic limits depending

on $\lambda \equiv \left(\frac{2 h L^2}{a k} \right)^{1/2} = \frac{L}{\left(\frac{a k}{2 h} \right)^{1/2}}$

which is a dimensionless rod length!

First, if $\lambda \ll 1$ then $\frac{\sinh \lambda}{\cosh \lambda} \approx \lambda$

$$\therefore Q = \frac{K\pi a^2 (T_1 - T_0)}{L} \left(\frac{2 h L^2}{a k} \right)$$

$$= h (2\pi a L) (T_1 - T_0)$$

(46)

which is the heat loss you get if the entire surface is at T_1 !

The limit $\lambda \gg 1$ yields $\frac{\sinh \lambda}{\cosh \lambda} \approx 1$

$$\therefore Q = \frac{k\pi a^2 (T_1 - T_0)}{k} \left(\frac{2hL^2}{ak} \right)^{1/2}$$

$$= (T_1 - T_0) \left(2\pi^2 a^3 h k \right)^{1/2}$$

which is indep. of L ! This is because the rod cools off over a lengthscale $\left(\frac{ak}{2h} \right)^{1/2}$ & does so exponentially! Thus, only the

length of $O(\left(\frac{ak}{2h} \right)^{1/2})$ contributes to the cooling at the base!

You could use this to optimize your design!

(47)

Over and over we have made use
of the heat transfer coefficient h :

$$q = h \Delta T$$

↑ ↑
 $\frac{E}{\text{area} \cdot \text{time}}$ appropriate ΔT
 ↓ ↓
 E area · time (varies w/ application)

For a slab of thickness δ

$$h = \frac{k}{\delta}$$

For external ht transfer from a sphere
(w/ no convection)

$$h = \frac{k}{a} \leftarrow \text{radius}$$

For an annulus (pipe insulation)

$$h = \frac{k}{R_0 \ln(R_1/R_0)}$$

(based on area
of inner (R_0) surf)

- this has the limiting value $\frac{k}{\Delta R}$ for $\frac{\Delta R}{R_0} \ll 1$

- Note: no sol'n as $R_1/R_0 \rightarrow \infty$

(48)

What about convection? For a cylinder (such as our rod) h arises from air (or water) blowing past!



If we think of this (boundary layer) region as insulation of thickness δ , then:

$$\delta = \frac{K}{\dot{V}}$$

What is δ ?? Fluid blows past over a time $t \sim D/U$

Energy diffuses a length

$$\delta \sim (\alpha t)^{1/2}$$

\hookrightarrow thermal diffusivity $\frac{K}{\rho C_p}$
over this time!

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$$\text{Thus: } h \sim \frac{K}{(x+t)^{1/2}} \sim \frac{K}{(\frac{xD}{\nu})^{1/2}}$$

$$= \frac{K}{D} \left(\frac{UD}{\nu} \right)^{1/2} \left(\frac{\nu}{\alpha} \right)^{1/2}$$

\uparrow \uparrow
Re Pr

where $\nu = \frac{\mu_{\text{visc}}}{\rho}$
(kinematic viscosity)

In fact, correlations based on exp't get pretty close to this!

from Whittaker (e.g., sec. 14-4)

$$h = \frac{K}{D} \left(0.4 Re^{1/2} + 0.06 Re^{2/3} \right) Pr^{0.4} \left(\frac{\mu_{\text{visc}}}{\mu_0} \right)^{1/4}$$

↑
correction
due to visc.
variation w/ T

many other correlations exist for different geometries. We will look at this and other correlations (& sources!) again and again!

(50)

It is useful to look at heat transfer in terms of dimensionless numbers. There are many, but so far we've looked at the Biot number:

$$Bi = \frac{\frac{h a}{K}}{\frac{R/a}{a}} = \frac{h a}{K} \cdot \frac{a}{R/a}$$

external h + transfer coef
 material length scale
 material thermal cond
 external h + transf. coef
 internal h + transf. coef

so if $Bi \gg 1$ we are dominated by internal resistance

if $Bi \ll 1$ we are dominated by external resistance.

$$\text{For general shapes } a \sim \frac{V}{A} \xrightarrow[\text{surf area}]{\text{vol}}$$

$$\text{(e.g., for a sphere } \frac{V}{A} \sim \frac{1}{3} a^2)$$

$$\text{cylinder } \frac{V}{A} \sim \frac{1}{2} a^2$$

$$\text{slab } \frac{V}{A} \sim a \text{ (half width)}$$

The second (and most important!) group is the Nusselt number - which looks the same!

$$Nu = \frac{hD}{K} \leftarrow \begin{array}{l} \text{diameter (or length scale)} \\ K \leftarrow \text{external} \\ h + \text{transf.} \\ \text{coef.} \end{array}$$

$$Nu = \frac{h}{\frac{K}{D}} \leftarrow \begin{array}{l} \text{actual } h + \text{transf. coef.} \\ \text{expected } h + \text{transf.} \\ \text{coef. if pure conduction} \end{array}$$

For our sphere in a solid, $h = \frac{K}{a}$

$$\therefore Nu = 2 \quad (\text{pure conduction limit})$$

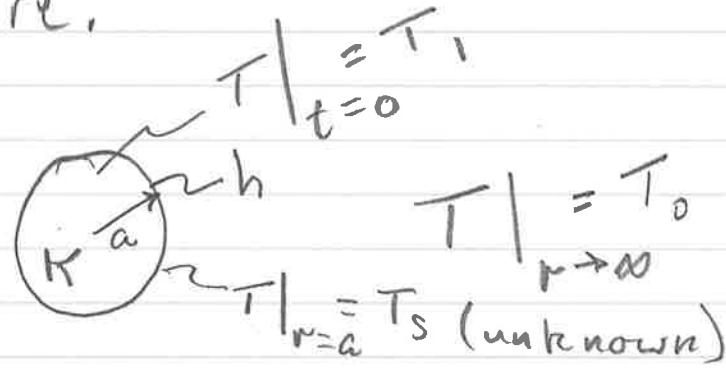
If we have convection, from Whittaker

$$\frac{hD}{K} \equiv Nu = 2 + \left(0.4 Re^{\frac{1}{2}} + 0.06 Re^{\frac{2}{3}}\right) Pr^{\frac{0.4}{3}} \left(\frac{h}{K}\right)^{\frac{1}{4}}$$

e.g., same as for a cylinder, but w/
conduction limit added in!

(52)

To see how this works, let's look at a classic problem: Quenching of a hot sphere!



$$q_r \Big|_{r=a} = h (T|_{r=a} - T_0)$$

where $\frac{hD}{K_{ext}} = Nu$ (either 2, or from correlation...)

OK, we have the PDE:

$$\rho C_p \frac{\partial T}{\partial t} = K \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right)$$

and $T|_{t=0} = T_1$, $T|_{r=0}$ = finite

$$-K \frac{\partial T}{\partial r} \Big|_{r=a} = q_r \Big|_{r=a} = h (T|_{r=a} - T_0)$$

(53)

Let's render dimensionless!

$$r^* = r/a, \quad T^* = \frac{T - T_0}{T_i - T_0} \quad (\text{from BC & IC})$$

$$t^* = t/t_c \quad (\text{to be determined!})$$

Recall $\alpha \equiv \frac{\kappa}{\rho C_p}$ (thermal diffusivity)

$$\therefore \frac{\rho G}{t_c} \frac{\partial T^*}{\partial t^*} = \frac{\kappa}{a^2} \frac{1}{r^{*2}} \frac{\partial}{\partial r^*} \left(r^{*2} \frac{\partial T^*}{\partial r^*} \right)$$

divide out

$$\therefore \frac{\partial T^*}{\partial t^*} = \left[\frac{t_c \alpha}{a^2} \right] \frac{1}{r^{*2}} \frac{\partial}{\partial r^*} \left(r^{*2} \frac{\partial T^*}{\partial r^*} \right)$$

$$\therefore \text{so } t_c = \frac{a^2}{\alpha} \text{ - diff time!}$$

And we have BC's:

$$T^* \Big|_{t^*=0} = 1 \quad T^* \Big|_{r^*=0} = \text{finite}$$

$$-\frac{\kappa}{a} \frac{\partial T^*}{\partial r^*} \Big|_{r^*=1} = h T^* \Big|_{r^*=1}$$

$$\text{or } \frac{\partial T^*}{\partial r^*} \Big|_{r^*=1} = -\frac{h a}{\kappa} T^* \Big|_{r^*=1} \quad \rightarrow \text{Biot } \star!$$

(54)

It's easiest to look at 2 limits,

$B_i \gg 1 \Rightarrow \underline{\text{internal resistance}}$

$B_i \ll 1 \Rightarrow \underline{\text{external resistance}}$

We do the latter first!

This is similar to the cooling fin: we want to look at the average temp

$$\bar{T} = \frac{1}{\underbrace{\frac{4}{3}\pi a^3}_{\text{vol of sphere}}} \int_0^a T \underbrace{4\pi r^2 dr}_dV$$

$$\therefore \bar{T}^* = 3 \int_0^1 T^* r^{*2} dr^*$$

To get the equation for \bar{T}^* , multiply PDE by $3r^{*2}dr^*$ and integrate!

$$\begin{aligned} \frac{\partial}{\partial T^*} \left[3 \int_0^1 T^* r^{*2} dr^* \right] &= 3 \int_0^1 \frac{1}{r^{*2}} \frac{\partial}{\partial r^*} \left(r^{*2} \frac{\partial T^*}{\partial r^*} \right) r^{*2} dr^* \\ &= 3 \left. r^{*2} \frac{\partial T^*}{\partial r^*} \right|_0^1 = 3 \left. \frac{\partial T^*}{\partial r^*} \right|_{r^*=1} \cancel{\text{cancels!}} \end{aligned}$$

(55)

$$\text{Now } \left. \frac{\partial T^*}{\partial r^*} \right|_{r^*=1} = -3Bi T^* \Big|_{r^*=1} \text{ from BC}$$

$$\text{so: } \frac{\partial \bar{T}^*}{\partial t^*} = -3Bi T^* \Big|_{r^*=1}$$

If $Bi \ll 1$ then $T^* \Big|_{r^*=1} \approx \bar{T}^*$ (no internal resistance)

$$\therefore \frac{\partial \bar{T}^*}{\partial t^*} \approx -3Bi \bar{T}^*, \quad \bar{T}^* \Big|_{t^*=0} = 1$$

$$\text{and } \bar{T}^* = e^{-3Bi t^*} \quad t^* \equiv \frac{\alpha t}{a^2}$$

sometimes called
Fourier ~~xx~~

$$\text{so } \frac{\bar{T} - T_0}{T_i - T_0} \approx e^{-3 \frac{\alpha h}{K} \frac{\cancel{\rho C_p} t}{\cancel{a^2}}} = e^{-\frac{3 h t}{\cancel{\rho C_p} a^2}}$$

We can rewrite this!

$$A = 4\pi a^2 \quad V = \frac{4}{3}\pi a^3$$

$$\therefore \frac{A}{V} = \frac{3}{a}$$

(56)

and

$$\frac{\bar{T} - T_0}{T_1 - T_0} \approx e^{-\frac{A h t}{3 C_p V}}$$

which is good for any shape (provided $B_i \ll 1$ and h is constant)!

This is called the Lumped Capacitance Model

Now for the $B_i \rightarrow \infty$ limit!

$$T^*|_{r^*=1} = -\frac{1}{B_i} \frac{\partial T^*}{\partial r^*}|_{r^*=1} \approx 0 !$$

$$\text{w/ } \frac{\partial T^*}{\partial t^*} = \frac{1}{r^{*2}} \frac{\partial}{\partial r^*} \left(r^{*2} \frac{\partial T^*}{\partial r^*} \right)$$

$$T^*|_{t^*=0} = 1 , \quad T^*|_{r^*=0} = \text{finite}$$

How do we solve? Use separation of variables

(57)

This only works for linear
homogeneous PDE's w/ homogeneous
B.C.'s - but that's a lot of
transport problems!

key ref: Boyce & DiPrima, Ch 10&11

(this was your text, mine was '77 3rd ed...)

$$\text{Ok, let } T^* = F(r^*) G(t^*)$$

\uparrow \uparrow
only $F^*(r)$ only $F^*(t)$

Plug in:

$$F \frac{\partial G}{\partial t^*} = G \frac{1}{r^{*2}} \frac{\partial}{\partial r^*} \left(r^{*2} \frac{\partial F}{\partial r^*} \right)$$

Divide by FG , let ' denote deriv:

$$\underbrace{\frac{G'}{G}}_{F^*(+)} = \underbrace{\frac{1}{r^{*2}F} \left(r^{*2} F' \right)'}_{F^*(r^*)} = -\sigma^2$$

constant!

Look at G :

$$\frac{dG}{dt^*} = -\sigma^2 G$$

$$\text{so } G = e^{-\sigma^2 t^*}$$

(exponential decay,
why choose $\underline{-\sigma^2}$)

Now for F :

$$(r^{*2}F')' + \sigma^2 r^{*2} F = 0$$

$$F(0) = \text{finite}, \quad F(1) = 0$$

We can solve this via a trick!

$$\text{Let } F = \frac{H}{r^*}$$

$$\text{so: } F' = -\frac{H}{r^{*2}} + \frac{H'}{r^*}$$

$$r^{*2}F' = -H + r^* H'$$

$$(r^*F')' = -H' + H' + r^* H''$$

So plugging in:

$$r^* H'' + \sigma^2 r^* H = 0$$

or $H'' + r^2 H = 0$

$$H(0) = r^* F(r^*) \Big|_{r^*=0} = 0$$

$$H(1) = r^* F(r^*) \Big|_{r^*=1} = 0$$

The solutions are just sines & cosines!

$$H = C_1 \sin \Gamma r^* + C_2 \cos \Gamma r^*$$

$$H(0) = 0 \therefore C_2 = 0$$

$$H(1) = 0 \therefore \Gamma = n\pi \quad n = 1, 2, 3, \dots$$

e.g., the eigenvalues!

$$\text{So: } T^* = \sum_{n=1}^{\infty} A_n e^{-n\pi r^*} \frac{\sin n\pi r^*}{n\pi r^*}$$

chosen so that
 $F_n(0) = 1$
 (can absorb into

It turns out (via orthogonality) that
 $\int_0^1 A_n (-1)^{n-1} \, dr \rightarrow \text{get to in a bit}$

$$A_n = 2(-1)^{n-1} \quad \text{w/ } A_1 = 2$$

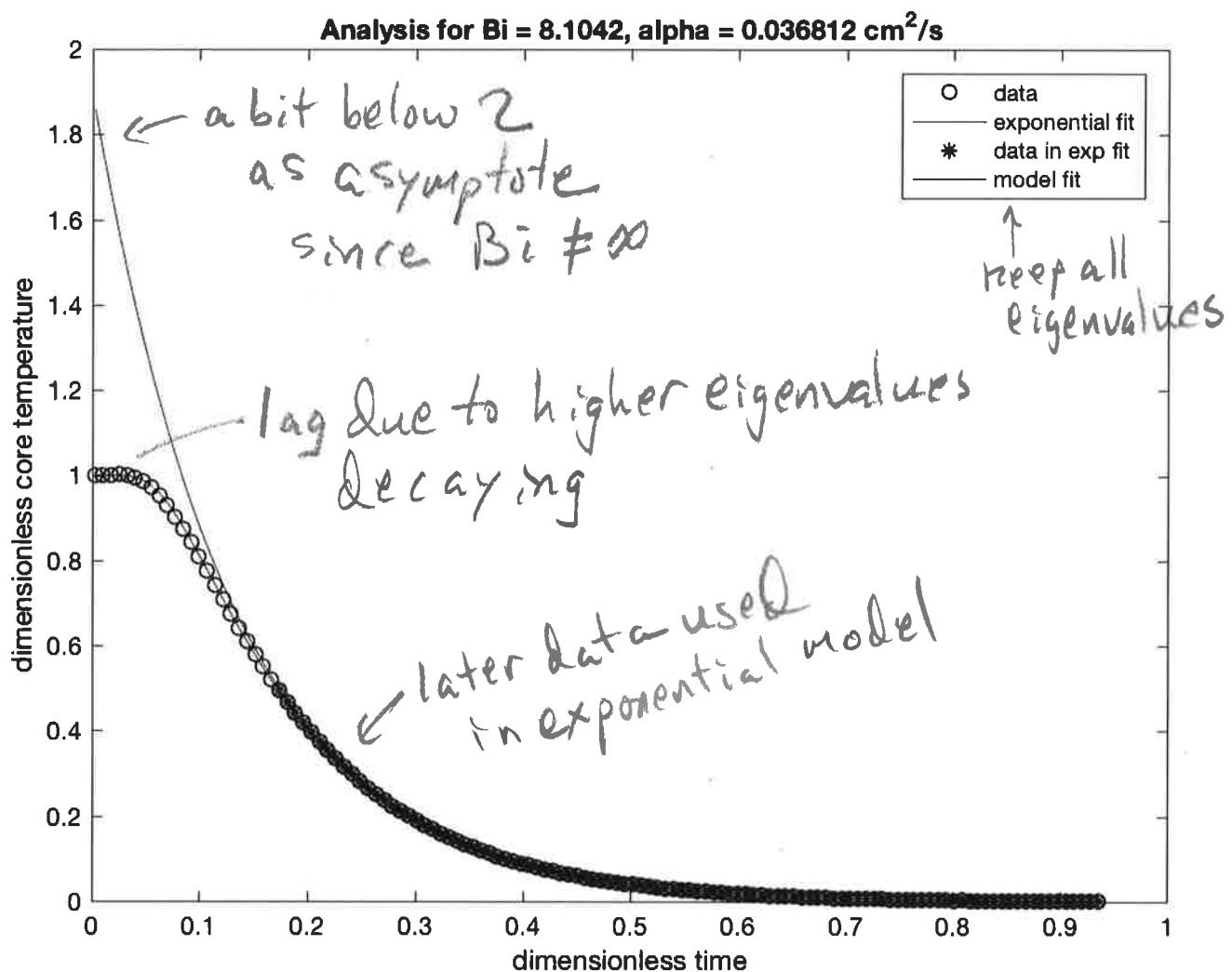
$$\text{So } T^*|_{B_i \rightarrow \infty} = \sum_{n=1}^{\infty} 2(-1)^n e^{-n^2 \pi^2 t^*} \frac{\sin n \pi r^*}{n \pi r^*} \quad (60)$$

Note that the higher eigenvalues decay away really fast! Thus, after a short time

$$T^* \approx 2 e^{-\pi^2 t^*} \frac{\sin \pi r^*}{\pi r^*}$$

so you can use an exponential fit of, say, $T^*|_{r^*=0}$ at later times to measure α ! This is done in UG lab.

$\downarrow \text{Bi is not infinite (but } \gg 1\text{)}$



Data from UG lab exp't, Steel sphere

(62)

Separation of variables problems (when it works!) lead to Sturm-Liouville Boundary Value problems. These are discussed in ch 11 of Boyce & DiPrima - here will just state theorem (they prove it!)

For a problem of the form:

$$[p(x)y']' - q(x)y + \lambda w(x)y = 0$$

on interval $0 < x < 1$

w/ homogeneous B.C.'s:

$$a_1 y(0) + a_2 y'(0) = 0$$

$$b_1 y(1) + b_2 y'(1) = 0$$

and p, p', q & w are continuous functions of x on $[0, 1]$ and

$$p(x) > 0 \text{ and } w(x) > 0 \text{ on } [0, 1]$$

(this condition can be relaxed for singular SL problems...)

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Then:

- 1) all eigenvalues λ & correspo eigenfunctions are real (not complex)
- 2) All eigenvalues are simple : one-to-one correspondence w/ eigenfunctions. and may be ordered by mag. w/ $\lambda_n \rightarrow 0$ as $n \rightarrow \infty$
- 3) Orthogonality: if ϕ_i, ϕ_j are eigenfunctions corresp. to λ_i, λ_j then $\int_0^1 \phi_i(x) \phi_j(x) w(x) dx = 0$
 if $i \neq j$ weight f^n !
- 4) The set of eigenfunctions is complete (you can represent any function over $[0, 1]$ by a linear combination of the $\phi_i(x)$ - very useful!)

(64)

Let's apply this to our quenching problem!

We had:

$$(r^2 F')' + \sigma^2 r^2 F = 0$$

$$F(0) = \text{finite} \quad F(1) = 0$$

↳ actually, $F'(0) = 0$ by symmetry

$$\text{so: } P(r) \equiv r^2 \quad w(r) \equiv r^2 \quad g(r) = 0$$

$$\lambda \equiv \sigma^2$$

$$\begin{aligned} a_1 &= 0, \quad a_2 = 1 \\ b_1 &= 1, \quad b_2 = 0 \end{aligned} \quad \left\{ \text{for B.C.'s} \right.$$

since $P(0) = 0$ (not pos.) it's a singular SL problem, but still works!

The key result is orthogonality, which we need to get our coef.

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we had $\phi_n = \frac{\sin n\pi r}{n\pi r}$, $N = n^2\pi^2$

and $T^* = \sum_{n=1}^{\infty} A_n e^{-n^2\pi^2 t^*} \frac{\sin n\pi r}{n\pi r}$

Now $T^* \Big|_{t^*=0} = \sum_{n=1}^{\infty} A_n \frac{\sin n\pi r}{n\pi r} = 1$
(Ic)

we get the A_n via orthogonality!

Multiply by $\frac{\sin m\pi r}{m\pi r} r^2$ & integrated!
 weight ρ_m^2

$$\begin{aligned} \therefore \sum_{n=1}^{\infty} A_n \int_0^1 \frac{\sin n\pi r}{n\pi r} \frac{\sin m\pi r}{m\pi r} r^2 dr \\ = \int_0^1 (1) \frac{\sin m\pi r}{m\pi r} r^2 dr \end{aligned}$$

by orthogonality, LHS is zero unless
 $n = m$!

$$\text{so } A_n \int_0^1 \frac{\sin^2 n\pi r}{n^2\pi^2} dr = \int_0^1 \frac{\sin n\pi r}{n\pi} r^2 dr$$

(66)

$$A_n = \frac{\int_0^1 \frac{\sin n\pi r}{n\pi} r^* dr^*}{\int_0^1 \frac{\sin^2 n\pi r}{n^2 \pi^2} dr^*}$$

$$= 2 \int_0^1 n\pi r \sin n\pi r dr$$

$$= 2 \left(\frac{\sin n\pi}{n\pi} - \cos(n\pi) \right)$$

$$= 2 (-1)^{n-1}$$

and we get

$$T^* = \sum_{n=1}^{\infty} 2(-1)^{n-1} \frac{-n^2 \pi^2 t^*}{\frac{\sin n\pi r}{n\pi r^*}}$$

Now in general we would get

$$T^* = T_0^* + \sum_{n=1}^{\infty} A_n e^{-\lambda_n t^*} \phi_n(x^*)$$

$$\text{where } A_n = \frac{\int_0^1 (T^*|_{t=0} - T_0^*|_{t=0}) \phi_n(x) w(x) dx}{\int_0^1 \phi_n^2(x) w(x) dx^*}$$

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The solution to a wide variety of separation of variable solutions are provided in Carslaw & Jaeger conduction of heat in solids. If you can't get an analytic solution, numerical solutions are easy to get.

How to solve!

- 1) Problem must be linear - if not, it won't work (but you may be able to linearize it even then)
- 2) Obtain the asymptotic solution at long times : this may not be constant, depending on BC's !

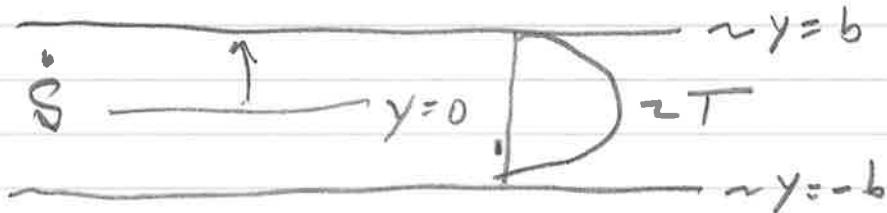
- 3) Subtract off this asymptotic solution at long times to render DE & BC's homogeneous (but not the IC!)
- 4) Use separation of variables to get a S-L eigenvalue problem
- 5) Determine the lead eigenvalue as this tells you how fast your asymptotic solution becomes valid!
- 6) Determine lead eigenfunction & (via orthogonality) the lead coef.
This is the last bit to decay away!
- 7) Get all the rest - if you need them!

For most problems, order of importance:

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- 1) asymptotic solution (what's left at the end)
- 2) lead eigenvalue (how fast things go away)
- 3) lead eigenfⁿ & coef (last correction to decay)
- 4) everything else

Let's apply this: slab with heat generation.



$$T|_{t=0} = T_0 \quad T|_{y=\pm b} = T_0$$

$$\rho C_p \frac{\partial T}{\partial t} = K \frac{\partial^2 T}{\partial y^2} + S$$

(70)

1) Render dimensionless:

$$y^* = y/b \quad t^* = t/t_c \quad T^* = \frac{T - T_0}{\Delta T_c}$$

$$\therefore T^* \Big|_{t^*=0} = T^* \Big|_{y^*=\pm 1} = 0$$

Now for DE:

$$\frac{\hat{S} \hat{C}_p \Delta T_c}{t_c \dot{S}} \frac{\partial T^*}{\partial t^*} = \frac{K \Delta T_c}{b^2} \frac{\partial^2 T^*}{\partial y^{*2}} + \dot{S}$$

Divide out by \dot{S} (has to be there!)

$$\left[\frac{\hat{S} \hat{C}_p \Delta T_c}{t_c \dot{S}} \right] \frac{\partial T^*}{\partial t^*} = \left[\frac{K \Delta T_c}{\dot{S} b^2} \right] \frac{\partial^2 T^*}{\partial y^{*2}} + 1$$

$$\therefore \Delta T_c = \frac{\dot{S} b^2}{K}$$

$$\therefore t_c = \frac{\hat{S} \hat{C}_p \Delta T_c}{\dot{S}} = \frac{b^2 \hat{S} \hat{C}_p}{K} = \frac{b^2}{\alpha} !$$

$$\text{So } \frac{\partial T^*}{\partial t^*} = \frac{\partial^2 T^*}{\partial y^{*2}} + 1$$

$$T^* \Big|_{t^*=0} = 0 \quad T^* \Big|_{y^*=\pm 1} = 0$$

2) Ok, at long times the $T^* = 0$ BC
 means we would be at S.S. (7)
 $y^* = \pm 1$

$$\therefore \frac{\partial T_{\infty}^*}{\partial t^*} = \frac{\partial^2 T_{\infty}^*}{\partial y^{*2}} + 1$$

$$O \quad \text{so } T_{\infty}^* = -\frac{1}{2} y^{*2} + A y^* + B$$

Let's use the symmetry condition

$$\left. \frac{\partial T^*}{\partial y^*} \right|_{y^*=0} = 0 \quad \therefore A = 0$$

and if $\left. T_{\infty}^* \right|_{y^*=\pm 1} = 0$ we have $B = \frac{1}{2}$

$$\text{so } T_{\infty}^* = \frac{1}{2} (1 - y^{*2})$$

3) subtract off T_{∞}^*

$$\text{Let } T_d^* = T^* - T_{\infty}^*$$

$$\therefore T^* = T_d^* + T_{\infty}^*$$

Plug into DE:

$$\frac{\partial \overline{T}_d^*}{\partial t^*} + \cancel{\frac{\partial \overline{T}_{\infty}^*}{\partial t^*}} = \frac{\partial^2 \overline{T}_d^*}{\partial y^{*2}} + \left[\frac{\partial^2 \overline{T}_{\infty}^*}{\partial y^{*2}} + 1 \right] \quad (72)$$

0

~~O~~ (removes source!)

$$\therefore \frac{\partial \overline{T}_d^*}{\partial t^*} = \frac{\partial^2 \overline{T}_d^*}{\partial y^{*2}}$$

$$\overline{T}_d^* \Big|_{t^*=0} = -\overline{T}_{\infty}^* \Big|_{t^*=0} = -\frac{1}{2}(1-y^{*2})$$

$$\overline{T}_d^* \Big|_{y^*=1} = 0, \quad \frac{\partial \overline{T}_d^*}{\partial y^*} \Big|_{y^*=0} = 0 \quad (\text{sym})$$

(1) Use separation of variables :

$$\overline{T}_d^* = G(t^*) F(y^*)$$

$$\therefore FG' = GF''$$

$$\text{or } \frac{G'}{G} = \frac{F''}{F} = -\nabla^2$$

$$-\sigma^2 t^2$$

$$\text{so } G = e$$

$$F'' + \sigma^2 F = 0 \quad F(0) = F(1) = 0$$

5) solve SL problem (this one's easy!)

$$F = A \sin \sigma y^* + B \cos \sigma y^*$$

$$F'(0) = 0 \therefore A = 0$$

$$F(1) = 0 \therefore \cos \sigma = 0$$

$$\therefore \sigma = (n - \frac{1}{2})\pi \quad n = 1, 2, 3, \dots$$

so the lead eigenvalue is $\frac{\pi}{2}$

and the solution decays as:

$$e^{-\left(\frac{\pi}{2}\right)^2 t^*} = e^{-\frac{\pi^2}{4} \frac{\alpha t}{J^2}}$$

Note that the second term decays nine times faster!

6) Get the lead coefficient via orthonormality:

$$T_0^* = \sum_{n=1}^{\infty} B_n e^{-\tau_n^2 t^*} \cos \tau_n y^*$$

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where $B_n = \frac{\int_0^1 -T_0^*|_{t=0} \cos \tau_n y^*}{\int_0^1 \cos^2 \tau_n y^* dy^*}$

Now $\int_0^1 \cos^2 \tau_n y^* dy^* = \frac{1}{2}$ (avg. of \cos^2 or \sin^2)

$$\therefore B_n = 2 \int_0^1 -\frac{1}{2}(1-y^*)^2 \cos[(n-\frac{1}{2})\pi y^*] dy^*$$

$$= \frac{8(\pi(2n-1) \sin(n\pi) + 2 \cos(n\pi))}{\pi^3 (2n-1)^3}$$

from Wolfram alpha ...

now $\sin(n\pi) = 0$ and $\cos(n\pi) = (-1)^n$

$$\therefore B_n = \frac{16(-1)^n}{\pi^3 (2n-1)^3}$$

w/ $B_1 = -\frac{16}{\pi^3} = -0.516\dots$

(75)

Note that B_2 is $27 \times$ smaller, and decays $9 \times$ faster!

7) Put it together:

$$T^* \approx \frac{1}{2} (1 - y^{*2}) - \frac{16}{\pi^3} e^{-\frac{\pi^2 t^*}{4}} \cos \frac{\pi y^*}{2}$$

+ small terms...

This is identical to start-up flow in a channel!

What is the wall heat flux?

$$q_w \Big|_{y=b} = -k \frac{\partial T}{\partial y} \Big|_{y=b} = -k \frac{\dot{s}_b^2}{b} \frac{\partial T^*}{\partial y^*} \Big|_{y^*=1}$$

$$= -\dot{s}_b \frac{\partial T^*}{\partial y^*} \Big|_{y^*=1}$$

$$\approx \dot{s}_b \left(1 - \frac{8}{\pi^2} e^{-\frac{\pi^2 t^*}{4}} + \dots \right)$$

Many other things could be calculated!

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Many linear heat (&mass!) transfer
probs admit SL solutions - but
it may not be possible to solve
analytically! We still want
the answer (in particular the lead
eigenvalue) - so we have to get
it numerically!

We get this via matrix methods

- Suppose we have a standard SL problem on $x \in [0, 1]$
- Discretize domain into $n+1$ nodes
- evaluate y at each x !

$$x_0 = 0 \quad x_1 \quad x_2 \quad x_3 \quad x_4 \quad x_n = 1 \quad \text{etc.}$$

$$y_0 \quad y_1 \quad \vdots \quad : \quad y_n \leftarrow \text{estimates} \\ \text{of } y(x_i)$$

To get the equation for the y_i we use a center diff formula.

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$$y'|_{x_i} \approx \frac{y_{i+1} - y_{i-1}}{2\Delta x}$$

error is $O(\Delta x^2 y'')$

→ numerical approx in Ch 8 of B&D

The second derivative is similar:

$$y''|_{x_i} \approx \frac{\frac{y_{i+1} - y_i}{\Delta x} - \frac{y_i - y_{i-1}}{\Delta x}}{\Delta x} = \frac{y_{i+1} - 2y_i + y_{i-1}}{\Delta x^2}$$

center diff

est of y' at $x_i + \frac{\Delta x}{2}$, etc.

This is also second order

Suppose we have the problem

$$y'' + \lambda y = 0$$

Let's Discretize y :

$$\tilde{y} = \begin{bmatrix} y_0 \\ \vdots \\ y_i \\ \vdots \\ y_n \end{bmatrix}$$

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we need to generate a matrix representing

y'' :

$$y'' = Ay$$

$$\begin{bmatrix} \frac{1}{\Delta x^2} & -\frac{2}{\Delta x^2} & \frac{1}{\Delta x^2} & 0 & \dots & 0 \\ 0 & \frac{1}{\Delta x^2} & -\frac{2}{\Delta x^2} & \frac{1}{\Delta x^2} & 0 & \dots & 0 \\ & & \frac{1}{\Delta x^2} & -\frac{2}{\Delta x^2} & \frac{1}{\Delta x^2} & & \end{bmatrix}$$

← replace w/ BC
at $x=0$

← replace w/ BC
at $x=1$

This is a tri-diagonal matrix!

What about the BC's?

$$\text{say } y'(0) = 0 \quad y(1) = 0$$

BC at $y=1$ would just be

$$y_n = 0 \quad \underline{\text{or}}$$

$$A_n = [0 \ 0 \ 0 \ \dots \ 1] \quad (\text{last row})$$

Derivative is more complex

We could use

$$y'(0) \approx \frac{y_1 - y_0}{\Delta x}$$

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but this is less accurate! It's a center diff. approx at $x = \frac{\Delta x}{2}$!

We can fix this by subtracting $\frac{\Delta x}{2} y''$

$$\begin{aligned} \left. y' \right|_{x=0} &\approx \frac{y_1 - y_0}{\Delta x} - \frac{\Delta x}{2} \frac{y_2 - 2y_1 + y_0}{\Delta x^2} \\ &= \frac{-\frac{1}{2}y_2 + 2y_1 - \frac{3}{2}y_0}{\Delta x} \end{aligned}$$

Which matches the first row of \tilde{A} :

$$\left[-\frac{3}{2} \frac{1}{\Delta x}, \frac{2}{\Delta x}, -\frac{1}{2\Delta x}, 0, \dots, 0 \right]$$

So how do we apply this to a SL problem?

We have:

$$(P(x)y')' - g(x)y + \lambda w(x)y = 0$$

$$\text{so } \left. (P(x)y')' \right|_{x_i} = \frac{P(x_i + \frac{\Delta x}{2}) \frac{y_{i+1} - y_i}{\Delta x} - P(x_i - \frac{\Delta x}{2}) \frac{y_i - y_{i-1}}{\Delta x}}{\Delta x}$$

(8D)

and it is easy to construct the matrix \tilde{A} :

$$\tilde{A} \tilde{y} + \lambda \tilde{w}(x) \tilde{y} = 0$$

where $\tilde{w}(x)$ is a diagonal matrix of the weights $w(\tilde{x})$

we replace the first and last rows w/ BC's and we get a standard eigenvalue problem!

The eigenvalues are just the λ_i , the eigenvectors are the finite dif rep. of the eigenfunctions

This is implemented in the Matlab function `s1solve.m`

```
function [lambda,eigenvec]=slsolve(varargin)
%This function solves the Sturm-Liouville eigenvalue problem given by:
%
% [p(x) y']' - q(x) y + lambda w(x) y = 0
%
% subject to the boundary conditions:
%
% bc(1) y(0) + bc(2) y'(0) = 0
%
% bc(3) y(1) + bc(4) y'(1) = 0
%
% over the domain 0 < x < 1.
%
% The function is called by the command:
%
% [lambda,eigenvec]=slsolve('pfun','qfun','wfun',bc,n);
%
% The function call requires that you provide the function names (or
% handles if you are using the anonymous function utility) for the
% functions p, q, and w. These functions must be able to handle an array
% of values. You also provide the boundary coefficients in the array bc.
% In addition, you may specify the degree of discretization n. Its default
% value is 50. The matrices which are generated are of size (n+1,n+1).
% The function returns the eigenvalues in the array lambda (sorted by size
% in ascending order) and the matrix eigenvec which contains the
% corresponding eigenfunctions. The eigenfunctions are all normalized by
% their maximum value over the domain 0 < x < 1.
%
% A last note on error: The code uses second order derivative
% approximations, so the error in the eigenvalues and eigenvectors will be
% of O(1/n^2). In general, the first few eigenvalues will be reliable, but
% the accuracy will deteriorate as you look at the higher eigenvalues, with
% the last few being meaningless.

p=varargin{1};
q=varargin{2};
w=varargin{3};
bc=varargin{4};

if nargin<5;n=50;else;n=varargin{5};end

h=1/n; %set discretization
x=[0:h:1]'; %this is the array of x values

%Now we set up the arrays used in making the matrix A:
pp=zeros(1,n+1);
pm=zeros(1,n+1);
ww=zeros(1,n+1);
qq=zeros(1,n+1);
for i=2:n
    pp(i)=feval(p,x(i)+h/2);
    pm(i)=feval(p,x(i)-h/2);
    ww(i)=feval(w,x(i));
    qq(i)=feval(q,x(i));
end

%The matrix W is easy:
weight=-diag(ww);
```

```
%The matrix A is a bit more complex. First we do
%the main diagonal:
a=diag(-pp-pm-qq*h^2);
%and then the super and sub diagonals:
a=a+diag(pp(1:n),1);
a=a+diag(pm(2:n+1),-1);

%Finally, we divide by h^2:
a=a/h^2;

%And now for the boundary conditions. First at the left edge:
a(1,1)=bc(1)-bc(2)*1.5/h;
a(1,2)=bc(2)*2/h;
a(1,3)=-bc(2)/2/h;

%sand at the right edge:
a(n+1,n+1)=bc(3)+bc(4)*1.5/h;
a(n+1,n)=-bc(4)*2/h;
a(n+1,n-1)=bc(4)/2/h;

%Now we are ready to calculate the eigenvalues:
[v,d]=eig(a,weight);

%The number of eigenvalues and vectors will be less
%than the size of A and W, thus:
evals=diag(d);
i=find(isinfinite(evals)); %The matlab 7 form of finite!
evals=evals(i);
evecs=v(:,i);

%Now we sort the eigenvalues and eigenvectors according
%to the size of the eigenvalues:
[~,i]=sort(abs(real(evals)));
lambda=evals(i);
evecs=evecs(:,i);

%and finally, we normalize the eigenvectors by their
%maximum value.
eigenvec=zeros(size(evecs));
for j=1:length(lambda)
    eigenvec(:,j)=evecs(:,j)/norm(evecs(:,j),inf)/sign(evecs(2,j));
end
```

Ok, let's implement this for a problem where we know the answer!

Let's just quench a slab!

$$\left. T \right|_{x=b} = T_0 \quad x=b$$

$$\left. T \right|_{t=0} = T_1 \quad x=0$$

$$\left. q \right|_x = 0 \text{ (symmetry)}$$

$$\rho C_p \frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$

Render Dimensionless!

Want homogeneous BC's, so subtract
asymptotic solution $\bar{T}_0 = T_0$

$$\therefore T^* = \frac{T - T_0}{T_1 - T_0} \quad x^* = \frac{x}{b}$$

and from PDE $t^* = \frac{t}{b^2} \frac{k}{\rho C_p} = \frac{\alpha t}{b^2}$

$$\text{So: } \frac{\partial T^*}{\partial t^*} = \frac{\partial^2 T^*}{\partial x^{*2}} \quad T^* \Big|_{t^*=0} \approx 1, T^* \Big|_{x^*=0} = 0$$

$$T^* \Big|_{t^*=0} = 1 \quad (\text{in homogeneous IC})$$

OK, use sep. of variables:

$$T^* = G(t^*) F(x^*)$$

$$\frac{G'}{G} = \frac{F''}{F} = -\lambda \quad (\text{or } -\sigma^2)$$

$$-\lambda t^*$$

$$\therefore G = e$$

$$F'' + \lambda F = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{SL problem!}$$

$$F(1) = 0 \quad F'(0) = 0$$

solution is one we've seen before!

$$F = A \cos \sqrt{\lambda} x^* + B \sin \sqrt{\lambda} x^*$$

$$F'(0) = 0 \quad \therefore B = 0$$

$$F(1) = 0 \quad \therefore \sqrt{\lambda_n} = (n - \frac{1}{2})\pi$$

and

$$T^* = \sum_{n=1}^{\infty} A_n e^{-\lambda_n t^*} \cos \sqrt{\lambda_n} x^*$$

where, from orthogonality,

$$A_n = \frac{\int_0^1 (1) \cos \sqrt{\lambda_n} x^* dx^*}{\int_0^1 \cos^2 \sqrt{\lambda_n} x^* dx^*} = \frac{-2(-1)^n}{(n - \frac{1}{2})\pi}$$

Contents

- Sturm-Liouville Example Problem
- Comparison of Eigenvalues
- First Five Eigenfunctions
- Calculation of the Coefficients
- Comparison of Decaying Solution

Sturm-Liouville Example Problem

We examine the numerical solution to the Sturm-Liouville problem of a slab of half-width 1 being quenched. Initially the temperature is 1 and at $t = 0$ the surface at $x = 1$ is lowered to zero. We use the symmetry condition at the centerline. Thus:

```
p = @x ones(size(x));
q = @x zeros(size(x));
w = @x ones(size(x));
bc = [0,1,1,0];

n = 100; %The number of points we would like (the number of intervals)

[lambda, eigenvecs] = slsolve(p,q,w,bc,n);

% And that's it!
```

Comparison of Eigenvalues

We have the exact eigenvalues $((n-1/2)\pi)^2$. We can compare them graphically and numerically. We find that the first 11 eigenvalues match to within 1%, but then the deviation gets larger. The highest eigenvalues are off by a factor of two or so. This is generically the case: the eigenvalues (and eigenfunctions) are sensitive to the degree of discretization as each higher eigenfunction has one more zero crossing, and you lose numerical accuracy! These higher eigenvalues would decay away very quickly, however.

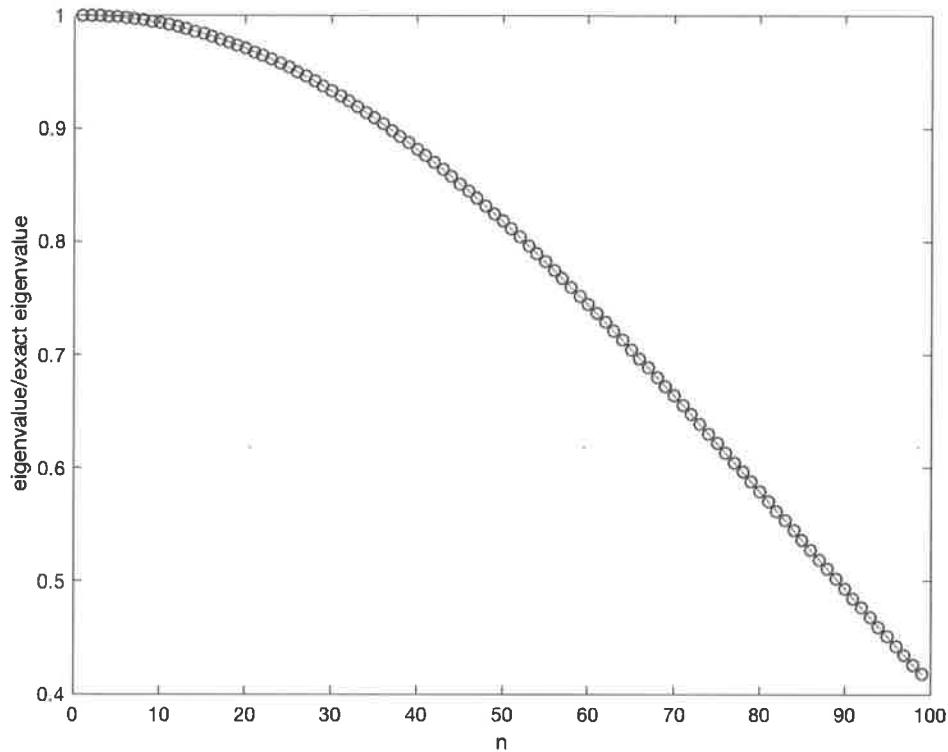
```
figure(1)
neigenvec=length(lambda);
exactlambda = (([1:neigenvec]'.5)*pi).^2;
eratio = lambda./exactlambda;
plot([1:neigenvec],eratio,'o-')
xlabel('n')
ylabel('eigenvalue/exact eigenvalue')
grid on

first20ratios = eratio(1:20)
```

```
first20ratios =
```

```
1.0000
0.9998
0.9995
0.9991
0.9984
0.9977
0.9967
0.9956
0.9944
0.9930
0.9915
```

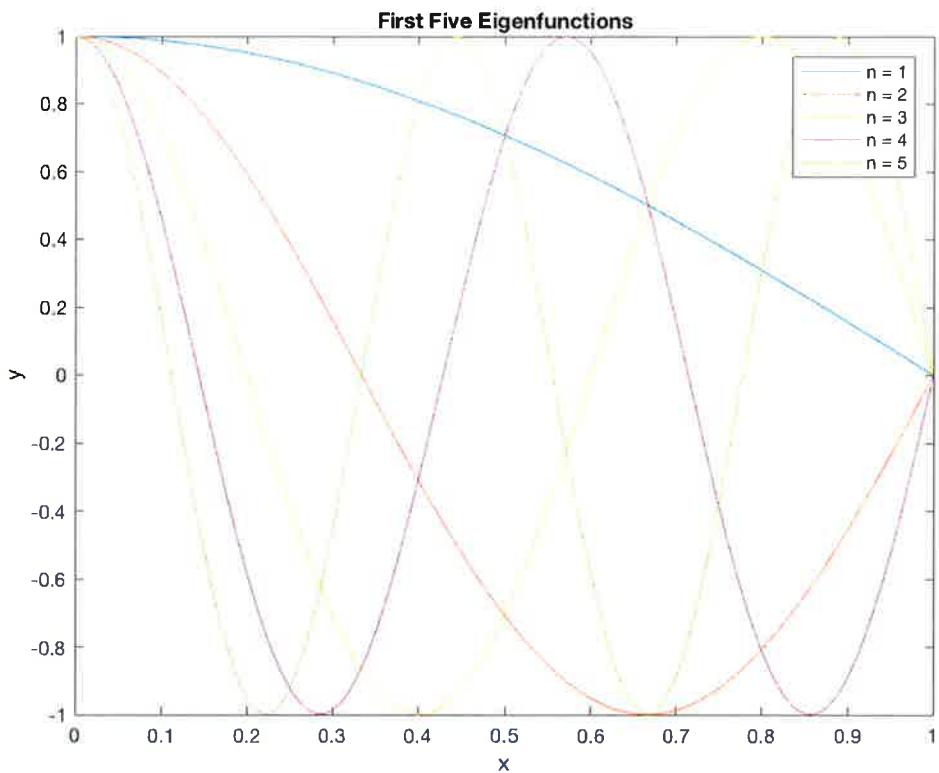
0.9898
0.9879
0.9859
0.9837
0.9814
0.9789
0.9763
0.9735
0.9706



First Five Eigenfunctions

We plot up the first five eigenfunctions. You will note that the eigenfunctions have a number of zero crossings that increase by one each time.

```
x = [0:1/n:1]';  
figure(2)  
plot(x,eigenvecs(:,1:5))  
xlabel('x')  
ylabel('y')  
title('First Five Eigenfunctions')  
legend('n = 1','n = 2','n = 3','n = 4','n = 5')  
grid on
```



Calculation of the Coefficients

We make use of orthogonality to calculate the coefficients. We can use the trapezoidal rule to do the integration. Comparison with the exact solution shows that the first coefficients are very good, but after awhile the values are a little random. These coefficients are very small, however.

```

weights = ones(1,n+1);
weights(1) = 0.5;
weights(n+1) = 0.5;
weights=weights/n;

tinit = ones(n+1,1); %The initial temperature

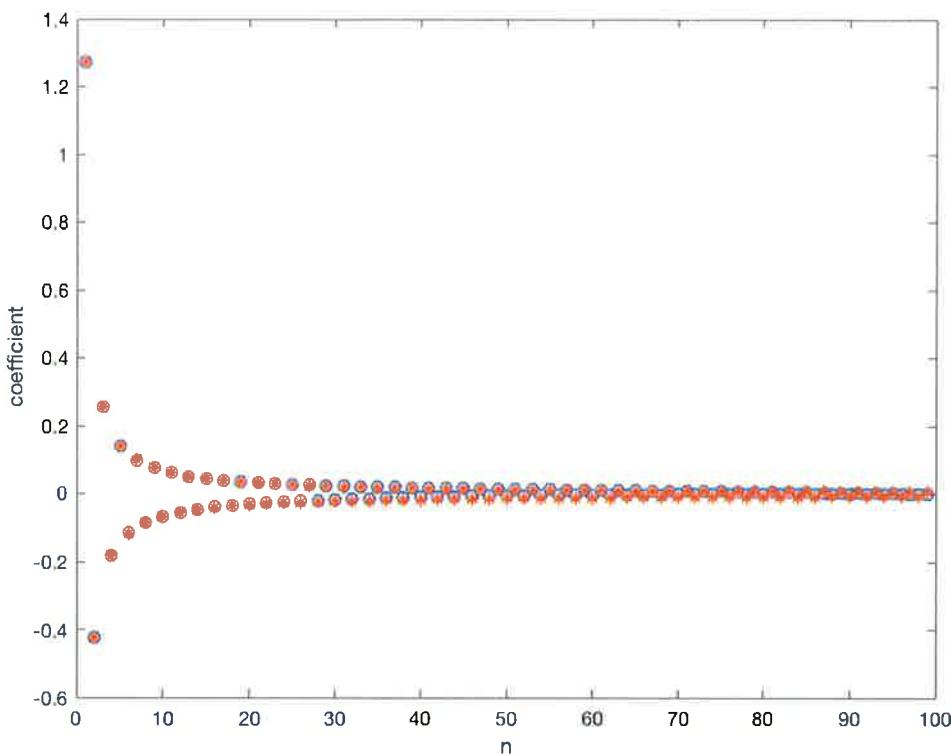
a = zeros(length(lambda),1);

for i = 1:length(lambda)
    numerator = weights*(w(x).*tinit.*eigenvecs(:,i));
    denominator = weights*(w(x).*eigenvecs(:,i).^2);
    a(i) = numerator/denominator;
end

aexact = -2*(-1).^[1:neigenvec]./([1:neigenvec]'.5)/pi;

figure(3)
plot([1:neigenvec]',a,'o',[1:neigenvec]',aexact,'*')
xlabel('n')
ylabel('coefficient')
grid on

```



Comparison of Decaying Solution

Here we calculate the temperature at the centerline as a function of time. We have both the exact solution as well as our numerical one. We plot this up for a dimensionless time of 4. The match is pretty much perfect except exactly at $t = 0$. This error occurs because of the problems with all of the higher eigenvalues and eigenfunctions - which decay away almost instantly. This related to the classic Gibbs ringing phenomenon, which is well known in signal processing. We avoid this by starting our time series at a value slightly greater than zero.

```

t = [0.0005:.001:4];
cltemps = zeros(size(t));
cltempexact = zeros(size(t));

for i = 1:length(t)
    nrangle = [1:1000]; %We use lots of eigenvalues for the exact expression
    cltempexact(i) = sum(-2*(-1).^nrangle./((nrangle-.5)/pi.*exp(-t(i)*(nrangle-.5).^2*pi^2)));

    %And now for the numerical value:
    cltemps(i) = sum(a.*exp(-lambda*t(i)).*eigenvecs(1,:));
end

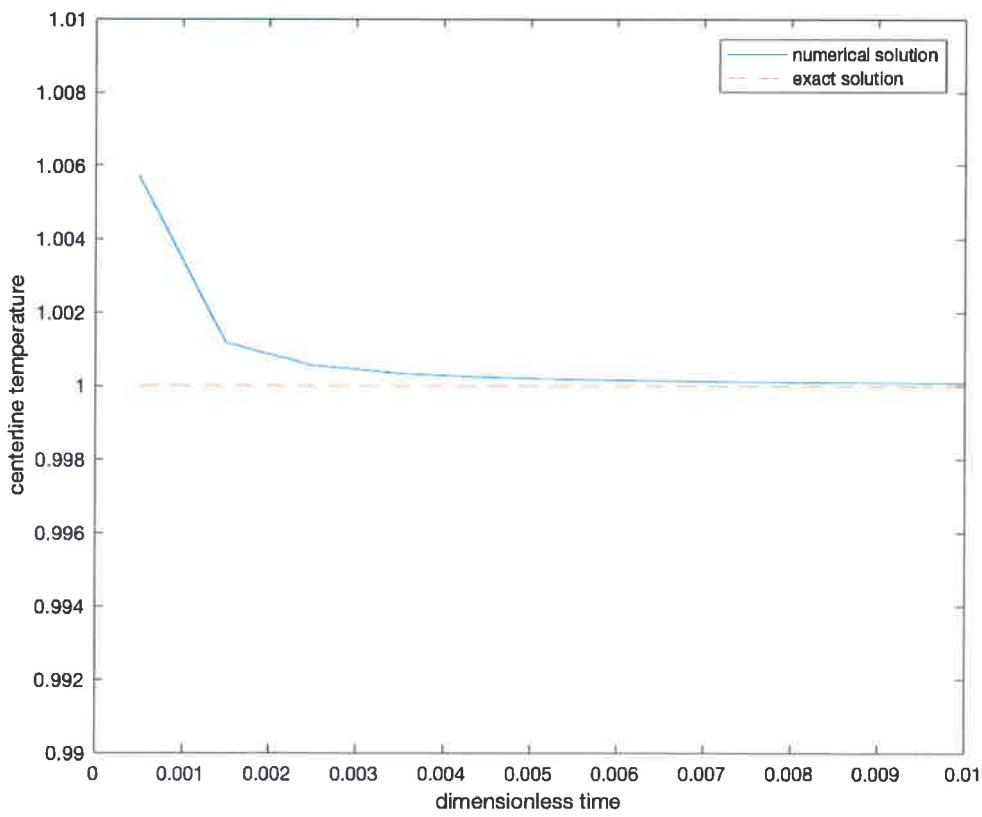
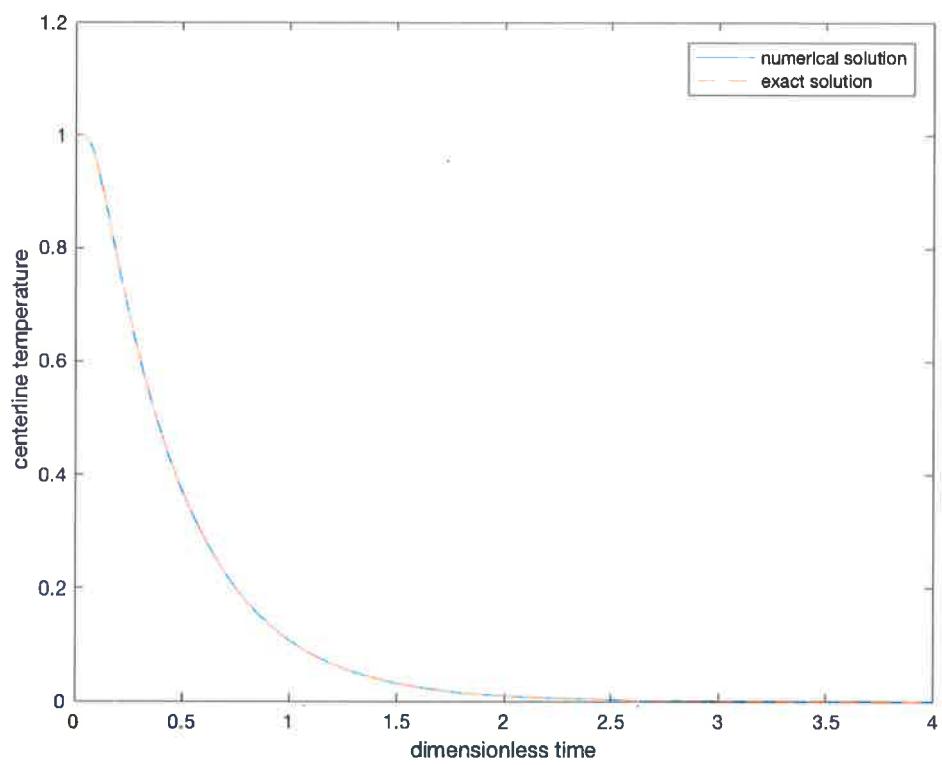
figure(4)
plot(t,cltemps,t,cltempexact,'--')
xlabel('dimensionless time')
ylabel('centerline temperature')
legend('numerical solution','exact solution')
grid on

figure(5)
plot(t,cltemps,t,cltempexact,'--')
xlabel('dimensionless time')
ylabel('centerline temperature')
legend('numerical solution','exact solution')

```

```
axis([0 1e-2 .99 1.01])  
grid on
```

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That problem had an analytic solution which was easy to get!
 We need numerics for nastier problems!

Suppose we are heating our slab w/ some flux q_0 at $x=0$. (still no problem!) And we have a gradient in the heat capacity and conductivity! This happens if you have, say, a gradient in composition for a composite: pretty common! Now we need numerics!

$$\underbrace{T|_{x=b} = T_0}_{x=b}$$

$$\underbrace{T|_{t=0} = T_0}_{}$$

$$\left. q_0 = -k \frac{\partial T}{\partial x} \right|_{x=0}^{x=0}$$

(91)

Let's take:

$$\rho C_p = (\rho C_p)_0 (1 + c_1 x)$$

$$k = k_0 (1 + c_2 x)$$

What is our PDE?

Recall $\hat{\rho} \frac{\partial T}{\partial t} = - \nabla \cdot \hat{q}$

and $\hat{q} = -k \nabla T$

Since k isn't constant we have to leave it in the middle of the operator!

$$\hat{\rho} \frac{\partial T}{\partial t} = \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right)$$

Ok, let's scale!

Clearly, $x^* = \frac{x}{b}$, $T^* = \frac{T - T_0}{\Delta T_C}$

$$t^* = \frac{t}{t_C}$$

(92)

From BC at $x=0$:

$$\left. -\frac{k_0 \Delta T_c}{b} \left(1 + \frac{c_2}{b} x^* \right) \frac{\partial T^*}{\partial x^*} \right|_{x^*=0} = q_o$$

$$\therefore \Delta T_c = \frac{q_o b}{k_0}$$

and $\left. \frac{\partial T^*}{\partial x^*} \right|_{x^*=0} = -1$

Finally, from PDE:

$$\frac{\Delta T_c}{T_c} (\rho c_p)_o \left(1 + \frac{c_1}{b} x^* \right) \frac{\partial T^*}{\partial t^*} = \frac{k_0 \Delta T_c}{b^2} \frac{\partial}{\partial x^*} \left(\left(1 + \frac{c_2}{b} x^* \right) \frac{\partial T^*}{\partial x^*} \right)$$

Dividing out gives:

$$t_c = \frac{(\rho c_p)_o b^2}{k_0} \quad \text{or} \quad t^* = \frac{\alpha_o t}{b^2}$$

where $\alpha_o = \frac{k_0}{(\rho c_p)_o}$ (ref diffusivity)

w/ PDE

$$\left(1 + c_1^* x^* \right) \frac{\partial T^*}{\partial t^*} = \frac{\partial}{\partial x^*} \left(\left(1 + c_2^* x^* \right) \frac{\partial T^*}{\partial x^*} \right)$$

$$c_1^* = c_1/b \quad c_2^* = c_2/b$$

(93)

To get an SL problem we must subtract off T_∞^* to remove inhomogeneous BC at $x^* = 0$!

At S.S. :

$$0 = \frac{\partial}{\partial x^*} \left((1 + c_2^* x^*) \frac{\partial T_\infty^*}{\partial x^*} \right)$$

$$\left. \frac{\partial T_\infty^*}{\partial x^*} \right|_{x^*=0} = -1 \quad \left. T_\infty^* \right|_{x^*=1} = 0$$

Integrating:

$$(1 + c_2^* x^*) \frac{\partial T_\infty^*}{\partial x^*} = \text{cst} = A$$

but $\left. \frac{\partial T_\infty^*}{\partial x^*} \right|_{x^*=0} \approx -1$ so $A = -1$

$$\therefore \frac{\partial T_\infty^*}{\partial x^*} = \frac{-1}{1 + c_2^* x^*}$$

$$\therefore T_{\infty}^* = -\frac{1}{C_2^*} \ln(1 + C_2^* x^*) + B$$

$$T_{\infty}^* \Big|_{x^*=1} = 0 \quad \therefore B = \frac{1}{C_2^*} \ln(1 + C_2^*)$$

$$\text{or } T_{\infty}^* = \frac{1}{C_2^*} \ln \left(\frac{1 + C_2^*}{1 + C_2^* x^*} \right)$$

$$\text{Now } T^* = T_{\infty}^* + T_d^*$$

$$\therefore (1 + C_1^* x^*) \frac{\partial T_d^*}{\partial t^*} = \frac{\partial}{\partial x^*} \left((1 + C_2^* x^*) \frac{\partial T_d^*}{\partial x^*} \right)$$

$$\frac{\partial T_d^*}{\partial x^*} \Big|_{x^*=0} = 0 \quad T_d^* \Big|_{x^*=1} = 0$$

$$(T_d^* + T_{\infty}^*) \Big|_{t^*=0} = 0$$

$$\therefore T_d^* \Big|_{t^*=0} = -T_{\infty}^* = -\frac{1}{C_2^*} \ln \left(\frac{1 + C_2^*}{1 + C_2^* x^*} \right)$$

(95)

$$\text{Let } T_d^* = G(t^*) F(x^*)$$

$$\therefore (1 + c_1 x^*) G' F = G((1 + c_2 x^*) F')$$

Divide by $(1 + c_1 x^*) F G$:

$$\frac{G'}{G} = \frac{((1 + c_2 x^*) F')'}{(1 + c_1 x^*) F} = -\lambda$$

$$\therefore G = e^{-\lambda t^*}$$

$$((1 + c_2 x^*) F')' + \lambda (1 + c_1 x^*) F = 0$$

$$F'(0) = 0 \quad F(1) = 0$$

$$\text{and } T_d^* = \sum_{n=1}^{\infty} A_n e^{-\lambda_n t^*} F_n(x^*)$$

$$\text{where } A_n = \frac{\int_0^1 -T_d^* F_n(x^*) (1 + c_1 x^*) dx^*}{\int_0^1 F_n^2(x^*) (1 + c_1 x^*) dx^*}$$

Let's solve!

Contents

- Sturm-Liouville Example: Varying Heat Capacity and Conductivity
- Eigenvalues, Eigenvectors, and Coefficients
- Temperature of the Lower Wall
- Temperature Profile at Various Times

Sturm-Liouville Example: Varying Heat Capacity and Conductivity

We examine the numerical solution to the Sturm-Liouville problem of a slab of width 1 undergoing a uniform heat flux at the bottom, and a fixed temperature at the top. The conductivity k and the heat capacity are linear functions of position. The dimensionless Sturm-Liouville problem for the decaying solution is:

$$((1+c2*x)*y)' + \lambda*(1+c1*x)*y = 0$$

$$y'(0) = 0; y(1) = 0$$

The asymptotic solution at long times is the logarithm:

$$T_{\infty} = (1/c2)*\log((1+c2)./(1+c2*x))$$

Thus, the initial value for the Sturm-Liouville expansion is just the negative of this function.

Solving the problem we get:

```
c1 = 2;
c2 = -.7;

p = @(x) (1 + c2*x);
q = @(x) zeros(size(x));
w = @(x) (1 + c1*x);
bc = [0,1,1,0];

n = 100; %The number of points we would like (the number of intervals)

[lambda, eigenvecs] = slsolve(p,q,w,bc,n);

Tinf = @(x) (1/c2)*log((1+c2)./(1+c2*x))

% And that's it!

Tinf =
function_handle with value:

@(x)(1/c2)*log((1+c2)./(1+c2*x))
```

Eigenvalues, Eigenvectors, and Coefficients

We are interested in the lead eigenvalues, coefficients, and eigenvectors. We just look at the first five:

```
firsteigenvecs = lambda(1:5)
```

% And we calculate the coefficients using the Trapezoidal Rule:

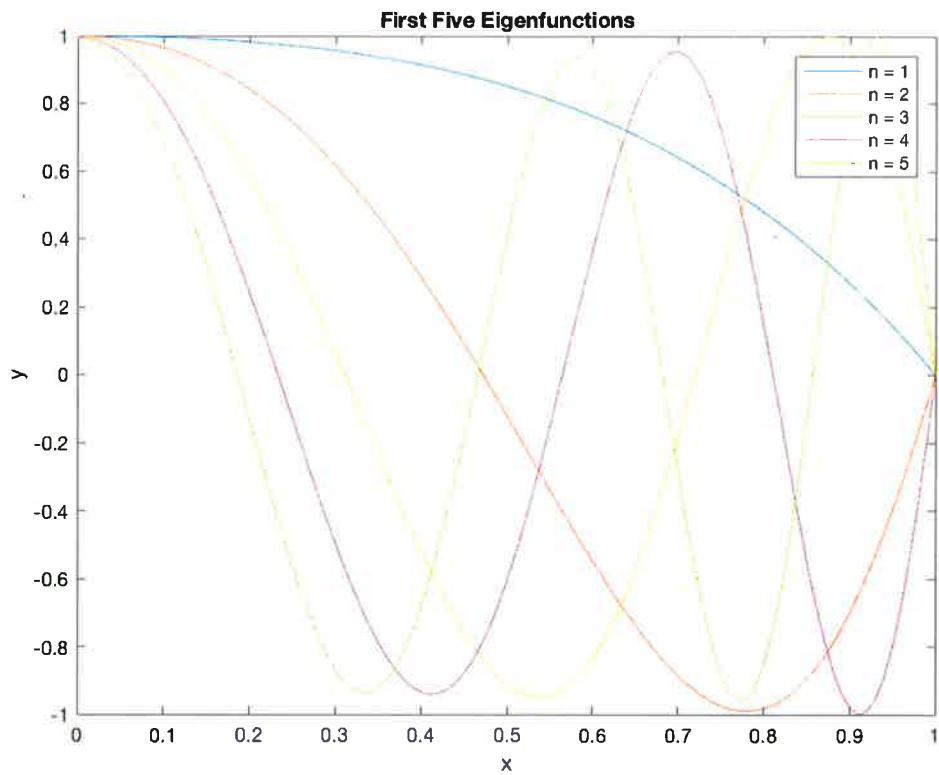
```
x = [0:1/n:1]';  
  
% The Trapezoidal Rule weights:  
weights = ones(1,n+1);  
weights(1) = 0.5;  
weights(n+1) = 0.5;  
weights=weights/n;  
  
a = zeros(length(lambda),1);  
  
for i = 1:length(lambda)  
    numerator = -weights*(w(x).*Tinf(x).*eigenvecs(:,i));  
    denominator = weights*(w(x).*eigenvecs(:,i).^2);  
    a(i) = numerator/denominator;  
end  
  
firstcoefficients = a(1:5)  
  
% And we plot the first five eigenfunctions:  
figure(1)  
plot(x,eigenvecs(:,1:5))  
xlabel('x')  
ylabel('y')  
title('First Five Eigenfunctions')  
legend('n = 1','n = 2','n = 3','n = 4','n = 5')  
grid on
```

) firsteigenvecs =

```
0.6849  
6.5141  
18.0404  
35.2805  
58.2210
```

firstcoefficients =

```
-1.3832  
-0.1558  
-0.0577  
-0.0298  
-0.0182
```



Temperature of the Lower Wall

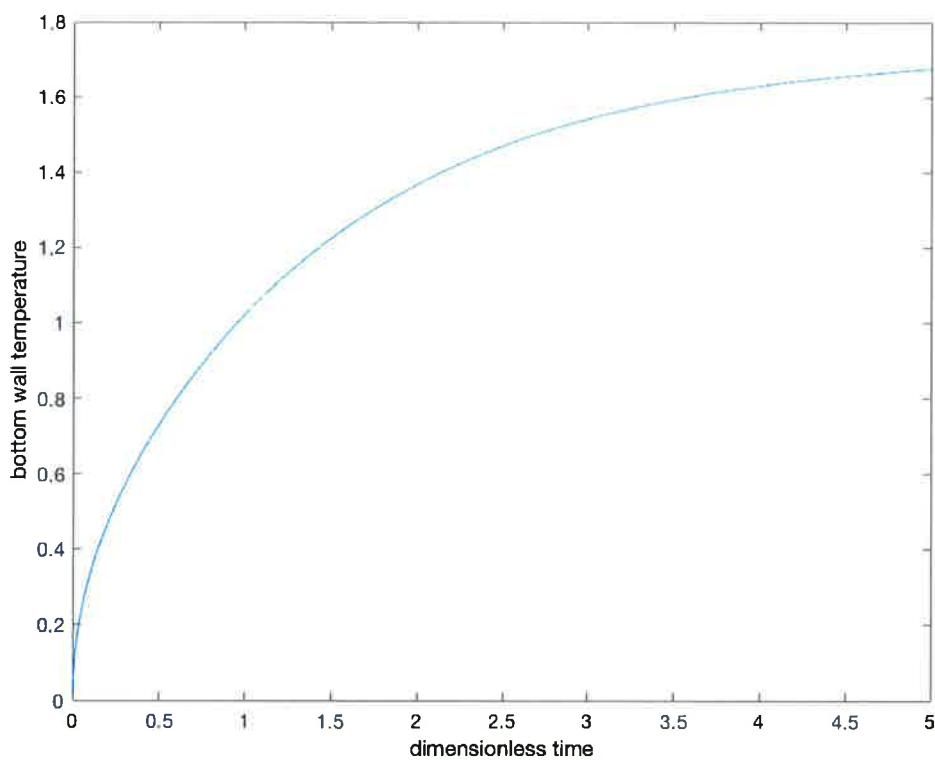
We wanted the temperature of the lower wall. This will be $T_{inf} + T_{decaying}$ evaluated at $x = 0$. So:

```
t = [0.0005:0.001:5];
tbottom = zeros(size(t)); %We initialize the array

for i = 1:length(t)
    tbottom(i) = log(1+c2)/c2 + sum(a.*exp(-lambda*t(i)).*eigenvecs(1,:));
end

figure(2)
plot(t,tbottom)
xlabel('dimensionless time')
ylabel('bottom wall temperature')
grid on
```

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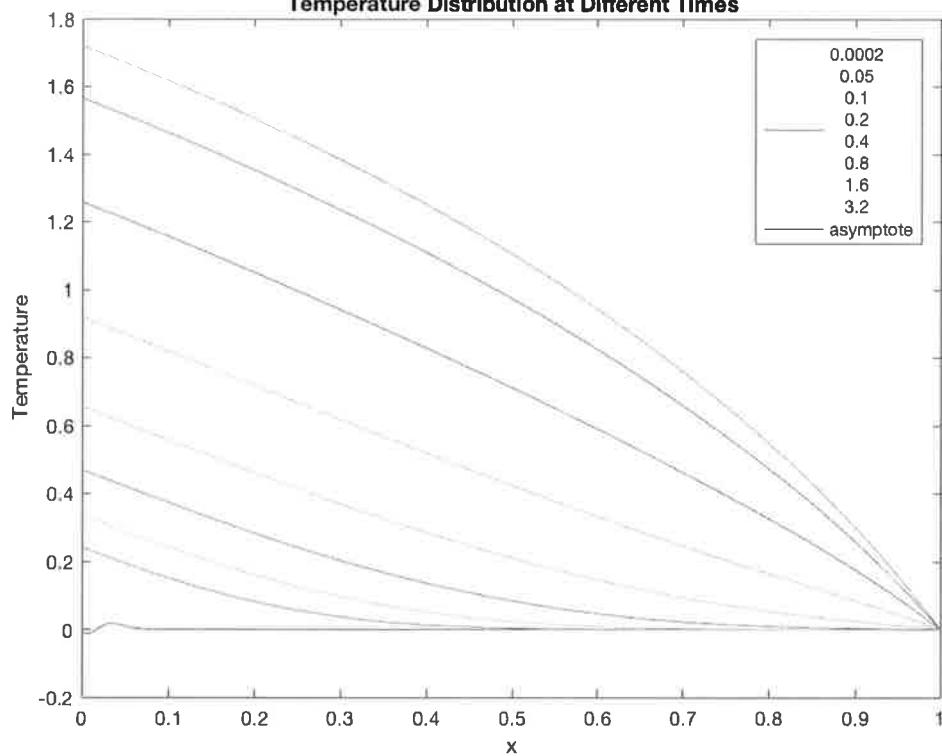
Temperature Profile at Various Times

We can also plot up the temperature distribution for specific times. You will note the issue near the origin at very short times. This is known as the Gibbs ringing phenomenon and is well known in signal processing.

```
tplot = [0.0002,.05,.1,.2,.4,.8,1.6,3.2]';

tprofile = zeros(length(x),length(tplot));
for j = 1:length(tplot)
    for i=1:length(x)
        tprofile(i,j) = log((1+c2)/(1+c2*x(i)))/c2 + sum(a.*exp(-lambda*tplot(j)).*eigenvecs(i,:));
    end
end
figure(3)
plot(x,tprofile,x,Tinf(x))
legend(num2str(tplot),'asymptote')
xlabel('x')
ylabel('Temperature')
title('Temperature Distribution at Different Times')
grid on
```

100

Temperature Distribution at Different Times

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For linear problems which admit separation of variables solutions, SL works great - either analytic (if possible) or numeric if not. But non-linear problems won't work!

Suppose κ is a $f^n(T)$ (and thus x & t too!). The equation won't separate, you can't "subtract off asymptotic solution", etc.

Usually solve these numerically!
 Dozens of methods have been developed, but for parabolic PDE the simpler is finite differences/marching solution!

Let's examine the slab again:

(102)

$$\frac{\sim T|_{x=b} = T_0}{\sim T|_{t=0} = T_0} \quad x=b$$

$\downarrow q = q_0$

but $K = K_0 (1 + C(T - T_0))$

$\uparrow \text{ref } K$ $\uparrow \text{ref temp.}$

Thus :

$$S_C \frac{\partial T}{\partial t} = \frac{\partial}{\partial x} \left(K_0 (1 + C(T - T_0)) \frac{\partial T}{\partial x} \right)$$

w/ B.C. : $T|_{x=b} = T_0$ $T|_{t=0} = T_0$

$$q_0 = -K_0 (1 + C(T - T_0)) \frac{\partial T}{\partial x} \Big|_{x=0}$$

This is non-linear in dependent variable!

First, we scale!

From BC : $x^* = \frac{x}{b}$ $T^* = \frac{T - T_0}{\Delta T_L}$

$$q_0 = -K_0 (1 + C \Delta T_L T^*) \frac{\Delta T_L}{b} \frac{\partial T^*}{\partial x^*} \Big|_{x^*=0}$$

so $\Delta T_L = \frac{q_0 b}{K_0}$ and define $C^* = C \Delta T_L$

From the PDE: $t^* = \frac{k_0 t}{g C_p b^2} = \frac{\alpha_0 t}{b^2}$

as usual!

So:

$$\frac{\partial T^*}{\partial t^*} = \frac{\partial}{\partial x^*} \left((1 + c^* T^*) \frac{\partial T^*}{\partial x^*} \right)$$

$$(1 + c^* T^*) \frac{\partial T^*}{\partial x^*} \Big|_{x^*=0} = -1 \quad T^* \Big|_{x^*=1} = T^* \Big|_{t^*=0} = 0$$

We want the asymptotic sol'n!

$$\frac{\partial}{\partial x^*} \left((1 + c^* T_\infty^*) \frac{\partial T_\infty^*}{\partial x^*} \right) = 0$$

Integrate:

$$(1 + c^* T_\infty^*) \frac{\partial T_\infty^*}{\partial x^*} = \text{const} = -1$$

from BC at $x^* = 0$!

Even though it's non-linear, we can still solve it:

$$(1 + c^* T_\infty^*) \frac{\partial T_\infty^*}{\partial x^*} \equiv \frac{1}{2c^*} \frac{\partial}{\partial x^*} (1 + c^* T_\infty^*)^2 = -1$$

Now we can integrate!

$$\frac{1}{2C^*} \left(1 + C^* T_{\infty}^* \right)^2 = -x^* + B$$

$$\text{Now } T_{\infty}^* \Big|_{x^*=1} = 0$$

$$\therefore \frac{1}{2C^*} = -1 + B \quad \therefore B = 1 + \frac{1}{2C^*}$$

so

$$\frac{1}{2C^*} \left(1 + C^* T_{\infty}^* \right)^2 = 1 - x^* + \frac{1}{2C^*}$$

$$\left(1 + C^* T_{\infty}^* \right)^2 = 1 + 2C^*(1-x^*)$$

$$\text{so } T_{\infty}^* = \frac{1}{C^*} \left[(1+2C^*(1-x^*))^{1/2} - 1 \right]$$

This looks strange, but as $C^* \rightarrow 0$
it is just $T_{\infty}^* \Big|_{C^* \rightarrow 0} = 1 - x^*$

(linear profile for constant K)

Now we solve for the transient!

We discretize our domain:

$$\underline{x} = \begin{bmatrix} 0 \\ \vdots \\ 1 \end{bmatrix} \quad \underline{T}^* = \begin{bmatrix} T_0^* \\ \vdots \\ T_n^* \end{bmatrix}$$

We thus have at the i^{th} node:

$$\frac{\partial T_i^*}{\partial t^*} = \left[\frac{\partial}{\partial x^*} \left((1 + c T^*) \frac{\partial T^*}{\partial x^*} \right) \right]_i$$

Which we get by finite differences!

Between $i+1$ & i :

$$\left. \left((1 + c T^*) \frac{\partial T^*}{\partial x^*} \right) \right|_{i+\frac{1}{2}} \approx \left(1 + c \frac{(T_{i+1}^* + T_i^*)}{2} \right) \frac{T_{i+1}^* - T_i^*}{\Delta x}$$

avg value
↙ for t^*

& equiv. expression for deriv. at $i-\frac{1}{2}$

$$\text{So } \frac{\partial T_i^*}{\partial t^*} \approx \left[\left(1 + c^* \frac{(T_{i+1}^* + T_i^*)}{2} \right) \frac{T_{i+1}^* - T_i^*}{\Delta x} - \left(1 + c^* \frac{(T_i^* + T_{i-1}^*)}{2} \right) \frac{T_i^* - T_{i-1}^*}{\Delta x} \right] \frac{1}{\Delta x}$$

and we march forward in time!

$$T_i^* \Big|_{t^* + \Delta t^*} \approx T_i^* \Big|_{t^*} + \Delta t \frac{\partial T_i^*}{\partial t^*}$$

This forward difference approach has stability issues! We have the Neumann condition:

$$\Delta t < \frac{1}{2} \frac{\Delta x^2}{\lambda}$$

for diffusion equations!

If Δt is just too large, it blows up!

This equation is good for interior nodes (not $i=0, n$)

On the edges we use BC's!

At the upper wall $T^* = 0$

$\therefore T_n^* = 0$ at all times!

The BC at $x^* = 0$ is more complex:

$$(1 + CT^*) \frac{\partial T^*}{\partial x^*} \Big|_{x^*=0} = -1$$

$$\text{Now } \frac{\partial T^*}{\partial x^*} \Big|_{x^*=0} \approx \frac{T_1^* - T_0^*}{\Delta x} - \frac{\Delta x}{2} \frac{T_2^* - 2T_1^* + T_0^*}{\Delta x}$$

$$= \frac{1}{\Delta x} \left(-\frac{1}{2} T_2^* + 2T_1^* - \frac{3}{2} T_0^* \right)$$

$$\text{so } \frac{(1 + CT^*)}{\Delta x} \left(-\frac{1}{2} T_2^* + 2T_1^* - \frac{3}{2} T_0^* \right) = -1$$

$$\text{or } T_0^* = \frac{4}{3} T_1^* - \frac{1}{3} T_2^* + \frac{2}{3} \frac{\Delta x}{1 + CT^*}$$

We'd like to eval. the last at $x^* = 0$ -
but then it's non-linear!

$$\text{Instead } T^* \Big|_{x^*=0} \approx T_1^* - \Delta x \frac{T_2^* - T_1^*}{\Delta x} = 2T_1^* - T_2^*$$

Thus in our scheme we update the
temp. at $x^*=0$:

$$T_0^* \approx \frac{4}{3} T_1^* - \frac{1}{3} T_2^* + \frac{2}{3} \frac{\Delta x}{1 + C^* (2T_1^* - T_2^*)}$$

we start our array with $T^*=0$
and update in time!

Contents

- Finite Difference Marching Solution: Temperature Dependent Conductivity
- Plot of Bottom Temperature

Finite Difference Marching Solution: Temperature Dependent Conductivity

In this script we demonstrate the simplest of the techniques for numerical solutions to non-linear parabolic PDEs: the finite difference approach. We solve the example problem of a heated slab of width 1 with a temperature dependent conductivity. We use a simple explicit forward difference in time and a second order finite difference in space. We take the conductivity to be $k = k_0 * (1 + c * (T - T_0))$.

```
c = 2;

% The analytic solution to the asymptotic temperature is just:
Tinf = @(x) ((1+2*c*(1-x)).^.5-1)/c

% We discretize the domain in space:
n = 50;
dx = 1/n;
x = [0:dx:1]'; %Note: there are n+1 elements

T = zeros(size(x)); %The initial condition

dt = .49/(c+1)/n^2; %The time discretization we need to avoid instability for c>0

t = 0;

tkeep = [0:dt:2]; %The times we want to evaluate the bottom temperature at
Tbottomkeep = zeros(size(tkeep)); %We initialize that array

pt = [2:n]'; %These are the indices of the interior points.

for i = 2:length(tkeep)
    right = (1+c*(T(pt+1)+T(pt))/2).*(T(pt+1)-T(pt))/dx;
    left = (1+c*(T(pt)+T(pt-1))/2).*(T(pt)-T(pt-1))/dx;
    dTdt = (right-left)/dx;
    T(pt) = T(pt)+dTdt*dt;

    % and the boundary conditions:
    T(n+1) = 0;
    T(1) = 4/3*T(2) - T(3)/3 + 2/3*dx/(1+c*(2*T(2)-T(3)));

    Tbottomkeep(i) = T(1);

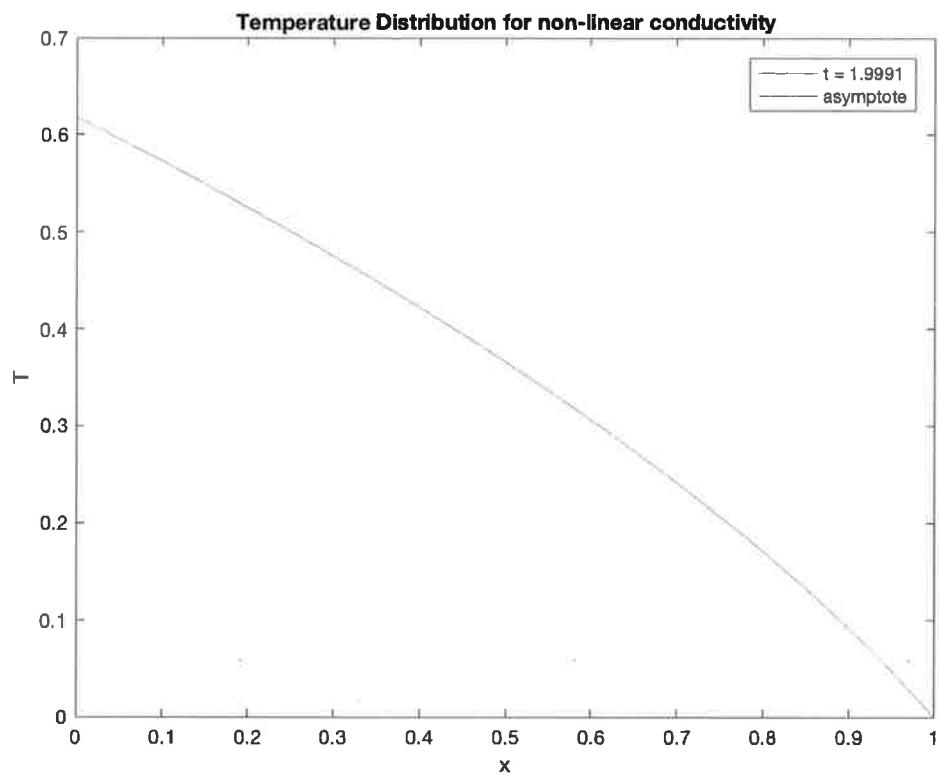
    % We add a little graphics (comment out for speed!)
    if i/200==floor(i/200) % We plot up every 200th iteration
        figure(1)
        plot(x,T,x,Tinf(x))
        xlabel('x')
        ylabel('T')
        legend(['t = ',num2str(tkeep(i))], 'asymptote')
        title('Temperature Distribution for non-linear conductivity')
        drawnow
    end
end

Tinf =
```

function_handle with value:

```
@(x)((1+2*c*(1-x)).^.5-1)/c
```

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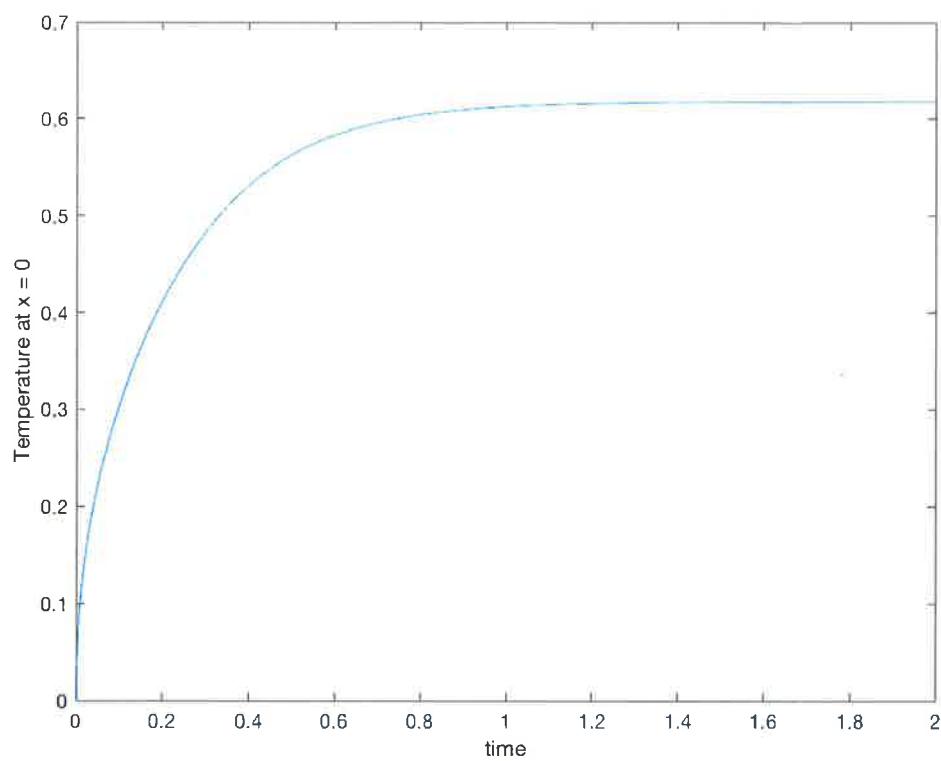


Plot of Bottom Temperature

We can plot up the bottom temperature vs. time. We could have kept some of the intermediate temperature profiles as well, but not all of them! Because of the Neumann condition we have to use a very small discretization in time: way too much data!

```
figure(2)
plot(tkeep,Tbottomkeep)
xlabel('time')
ylabel('Temperature at x = 0')
grid on
```

III



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There are many methods & canned PDE solvers on all computational platforms!

In Matlab these are in the Partial Differential Equation Toolbox - search on this plus "Documentation" in a browser to get the tutorial.

If it's a simple problem, directly coding a finite difference algorithm is probably easiest - if it's a harder problem/more complicated system, learn and use a canned solver

Upshot: If you can write down equation, you can solve it!

Partial Differential Equation Toolbox

Solve partial differential equations using finite element analysis

Partial Differential Equation Toolbox™ provides functions for solving structural mechanics, heat transfer, and general partial differential equations (PDEs) using finite element analysis.

You can perform linear static analysis to compute deformation, stress, and strain. For modeling structural dynamics and vibration, the toolbox provides a direct time integration solver. You can analyze a component's structural characteristics by performing modal analysis to find natural frequencies and mode shapes. You can model conduction-dominant heat transfer problems to calculate temperature distributions, heat fluxes, and heat flow rates through surfaces. You can also solve standard problems such as diffusion, electrostatics, and magnetostatics, as well as custom PDEs.

Partial Differential Equation Toolbox lets you import 2D and 3D geometries from STL or mesh data. You can automatically generate meshes with triangular and tetrahedral elements. You can solve PDEs by using the finite element method, and postprocess results to explore and analyze them.

Get Started

Learn the basics of Partial Differential Equation Toolbox

Geometry and Mesh

Define a geometry and discretize it using a triangular or tetrahedral mesh

Structural Mechanics

Solve linear static, transient, modal analysis, and frequency response problems

Heat Transfer

Solve conduction-dominant heat transfer problems with convection and radiation occurring at boundaries

Electromagnetics

Solve problems that model electric and magnetic fields

General PDEs

Solve general linear and nonlinear PDEs for stationary, time-dependent, and eigenvalue problems

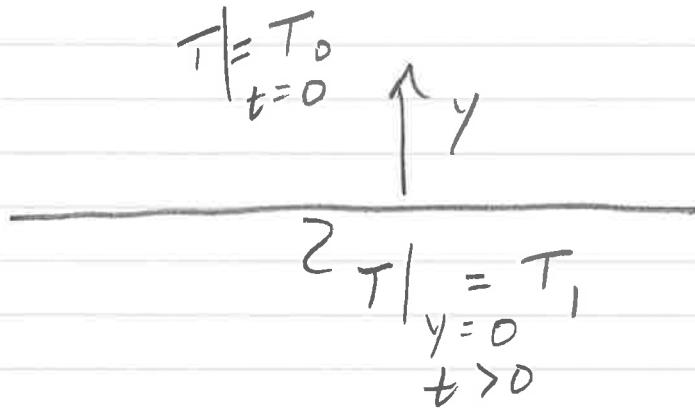
(114)

So far we've (mostly) looked at bounded domains (slab, sphere, rod, etc.)

— What about semi-infinite domains?

These problems are usually length scale deficient and admit boundary layer / self-similar solutions!

The classic problem is ex. 12.1-1 in BS&L (we'll solve a different way)



$$\text{Now } \rho C_p \frac{\partial T}{\partial t} = K \frac{\partial^2 T}{\partial y^2}$$

Let's render dimensionless!

$$\text{From B.C., } T^* = \frac{T - T_0}{T_1 - T_0}$$

$$\therefore T^* \Big|_{t=0} = 0 \quad T^* \Big|_{y^*=0, t^*>0} = 1$$

Let's take $t^* = t/t_c$, $y^* = y/\delta$

$$\text{so : } \hat{\rho} \frac{\Delta T_c}{t_c} \frac{\partial T^*}{\partial t^*} = \frac{k \alpha_c \delta^2 T^*}{\delta^2 \frac{\partial y^*}{\partial t^*}}$$

Divide out:

$$\left[\frac{\delta^2}{t_c (\rho \hat{C}_p)} \right] \frac{\partial T^*}{\partial t^*} = \frac{\partial^2 T^*}{\partial y^*^2}$$

$$\text{so } \frac{\delta^2}{\alpha t_c} = 1 \quad \text{or} \quad \frac{\delta}{(\alpha t_c)^{1/2}} = 1$$

But we're done! What's t_c ??

We get the dimensionless problem

$$\frac{\partial T^*}{\partial t^*} = \frac{\partial^2 T^*}{\partial y^*^2}; T^* \Big|_{t^*=0} = 0$$

$$T^* \Big|_{y^* \rightarrow \infty} = 0 \quad T^* \Big|_{\substack{y^* = 0 \\ t^* > 0}} = 1$$

but never specified t_c !

This means that the solution is self-similar: T^* is not a function of

of y & t independently, but instead is a function of a similarity variable which is a combination of y & t !

We can turn our PDE into an ODE!

A more general way of getting self-similar solutions is via Morgan's Theorem:

- 1) If a well posed problem (e.g., DE, BC's, location of BC's) is invariant to a one parameter group of continuous transformations then the number of independent variables may be reduced by one.
- 2) Reduction is accomplished by choosing as new dependent

and independent variables combinations
which are invariant under the
transformation.

What does this mean? Simplest approach is via simple affine stretching / scaling!

We have:

$$\frac{\partial T^*}{\partial t^*} = \frac{\partial^2 T^*}{\partial y^{*2}} \quad T^* \Big|_{t^*=0} = 0$$
$$T^* \Big|_{y^* \rightarrow \infty} = 0$$
$$T^* \Big|_{y^*=0} = 1$$

Let's stretch (scale) T^*, y^*, t^*

$$\text{Let } T^* = A \bar{T}, \quad t^* = B \bar{t}, \quad y^* = C \bar{y}$$

where A, B, C are parameters (our group!)

Plug into PDE:

$$\frac{A}{B} \frac{\partial \bar{T}}{\partial \bar{t}} = \frac{A}{C^2} \frac{\partial^2 \bar{T}}{\partial \bar{y}^2}$$

Divide through

$$\therefore \frac{\partial \bar{T}}{\partial \bar{t}} = \left[\frac{B}{C^2} \right] \frac{\partial^2 \bar{T}}{\partial \bar{y}^2}$$

so DE will be invariant if $\frac{B}{C^2} = 1$!

Now for BC's:

$$A \bar{T} \Big|_{\bar{t}=0} = 0 \Rightarrow \bar{T} \Big|_{\bar{t}=0} = 0 \quad (\text{no restriction})$$

$$A \bar{T} \Big|_{C \bar{y} \rightarrow \infty} = 0 \Rightarrow \bar{T} \Big|_{\bar{y} \rightarrow \frac{\infty}{C} = \infty} = 0 \quad (\text{also no restr.})$$

Finally $A \bar{T} \Big|_{C \bar{y} = 0} = 1 \Rightarrow \bar{T} \Big|_{\bar{y}=0} = \begin{bmatrix} 1 \\ A \end{bmatrix}$

so if $A = 1$ and $\frac{B}{C^2} = 1$

our problem is invariant!

Now for the second part: the transf.

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New dep. variable invariant under
 transf: since $A = 1$, $T^* = f$
 (boring - no change here!)

New indep variable:

$\frac{B}{C^2} = 1$ so $\frac{t^*}{y^{*2}}$ is invariant

$$\text{e.g. } \left(\frac{B}{C^2}\right) \frac{\bar{t}}{\bar{y}^2} = \frac{\bar{t}}{\bar{y}^2}$$

$\therefore \bar{z} = \frac{t^*}{y^{*2}}$ would work as a
 new indep. variable!

$$\text{e.g. } T^* = f(z) \quad z = \left(\frac{t^*}{y^{*2}}\right)$$

This works but very very badly!!

Instead use canonical form!

Put all the complexity in the
indep. variable whose highest deriv.
 in PDE is the lowest!

(120)

We have a 2nd deriv. w.r.t. y^*
but only 1st deriv w.r.t. t^* ∴ put
complexity in t^* !

Recall $\frac{B}{C^2} = 1$

$\therefore \frac{C}{B^{1/2}} = 1$ is the same!

$\therefore \tilde{y} = \frac{y^*}{t^{*1/2}}$ is in canonical form

$\therefore T^* = f(\tilde{y}) \quad \tilde{y} = \frac{y^*}{t^{*1/2}}$

(note: BSL uses $\frac{y^*}{2t^{*1/2}}$ - no sig. to factor
of 2!)

Now to get the new ODE!

$$\frac{\partial T^*}{\partial y^*} = \frac{\partial f}{\partial y^*} = \frac{\partial f}{\partial \tilde{y}} \frac{\partial \tilde{y}}{\partial y^*} = f' \frac{1}{t^{*1/2}}$$

$$\frac{\partial^2 T^*}{\partial y^{*2}} = \frac{\partial}{\partial y^*} \left(\frac{\partial T^*}{\partial y^*} \right) = f'' \frac{1}{t^*}$$

These are easy because of canonical form!

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Now for t^* : harder!

$$\frac{\partial T^*}{\partial t^*} = \frac{df}{d\zeta} \frac{\partial \zeta}{\partial t^*}$$

$$\text{but } \frac{\partial \zeta}{\partial t^*} = \frac{\partial}{\partial t^*} \left(\frac{y^*}{t^{*3/2}} \right) = -\frac{1}{2} \frac{y^{*2}}{t^{*5/2}} = -\frac{1}{2} \frac{y^*}{t^*}$$

In general if $\zeta \equiv \frac{y^*}{t^{*n}}$

then $\frac{\partial \zeta}{\partial t^*} = -n \frac{\zeta}{t^*}$ - very convenient!

so:

$$-\frac{1}{2} \frac{\zeta}{t^*} f' = \frac{1}{t^*} f''$$

$$\text{or } f'' = -\frac{1}{2} \zeta f'$$

w/ BC's $f(0) = 1, f(\infty) = 0$

$$\begin{array}{ccc} \uparrow & & \downarrow \\ \frac{y^*}{t^*} \rightarrow \infty & & t^* \rightarrow 0 \\ \swarrow & & \searrow \end{array}$$

collapses BC & IC!

How do we solve? This one's pretty easy!

Divide by f' :

$$\underbrace{\frac{1}{f'}}_{\hookrightarrow} \frac{\frac{df'}{dz}}{f'} = -\frac{1}{2}z^2$$

$$\hookrightarrow = \frac{d \ln f'}{dz}$$

Now integrate!

$$\therefore \ln f' = -\frac{1}{4}z^2 + \text{cst}$$

$$\text{or } f' = f'(0) e^{-\frac{1}{4}z^2}$$

\hookrightarrow unknown - but yields
the heat flux!

$$f = 1 + \int_0^z f'(0) e^{-\frac{1}{4}y^2} dy$$

\uparrow applied BC at $y=0$ to get constant

Now we have $f(\infty) = 0$

$$\therefore 0 = 1 + \int_0^\infty f'(0) e^{-\frac{1}{4}y^2} dy$$

$$\text{or } f'(0) = -\frac{1}{\int_0^\infty e^{-\frac{1}{4}y^2} dy}$$

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which yields $\gamma = \frac{1}{4} z^2$

$$f(z) = 1 - \frac{\int_0^z e^{-\frac{1}{4}t^2} dt}{\int_0^\infty e^{-\frac{1}{4}t^2} dt}$$

Now these integrals are related to
the error function $\text{erf}(x)$

$$\text{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

Thus after a little algebra :

$$T^* = 1 - \text{erf}\left(\frac{z}{2}\right) \equiv \text{erfc}_1\left(\frac{z}{2}\right)$$

Complementary
error function

$$\text{or } \frac{T - T_0}{T_1 - T_0} = 1 - \text{erf}\left(\frac{y}{\sqrt{4\alpha t}}\right)$$

which is the eqn 12.1-8 in BS&L...

What does this mean? There is
a penetration depth that goes as
 $y \sim (\alpha t)^{1/2}$ over which the

temp. varies! Note that for a finite slab (of thickness b) you can regard it as infinite if $\frac{b}{\lambda} \gg 1$ as for short times the energy doesn't diffuse to the other wall (yet).

There's another way to solve this - which is useful if you don't know error functions! Set it up as a system of 1st order ODE's & solve via the shooting method!

$$f'' = -\frac{1}{2} \gamma f', \quad f(0) = 1 \quad f(\infty) = 0$$

so:

$$\text{let } \tilde{f} = \begin{Bmatrix} f \\ f' \end{Bmatrix} = \begin{Bmatrix} f_1 \\ f_2 \end{Bmatrix}$$

$$\therefore \frac{d}{dz} \begin{Bmatrix} f_1 \\ f_2 \end{Bmatrix} = \begin{Bmatrix} f_2 \\ -\frac{1}{2} \gamma f_2 \end{Bmatrix}$$

Thus we have:

$$f_1(0) = 1 \quad (\text{BC})$$

$$f_2(0) = ?? = x \quad (\text{unknown})$$

Adjust x until $f_1(\infty) = 0$!

We actually don't have to go out very far!

This is done numerically on the next page - very simple to do!

Note that this also works for non-linear problems (like the Blasius eq'n) for which there is no analytical solution!

Contents

- Heated Semi infinite slab: comparison of numerical solution to exact
- Plotting things up
- Conclusion

Heated Semi infinite slab: comparison of numerical solution to exact

In this case we use the shooting method to compare the numerical solution for this problem to the exact error function solution. We use the function miss.m to get the degree to which we miss our boundary condition at infinity. Because the solution decreases exponentially as $\exp(-0.5 \eta^2)$ we just go out to a value of 10.

The miss program is:

```
function out = miss(x) % This function takes in a guess for the derivative of the temperature at % y = 0 for an impulsively heated semi-infinite domain.
```

```
fdot = @(eta,f) [f(2), -0.5*eta*f(2)]; %The differential equation
```

```
f0 = [1,x]; %The initial value
```

```
[etaout fout] = ode45(fdot,[0 10],f0);
```

```
out = fout(end,1);
```

```
x = -1; % Our initial guess
```

```
x = fzero('miss',x) % Our solution!
```

```
x =
```

```
-0.5642
```

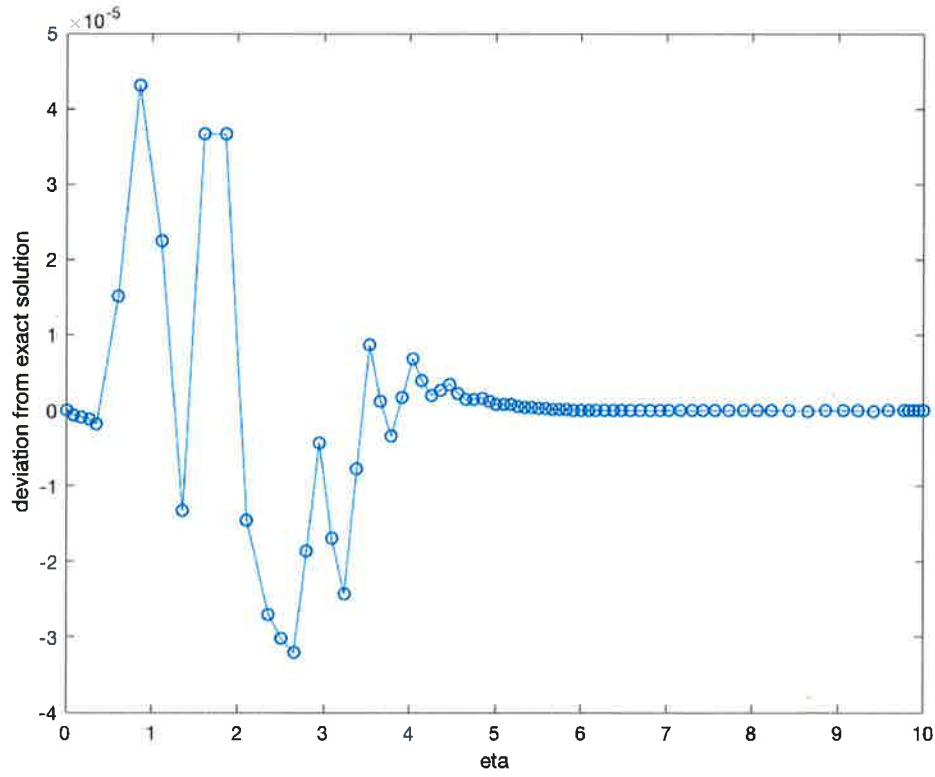
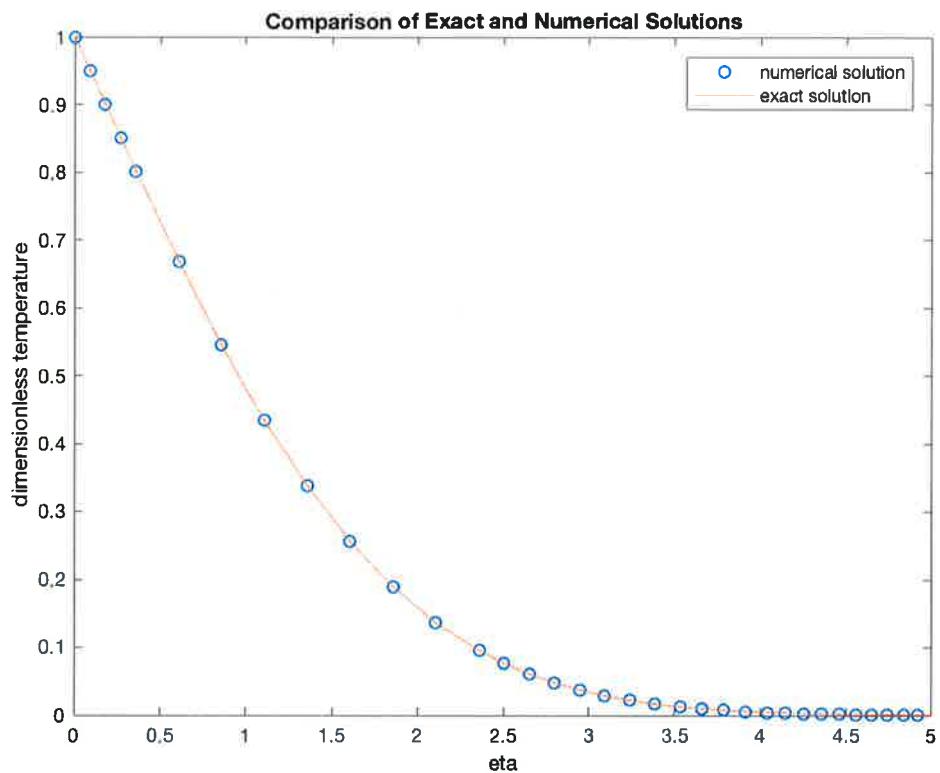
Plotting things up

We just cut and paste from the miss.m routine to get the profile:

```
fdot = @(eta,f) [f(2); -0.5*eta*f(2)]; %The differential equation
f0 = [1,x]; %The initial value
[etaout fout] = ode45(fdot,[0 10],f0);
fexact = 1 - erf(etaout/2); %The exact solution
figure(1)
plot(etaout,fout(:,1),'o',etaout,fexact)
legend('numerical solution','exact solution')
xlabel('eta')
ylabel('dimensionless temperature')
title('Comparison of Exact and Numerical Solutions')
axis([0 5 0 1])
```

% We can also plot up the deviation:
figure(2)
plot(etaout,fout(:,1)-fexact,'o-')
xlabel('eta')
ylabel('deviation from exact solution')

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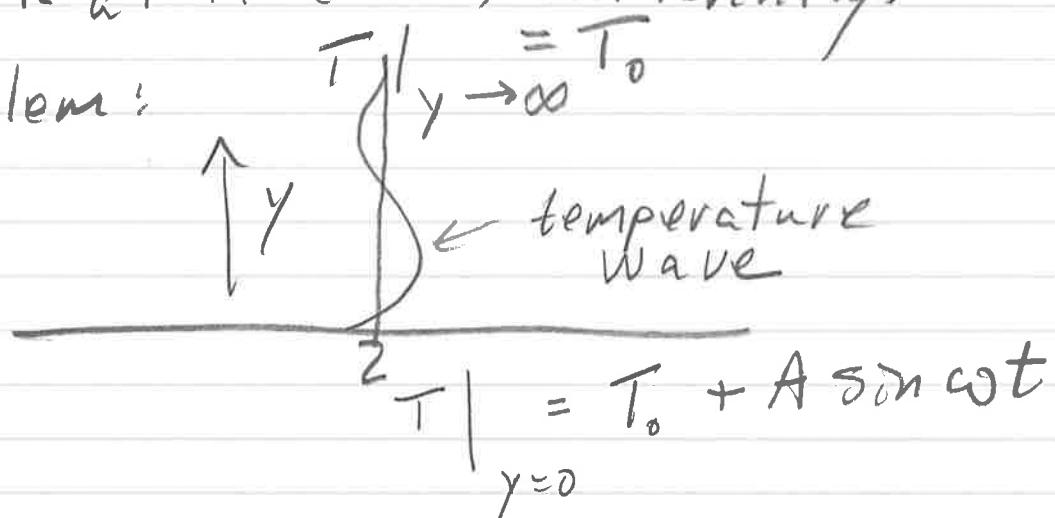
Conclusion

The deviation between the numerical and exact solutions is less than $5e-5$ for all eta. This could be further reduced if you set a tighter tolerance for fzero (the root finder) or ode45 (the integrator), but it illustrates the ease of solving this sort of problem numerically.

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Another example of semi-infinite domains is found in periodic heating. This is what determines how deep you have to bury pipes to avoid freezing, or to set foundations to avoid melting permafrost for the Alaska pipeline! It's covered in example 12.1-3 of BS&L, but again we'll look at it (abit) differently.

The problem:



We have the PDE (as usual):

$$\rho C_p \frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial y^2}$$

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$$\text{w/ BC's : } T \Big|_{y \rightarrow \infty} = T_0$$

$$T \Big|_{y=0} = T_0 + A \sin \omega t$$

where ω is the angular frequency of the oscillation!

Let's scale:

$$T^* = \frac{T - T_0}{\Delta T_c}, \quad t^* = \frac{t}{t_c}, \quad y^* = \frac{y}{s}$$

From BC:

$$T^* \Delta T_c + T_0 = T_0 + A \sin[(\omega t_c) t^*]$$

or $T^* = \left[\frac{A}{\Delta T_c} \right] \sin \left([\omega t_c] t^* \right)$

so $\Delta T_c = A$, $t_c = \frac{1}{\omega}$, no surprise!

Now for PDE

$$\frac{\Delta T_c}{t_c} \hat{f}_4 \frac{\partial T^*}{\partial t^*} = \kappa \frac{\Delta T_c}{s^2} \frac{\partial^2 T^*}{\partial y^{*2}}$$

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Divide out:

$$\frac{\partial T^*}{\partial t^*} = \left[\frac{\alpha b_c}{S^2} \right] \frac{\partial^2 T^*}{\partial y^{*2}}$$

$$\text{so } S = (\alpha t_c)^{1/2} = \left(\frac{\alpha}{\omega} \right)^{1/2}$$

which is the penetration depth -
the length scale of our diffusing
wave!

$$\text{so: } \frac{\partial T^*}{\partial t^*} = \frac{\partial^2 T^*}{\partial y^{*2}}$$

$$T^* \Big|_{y^* \rightarrow \infty} = 0 \quad T^* \Big|_{y^*=0} = \sin t^*$$

For periodic problems we are only interested in the asymptotic sol'n - but that's also periodic!

We can't take $T^* = \sin t^* f(y^*)$

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because the phase will shift
 w/ depth due to the diffusion time!
 Instead, because the problem is
linear, we solve via analytic
continuation onto the complex plane!

Remember the Euler formula?

$$e^{it^*} = \cos t^* + i \sin t^*$$

Let's let our BC become:

$$\hat{T} \Big|_{y^*=0} = e^{it^*} = \cos t^* + i \sin t^*$$

In this way $T^* = \text{Im}\{\bar{T}\}$
 (the real part would be the temp.
 & diff. driven by $\cos t^*$!)

$$\text{So: } \frac{\partial \hat{T}}{\partial t^*} = \frac{\partial^2 \hat{T}}{\partial y^{*2}}, \quad \hat{T} \Big|_{y^* \rightarrow \infty} = 0$$

$$\hat{T} \Big|_{y^*=0} = e^{it^*}$$

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Now we take $\hat{T} = f(y^*) e^{it^*}$

$$\text{So } f(0) = 1, f(\infty) = 0$$

Plug onto PDE:

$$\frac{\partial^2 \hat{T}}{\partial y^* \partial z} = e^{it^*} f''$$

$$\frac{\partial \hat{T}}{\partial t^*} = i e^{it^*} f$$

so eqn for f is simple!

$$f'' e^{it^*} = i f e^{it^*}$$

$$\text{w/ } f(0) = 1, f(\infty) = 0$$

The solutions are just exponentials!

$$f = c_1 e^{\sqrt{i} y^*} + c_2 e^{-\sqrt{i} y^*}$$

we want decaying sol'n, so $c_1 = 0$

$$\text{and } c_2 = 1 !$$

$$\text{Thus: } \hat{T} = e^{-\sqrt{i} y^* i t^*}$$

OK, what's \sqrt{i} ?

$$\sqrt{i} = \frac{1+i}{\sqrt{2}}$$

$$\text{e.g. } \left(\frac{1+i}{\sqrt{2}}\right)^2 = \frac{1}{2}(1 + 2i + i^2) = i$$

$$\begin{aligned} \text{So } \hat{T} &= e^{-\frac{y^*}{\sqrt{2}}} e^{i(t^* - \frac{y^*}{\sqrt{2}})} \\ &= e^{-\frac{y^*}{\sqrt{2}}} \left(\cos(t^* - \frac{y^*}{\sqrt{2}}) + i \sin(t^* - \frac{y^*}{\sqrt{2}}) \right) \end{aligned}$$

The imaginary part is:

$$T^* = \text{Im}\{\hat{T}\} = e^{-\frac{y^*}{\sqrt{2}}} \sin(t^* - \frac{y^*}{\sqrt{2}})$$

What does this mean?

The amplitude of the wave decreases exponentially: $e^{-\frac{y^*}{\sqrt{2}}} = e^{-\frac{y}{\sqrt{2\alpha/\omega}}}$

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so a higher frequency means a shorter penetration depth!

The other bit is the phase lag:

when $\gamma^*/\sqrt{2} = \pi$ your temp. will

be 180° out of phase w/ the surface!

(But the mag will be $e^{-\pi}$ - pretty small!)

This technique is very useful for many linear periodic problems!

What happens if the slab is finite? Now we get another length scale!

$$\text{---} \sim q=0 \quad y=b$$

$$\text{---} \quad y=0$$

$$T = T_0 + A \sin \omega t$$

We have the same eqn, but
we will scale differently!

$$\text{Let } y^* = y/b, \quad t^* = t/t_c,$$

$$T^* = \frac{T - T_0}{A} \leftarrow \text{forced by BC}$$

$$\text{So : } \left[\frac{b^2}{\alpha t_c} \right] \frac{\partial T^*}{\partial t^*} = \frac{\partial^2 T^*}{\partial y^{*2}}$$

$$T^* \Big|_{y^*=0} = \sin([\omega t_c] t^*)$$

$$\frac{\partial T^*}{\partial y^*} \Big|_{y^*=1} = 0 \quad (\text{no flux})$$

How do we pick t_c ? Usually for periodic problems we still use $t_c = 1/\omega$

$$\text{So : } \left(\frac{\omega b^2}{\alpha} \right) \frac{\partial T^*}{\partial t^*} = \frac{\partial^2 T^*}{\partial y^{*2}}$$

$$T^* \Big|_{y^*=0} = \sin t^* \quad \frac{\partial T^*}{\partial y^*} \Big|_{y^*=1} = 0$$

$$\text{Let's define } \beta^2 \equiv \frac{\omega b^2}{\alpha}$$

so $\beta = \frac{b}{(\frac{\alpha}{\omega})^{1/2}}$ is a ratio of our two length scales!

This is known as the Womersley number (usually used in fluid mechanics)

if $\beta \gg 1$ you are at high frequency and our solution is the same as an unbounded system!

if $\beta \ll 1$ you are at low frequency and you just have a pseudo-steady temperature!

Let's solve for $\beta \sim O(1)$:

use analytic continuation again!

$$\hat{T} \Big|_{y^*=0} = e^{it^*}$$

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As before, let $\hat{T} = e^{it^*} f(y^*)$

$$\therefore i\beta^2 f = f'' \quad f(0) = 1 \quad f'(1) = 0$$

Now our solutions are hyperbolics!

$$f = C_1 \sinh \sqrt{i}\beta y^* + C_2 \cosh \sqrt{i}\beta y^*$$

$$f(0) = 1 \quad \text{so } C_2 = 1$$

$$f'(1) = 0 = C_1 \sqrt{i}\beta \cosh \sqrt{i}\beta$$

$$+ \sqrt{i}\beta \sinh \sqrt{i}\beta$$

$$\therefore C_1 = -\frac{\sinh \sqrt{i}\beta}{\cosh \sqrt{i}\beta}$$

$$\text{so } \hat{T} = e^{it^*} \left(\cosh \sqrt{i}\beta y^* - \frac{\sinh \sqrt{i}\beta \sinh \sqrt{i}\beta}{\cosh \sqrt{i}\beta} \right)$$

$$\text{and } T^* = \operatorname{Im} \{ \hat{T} \}$$

At $y^* = 1$ we get:

$$\begin{aligned} \hat{T}^* \Big|_{y^*=1} &= e^{it^*} \left(\cosh \sqrt{i}\beta - \frac{\sinh^2 \sqrt{i}\beta}{\cosh \sqrt{i}\beta} \right) \\ &= e^{it^*} \left(\cosh \sqrt{i}\beta - \frac{\cosh^2 \sqrt{i}\beta - 1}{\cosh \sqrt{i}\beta} \right) \\ &= \frac{e^{it^*}}{\cosh \sqrt{i}\beta} \end{aligned}$$

$$\text{and } T^* \Big|_{y^*=1} = \operatorname{Im} \left\{ \frac{e^{it^*}}{\cosh \sqrt{i}\beta} \right\}$$

The amplitude of $T^* \Big|_{y^*=1}$ is just

$$\left| \frac{1}{\cosh \sqrt{i}\beta} \right|$$

These sorts of complex things are easy to plot up in matlab, which handles $i \equiv \sqrt{-1}$ just fine! Most functions in Matlab can take complex arguments.

Contents

- Temperature Distribution in a Finite Slab with Periodic Heating
- Plot of Upper Surface Amplitude as a Function of Beta
- Conclusion

Temperature Distribution in a Finite Slab with Periodic Heating

In this script we plot up the temperature distribution in a finite thickness slab where we have oscillatory heating at the bottom and an insulation condition at the top. We start by plotting the temperature distribution at a number of times:

```
i = (-1)^.5; %just in case i was used as an index elsewhere!
beta = 4;

% We require t to be a column vector and y to be a row vector.

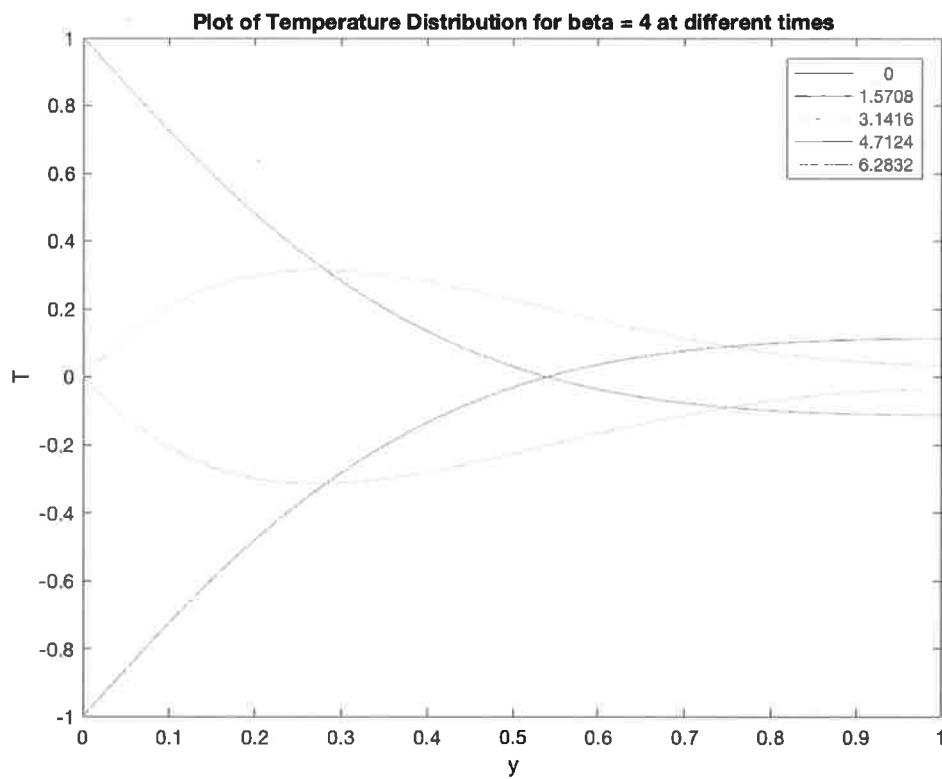
T = @(t,y) imag(exp(i*t)*(cosh(i^.5*beta*y)-sinh(i^.5*beta)/cosh(i^.5*beta)*sinh(i^.5*beta*y)));

t = [0,pi/2,pi,3*pi/2,2*pi]';
y = [0:.01:1];

figure(1)
plot(y,T(t,y))
grid on
xlabel('y')
ylabel('T')
legend(num2str(t))
title(['Plot of Temperature Distribution for beta = ',num2str(beta),' at different times'])

T =
function_handle with value:

@(t,y)imag(exp(i*t)*(cosh(i^.5*beta*y)-sinh(i^.5*beta)/cosh(i^.5*beta)*sinh(i^.5*beta*y)))
```

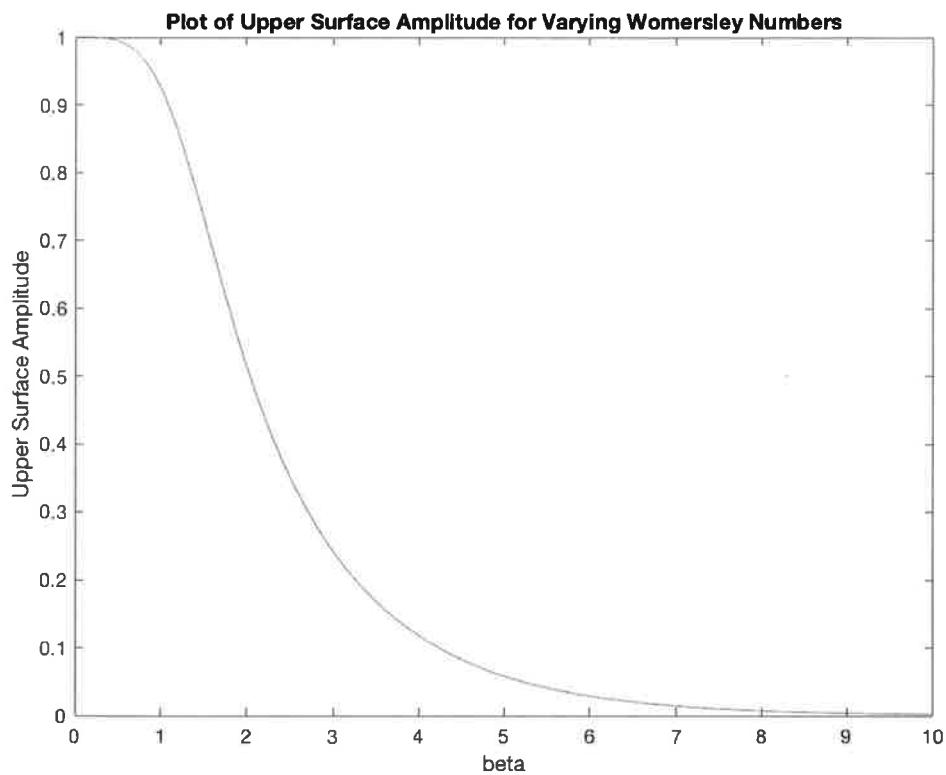


Plot of Upper Surface Amplitude as a Function of Beta

We can also plot up the amplitude of the temperature variation of the upper surface as a function of beta.

```
beta = [0:.01:10];
Tamp = abs(1.0./cosh(i^.5*beta));

figure(2)
plot(beta,Tamp)
xlabel('beta')
ylabel('Upper Surface Amplitude')
title('Plot of Upper Surface Amplitude for Varying Womersley Numbers')
```



Conclusion

As can be seen, for small values of the Womersley number the oscillations at the upper surface are the same as the lower: the whole slab is at a uniform, time varying temperature. For large Womersley number, however, the amplitude of the oscillations at the upper surface decreases exponentially.

So far we have focused on ht transfer in solids, but we need to consider fluids too! The necessary eqn's are derived in ch 11 of BSDL.

Key is that total energy is conserved!

Let \hat{U} be the internal energy per unit mass.

Then $\rho\hat{U}$ is internal energy/vol

Likewise $\frac{1}{2}\rho u^2$ is the KE/vol of the fluid

So $(\frac{1}{2}\rho u^2 + \rho\hat{U})$ is the total energy/volume!

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Now let's draw a control volume



$$\left\{ \text{accum of } E \right\}_{\text{in } D} + \left\{ E \text{ out by convection} \right\}$$

$$+ \left\{ E \text{ out by conduction} \right\} = \left\{ \text{sources} \right\}$$

$$\left\{ \text{accum of } E \right\}_{\text{in } D} = \frac{\partial}{\partial t} \int_D \left(\frac{1}{2} \rho u^2 + \rho \hat{U} \right) dV$$

$$\left\{ E \text{ out by convection} \right\} = \int_{\partial D} \left(\frac{1}{2} \rho u^2 + \rho \hat{U} \right) \underline{u} \cdot \underline{n} dA$$

vol flux
normal to ∂D

$$\left\{ E \text{ out by conduction} \right\} = \int_{\partial D} \underline{\underline{\sigma}} \cdot \underline{\underline{n}} dA$$

What are the sources?

This is total energy (including KE)
so it includes forces as well as
thermal sources:

$$\int_{\partial D} \underline{u} \cdot \underline{P} \cdot \underline{n} dA \quad (\text{pressure forces})$$

shear forces (use diff. sign convention)

$$+ \int_{\partial D} \underline{u} \cdot \underline{\tau} \cdot \underline{n} dA \quad (\text{viscous forces})$$

$$+ \int_D \underline{g} \cdot \underline{u} dV \quad (\text{gravity forces})$$

$$+ \int_D \dot{s} dV \quad (\text{thermal sources like rxn, dissip, etc.})$$

To get an eq'n at a point in the fluid, apply divergence theorem to surface integrals to convert to vol. integrals. Since D is arb. eq'n is valid at every point in flow!

So we get eq'n 11.1-7:

$$\begin{aligned} \frac{\partial}{\partial t} \left(\frac{1}{2} \rho u^2 + \rho \hat{U} \right) + \nabla \cdot \left[\left(\frac{1}{2} \rho u^2 + \rho \hat{U} \right) \hat{u} \right] \\ = - \nabla \cdot \hat{q} - \nabla \cdot (\rho \hat{u}) + \nabla \cdot (\hat{\tau} \cdot \hat{u}) \\ + g(\hat{u} \cdot \hat{g}) + \dot{S} \end{aligned}$$

We want to get rid of ρE term & just have it involve internal energy. We subtract off the mechanical energy balance (from $F=ma$) used last term!

You thus get eq. 11.2-1:

$$\begin{aligned} \frac{\partial}{\partial t} (\rho \hat{U}) + \nabla \cdot (\rho \hat{U} \hat{u}) = - \nabla \cdot \hat{q} \\ - \rho (\hat{\tau} \cdot \hat{u}) + \hat{\tau} : \nabla \hat{u} + \dot{S} \end{aligned}$$

\uparrow
reversible conversion
of mechE to thermal
Energy (pressure work)

\uparrow
Irreversible conversion
(viscous dissipation)

so $-P(\nabla \cdot \tilde{u}) \Rightarrow$ if you compress a
(pos or neg!) gas it gets hot!

$\Sigma: \nabla \cdot \tilde{u} \Rightarrow$ Viscous heating due to
shear - always positive
(but usually small -
not always!)

From Thermo we can relate \hat{U} to $T \& P$

This yields eq'n 11.2-5:

$$\rho \hat{C}_p \left(\frac{\partial T}{\partial t} + \tilde{u} \cdot \nabla T \right) = - \nabla \cdot \tilde{q} \\ + \tilde{\zeta} \tilde{\nabla} \tilde{u} - \left(\frac{\partial \ln \rho}{\partial \ln T} \right) \frac{DP}{Dt} + \dot{s}$$

Note: $\frac{DP}{Dt} \equiv \frac{\partial P}{\partial t} + \tilde{u} \cdot \nabla P$

(material derivative, Lagrangian perspective)

For a fluid at constant pressure
(usual case), neglecting viscous
dissip. as it is usually small,

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we get (w/ Fourier's Law, const. κ):

eq'n 11.2-8:

$$\hat{\rho} \hat{C}_p \left(\frac{\partial T}{\partial t} + \underline{u} \cdot \nabla T \right) = \kappa \nabla^2 T + \dot{s}$$

This is the eq'n we will use - but if you work w/ compressible gases (e.g., gas turbines!) you would use a different form! Table 11.4-1 has lots of versions for different applications!

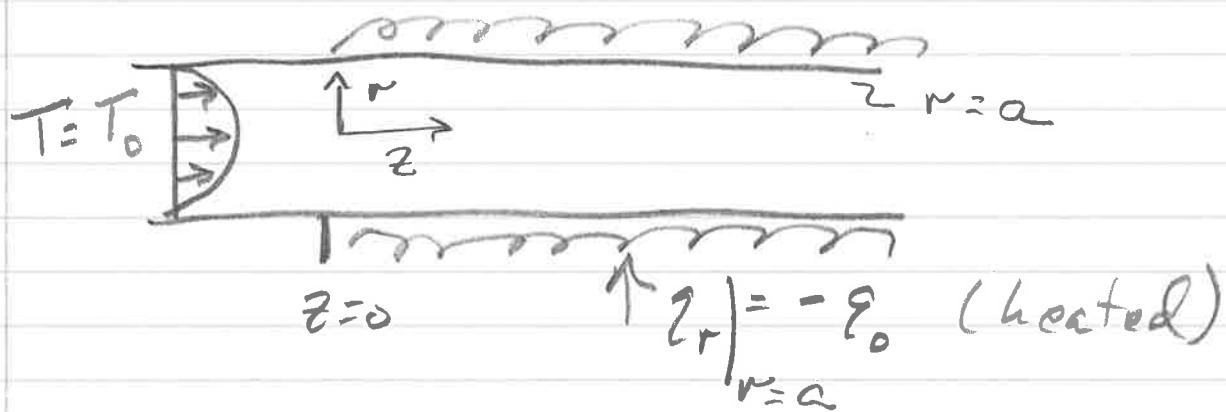
So: let's review $\frac{DT}{Dt} \equiv \frac{\partial T}{\partial t} + \underline{u} \cdot \nabla T$

This is material derivative: there are 2 ways a fluid element can change temp. (1) $\frac{\partial T}{\partial t} = \text{time deriv}$
 (2) $\underline{u} \cdot \nabla T \equiv \text{convected in direction of temp. gradient!}$

Material derivative has both pieces!

OK, let's apply this!

Probably the classic problem in convective transport is the Graetz (or Nusselt-Graetz) problem: laminar flow through a heated pipe!



We want to calculate the heat transfer coefficient:

$$\dot{Q}_0 = h (T|_{r=a} - T_b)$$

T_b is the bulk or cup-mixing temperature \Rightarrow what you would get for the temp. in a cup holding

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the fluid coming out of the pipe!

$$\bar{T}_b = \frac{\int_0^a T u_z 2\pi r dr}{\int_0^a u_z 2\pi r dr}$$

This is much more useful than the area avg \bar{T} or centerline T !

What are the equations governing this problem? Assume incompressible flow w/ constant properties!

$$CE: \nabla \cdot \underline{u} = 0$$

$$NS: \rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla P + \mu \nabla^2 \underline{u} + \rho g$$

Energy:

$$\rho \hat{C}_P \left(\frac{\partial T}{\partial t} + \underline{u} \cdot \nabla T \right) = \kappa \nabla^2 T + \mu \phi_v$$

$(z : \underline{u})$

Viscous Dissip.

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How do we solve?

- 1) choose coord system in which body has convenient rep! \Rightarrow cyl. coord!
- 2) Get rid of terms that are zero
- 3) scale the rest to further simplify!

Start with C.E. & velocity profile!

$$\nabla \cdot \underline{u} = 0$$

$$\therefore \frac{1}{r} \frac{\partial}{\partial r} (r u_r) + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial u_z}{\partial z} = 0$$

Assume unidirectional flow!

$$\therefore u_r = u_\theta = 0 \text{ and } \frac{\partial u_z}{\partial z} = 0!$$

This is valid for fully developed flow!
otherwise (if $\frac{\partial u_z}{\partial z} \neq 0$) then $u_r \neq 0$!

Now for z-component of NS eqns:

(152)

$$g \left(\frac{\partial u_z}{\partial t} + u_r \frac{\partial u_z}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_z}{\partial \theta} + u_z \frac{\partial u_z}{\partial z} \right) \\ = - \frac{\partial P}{\partial z} + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_z}{\partial \theta^2} \right. \\ \left. + \frac{\partial^2 u_z}{\partial z^2} \right] + \rho g_z$$

Ok, assume unidirectional flow
in z dir., also axisymmetric.

We can ignore ρg_z term as it
is the difference from hydrostatics
that drives flow $(-\frac{\partial P}{\partial z} + \rho g_z) \equiv -\frac{\partial P}{\partial z}$
(augmented pressure!)

since from CE $\frac{\partial u_z}{\partial z} = 0 \therefore \frac{\partial^2 u_z}{\partial z^2} = 0!$

We're left with:

$$g \frac{\partial u_z}{\partial t} = - \frac{\partial P}{\partial z} + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_z}{\partial r} \right) \right]$$

Assume SS too!

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In general we impose a flow rate or avg. vel \bar{U} which yields the pressure gradient!

Anyway, we get Poiseuille flow:

$$u_z = 2 \bar{U} \left(1 - \frac{r^2}{a^2} \right)$$

e.g., CL velocity is twice average!
(geometry specific: this is for circular tube only!)

This yields $\frac{\partial P}{\partial z} = - \frac{8\mu \bar{U}}{a^2}$

with flow rate $\bar{Q} = \bar{U} \pi a^2$

Ok, now for energy!

$$\begin{aligned} & \rho C_p \left(\frac{\partial T}{\partial t} + u_r \frac{\partial T}{\partial r} + \frac{u_\theta}{r} \frac{\partial T}{\partial \theta} + u_z \frac{\partial T}{\partial z} \right) \\ &= \kappa \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \theta^2} + \frac{\partial^2 T}{\partial z^2} \right] \\ & \quad + \mu \phi_v \end{aligned}$$

(154)

Again, assume SS, so $\frac{\partial T}{\partial t} = 0$

unidirectional flow $\therefore u_r = u_\theta = 0$

axi-symmetric so $\frac{\partial^2 T}{\partial \theta^2} = 0$

$$\hat{f} \hat{C}_p 2U \left(1 - \frac{r^2}{a^2}\right) \frac{\partial T}{\partial z} = k \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{\partial^2 T}{\partial z^2} \right] + \mu \left(\frac{\partial u_z}{\partial r} \right)^2$$

\curvearrowright viscous dissipation

OK, now for BC's:

$$T \Big|_{z \rightarrow -\infty} = T_0 \quad \frac{\partial T}{\partial r} \Big|_{r=0} = 0 \quad (\text{farate})$$

$$-\kappa \frac{\partial T}{\partial r} \Big|_{r=a, z>0} = -q_0 \quad (\text{heating})$$

So let's scale this!

$$\text{Let } r^* = \frac{r}{a}, \quad z^* = \frac{z}{z_c}, \quad T^* = \frac{T - T_0}{\Delta T_c}$$

Look at inhomogeneous BC:

$$-\kappa \frac{\Delta T_c}{a} \left. \frac{\partial T^*}{\partial r^*} \right|_{\substack{r^*=1 \\ z^*>0}} = -q_0$$

$$\therefore \Delta T_c = \frac{q_0 a}{\kappa}$$

and $\left. \frac{\partial T^*}{\partial r^*} \right|_{\substack{r^*=1 \\ z^*>0}} = 1$

And for DE:

$$\begin{aligned} & \frac{g \hat{C}_p U \Delta T_c}{z_c} 2(1-r^{*2}) \frac{\partial T^*}{\partial z^*} = \kappa \frac{\Delta T_c}{a^2} \frac{1}{r^*} \frac{\partial}{\partial r^*} \left(\kappa \frac{\partial T^*}{\partial r^*} \right) \\ & + \kappa \frac{\Delta T_c}{z_c^2} \frac{\partial^2 T^*}{\partial z^{*2}} + \mu \left(\frac{4 U w}{a^2} \right)^2 \\ & \hookrightarrow \left(\frac{16 \mu U^2}{a^2} \right) r^{*2} \end{aligned}$$

OK - next divide by
scaling of important term!

Heating from wall, so radial cond. has
to matter!

Divide by $\frac{\kappa \Delta T_c}{a^2}$

So:

$$\left[\frac{g \hat{C}_p U a^2}{K z_c} \right] r^2 (1 - r^{*2}) \frac{\partial T^*}{\partial z^*}$$

$$= \frac{1}{r^*} \frac{\partial}{\partial r^{*2}} \left(r^{*2} \frac{\partial T^*}{\partial r^*} \right) + \left[\frac{a^2}{z_c^2} \right] \frac{\partial^2 T^*}{\partial z^{*2}}$$

$$+ \left[\frac{16 \alpha U^2}{K \Delta T_c} \right] r^{*2}$$

Choose z_c so that we balance axial convection w/ radial conduction!

$$\therefore z_c = \frac{g \hat{C}_p a^2}{K} U \equiv \left(\frac{a^2}{\alpha} \right) U$$

\hookrightarrow defⁿ time

$\therefore z_c$ is the distance fluid is convected down the tube during radial difⁿ t!

So we are left w/ two groups.

Look at $\frac{a^2}{z_c^2} = \frac{a^2}{\left(\frac{a^2}{\alpha} U \right)^2} = \left(\frac{\alpha}{U a} \right)^2 = \left[\frac{U a}{\alpha} \frac{\alpha}{U} \right]^2$

(157)

$$= \left(\frac{1}{Re} \frac{1}{Pr} \right)^2$$

normally Re is D , nota!

In general, $Re Pr >> 1$!!

Say, water in a 2 cm dia pipe
at slow speed of 10 cm/s

$$\frac{Ua}{\nu} = \frac{(10)(1)}{0.01} = 1000!$$

$$Pr \approx 7 \quad (20^\circ C)$$

$$\therefore \frac{\alpha}{Ua} = \frac{1}{7000} \quad \left(\frac{\alpha}{Ua} \right)^2 = \underline{2 \times 10^{-8}}$$

That is why you neglect thermal diff' in direction of motion!
It's small!

O.k., what about viscous dissipation?

$$\frac{16 \mu U^2}{K \Delta T_c} = \frac{16 \mu U^2}{q_0 a} \approx \frac{(16)(0.01)(10)^2}{(10^{-3})(1)} = 0.016$$

e.g., $1 \text{ W/m}^2 = 1000 \frac{\text{erg}}{\text{s cm}^2}$

This is actually high - usually q_0 is bigger!

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Except for specific cases, if you are heating things, viscous dissipation is negligible!

$$\text{So: } 2(1 - r^{*2}) \frac{\partial T^*}{\partial z^*} = \frac{1}{r^{*2}} \frac{\partial}{\partial r^{*2}} \left(r^{*} \frac{\partial T^*}{\partial r^*} \right)$$

$$T^* \Big|_{z^*=0} = 0 \quad \frac{\partial T^*}{\partial r^*} \Big|_{r^{*}=1} = 1 \quad \frac{\partial^2 T^*}{\partial r^{*2}} \Big|_{r^{*}=0} = 0 \text{ (Physic)}$$

We want the asymptotic solution!

It gets hotter w/ z^* , so expect

$$T_\infty^* = z^* f_1(r^*) + f_2(r^*)$$

$$\therefore \frac{1}{r^{*2}} (r^{*} f_1')' = 0 \quad f_1'(0) = 0 \quad \underline{f_1'(1) = 0}$$

This just yields $f_1 = c$ (cst!)

Now for f_2 :

$$\frac{1}{r^{*2}} (r^{*} f_2')' = 2(1 - r^{*2}) f_1; \quad f_2'(0) = 0, \quad \underline{f_2'(1) = 1}$$

(158)

Except for specific cases, if you are heating things, viscous dissipation is negligible!

$$\text{So: } 2(1 - r^{*2}) \frac{\partial T^*}{\partial z^*} = \frac{1}{r^{*2}} \frac{\partial}{\partial r^*} \left(r^* \frac{\partial T^*}{\partial r^*} \right)$$

$$T^* \Big|_{z^*=0} = 0 \quad \frac{\partial T^*}{\partial r^*} \Big|_{r^*=1} = 1 \quad \frac{\partial T^*}{\partial r^*} \Big|_{r^*=0} = O(\text{Ansatz})$$

We want the asymptotic solution!

It gets hotter w/ z^* , so expect

$$T^*_w = z^* f_1(r^*) + f_2(r^*)$$

$$\therefore \frac{1}{r^{*2}} (r^* f_1')' = 0 \quad f_1'(0) = 0 \quad \underline{f_1'(1) = 0}$$

This just yields $f_1 = c$ (cst!)

Now for f_2 :

$$\frac{1}{r^{*2}} (r^* f_2')' = 2(1 - r^{*2}) f_1; \quad f_2'(0) = 0, \quad \underline{f_2'(1) = 1}$$

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f_1 is a constant, so we just integrate:

$$\begin{aligned} (r^* f_2') &= c \int 2(1-r^{*2}) r^* dr^* \\ &= \left(r^{*2} - \frac{1}{2} r^{*4}\right) c + c_2 \end{aligned}$$

divide:

$$f_2' = c \left(r^* - \frac{1}{2} r^{*3}\right) + \frac{c_2}{r^*}$$

$$\text{but } f_2'(1) = 1$$

$$\therefore c = 2!$$

$$\text{so } f_2' = 2r^* - r^{*3}$$

$$f_2 = r^{*2} - \frac{1}{4} r^{*4} + c_3$$

We require that the flow average temp at $z^*=0$ vanishes!

$$\int_0^1 f_2 2(1-r^{*2}) r^* dr^* = 0$$

$$\text{so } c_3 + \int_0^1 \left(r^{*2} - \frac{1}{4} r^{*4}\right) 4(1-r^{*2}) r^* dr^* = 0$$

$$= c_3 + \frac{7}{24} \quad \text{so } c_3 = -\frac{7}{24}$$

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$$\therefore \bar{T}_\infty = 2z^* + r^{*2} - \frac{1}{4}r^{*4} - \frac{7}{24}$$

We can define the heat transfer coefficient:

$$h_\infty = \frac{\dot{E}_0}{T|_{r=a} - T|_{r=b}} = \frac{k}{a} \frac{1}{\bar{T}|_{r=1} - \bar{T}|_{r=b}}$$

but $\bar{T}|_{r=b} = 2z^*$! (as from an energy balance)

$$\bar{T}|_{r=1} = 2z^* + 1 - \frac{1}{4} - \frac{7}{24} = \frac{11}{24}$$

$$\text{so } h_\infty = \frac{k}{a} \frac{24}{11} \quad (\text{note: } Nu = \frac{hD}{k} = \frac{48}{11})$$

How long does it take to get there?

$$\text{Let } \bar{T}^* = \bar{T}_\infty^* + \bar{T}_d^*$$

$$2(1-r^{*2}) \frac{\partial \bar{T}_d^*}{\partial z^*} = \frac{1}{r^*} \frac{\partial}{\partial r^*} \left(r^* \frac{\partial \bar{T}_d^*}{\partial r^*} \right)$$

$$\frac{\partial \bar{T}_d^*}{\partial r^*} \Big|_{r^*=0,1} = 0 \quad \bar{T}_d^* \Big|_{z^*=0} = -\bar{T}_\infty^* \Big|_{z^*=0}$$

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Solve via sep. of variables:

$$\bar{T}_\infty^* = G(z^*) F(r^*)$$

$$\therefore \frac{G'}{G} = \frac{(r^* F')'}{2r^*(1-r^{*2})F} = -\sigma^2$$

$$F'(0) = F'(1) = 0$$

This has to be solved numerically,
but it's easy to do!

$$\cdot P(x) \equiv r^*$$

$$g(x) \equiv 0$$

$$w(x) \equiv 2r^*(1-r^{*2})$$

$$\text{and } -\bar{T}_\infty^* \Big|_{z^*=0} = -\left(r^{*2} - \frac{1}{4}r^{*4} - \frac{7}{24}\right)$$

From the numerical solution,

$$\sigma^2 \approx 12.8$$

so it decays pretty fast!

The numerical distance goes as $z \cdot \sqrt{\frac{a^2}{\alpha}}$
which may be fairly large! (for $\text{RePr} \gg 1$)

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- Temperature of the Cylinder Wall
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- Heat Transfer Coefficient
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The Nusselt-Graetz Problem: Constant Heat Flux at the Wall

We solve the Sturm-Liouville problem for constant heat flux at the wall for laminar flow through a circular tube.

The eigenvalue problem for the decaying solution is

$$(x^*y')' + \lambda * 2 * r^*(1 - r^2)^*y = 0$$

$$y'(0) = 0; y'(1) = 0$$

The asymptotic solution at large z is:

$$T_{\infty} = 2*z + r^2 - r^4/4 - 7/24$$

Thus, the initial value for the Sturm-Liouville expansion is just the negative of this function.

Solving the problem we get:

```
p = @(x) x;
q = @(x) zeros(size(x));
w = @(x) 2*x.* (1-x.^2);
bc = [0,1,0,1];

n = 100; %The number of points we would like (the number of intervals)

[lambda, eigenvecs] = slsolve(p,q,w,bc,n);

Tinf = @(z,r) 2*z + r.^2 - r.^4/4 - 7/24

% And that's it!

Tinf =
function_handle with value:
@(z,r) 2*z+r.^2-r.^4/4-7/24
```

Eigenvalues, Eigenvectors, and Coefficients

We are interested in the lead eigenvalues, coefficients, and eigenvectors. We just look at the first five:

```
firsteigenvecs = lambda(1:5)

% And we calculate the coefficients using the Trapezoidal Rule:

r = [0:1/n:1]';

% The Trapezoidal Rule weights:
weights = ones(1,n+1);
weights(1) = 0.5;
weights(n+1) = 0.5;
weights=weights/n;

a = zeros(length(lambda),1);

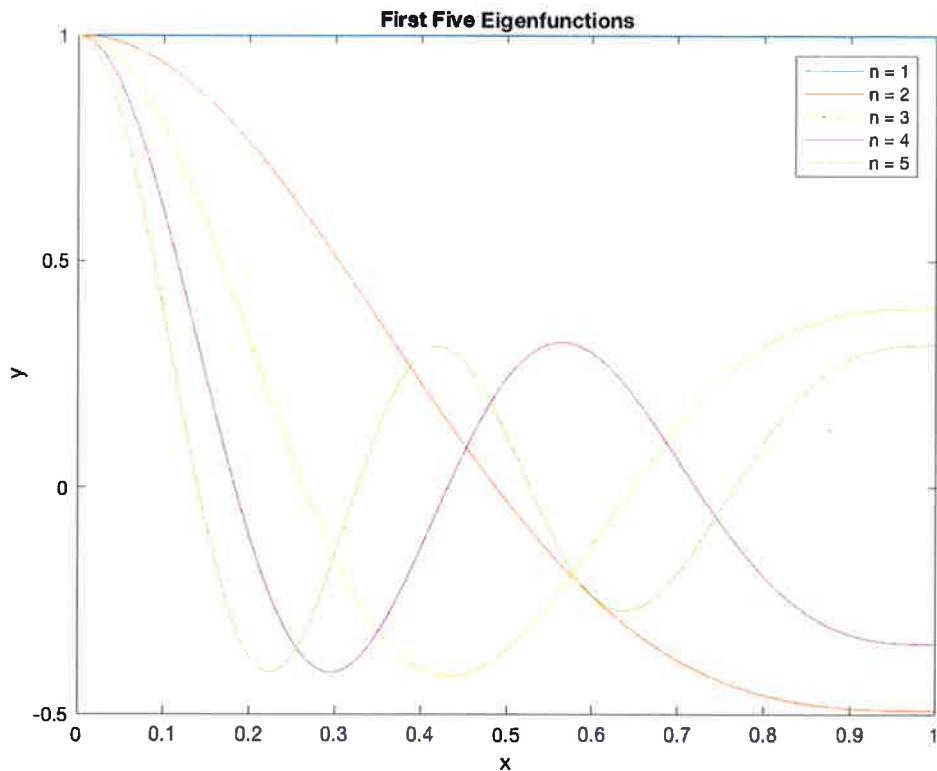
for i = 1:length(lambda)
    numerator = -weights*(w(r).*Tinf(0,r).*eigenvecs(:,i));
    denominator = weights*(w(r).*eigenvecs(:,i).^2);
    a(i) = numerator/denominator;
end

firstcoefficients = a(1:5)

% And we plot the first five eigenfunctions:
figure(1)
plot(r,eigenvecs(:,1:5))
xlabel('x')
ylabel('y')
title('First Five Eigenfunctions')
legend('n = 1','n = 2','n = 3','n = 4','n = 5')
grid on

firsteigenvecs =
0.0000
12.8321
41.8881
86.9418
147.9090

firstcoefficients =
0.0000
0.4035
-0.1749
0.1049
-0.0728
```



Temperature of the Cylinder Wall

We want the temperature at the outer radius, necessary for obtaining the heat transfer coefficient:

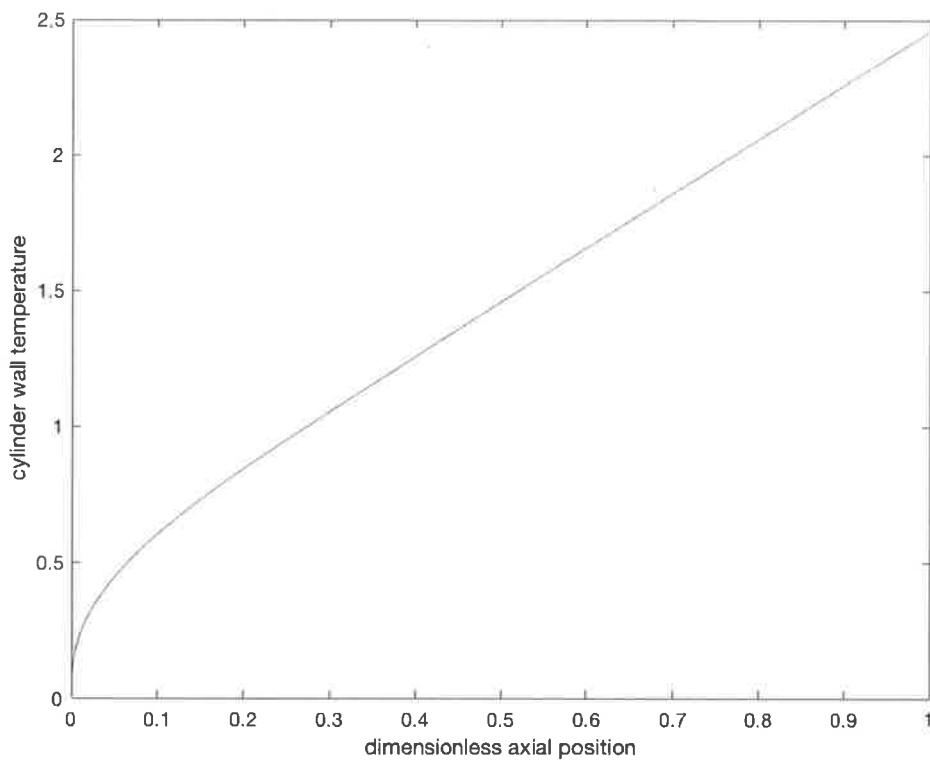
```

z = [0.0005:0.001:1];
twall = zeros(size(z)); %we initialize the array

for i = 1:length(z)
    twall(i) = Tinf(z(i),1) + sum(a.*exp(-lambda*z(i)).*eigenvecs(end,:)');
end

figure(2)
plot(z,twall)
xlabel('dimensionless axial position')
ylabel('cylinder wall temperature')
grid on

```



Temperature Profile at Various Times

We can also plot up the temperature distribution for specific z locations. You will note the issue near the origin at very small z . This is known as the Gibbs ringing phenomenon and is well known in signal processing.

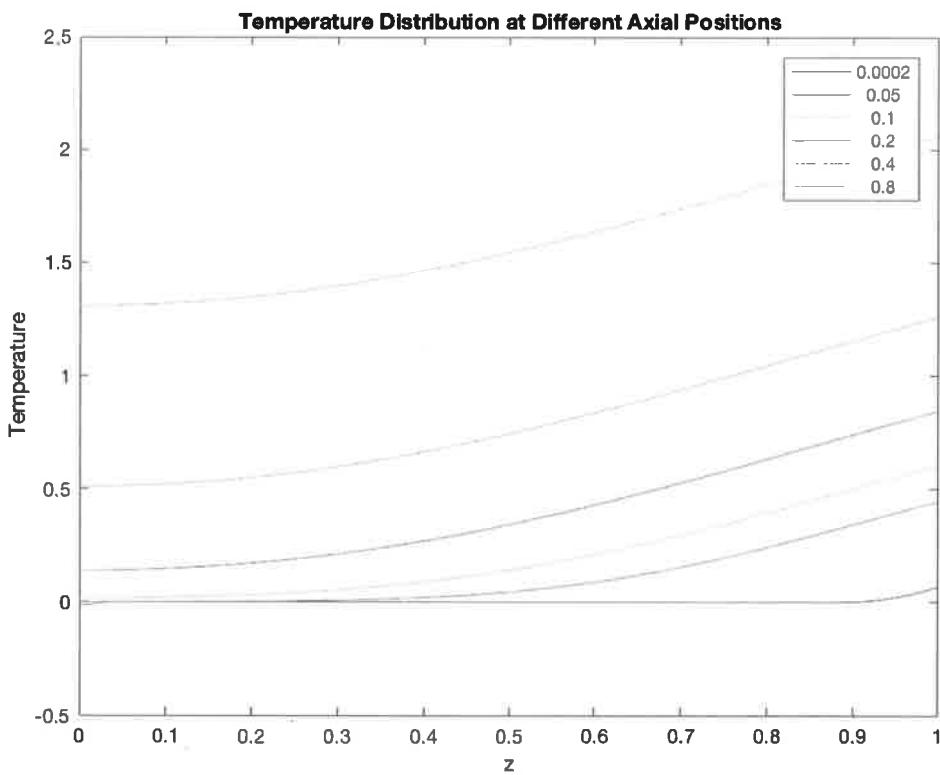
```

zplot = [0.0002,.05,.1,.2,.4,.8]';

tprofile = zeros(length(r),length(zplot));
for j = 1:length(zplot)
    for i=1:length(r)
        tprofile(i,j) = Tinf(zplot(j),r(i)) + sum(a.*exp(-lambda*zplot(j)).*eigenvecs(i,:));
    end
end
figure(3)
plot(r,tprofile)
legend(num2str(zplot))
xlabel('z')
ylabel('Temperature')
title('Temperature Distribution at Different Axial Positions')
grid on

```

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Heat Transfer Coefficient

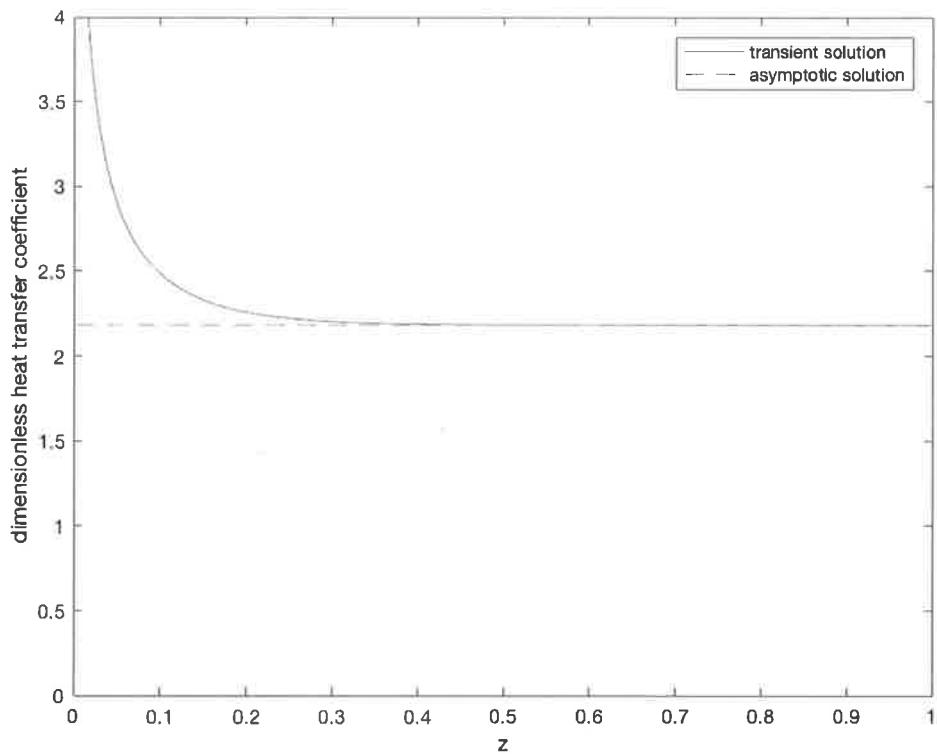
Finally, we are interested in how the heat transfer coefficient varies with axial position. The dimensionless value is just the inverse of $t_{\text{wall}} - Tb(z)$, where $Tb(z)$ is just $2z$. So:

```

h = 1./(twall - 2*z);

figure(4)
plot(z,h,z,24/11*ones(size(z)), '--')
axis([0,1,0,4])
xlabel('z')
ylabel('dimensionless heat transfer coefficient')
legend('transient solution', 'asymptotic solution')
grid on

```



Conclusion

The initial heat transfer coefficient is larger than the asymptotic value due to the small thickness of the developing boundary layer. After a short distance, however, the asymptotic result is reached. The zero initial eigenvalue is the result of a zero derivative condition at both $r = 0$ and $r = 1$, however the coefficient for it is likewise zero, removed via the energy balance enforced on the asymptotic solution.

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From our calculations we found that the Nusselt number Nu is a function of dimensionless distance down the pipe. This is the local Nu and our $\bar{z}^* = \frac{\bar{z}}{UD^2/\alpha}$

It's usually written in terms of diameter $D = 2a$, thus:

$$\frac{h_{loc}D}{k} = Nu_{loc} = \frac{48}{11} + f^L \left(\frac{\bar{z}}{UD^2/\alpha} \right)$$

This ratio is Gz , Graetz #

$$Gz = \frac{UD^2}{\alpha \bar{z}} = \left(\frac{UD}{2} \right) \left(\frac{2}{\alpha} \right) \left(\frac{D}{\bar{z}} \right)$$

\uparrow \uparrow
Re Ph

The solution is valid as $Gz \rightarrow 0$, but actually is good way before! Let's look at some numbers.

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The lead eigenfunction decays exponentially
as $e^{-4\lambda_1 \frac{z}{UD^2}}$ where $\lambda_1 = 12.8$

So the term is small when

$$z > 50 \frac{UD^2}{\lambda}$$

Suppose we have water flowing through
a 1cm ID tube at 10 cm/s. This yields

$$Re = \frac{(10)(1)}{(0.01)} = 1000 \text{ so it's laminar}$$

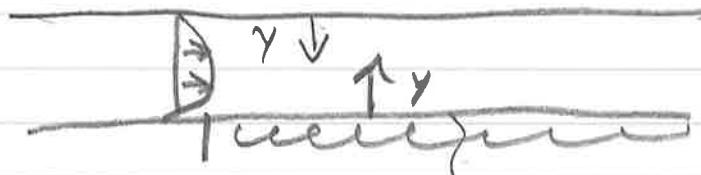
$$Pr = \frac{\nu}{\alpha} = 7, \text{ so } \frac{UD^2}{\alpha} = 7000 \text{ cm} = 70 \text{ m!}$$

Thus, even though λ_1 is large, you
are still in the entrance region for
over 1m!

For short tubes we can look
at the entrance region using
boundary layer analysis!

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we define a coord $y = a - w$
 (e.g., distance from wall)



$$z=0 \quad \left. \frac{\partial y}{\partial z} \right|_{y=0} = - \left. \kappa \frac{\partial T}{\partial y} \right|_{y=0} = g_0$$

Let the characteristic thickness of BL be $\delta \ll a$

$$\text{Recall } u_z = 2U \left(1 - \frac{w^2}{a^2} \right)$$

$$\text{Now } w = a - y$$

$$\begin{aligned} \therefore u_z &= 2U \left(1 - \frac{(a-y)^2}{a^2} \right) \\ &= 2U \left(1 - 1 + 2 \frac{y}{a} - \frac{y^2}{a^2} \right) \xrightarrow{\text{small}} \end{aligned}$$

$$\therefore u_z \approx \frac{4U}{a} y \quad \text{or} \quad \frac{8U}{D} y$$

$$\text{Let } \dot{\gamma} = \frac{8U}{D} \quad \text{shear rate at wall}$$

Provided $\frac{\delta}{a} \ll 1$ we can approximate

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our equation w/ Cartesian coords -
the "flat earth limit"!

$$g \hat{C}_p \dot{\gamma} y \frac{\partial T}{\partial z} = \kappa \frac{\partial^2 T}{\partial y^2}$$

$$T \Big|_{y \rightarrow \infty} = T_0 \quad T \Big|_{z=0} = T_0 - \kappa \frac{\partial T}{\partial y} \Big|_{y=0} = \varrho_0$$

Because $\delta/a \ll 1$ (for small z !)

we have $T_b \approx T_0$ (most of tube is unheated)

$$\text{Thus } h \approx \frac{\varrho_0}{T \Big|_{y=0} - T_0}$$

Let's scale:

$$T^* = \frac{T - T_0}{\Delta T_c} \quad y^* = \frac{y}{\delta} \quad z^* = \frac{z}{z_c}$$

Plug in:

$$\frac{g \hat{C}_p \dot{\gamma} \Delta T_c}{z_c} y^* \frac{\partial T^*}{\partial z^*} = \frac{\kappa \Delta T_c}{\delta^2} \frac{\partial^2 T^*}{\partial y^{*2}}$$

so:

$$\left[\frac{s^3 \dot{\gamma}}{\alpha z_c} \right] y^* \frac{\partial T^*}{\partial z^*} = \frac{\partial^2 T^*}{\partial y^{*2}}$$

$$\text{Thus } \delta = \left(\frac{\alpha z_c}{\delta} \right)^{1/3}$$

And from the BC:

$$-\frac{\Delta T_c}{\delta} + \left. \frac{\partial T^*}{\partial y^*} \right|_{y^*=0} = q_0$$

$$\text{or } \left. \frac{\partial T^*}{\partial y^*} \right|_{y^*=0} = - \left[\frac{q_0 \delta}{K \Delta T_c} \right]$$

$$\text{so } \Delta T_c = \frac{q_0 \delta}{K} = \frac{q_0}{K} \left(\frac{\alpha z_c}{\delta} \right)^{1/3}$$

$$\text{Thus: } y^* \frac{\partial T^*}{\partial z^*} = \frac{\partial^2 T^*}{\partial y^{*2}}$$

$$\left. T^* \right|_{y^* \rightarrow \infty} = \left. T^* \right|_{z^*=0} = 0 ; \left. \frac{\partial T^*}{\partial y^*} \right|_{y^*=0} = -1$$

$$\text{Note: } h = \frac{q_0}{T \left. \frac{\partial T^*}{\partial y^*} \right|_{y=0}} = \frac{q_0}{K \Delta T_c} \left. \frac{1}{T^*} \right|_{y=0}$$

$$= \frac{K}{\left(\frac{\alpha z_c}{\delta} \right)^{1/3}} \left. \frac{1}{T^*} \right|_{y^*=0}$$

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We can use this to get the local Nu in the entrance region:

$$\begin{aligned} Nu_{loc} &= \frac{hD}{k} = \frac{D}{k} K \left(\frac{8U}{D \times z_c} \right)^{1/3} \frac{1}{T^*} \Big|_{y=0} \\ &= 2 \left(\frac{UD}{\alpha} \frac{D}{z_c} \right)^{1/3} \frac{1}{T^*} \Big|_{y=0} \\ &= 2 (G z_c)^{1/3} \frac{1}{T^*} \Big|_{y=0} \end{aligned}$$

where $G z_c = Re Pr \frac{D}{z_c}$

Now we need $T^* \Big|_{y=0}$!

z_c disappeared from dimensionless eq'n, so we are length scale deficient

Affine stretching would yield the same thing!

$$\text{Let } T^* = A \bar{T}, \quad z^* = B \bar{z}, \quad y^* = C \bar{y}$$

$$\therefore \frac{AC}{B} \bar{y} \frac{\partial \bar{T}}{\partial \bar{z}} = \frac{A}{C^2} \frac{\partial^2 \bar{T}}{\partial \bar{y}^2}$$

divide out:

$$\frac{C^3}{B} \bar{y} - \frac{\partial \bar{T}}{\partial \bar{z}} = \frac{\partial^2 \bar{T}}{\partial \bar{y}^2}$$

and from BC: $\frac{A}{C} \frac{\partial \bar{T}}{\partial \bar{y}} \Big|_{\bar{y}=0} = -1$

$$\text{so } \frac{A}{C} = 1 \quad \frac{C^3}{B} = 1$$

or in canonical form

$$\frac{C}{B^{1/3}} = 1 \quad \therefore \quad \bar{z} = \frac{\bar{y}^*}{\bar{z}^{*1/3}}$$

$$\frac{A}{B^{1/3}} = 1 \quad \therefore \quad \frac{\bar{T}^*}{\bar{z}^{*1/3}} = f(\bar{z})$$

so we know $\bar{T}^* \Big|_{\bar{y}^*=0} = \bar{z}^{*1/3} f(0)$

and thus

$$Nu_{loc} = \frac{2}{f(0)} \left(\frac{UD}{\alpha} \frac{D}{\bar{z}} \right)^{1/3}$$

Now we just need $f(0)$!

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We take deriv. to get transformed ODE:

$$\frac{\partial T^*}{\partial y^*} = f' \quad \therefore f'(0) = -1 \quad (\text{BC})$$

$$\frac{\partial^2 T^*}{\partial y^{*2}} = \frac{1}{z^{*1/3}} f''$$

$$\frac{\partial T^*}{\partial z^*} = \frac{\partial}{\partial z^*} \left(z^{*1/3} f(z) \right) = \frac{1}{3} z^{*-2/3} f$$

$$+ z^{*1/3} f' \left(-\frac{1}{3} \frac{2}{z^*} \right)$$

$$= \frac{1}{3} z^{*-2/3} (f - \frac{2}{3} f')$$

So:

$$\frac{1}{3} y^* z^{*-2/3} (f - \frac{2}{3} f') = z^{*-1/3} f''$$

$$\text{or } f'' = \frac{1}{3} z (f - \frac{2}{3} f')$$

$$\text{w/ BC's } f'(0) = -1, f(\infty) = 0$$

You can solve analytically, but
it's easier to get numerically!

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$$\text{Let } \tilde{f} = \begin{bmatrix} f \\ f' \end{bmatrix} = \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

$$\therefore \tilde{f}' = \begin{bmatrix} f_2 \\ \frac{1}{3} g(f_1 - 3f_2) \end{bmatrix}$$

$$\text{w/ } \tilde{f}(0) = \begin{bmatrix} x \\ -1 \end{bmatrix} \text{ where } x \text{ is our shooting param!}$$

we found $x = 1.5363$,

$$\text{thus } Nu_{loc} = 1.3018 \left(\frac{UD}{\lambda} \frac{D}{z} \right)^{1/3}$$

which matches table 14.2-1 :

$$Nu_{loc} = \frac{2 \Gamma(2/3)}{9^{1/3}} \left(\frac{UD}{\lambda} \frac{D}{z} \right)^{1/3}$$

to our precision of integration

Contents

- Nusselt-Graetz Entrance Region Problem
- Conclusion:

Nusselt-Graetz Entrance Region Problem

In this problem we look at the boundary layer solution for the Nusselt-Graetz problem for short tubes in the entrance region. We use the constant wall heat flux boundary condition. The transformed ODE is:

$$f' = 1/3 * \eta * (f - \eta * f')$$

$$f(0) = -1; f(\infty) = 0$$

We want the temperature at the wall $f(0)$, which is our unknown shooting parameter. We solve the differential equation in the function miss4.m given below:

function out = miss4(x) % This function takes in a guess for the unknown wall temperature for the % constant heat flux entrance length problem and returns the temperature % far away.

```
fdot = @(eta,f) [f(2); 1/3*eta*(f(1) - eta*f(2))];
```

```
f0 = [x,-1];
```

```
[etaout fout] = ode23(fdot,[0,10],f0);
```

```
)out = fout(end,1);
```

```
x = fzero('miss4',1)
```

```
% We can plot it up too:
```

```
fdot = @(eta,f) [f(2); 1/3*eta*(f(1) - eta*f(2))];
```

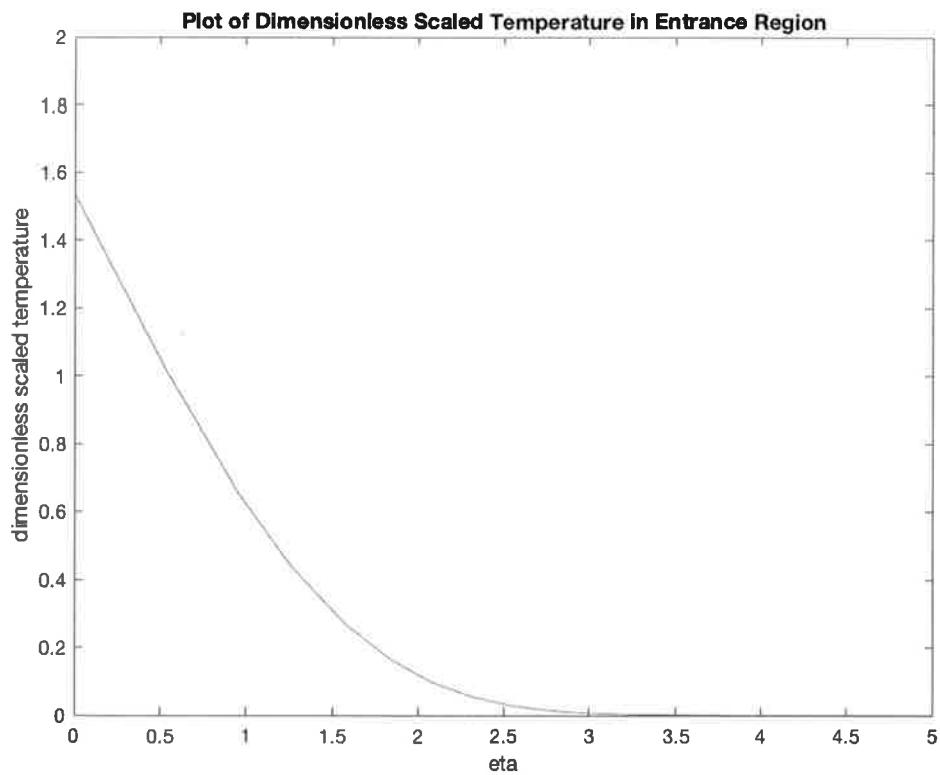
```
f0 = [x,-1];
```

```
[etaout fout] = ode23(fdot,[0,10],f0);
```

```
figure(1)
plot(etaout,fout(:,1))
xlabel('eta')
ylabel('dimensionless scaled temperature')
title('Plot of Dimensionless Scaled Temperature in Entrance Region')
axis([0 5 0 2])
grid on
```

```
x =
```

```
1.5363
```



Conclusion:

The boundary layer solution converges quite fast, so a limit of 10 is more than adequate. The dimensionless wall temperature is $f(0) = 1.5363$, a nicely $O(1)$ result.

It's interesting to see where the entrance region Nu_{loc} crosses the asymptotic $\text{Nu}_{\text{loc}} = \frac{48}{11}$

This occurs at :

$$\frac{48}{11} = 1.3018 \left(\frac{UD}{\alpha} \frac{D}{z} \right)^{1/3}$$

$$\text{or } z = 0.0266 \frac{UD^2}{\alpha}$$

which is about what would be expected from the lead eigenvalue. These results are plotted below.

Next week we'll see what you do with h: heat exchangers!

Contents

- Comparison of Local Nusselt Number Calculations
- Conclusion

Comparison of Local Nusselt Number Calculations

In this script (which must be run after the `nusseltgraetz.m` script) compares the asymptotic 48/11 solution, the Sturm-Liouville solution, and the thermal boundary layer solution for the local Nusselt number for the constant wall heat flux problem. We convert z and h to the conventional scalings $\text{Nu} = hD/k$ and $z^* = z/(UD^2/\alpha)$.

```

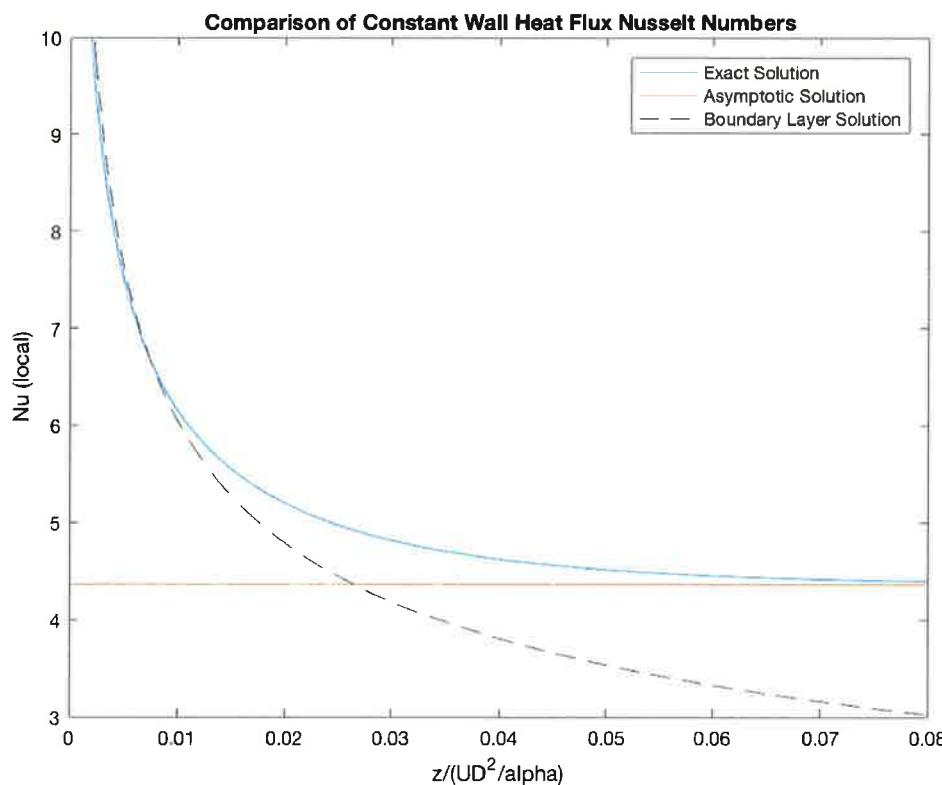
zstar = z/4;

Nu = 2*h;

NuBL = 2*gamma(2/3)/9^(1/3)./zstar.^^(1/3);

figure(1)
plot(zstar,Nu,zstar,48/11*ones(size(zstar)),zstar,NuBL,'--k')
xlabel('z/(UD^2/\alpha)')
ylabel('Nu (local)')
legend('Exact Solution','Asymptotic Solution','Boundary Layer Solution')
title('Comparison of Constant Wall Heat Flux Nusselt Numbers')
axis([0 .08 3 10])
grid on

```



Conclusion

Examination of the graph indicates that the boundary layer solution is good up to a dimensionless value of about 0.01 while the asymptotic solution is approached at a dimensionless value of 0.05.

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We have often discussed analogy between mass, mom. & E transfer - this is particularly useful in understanding heat exchangers.

These usually operate under turbulent conditions as eddies are far more efficient at mixing up fluids than is diffusion! Most resistance to transport is in a narrow layer at the walls.

Let's compare momentum & energy transport along a flat plate (or inside wall of a tube in the "flat earth limit").

X-mom:

$$\rho \vec{u} \cdot \nabla u_x = -\frac{\partial P}{\partial x} + \mu \nabla^2 u_x$$

and the energy eq'n:

$$\rho \hat{C}_p \underline{u} \cdot \nabla T = \kappa \nabla^2 T$$

In the boundary layer $\frac{\partial P}{\partial x}$ is usually small - certainly for the Blasius problem where it's zero!

$$\text{If } \frac{\mu}{\rho} = \frac{\kappa}{\hat{C}_p} \quad (\text{e.g., } \text{Pr} = 1)$$

we get the dimensionless temp.
& u_x profiles are identical (for same BC's)

This means: $u_x|_{y=0} = 0$ (no-slip)

$$\left. \frac{\partial}{\partial y} \left(\frac{u_x}{u_{\infty}} \right) \right|_{y=0} = \left. \frac{\partial}{\partial y} \left(\frac{T - T_s}{T_{\infty} - T_s} \right) \right|_{y=0}$$

$$\text{Now } h \equiv \frac{\partial T}{\partial x} = \kappa \left. \frac{\partial}{\partial y} \left(\frac{T - T_s}{T_{\infty} - T_s} \right) \right|_{y=0}$$

$$\therefore h = + \kappa \left. \frac{\partial}{\partial y} \left(\frac{u_x}{u_{\infty}} \right) \right|_{y=0}$$

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$$\text{but } \tau_w = \mu \left. \frac{du_x}{dy} \right|_{y=0}$$

$$\text{so } h = k \frac{\tau_w}{\mu U_\infty} \quad \text{for } Pr = 1 !$$

Recall from last term we had
the Fanning Friction Factor f_f

$$f_f \equiv \frac{\tau_w}{\frac{1}{2} \rho U_\infty^2} \begin{matrix} \leftarrow \text{wall shear stress} \\ \leftarrow \text{KE/Vol of fluid} \end{matrix}$$

$$\text{so : } h = k \frac{\frac{1}{2} \rho U_\infty^2 f_f}{\mu U_\infty}$$

$$\text{but } Pr = 1 \text{ (assumed!)}$$

$$\therefore \mu = \frac{k}{C_p} \quad Pr = \frac{k}{C_p}$$

$$\text{so } h = \frac{1}{2} (\rho U_\infty^2) f_f$$

We can define the Stanton St :

$$St \equiv \frac{h}{\rho U_\infty C_p} = \frac{Nu}{Re Pr}$$

Thus, we get $St = \frac{f_f}{2}$

which is the Reynolds Analogy
good (only) for $Pr = 1$!

What is $St \equiv \frac{\text{heat flux}}{\text{convective flux}}$

For liquids (other than metals!)

$Pr > 1$ (usually $\gg 1$). This means
that $\alpha < \nu$ and energy transport
is less efficient. This yields the
Colburn Analogy

$$St \approx \frac{f_f}{2} Pr^{-2/3}$$

$$\text{or } j_H \equiv St Pr^{2/3} = \frac{1}{2} f_f$$

↳ Colburn "j factor"

there's an equivalent j_Δ for mass
transfer w/ $Sc = \frac{\nu}{D}$ rather than Pr !

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This is fine for laminar^{BL} flow, but we can do a little better for turbulent boundary layers! If we apply Prandtl Mixing Length theory (discussed last term) to this, we get the Prandtl Analogy:

$$St = \frac{h}{g U_\infty C_p} = \frac{f f/2}{1 + 5\sqrt{f f/2} (\Pr - 1)}$$

A further improvement by von Karman included the buffer region & led to the von Karman Analogy:

$$St = \frac{h}{g U_\infty C_p} = \frac{f f/2}{1 + 5\sqrt{f f/2} \left\{ \Pr - 1 + \ln \left(1 + \frac{5}{6} (\Pr - 1) \right) \right\}}$$

All reduce to the Reynolds Analogy for $\Pr = 1$.

What's f_f ??

For turbulent flow in a pipe:

$$\frac{1}{\sqrt{f_f}} = 4.0 \log_{10} \left\{ Re \sqrt{f_f} \right\} - 0.40$$

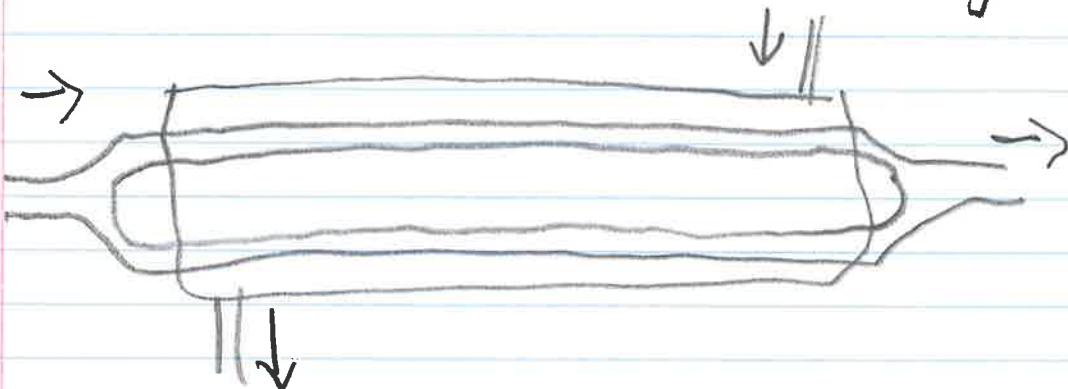
for $Re > 3000$

from Prandtl mixing length theory &
exp³⁺!

For $3000 < Re < 10^5$ we have the
useful correlation

$$f_f \approx \frac{0.0791}{Re^{1/4}}$$

Let's apply this! Suppose we have
a shell & tube heat exchanger:



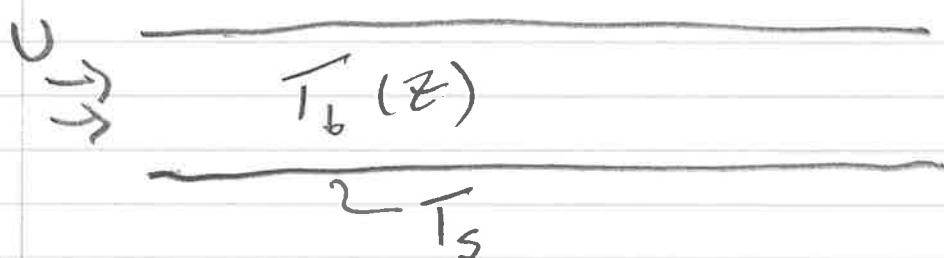
Let's make this even simpler: We feed shell side w/ condensing steam! This gives extremely high heat transfer to the pipes, so that the wall temperature is essentially constant!

Our overall heat transfer coef. is thus (resistances in series!):

$$h_{\text{eff}} = \left(\frac{1}{h_{\text{internal}}} + \frac{1}{h_{\text{wall}}} + \frac{1}{h_{\text{ext}}} \right)^{-1}$$

if walls are copper and $h_{\text{ext}} \sim \infty$, we get $h_{\text{eff}} \approx h_{\text{internal}} = h$

What is our temperature profile?



$$\text{So } \hat{s} \hat{c}_p U \frac{\pi D^2}{4} \frac{Q T_b}{\Delta z} = h \pi D (T_s - \bar{T}_b)$$

$$\therefore \frac{1}{T_s - \bar{T}_b} \frac{Q T_b}{\Delta z} = \frac{4 h}{\hat{s} \hat{c}_p U D} = 4 \frac{st}{D}$$

$$\therefore - \frac{Q \ln(T_s - \bar{T}_b)}{\Delta z} = 4 \frac{st}{D}$$

$$\therefore \ln(\bar{T}_s - \bar{T}_b) = -4 \frac{st}{D} z + cst - 4 st \frac{z}{D}$$

$$\text{or } \bar{T}_b = \bar{T}_s - (T_s - \bar{T}_{b_0}) e^{-4 st \frac{z}{D}}$$

$$\text{At } z = L \quad -4 st \frac{L}{D}$$

$$\bar{T}_b = \bar{T}_s - (T_s - \bar{T}_{b_0}) e^{-4 st \frac{L}{D}}$$

$\underbrace{\quad}_{z=L}$ outlet temperature!

Let's pick some numbers:

$$\text{Take } T_s = 100^\circ\text{C}, \bar{T}_{b_0} = 20^\circ\text{C}$$

and working fluid is water

Say that $U = 2 \text{ m/s} = 200 \text{ cm/s}$

and $D = 2 \text{ cm ID}$, $L = 1 \text{ m}$

This yields a flow rate $= U \frac{\pi D^2}{4} = 0.63 \text{ l/s}$

We need some properties. Let's evaluate at the average of T_f & $T_b = 60^\circ\text{C}$

so: $\nu = 0.47 \text{ cm}^2/\text{s}$, $\rho = 0.99 \text{ g/cm}^3$

$$\hat{C}_p = 4.18 \frac{\text{J}}{\text{g}^\circ\text{K}}, \alpha = 0.0016 \frac{\text{cm}^2}{\text{s}}$$

$$\therefore Pr = \frac{\nu}{\alpha} = 3.14; \rho \hat{C}_p = 4.14 \frac{\text{J}}{\text{cm}^3 \text{K}}$$

$$Re = \frac{(200)(2)}{(0.0047)} = 8.51 \times 10^4$$

$$\therefore f_f \approx \frac{0.0791}{Re^{1/4}} = 0.0046$$

$$\text{What's } St? T_b|_{z=L} ? \Rightarrow \% = 50$$

Reynolds Analogy:

$$St = f_f/2 = 0.0023 \Rightarrow T_b|_L = 49.5^\circ\text{C}$$

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Colburn Analogy:

$$St = \frac{f_f}{2} Pr^{-2/3} = 1.07 \times 10^{-3}; T_{b_L} = 35.5^\circ C$$

Prandtl Analogy:

$$St = 1.52 \times 10^{-3}; T_{b_L} = 41.0^\circ C$$

von Karman Analogy:

$$St = 1.31 \times 10^{-3}; T_{b_L} = 38.4^\circ C$$

Because Colburn analogy is close to the von Karman analogy, and is much simpler, it is usually used...

For these conditions the flow was turbulent. What if it were laminar?

If it were fully developed (it's not) we would have (for this BC) $Nu = \frac{hD}{k} = 3.66$

$$\text{Recall } St = \frac{h}{\rho C_p U} = \frac{hD}{k} \frac{k}{\rho C_p U D} = \frac{Nu}{Re Pr}$$

(191)

So if the thermal profile was fully developed (e.g. a really long tube) and it were (magically) laminar,

$$St_{\text{laminar}} = \frac{3.66}{(8.51 \times 10^4)(3.14)} = 1.4 \times 10^{-5}$$

This is two orders of mag. below the turbulent result!

For a shorter laminar pipe we could use the boundary layer analysis or the Mills correlation:

$$Nu = \frac{hD}{k} = 3.66 + \frac{0.065 Re Pr \frac{D}{L}}{1 + 0.04 (Re Pr \frac{D}{L})^{2/3}}$$

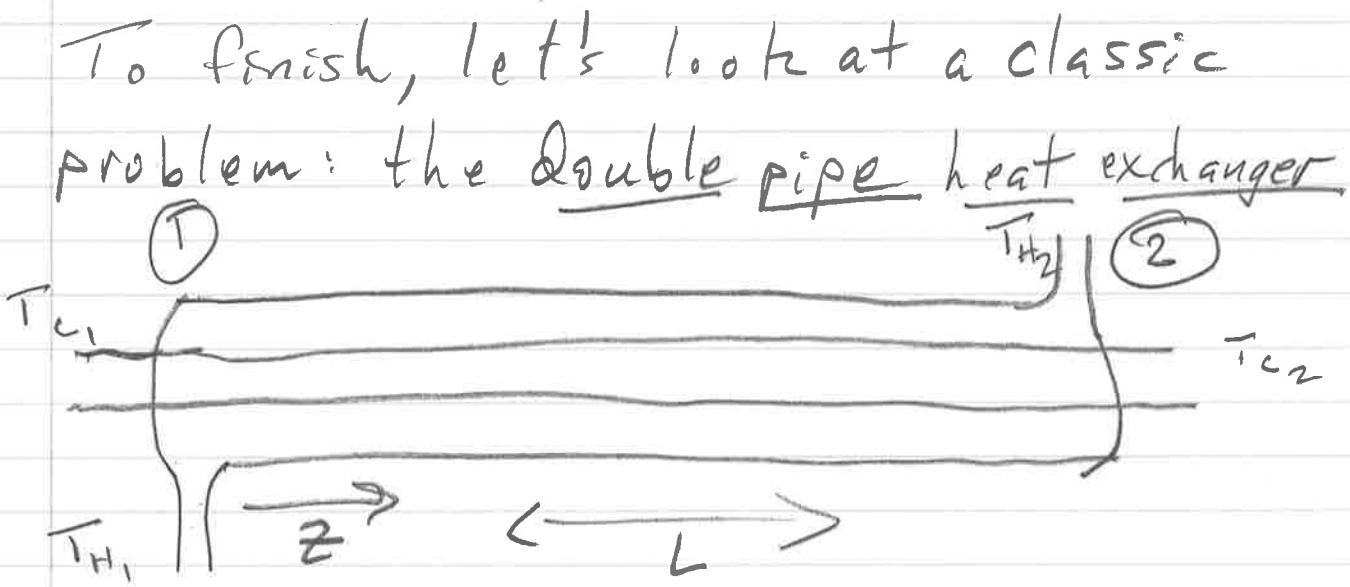
which smoothly goes from the developed value of 3.66 to the Seider-Tate correlation obtained by integrating our BL result over the pipe length.

(192)

Even for this, $Nu = 30.4$ (a lot higher as our profile is still developing!) but

$$St = \frac{Nu}{RePr} = 1.1 \times 10^{-4}, \text{ still an order of mag. lower!}$$

This is why you really really want your heat exchangers to be turbulent! It's much more efficient!



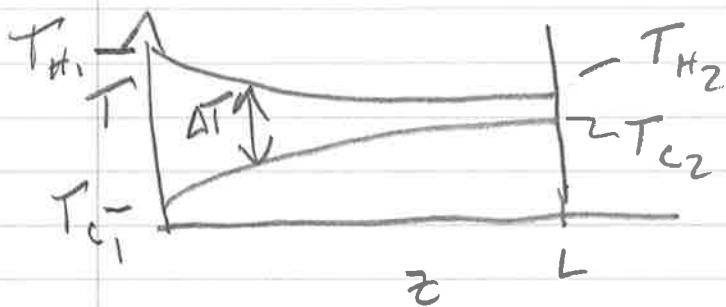
Two concentric cylinders, one carrying the cold stream, one the hot!

(193)

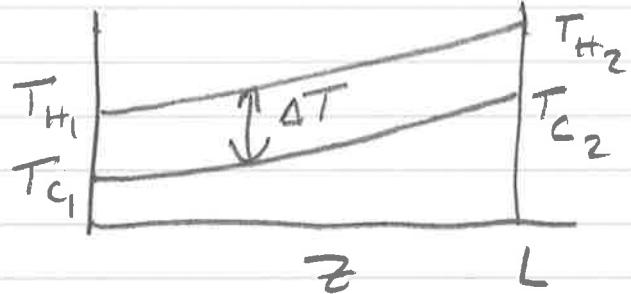
This can be operated in co-current (same direction of flow) or counter-current (opposite directions).

In general:

Co-current:



Counter-current



Note that for co-current the leaving cold temp $T_{C2} <$ the leaving hot temp T_{H2}

For counter-current you can have leaving cold $T_{C2} >$ leaving hot T_{H1} , & it is more efficient

We have a differential area $dA = \pi D dz$
where D is a ref diameter (usually inner pipe)

(194)

We also have an overall heat transfer coeff:

$$U = \left[\frac{1}{h_{\text{inner}}} + \frac{1}{h_{\text{wall}}} + \frac{1}{h_{\text{outer}}} \right]^{-1}$$

(→ $\not\equiv$ velocity, but usual symbol!)

We can define some $dg = U \Delta T dA$ as the differential heat transfer along the tube.

Finally, we define a capacity for heat for each stream:

$$C_H = \dot{m}_H \hat{C}_{PH} \quad \begin{matrix} \leftarrow \text{heat capacity} \\ \leftarrow \text{massflow} \end{matrix}$$

$$C_c = \dot{m}_c \hat{C}_{pc} \quad \text{for cold stream.}$$

From an energy balance:

$$dg = C_c \Delta T_c = C_H \Delta T_H$$

(195)

$$\text{Thus } \Delta \bar{T} = \Delta(T_{H_2} - T_{C_1})$$

$$= \frac{\Delta Q}{C_H} - \frac{\Delta Q}{C_C} = \Delta Q \left(\frac{1}{C_H} - \frac{1}{C_C} \right) = \frac{\Delta Q}{C_H} \left(1 - \frac{C_H}{C_C} \right)$$

We also have the overall energy balance:

$$C_H (T_{H_2} - T_{H_1}) = C_C (T_{C_2} - T_{C_1}) = Q$$

$$\text{Thus } \frac{C_H}{C_C} = \frac{T_{C_2} - T_{C_1}}{T_{H_2} - T_{H_1}}$$

Plug this into the relation for $\Delta \bar{T}$:

$$\Delta \bar{T} = \frac{\Delta Q}{C_H} \left(1 - \frac{T_{C_2} - T_{C_1}}{T_{H_2} - T_{H_1}} \right) = \frac{\Delta Q}{C_H (T_{H_2} - T_{H_1})} (\Delta T_2 - \Delta T_1)$$

$$\text{so } \Delta \bar{T} = \frac{\Delta Q}{Q} (\Delta T_2 - \Delta T_1)$$

$$\text{Now } \Delta Q = U \Delta T \Delta A$$

$$\text{so } \frac{\Delta \bar{T}}{\Delta T} = \frac{U \Delta A}{Q} (\Delta T_2 - \Delta T_1)$$

$$\text{or } \frac{Q \ln \Delta T}{\Delta A} = \frac{U}{Q} (\Delta T_2 - \Delta T_1)$$

(196)

If U is constant (not bad for turbulent flow as development region is very short!)

Then:

$$\ln \Delta T_2 = \ln \Delta T_1 + \frac{UA}{Q} (\Delta T_2 - \Delta T_1)$$

or, rearranging,

$$Q = UA \frac{\Delta T_2 - \Delta T_1}{\ln \frac{\Delta T_2}{\Delta T_1}}$$

This is known as the log mean temperature difference ΔT_{Lm}

Note that if $\Delta T_2 = \Delta T_1$, this just reduces to ΔT . It gets things right (or better) if ΔT is changing!

(197)

So we have the overall balances:

$$\bar{T}_{H_2} - \bar{T}_{H_1} = \frac{Q}{C_H}$$

$$\bar{T}_{C_2} - \bar{T}_{C_1} = \frac{Q}{C_C}$$

and

$$Q = UA \frac{\Delta T_2 - \Delta T_1}{\ln \frac{\Delta T_2}{\Delta T_1}}$$

So if you know the entering hot & cold temperatures, J , C_H , C_C & A you can calculate the exit temps.

If you specify, say, some other combination you can get the rest!

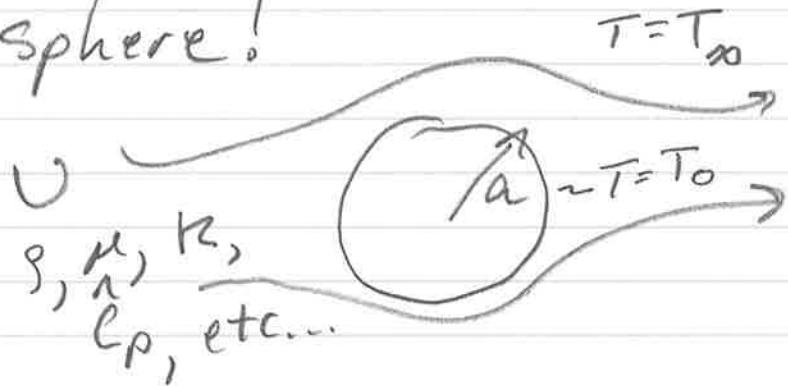
This works for both cocurrent & counter-current exchangers!

There are many other designs, but w/ approp. correlations they can be analyzed in the same way!

(198)

We've discussed convective heat transfer for internal flows - but what about external flows?

The classic example is flow past a sphere!



What is the Nusselt $\mathcal{N} = \frac{hD}{k}$?

At S.S., we have:

$$\rho \hat{C}_p \hat{u} \cdot \nabla \hat{T} = k \nabla^2 \hat{T}$$

$$T|_{r=a} = T_0 \quad T|_{r \rightarrow \infty} = T_\infty$$

Let's scale:

$$\tilde{u}^* = \frac{\tilde{u}}{\tilde{U}}, \quad T^* = \frac{T - T_\infty}{T_0 - T_\infty}$$

$$\tilde{x}^* = \frac{\tilde{x}}{a} \quad (\text{e.g., } \tilde{r}^* = \frac{\tilde{r}}{a})$$

$$\therefore \left(\frac{Ua}{\alpha}\right) u^* \cdot \nabla^* T^* = \nabla^{*^2} T^*$$

$$T^* \Big|_{r^*=1} = 1 \quad T^* \Big|_{r^* \rightarrow \infty} = 0$$

where $\frac{Ua}{\alpha} = \frac{1}{2} \frac{UD}{\alpha} = \frac{1}{2} Re Pr = \frac{1}{2} Pe$

Now if $Pe = 0$ we have the pure conduction result!

$$\underline{T^* = \frac{1}{Nu^*}}$$

What's the heat flux?

$$q_w \Big|_{r^*=a} = -k \frac{\partial T^*}{\partial r^*} \Big|_{r^*=a} = -\frac{k}{a} (T_o - T_\infty) \frac{\partial T^*}{\partial r^*} \Big|_{r^*=a}$$

$$\text{Thus } h = \frac{k}{a} \left(-\frac{\partial T^*}{\partial r^*} \Big|_{r^*=a} \right)$$

$$\text{and } Nu = \frac{hD}{k} = 2 \left(-\frac{\partial T^*}{\partial r^*} \Big|_{r^*=a} \right)$$

but for pure conduction $T^* = \frac{1}{Nu^*}$

$$\therefore Nu = 2 !$$

(200)

You get a similar result for finite shapes (not infinite cylinders, etc., due to Stokes Paradox analog), just the number is a bit different!

OK, now for convection: this depends on the velocity profile in a complex way! If $Re \ll 1$ (really small sphere!) and you have $Re \ll RePr \ll 1$

then Taylor & Arivoss showed

$$Nu = 2 + \frac{1}{2} Pe + O(Pe^2 \ln Pe)$$

Via singular perturbation expansion — a really advanced technique!

For higher Re the problem isn't tractable at all!

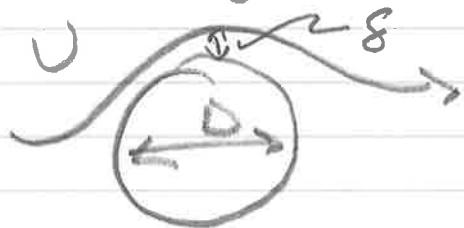
201

Instead, let's use correlations & reasoning!

$$\text{Recall } Nu = \frac{hD}{K} \text{ and } h \sim \frac{K}{\delta}$$

where δ is the distance over which diffusion of E takes place!

We have the geometry:



Fluid flows past our object in time D/U . During this time energy diffuses a distance of $\delta \sim O((\alpha t_c)^{1/2}) \sim O\left(\left(\frac{\alpha D}{U}\right)^{1/2}\right)$ from a Lagrangian (fluid element) sense!

$$\text{Thus, } Nu = \frac{hD}{K} \sim \frac{D}{K} \frac{K}{\left(\frac{\alpha D}{U}\right)^{1/2}}$$

$$= \left(\frac{UD}{\alpha}\right)^{1/2} \sim (Re Pr)^{1/2}$$

So we expect $Nu \sim Re^{\frac{1}{2}} Pr^{\frac{1}{2}}$ (202)

What are the results of correlations?

We have the Whittaker Correlation:

$$Nu = 2 + (0.4 Re^{\frac{1}{2}} + 0.06 Re^{\frac{2}{3}}) Pr^{0.4} \left(\frac{\mu_{\infty}}{\mu_0}\right)^{\frac{1}{4}}$$

where the extra term accounts for an added effect of turbulence.

The viscosity ratio accounts for the effect of temp. inside the boundary layer (very small for gases).

This correlation is good for

$$3.5 < Re < 7.6 \times 10^4 ; 0.71 < Pr < 380$$

$$\text{and } 1.0 < \frac{\mu_{\infty}}{\mu_0} < 3.2$$

You should always check to see if you are in the right range!

what about other shapes?

For a horizontal cylinder there is no conduction limit, and Whittaker proposed the same correlation but without the "²".

For a general shape,

$$\text{Nu} \approx \text{Nu}_{\text{Re}=0} + 0.6 \text{ Re}^{1/2} \text{Pr}^{1/3}$$

pure cond. limit

as a reasonable estimate.

Many correlations are available, but they yield similar results!

For forced convection along a flat plate we would just use

the Colburn Analogy for $\text{Nu} = -f_t^{-1/2}$
for laminar flow $f_t = 0.664 \left(\frac{Ux}{V} \right)$

from solution to the Blasius problem.

$$\text{Thus } \text{Nu}_x = 0.332 \text{ Re}_x^{1/2} \text{ Pr}^{1/3} \quad (204)$$

This is the local Nusselt ~~**~~ defined
as $\text{Nu}_x = \frac{h_{\text{loc}} x}{k}$; $\text{Re}_x = \frac{U x}{\nu}$

Note that because we don't have a
length scale perpendicular to the flow
(like D !) we define it in terms of
 x - distance down the plate!

In all other cases use the
transverse length (e.g. pipe diameter)

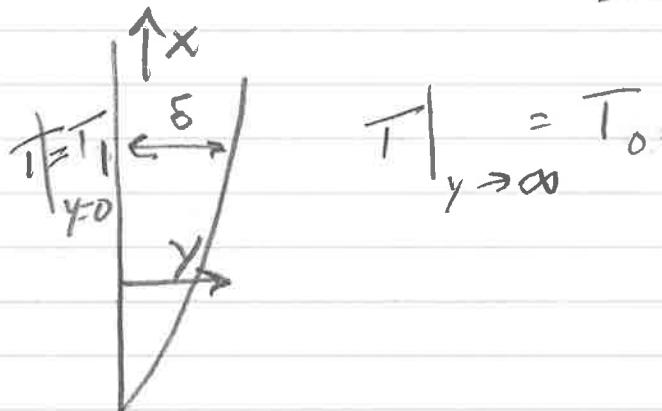
Osc-convection is usually the
strongest source of heat transfer -
but what if we don't force it?

You get "free" or "natural" convection!
This arises from gravity and the
change in density w/ temperature!

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This means we have to solve both momentum & energy simultaneously!

Let's look at a vertical heated plate:



The key is that density is a decreasing function of temperature (usually!).

$$\rho = \rho_0 (1 - \beta (T - T_0)).$$

where $\beta = -\frac{1}{\rho} \frac{\partial \rho}{\partial T}$ is the coef. of thermal expansion!

For an ideal gas $\beta = \frac{1}{T} \leftarrow ^\circ K$!

For water it's $\sim 2.2 \times 10^{-4}$ at $22^\circ C$

and increases to $\sim 5 \times 10^{-4} ^\circ C$ at $50^\circ C$

Changes are small, but they matter!

Let's write down the eq'n's:

$$\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} = 0 \quad (\text{incompressible})$$

x -momentum:

$$\rho \left(u_x \frac{\partial u_x}{\partial x} + u_y \frac{\partial u_x}{\partial y} \right) = - \frac{\partial P}{\partial x} + \mu \left(\frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial y^2} \right) + \rho g_x$$

Energy:

$$\rho \hat{c}_p \left(u_x \frac{\partial T}{\partial x} + u_y \frac{\partial T}{\partial y} \right) = \kappa \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right)$$

The buoyancy term becomes:

$$\rho g_x = -\rho_0 g (1 - \beta(T - T_0))$$

Far from the plate $T = T_0$ and there is no flow. Thus we get hydrostatics:

$$\left. -\frac{\partial P}{\partial x} - \rho_0 g \right|_{y \rightarrow \infty} = 0$$

As we saw last term, the pressure distribution outside the boundary

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layer is impressed on the boundary layer! In other words, by scaling the y -momentum equations you find you can't have a pressure differential over a thin ($O(8)$) region!

Thus at the plate:

$$-\frac{\partial P}{\partial x} + \rho g_x = \rho_0 \beta (T - T_0)$$

This is the Boussinesq approximation: the only material property that varies w/ temperature is density, and that just in the buoyancy term!

So:

$$\rho \left(u_x \frac{\partial u_x}{\partial x} + u_y \frac{\partial u_x}{\partial y} \right) = \mu \left(\frac{\partial u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial y^2} \right) + \rho_0 \beta (T - T_0)$$

OK, let's scale!

$$u_x^* = \frac{u_x}{U_c}, \quad u_y^* = \frac{u_y}{V_c} \quad T^* = \frac{T - T_0}{T_1 - T_0}$$

$$x^* = \frac{x}{H} \quad y^* = \frac{y}{\delta} \quad \Delta T$$

plate height

We start w/ CE:

$$\frac{U_c}{H} \frac{\partial u_x^*}{\partial x^*} + \frac{V_c}{\delta} \frac{\partial u_y^*}{\partial y^*} = 0$$

$$\therefore \left[\frac{\delta}{V_c} \frac{U_c}{H} \right] \frac{\partial u_x^*}{\partial x^*} + \frac{\partial u_y^*}{\partial y^*} = 0$$

||
1

$$\text{or } V_c = \frac{\delta}{H} U_c \text{ as usual...}$$

Now for energy: same scale!

$$\hat{f} \hat{C}_P \frac{U_c \Delta T}{H} \left(u_x^* \frac{\partial T^*}{\partial x^*} + u_y^* \frac{\partial T^*}{\partial y^*} \right)$$

$$= K \frac{\Delta T}{\delta^2} \left(\frac{\delta^2}{H^2} \frac{\partial^2 T^*}{\partial x^{*2}} + \frac{\partial^2 T^*}{\partial y^{*2}} \right)$$

Divide out:

$$\left[\frac{\delta^2 U_c}{\alpha H} \right] \left(u_x * \frac{\partial T^*}{\partial x^*} + u_y * \frac{\partial T^*}{\partial y^*} \right)$$

$$\stackrel{H}{=} \frac{\delta^2}{H^2} \frac{\partial^2 T^*}{\partial x^{*2}} + \frac{\partial^2 T^*}{\partial y^{*2}}$$

$$\therefore \delta = \left(\frac{\alpha H}{U_c} \right)^{1/2} \equiv \left(\frac{H}{U_c} \right)^{1/2}$$

↑ time to flow
 thermal → up plate
 diffusivity

and we take $\frac{\delta}{H} \ll 1$ (thin BL)

so we ignore diff' in direction of motion!

Now for the x-mom eq'n:

$$\frac{\delta U_c^2}{H} \left(u_x * \frac{\partial u_x^*}{\partial x^*} + u_y * \frac{\partial u_x^*}{\partial y^*} \right) = \frac{\mu U_c}{\delta^2} \left(\frac{\partial^2 u_x^*}{\partial y^{*2}} + \frac{\delta^2}{H^2} \frac{\partial^2 u_x^*}{\partial x^{*2}} \right) + g_0 \beta g \Delta T T^*$$

small

Let's divide by $\frac{\mu U_c}{\delta^2}$

(210)

$$\left[\frac{\delta^2 U_c}{\Delta H} \right] \left(u_x^* \frac{\partial u_x^*}{\partial x^*} + u_y^* \frac{\partial u_x^*}{\partial y^*} \right) = \frac{\partial^2 u_x^*}{\partial y^{*2}} \\ + \frac{\delta^2}{H^2} \frac{\partial^2 u_x^*}{\partial x^{*2}} + \left[\frac{\delta^2 \rho_0 \beta g \Delta T}{\mu U_c} \right] T^* \\ \rightarrow \equiv \frac{1}{P_r} \text{ as } \delta \text{ was scaled in Eqn}$$

$$\left[\frac{\delta^2 \rho_0 \beta g \Delta T}{\mu U_c} \right] = 1$$

$$U_c = \frac{\alpha H}{\delta^2}$$

$$\therefore \frac{\delta^4 \rho_0 \beta g \Delta T}{\mu \alpha H} = 1 \quad (\text{take } \nu = \frac{\mu}{\rho_0})$$

$$\therefore \delta = \left(\frac{\alpha H}{\beta g \Delta T} \right)^{1/4}$$

This is what we need!

$$q_y = -k \frac{\partial T}{\partial y} \Big|_{y=0} = -\frac{k \Delta T}{\delta} \frac{\partial T^*}{\partial y^*} \Big|_{y^*=0}$$

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$$\text{so } q_y \sim k \Delta T \left(\frac{\beta g \Delta T}{\gamma \alpha H} \right)^{1/4}$$

$$\text{or } h = \frac{q_y}{\Delta T} = \frac{k}{H} \left(\frac{\beta g \Delta T H^3}{2 \alpha} \right)^{1/4} \times \left. \frac{-\partial T^*}{\partial y^*} \right|_{y^*=0}$$

The quantity $\frac{\beta g \Delta T H^3}{2 \alpha} \equiv \text{Rayleigh} \neq$

$$Ra = Gr Pr$$

\hookrightarrow Grashoff \neq , closely related!

$$\therefore Nu_H \sim Ra^{1/4}$$

So:

$$\frac{\partial u_x^*}{\partial x^*} + \frac{\partial u_y^*}{\partial y^*} = 0 \quad (\text{CE})$$

$$u_x^* \frac{\partial T^*}{\partial x^*} + u_y^* \frac{\partial T^*}{\partial y^*} = \frac{\partial^2 T^*}{\partial y^*} \quad (\text{E})$$

$$\frac{1}{Pr} \left(u_x^* \frac{\partial u_x^*}{\partial x^*} + u_y^* \frac{\partial u_x^*}{\partial y^*} \right) = \frac{\partial^2 u_x^*}{\partial y^{*2}} + T^*$$

$$\text{w/ BC's: } T^* \Big|_{y^*=0} = 1 \quad T^* \Big|_{y^* \rightarrow \infty} = 0$$

$$u_x^* \Big|_{y^*=0} = u_y^* \Big|_{y^*=0} = 0 \quad u_x^* \Big|_{y^* \rightarrow \infty} = 0$$

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Note that H disappeared - but we didn't specify it! That means that the profile is self-similar!

We can turn PDE's onto ODE's!

Because the x -mom eqn is non-linear, you have to solve it numerically as a set of 5 coupled 1st order ODEs.

T will also be a (weak) function of \Pr - you can't get rid of it.

Numerical solution shows that

$$Nu = \frac{h_m T}{k} = C Ra^{1/4}$$

mean over
whole plate

where $C = 0.518$ for air ($\Pr = 0.73$)

and $C = 0.670$ for $\Pr \rightarrow \infty$

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What about other shapes? The scaling & mechanism is the same!

For a sphere we have the Churchill correlation:

$$Nu = \frac{hD}{K} = 2 + \frac{0.589 Ra^{1/4}}{(1 + (0.492/\Pr)^{9/16})^{4/9}}$$

conduction

$$\text{where } Ra = \frac{\beta g \Delta T D^3}{\nu \alpha}$$

Similar results have been obtained for many shapes. The most common are tabulated in 14.6-1 of BS&L

Correlations have been developed for combinations of free & forced convection, turbulence, etc.

Remember: $h \sim \frac{k}{\delta}$ where δ is some appropriate length scale!

So far we've looked at conductive
& convective transport - now we look
at radiation

This is Energy transmission via
electromagnetic radiation, propagating
w/ velocity $C = 3 \times 10^{10}$ cm/s across
space, even in a vacuum!

Sometimes this is the largest source
of energy transport!

What is electromagnetic radiation?

When a molecule is heated it moves
into a higher energy excited state.

low temps, just rotation

higher temps, vibrations

plasma temps = ionization

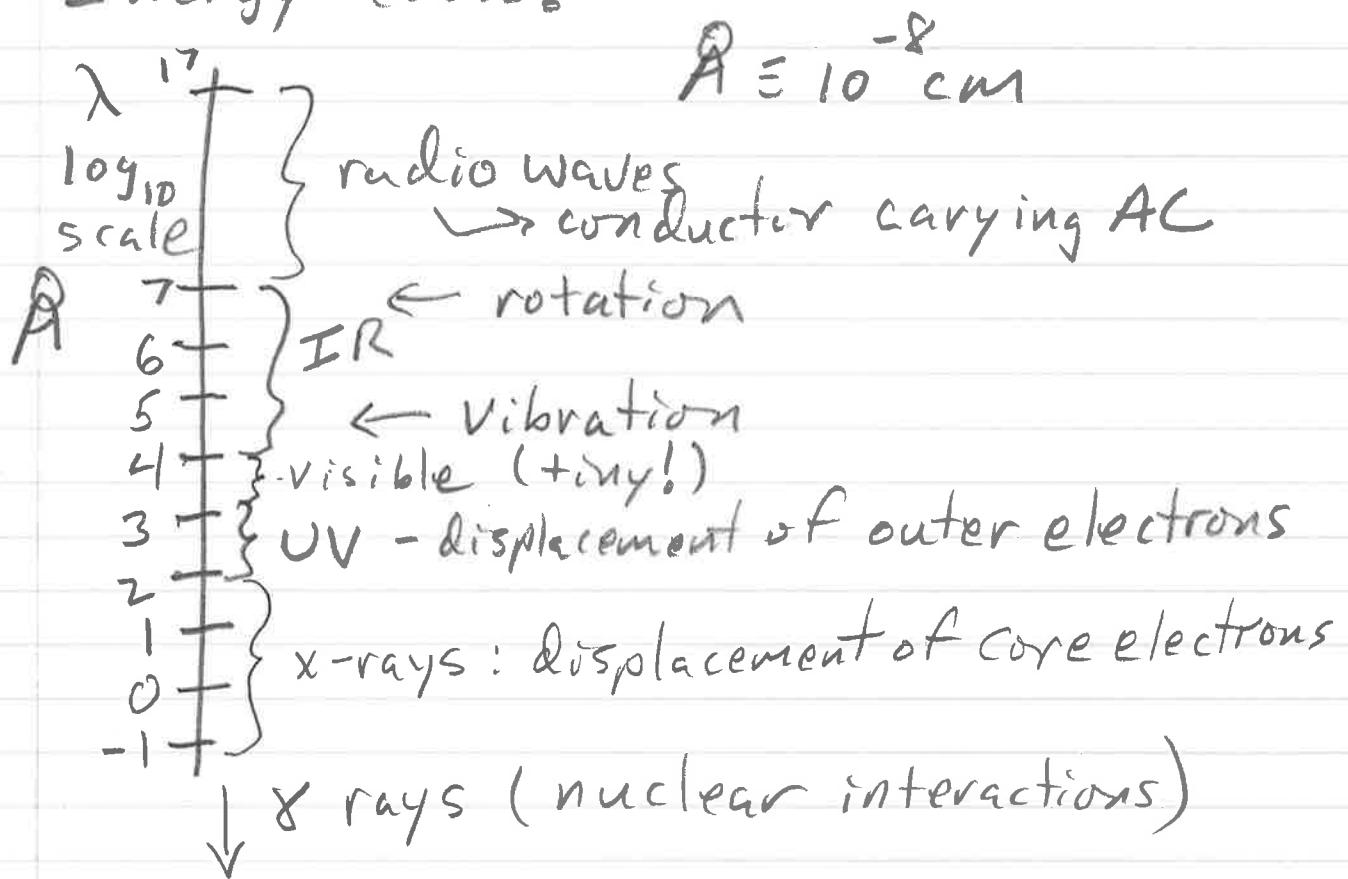
Transition is accomplished by thermal
interaction or by absorption of
radiation.

Transition to lower energy state is by thermal interaction or emission of radiation

Radiation is quantized: A transition of energy ΔE emits a photon of energy $\Delta E = h\nu \leftarrow$ frequency of radiation
 \hookrightarrow Planck's constant

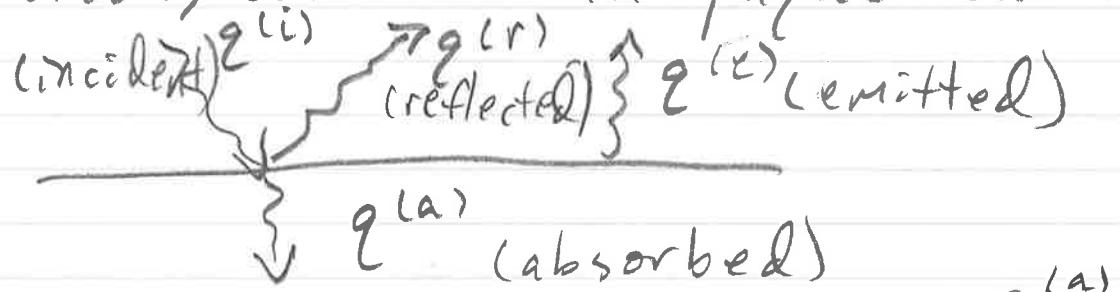
The wavelength of radiation is $\lambda = c/\nu$

There is a continuous spectrum of Energy levels!



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To examine the heat flux from radiation, consider an opaque solid:



We define absorptivity $\alpha = \frac{q^{(a)}}{q^{(i)}}$

the absorptivity is a f^n (angle)
and ω .

By definition $\alpha \leq 1$ for all ω
we have an ideal gray body:

$\alpha_\omega < 1$ but indep of ω

If $\alpha_\omega = 1$ then it is a black body
which absorbs all incident radiation.

A black body emits the largest flux
of thermal radiation at all frequencies!

(217)

We can define an emissivity ϵ :

$$\epsilon = \frac{q^{(e)}}{q_b^{(e)}} \quad \& \quad \epsilon_v = \frac{\epsilon_v^{(e)} d\lambda}{q_v^{(e)} d\lambda}$$

\nwarrow blackbody \searrow at frequency λ

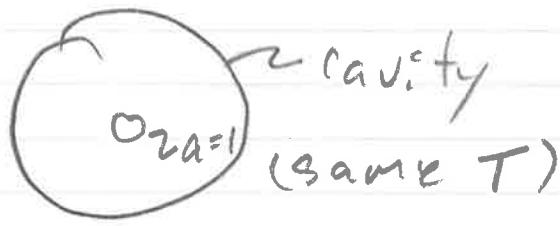
Now we prove that $\epsilon = \epsilon_b$!

Suppose we have an evacuated cavity w/ isothermal walls. At equilibrium there is no net exchange of energy between the cavity (filled w/ radiation) and the walls. Thus, the energy distribution of the cavity radiation is a function of T alone - wall composition doesn't matter!

It is also isotropic and unpolarized.

OK, now put a black body in the cavity at the same temp.

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The black body absorbs the cavity radiation: $q_b^{(a)} = q^{(cav)} \equiv q_b^{(e)}$

and has to emit the same!

i.e. Cavity radiation \equiv black body radiation.

If you put a gray body in you get

$$q^{(a)} = \alpha q_b^{(e)} = \frac{\epsilon}{\eta} q_b^{(e)}$$

because no change in T !

$$\therefore \alpha = \epsilon$$

and at all λ , $\alpha_\lambda = \epsilon_\lambda$

emissivity \equiv absorptivity

This is known as Kirchhoff's Law

Ok, how does $q_b^{(e)}$ depend on temperature?

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Let's look at cavity radiation.

Consider it as a gas made up of photons w/ energy $h\nu$ and momentum $h\nu/c$. Because it is isotropic the energy density is:

$$u^{(r)} = \frac{4}{c} g_b^{(e)} \quad (\text{energy/volume})$$

The momentum of the photons exerts a pressure on the walls

$$P^{(r)} = \frac{1}{3} u^{(r)}$$

(This pressure is what drives light sails in space!)

The internal energy of our gas is

$$U = V u^{(r)}$$

From thermo:

$$\left(\frac{\partial U}{\partial V}\right)_T = T \left(\frac{\partial P}{\partial T}\right)_V - P$$

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Thus :

$$u^{(n)} = \frac{\pi}{3} \frac{Q u^{(n)}}{Q T} - \frac{u^{(n)}}{3}$$

$$\text{or } \frac{Q \ln u^{(n)}}{Q \ln T} = 4 \quad \text{so } u^{(n)} = b T^4$$

some const.

Thus, $q_b^{(e)} = \sigma T^4$ (Stefan-Boltzmann Law)

$$\sigma = 5.67 \times 10^{-8} \frac{W}{m^2 K^4}$$

You get the same thing from quantum theory! If photons obey Bose-Einstein Statistics then you get Planck's Distribution Law:

$$q_{b\lambda}^{(e)} = \frac{2\pi c^2 h}{\lambda^5} \frac{1}{e^{ch/\lambda kT} - 1}$$

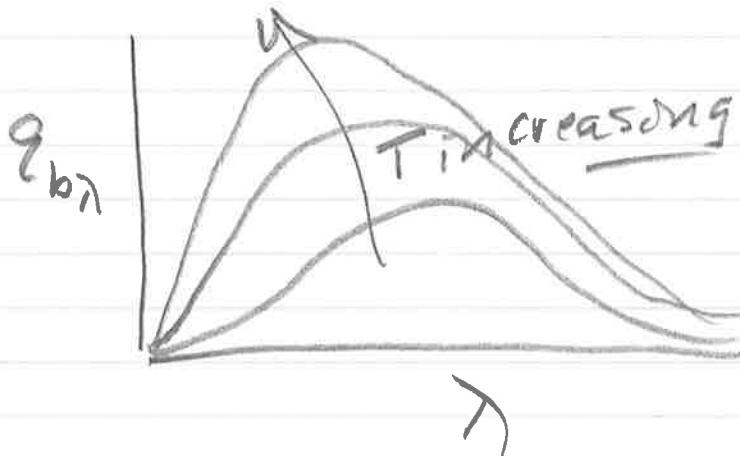
which, integrated over λ yields:

$$q_b^{(e)} = \left(\frac{2}{15} \frac{\pi^5 k^4}{c^2 h^5} \right) T^4$$

$\rightarrow \sigma$

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What does this distribution look like?

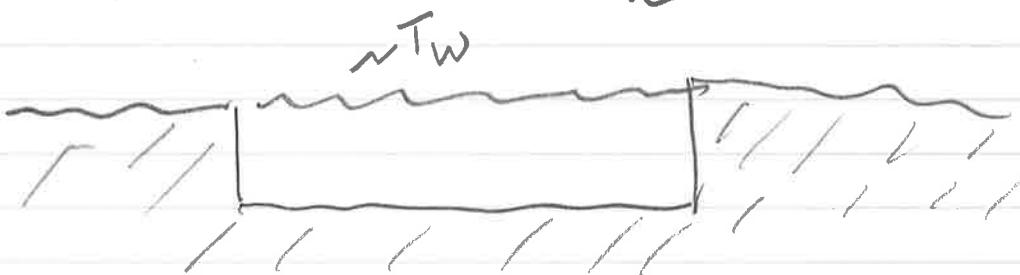


the max in q_{br} shifts to shorter wavelengths (higher λ) w/ inc. T

For the sun the max is visible (green)

OK, now let's solve a problem! (ex 16.5-3)

Suppose you put a pan of water out in the desert at night (insulating its bottom!). At what air temp. will it freeze? T_a



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For dry still air you have a balance between natural convection to the surface & thermal radiation away!

$$\therefore \mathcal{E} = h(T_a - T_w) = \epsilon \sigma T_w^4 - \epsilon \sigma T^4$$

but $T \approx 0$

clear dry night is transparent (night sky!) to thermal radiation & space is cold

Ignore back radiation!

What's h ? For a horizontal plane

$$\text{it's roughly } h = 1.3 (T_a - T_w)^{1/4}$$

where h is in $\frac{W}{m^2 K}$ and T is $^\circ C$ ($or ^\circ K$)

$$\text{so: } 1.3 (T_a - T_w)^{5/4} = \epsilon \sigma T_w^4$$

$$\text{then } T_a = T_w + \left(\frac{\epsilon \sigma T_w^4}{1.3} \right)^{4/5}$$

Now at freezing $T_w = 273^\circ K$

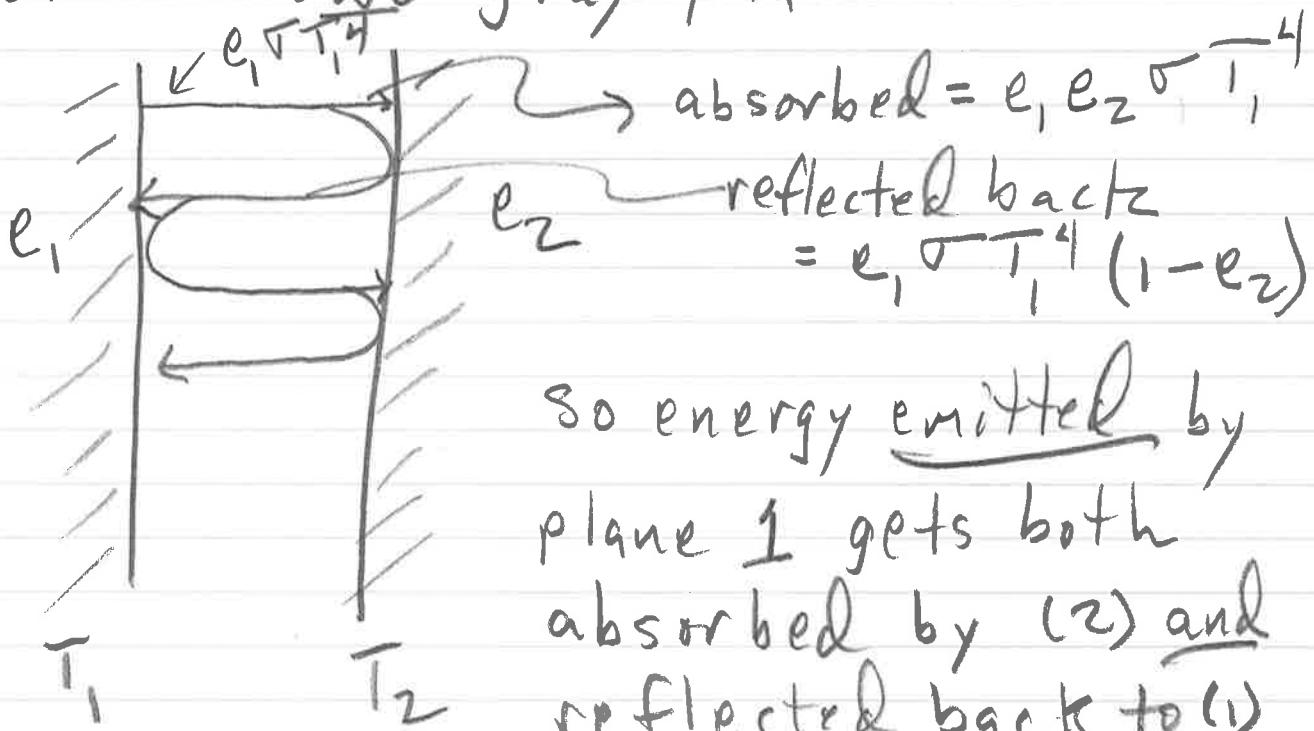
and $\epsilon \approx 0.95$ (black body at thermal λ)
close, anyway!

$$\therefore T_a \approx T_w + \left(\frac{(5.67 \times 10^{-8}) (273)^4}{0.95 / 1.3} \right)^{4/5} \overset{223}{\textcircled{223}}$$

$$= T_w + 78^\circ K \equiv 78^\circ C!$$

This is unrealistic because you would get gain through your insulation, but it does show why the desert is cold at night (and why clouds keep it warmer!)

OK, how about energy exchange between two gray planes?



Thus, the energy transmitted from (1) to (2) is:

$$\epsilon_1 \epsilon_2 \sigma T_1^4 \sum_{i=0}^{\infty} (1-\epsilon_1)^i (1-\epsilon_2)^i = \frac{\epsilon_1 \epsilon_2 \sigma T_1^4}{1 - (1-\epsilon_1)(1-\epsilon_2)} = \frac{\sigma T_1^4}{\frac{1}{\epsilon_1} + \frac{1}{\epsilon_2} - 1}$$

↳ summing series!

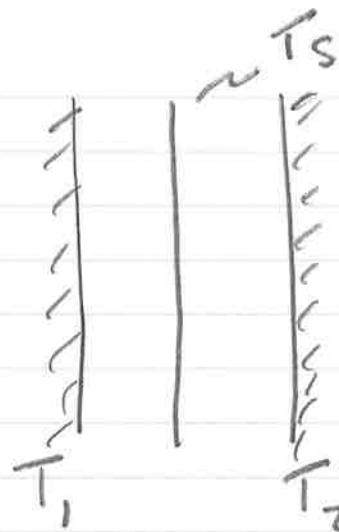
The energy from (2) to (1) is the same!

$$= \frac{\sigma T_2^4}{\frac{1}{\epsilon_1} + \frac{1}{\epsilon_2} - 1}$$

$$\therefore \text{Net flux is } \dot{E}_{12} = \frac{\sigma (T_1^4 - T_2^4)}{\left(\frac{1}{\epsilon_1} + \frac{1}{\epsilon_2} - 1\right)}$$

We can use this to see the effect of a radiation shield.

Put a thin sheet w/ low ϵ between two surfaces!



$$\text{Now } q_{1s} = \frac{\sigma (T_1^4 - T_s^4)}{\frac{1}{e_1} + \frac{1}{e_s} - 1}$$

and $q_{s2} \equiv q_{1s} = \frac{\sigma (T_s^4 - T_2^4)}{\frac{1}{e_2} + \frac{1}{e_s} - 1}$

∴ solve for T_s and get:

$$q_{12}^{(w/s)} = \frac{\sigma (T_1^4 - T_2^4)}{\left(\frac{1}{e_1} + \frac{1}{e_s} - 1\right) + \left(\frac{1}{e_2} + \frac{1}{e_s} - 1\right)}$$

If $e_1 = e_2 = e$

$$q_{12}^{(w/s)} = \frac{1}{2} \frac{\sigma (T_1^4 - T_2^4)}{\left(\frac{1}{e} + \frac{1}{e_s} - 1\right)}$$

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so the ratio of w/s & without is:

$$\frac{E_{1,2}^{(w/s)}}{Q_{1,2}} = \frac{1}{2} \frac{\left(\frac{2}{e} - 1\right)}{\left(\frac{1}{e} + \frac{1}{e_s} - 1\right)}$$

Even if $e_s = e$, we have a factor of 2 improvement, and it is still reducing energy transp. if $e_s = 1$!
 (but a lot better if $e_s \ll 1$!)

You get a further reduction w/
 multiple layers! In general, however,
you would have conduction in the
 air between that limits the effect.

To finish off, let's look at spectral effects: What happens if two sources are at dif. T and e_s is a function of ν ?

This is exactly the greenhouse effect!

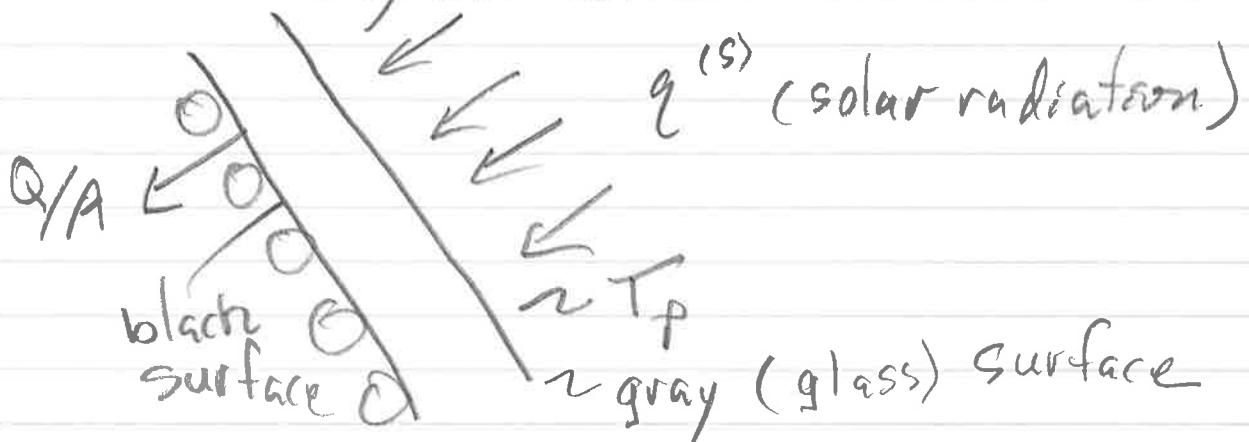
The sun is a black body at 5800°K and $\left|q_{\lambda}\right|$ is $\lambda \sim 0.5\mu\text{m}$

$>99\%$ of total E is for $\lambda < 4\mu\text{m}$

For a body at 300°K $\lambda_{\max} \approx 10\mu\text{m}$ and $>99\%$ of total E is $\lambda > 4\mu\text{m}$!

We can maximize solar gain if we cover our absorber w/ a sheet of glass! glass is transparent to short wavelengths and a black body to long!

Let's analyze our solar water heater!



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Ok, let's say we are boiling water!

$$\therefore T_c = 373^\circ K$$

we have air at $300^\circ K$ blowing over our glass plate w/ velocity of 10 mph, thus

$$h_s \approx 20 \frac{W}{m^2 K} \text{ (approx external } h)$$

We have natural convection between the collector & glass plate, take $h_i \approx 2 \frac{W}{m^2 K}$

we have an incident solar flux of

$$q^{(s)} = 1350 \frac{W}{m^2}$$

We can do an energy balance on the plate!

$$0 = e\sigma T_c^4 - 2e\sigma T_p^4 + e\sigma T_a^4$$

$$- h_s (T_p - T_a) + h_i (T_c - T_p)$$

\uparrow
losses to
atmosphere

\uparrow
gain from
collector

If we take $e=1$ then

$$T_p = 323^\circ K$$

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What is the energy gain of our collector?

$$\frac{\dot{Q}}{A} = \epsilon^{(s)} + \epsilon \sigma T_p^4 - (1-\epsilon) \sigma T_c^4 \quad (\text{reflectivity of top plate})$$

$$- h_i (T_c - T_p)$$

So if $\epsilon = 1$ then $\frac{\dot{Q}}{A} = 770 \text{ W/m}^2$
(about half incident $\epsilon^{(s)}$)

We can do better w/ low emissivity coatings! A "low ϵ " Fe₂O₃ glass is commercially available.

Ideally $t = 1$ for $0 < \lambda < 2.5 \mu\text{m}$

and $\epsilon = \alpha = 0.25$ for $\lambda > 2.5 \mu\text{m}$
 $(t=0)$

Plugging this in yields $T_p = 312^\circ\text{K}$

and $\dot{Q}/A = 1090 \text{ W/m}^2$

If $\epsilon = 0$ (perfect) then $T_p = 307^\circ\text{K}$

and $\dot{Q}/A = 1220 \text{ W/m}^2$!

Now let's look at Mass Transport

This is very closely related to energy transport, and most problems are identical w/ identical solutions!

There are differences, and we'll focus on these!

Key differences:

Fick's law: diffusive mass transfer is due to gradients in either mass fraction (liquids) or mole fraction (gases). Diffusion can lead to convection since mass is moving!

This is primarily important in gases.

In liquids the diffusivity is very small rel. to α & D . Thus it matters only on small length scales.

Otherwise it's dominated by the fluid motion! 231

Ok, let's define things! We need parallel definitions for mass & molar basis:

<u>Mass</u>	<u>Molar</u>
MASS conc.: ρ_i	molar conc.: C_i
$\rho_i = \frac{\text{mass of species } i \text{ in}}{\text{Volume } V}$	$C_i = \frac{\text{moles of species } i \text{ in}}{\text{Volume } V}$
connection: $C_i = \frac{\rho_i}{M_i \times \text{mol wt.}}$	
mass fraction w_i	mole fraction x_i
$w_i = \frac{\text{mass of } (i) \text{ in } V}{\text{total mass in } V}$	$x_i = \frac{\text{moles of } (i) \text{ in } V}{\text{total moles in } V}$
$= \frac{\rho_i}{\sum \rho_i} = \frac{\rho_i}{\rho} \quad \xrightarrow{\text{total density}}$	$= \frac{C_i}{\sum C_i} = \frac{C_i}{C} \quad \xrightarrow{\text{molar density}}$

For an ideal gas C is fixed by the ideal gas law (moles occupy same space)

Now for velocities

Let \tilde{u}_i be the velocity of species i in a mixture!

We can define two average velocities:

Mass

mass avg. vel. \tilde{u} :

$$\tilde{u} \equiv \frac{\sum \bar{s}_i \tilde{u}_i}{\sum \bar{s}_i}$$

$$= \sum w_i \tilde{u}_i$$

\tilde{u} : total mass flux in mixture!

Molar

molar avg. vel. \tilde{u}^+

$$\tilde{u}^+ = \frac{\sum c_i \tilde{u}_i}{\sum c_i} \equiv \sum x_i \tilde{u}_i$$

\tilde{u}^+ : total molar flux in a mixture!

↑
used in conservation
of momentum!

Diffusion velocity is the difference between species velocity & avg velocity!

Mass	Molar
$\tilde{u}_i - \bar{u} \equiv \text{vel. of}$ <u>(i) relative to avg!</u>	$u_i - \bar{u}^+ \equiv \text{molar diffusive}$ velocity

We can also define fluxes

Mass	Molar
$\tilde{n}_i \equiv \rho_i \tilde{u}_i$ mass flux of (i)	$\tilde{N}_i \equiv c_i u_i^+$ molar flux of (i)

And the relative fluxes

Mass	Molar
$\tilde{j}_i = \rho_i (\tilde{u}_i - \bar{u})$	$\tilde{J}_i = c_i (u_i^+ - \bar{u}^+)$
where	$\sum \tilde{j}_i = \sum \rho_i \tilde{u}_i - \rho \bar{u}$ <u>= 0</u>
$\sum \tilde{j}_i = \sum \rho_i \tilde{u}_i - \rho \bar{u}$ <u>= 0</u>	$\sum \tilde{J}_i = \sum c_i u_i^+ - c \bar{u}^+$ <u>= 0</u>
$\text{so } \tilde{n}_i = \rho_i \bar{u} + \tilde{j}_i$	$\tilde{N}_i = c_i \bar{u}^+ + \tilde{J}_i$

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Now we relate the relative flux to concentration gradients via Fick's Law!

For a binary system (A & B)

$$\dot{j}_A = -s D_{AB} \nabla w_A$$

or $\dot{J}_A = -c D_{AB} \nabla x_A$

This yields the total flux

Mass: $\dot{n}_A = \dot{n}_A + \dot{n}_B$ (binary!)

$$\therefore \dot{n}_A = s_A \dot{u} + \dot{j}_A$$

$$= w_A (\dot{n}_A + \dot{n}_B) - s D_{AB} \nabla w_A$$

Molar:

$$\dot{N}_A = x_A (\dot{N}_A + \dot{N}_B) - c D_{AB} \nabla x_A$$

\uparrow
this is why diffusion of A
leads to convection unless $x_A \ll 1$

OK, what is D_{AB} ?

First, $D_{AB} = D_{BA}$

but it may be composition dependent!

What is D_{AB} in a gas? It is similar to both α & ν since transport is via the same mechanism!

For a low density gas

$$D_{AB} \sim T^{3/2} \bar{\rho}^{-1} \quad \text{and is a very weak function of } x_A, x_B$$

We have the analogy to $Pr = \frac{\nu}{\alpha} :$

$$\text{Schmidt } \cancel{\times} Sc = \frac{\nu}{D_{AB}}$$

This is O(1) for gases!

$$\text{Sometimes people use the Lewis } \cancel{\times} Le = \frac{\alpha}{D_{AB}} = \frac{Sc}{Pr}$$

This is also O(1) for gases.

BS&L gives empirical correlations for D_{AB}

Ok, now for liquids.

D_{AB} is very composition dependent but usually one species is dilute!

This suggests we use a hydrodynamic approach! The Nernst-Einstein eq'n:

$$D_{AB} = \frac{kT}{\eta} \frac{u_A}{F_A} \quad \left. \begin{array}{l} \text{mobility of} \\ \text{molecule A in} \\ \text{fluid!} \end{array} \right\}$$

thermal energy
of molecule

k = Boltzmann's constant!

Suppose we have a colloidal particle
(a really really small sphere...)

We have Stokes Law!

$$F_A = 6\pi \eta \frac{\downarrow \text{viscosity}}{\uparrow \text{radius}} u_A$$

This yields the Stokes-Einstein Eq.

$$\eta_{AB} = \frac{KT}{6\pi\mu_B a}$$

$a \leftarrow$ radius of "A"
viscosity of "B"

Usually this is used for particles 1 μm diam.
or smaller.

It also works for large macromolecules
(e.g., polymers, coiled DNA, proteins) in
solution where "a" is radius of
gyration

For small molecules you get slip at the
surface. The 6π factor for a solid
sphere becomes 4π for a bubble!

For a liquid you estimate a from
the molecules/volume \tilde{N}/\tilde{V}

If you have a cubic lattice

$$2a \approx \left(\frac{\nabla}{N}\right)^{1/3}$$

so for self-diffusion

$$D_{AA} = \frac{1}{2\pi} \frac{kT}{m_A} \left(\frac{N}{\nabla_A}\right)^{1/3}$$

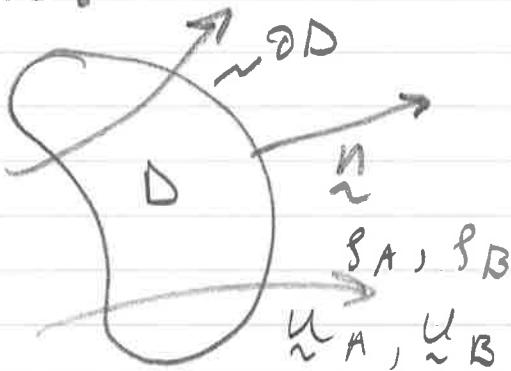
which is good for non-polar liquids.

What about solids? This is much smaller
and is highly material dependent!

Where it matters: Diffusion of gases
through membranes! It's the basis
of solid membrane separation techniques,
and much of the work some of
your classmates are doing right now!

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OK, we need to develop conservation equations!



What is a conservation eqn for species A?

$$\left\{ \text{accum of } A \right\}_{\text{in } D} + \left\{ A \text{ traveling } \underline{\text{out}} \right\}_{\text{through } \partial D} = \left\{ \text{source} \right\}_{\text{of } A}$$

$$\therefore \int_D \frac{\partial s_A}{\partial t} dV + \int_{\partial D} s_A \underbrace{u_A \cdot n}_{\parallel n_A} dA = \int_D r_A dV$$

↑
rate of
prod. of A

$$\therefore \frac{\partial s_A}{\partial t} = - \nabla \cdot \underline{n}_A + r_A$$

Similarly,

$$\frac{\partial s_B}{\partial t} = - \nabla \cdot \underline{n}_B + r_B$$

(240)

We can add these up!

$$\frac{\partial (\rho_A + \rho_B)}{\partial t} = -\nabla \cdot (\underline{n}_A + \underline{n}_B) + (r_A + r_B)$$

Now on a mass basis $r_A = -r_B$!

$$\text{likewise } \underline{n}_A + \underline{n}_B = \rho \underline{u}$$

$$\text{and } \rho = \rho_A + \rho_B$$

$$\therefore \text{we get the C.E. : } \frac{\partial \rho}{\partial t} = -\nabla \cdot (\rho \underline{u})$$

$$\begin{aligned} \text{Now recall } \underline{n}_A &= \rho_A \underline{u} + \dot{\underline{j}}_A \\ &= \omega_A \rho \underline{u} - \rho D_{AB} \nabla \omega_A \end{aligned}$$

$$\therefore \frac{\partial \rho_A}{\partial t} + \nabla \cdot (\rho_A \underline{u}) = \nabla \cdot (\rho D_{AB} \nabla \omega_A) + r_A$$

If ρ & D_{AB} are constant, $\nabla \cdot \underline{u} = 0$

and:

$$\underbrace{\frac{\partial \rho_A}{\partial t}}_{\text{accrued by A}} + \underbrace{\underline{u} \cdot \nabla \rho_A}_{\text{conv. of A}} = \underbrace{D_{AB} \nabla^2 \rho_A}_{\text{diff. of A}} + \underbrace{r_A}_{\text{prod. of A}}$$

(241)

On a molar basis we get, similarly,

$$\frac{\partial c_A}{\partial t} + \nabla \cdot \underline{N}_A = R_A$$

and

$$\frac{\partial c_B}{\partial t} + \nabla \cdot \underline{N}_B = R_B$$

$$W/ \frac{\partial c}{\partial t} + \nabla \cdot (c \underline{u}^+) = \underbrace{R_A + R_B}_{\text{not necessarily zero!}}$$

(say $A \rightarrow 2B$!)

This yields:

$$\frac{\partial c_A}{\partial t} + \nabla \cdot (c_A \underline{u}^+) = \nabla \cdot (c \delta_{AB} \nabla x_A) + R_A$$

or, if c is constant (gases)

$$\frac{\partial c_A}{\partial t} + \underline{u}^+ \cdot \nabla c_A = \delta_{AB} \nabla^2 c_A + (x_B R_A - x_A R_B)$$

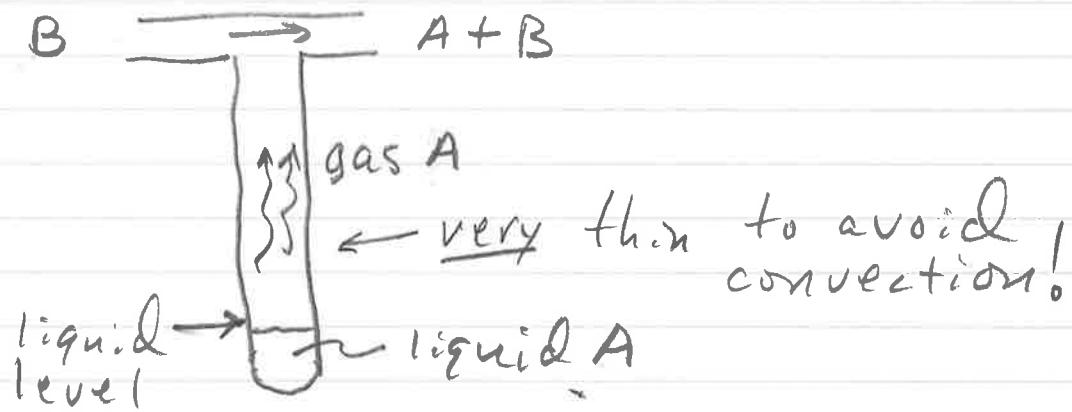
The last term arises because for constant c ,

$$\nabla \cdot \underline{u}^+ = R_A + R_B$$

Note: if $R_B = -R_A$, $x_B R_A - x_A R_B = R_A$!

Now we use this to solve mass transfer problems!

Classic example: the Stefan Tube



Developed in 1874 to measure gas phase diffusivities

Key idea: at $z=0$, the evaporating liquid is at equilibrium w/ molar concentration x_A . It diffuses out the tube & is swept away by gas B. As it evaporates the liquid level drops very slowly! You would measure this change and use it to calculate D_{AB} !

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We have the equation for \tilde{N}_A :

$$\tilde{N}_A = X_A (\tilde{N}_A + \tilde{N}_B) - c \Delta_{AB} \nabla \tilde{x}_A$$

$$\frac{\partial C_A}{\partial z} + \nabla \cdot \tilde{N}_A = R_A$$

w/ similar eq'n for B.

We only need to worry about flux in z-direction. We have no rxn ($R_A = 0$).

We assume pseudo-steady state!

The molar conc. in the liquid is 10^3 higher than the gas, so this is good!

This yields:

$$\frac{\partial N_{Az}}{\partial z} = 0 \quad ; \quad \frac{\partial N_{Bz}}{\partial z} = 0$$

$$\therefore N_{Az} = \text{cst} ; N_{Bz} = \text{cst} !$$

We further assume B doesn't dissolve in liquid A!

$$\therefore N_{Bz} \Big|_{z=0} = 0 \text{ so } N_{Bz} = 0 \text{ everywhere!}$$

$$\text{So : } N_{Az} = x_A (N_{Az} + \cancel{N_{Bz}}) - c h_{AB} \frac{\partial x_A}{\partial z}$$

↓
0

$$\text{and } N_{Az} = N_{A_0} \text{ (constant)}$$

$$\text{Thus } -c h_{AB} \frac{\partial x_A}{\partial z} = (1 - x_A) N_{A_0}$$

$$\text{with B.C.'s } x_A \Big|_{z=0} = x_{A_0}, x_A \Big|_{z=h} = x_{A_1} = 0$$

(usually take $x_{A_1} = 0$ for "clean" B)

Let's render dimensionless

$$x_A^* = \frac{x_A}{x_{A_0}} \quad z^* = \frac{z}{h} \quad N_{A_0}^* = \frac{N_{A_0}}{N_{A_C}}$$

$$\therefore -c h_{AB} \frac{x_{A_0}}{h} \frac{\partial x_A^*}{\partial z^*} = (1 - x_{A_0} x_A^*) N_{A_0}^* N_{A_C}$$

Divide out :

$$-\left[\frac{c h_{AB} x_{A_0}}{h N_{A_C}} \right] \frac{\partial x_A^*}{\partial z^*} = (1 - x_{A_0} x_A^*) N_{A_0}^*$$

$$\therefore N_{A_C} = \frac{c h_{AB} x_{A_0}}{h}$$

(245)

This is the characteristic magnitude of the molar flux

$$\text{So: } \frac{\partial x_A^*}{\partial z^*} = - (1 - x_{A_0}) x_A^* N_{A_0}$$

$$x_A^* \Big|_{z^*=0} = 1 \quad x_A^* \Big|_{z^*=1} = 0$$

Let's look at the dilute limit $x_{A_0} \ll 1$

In this case,

$$\frac{\partial x_A^*}{\partial z^*} \approx -N_{A_0}$$

$$x_A^* = -N_{A_0} z^* + C_1$$

$$\text{but } x_A^* \Big|_{z^*=0} = 1 \quad \therefore C_1 = 1$$

and since $x_A^* \Big|_{z^*=1} = 0$, $N_{A_0} = 1$!

$$\text{So } x_A^* = 1 - z^*$$

which is identical to ss cond. in a slab!

In this limit:

$$N_{A_2} = N_{A_c} = \frac{c D_{AB} x_{A_0}}{h}$$

so if you measure N_{A_2} by looking at the liquid level and know x_{A_0} , you get D_{AB} !

OK, what if x_{A_0} isn't small??

We have:

$$\frac{\partial x_A^*}{\partial z^*} = - (1 - x_{A_0} x_A^*) N_{A_0}^*$$

Divide:

$$\frac{1}{1 - x_{A_0} x_A^*} \frac{\partial x_A^*}{\partial z^*} = - N_{A_0}^*$$

$$\frac{1}{x_{A_0}} \frac{\partial \ln(1 - x_{A_0} x_A^*)}{\partial z^*} = N_{A_0}^*$$

$$\therefore \ln(1 - x_{A_0} x_A^*) = x_{A_0} N_{A_0}^* z^* + C_1$$

$$x_A^* \Big|_{z^*=0} = 1$$

$$\therefore \ln(1 - x_{A_0}) = C_1$$

$$\text{so } \ln \left(\frac{1 - x_{A_0} x_A^*}{1 - x_{A_0}} \right) = x_{A_0} N_{A_0}^* z^*$$

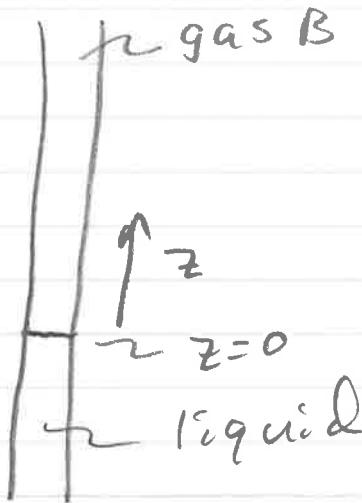
but at $z^* = 1$ $x_A^* = 0$

$$\therefore \ln \left(\frac{1}{1 - x_{A_0}} \right) = x_{A_0} N_{A_0}^*$$

$$\text{so } N_{A_0}^* = - \frac{\ln(1 - x_{A_0})}{x_{A_0}} \geq 1$$

and the flux is increased by this factor due to the convection arising from diffusion!

OK, what if we look at the transient problem?



We have a long tube filled w/ gas B & dip

it into liquid A so that the liquid level is kept at $z = 0$

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Again,

$$\frac{\partial C_A}{\partial t} + \frac{\partial N_A z}{\partial z} = 0 ; \quad \frac{\partial C_B}{\partial t} + \frac{\partial N_B z}{\partial z} = 0$$

Let's add these!

$$\frac{\partial(C_A + C_B)}{\partial t} + \frac{\partial}{\partial z}(N_A z + N_B z) = 0$$

$\frac{\partial C}{\partial t} = 0$ because C is constant for our gas! $\checkmark N_B z|_{z=0} = 0$

$$\therefore N_A z + N_B z = N_A \neq f^u(z)!$$

but both $N_A z$ & $N_B z$ will be $f^u(z, t)$ - just the sum is only a $f^u(t)$

$$\text{so } N_A z = x_A (N_A z + N_B z) - c k_{AB} \frac{\partial x_A}{\partial z}$$

$$\text{At } z=0 \quad N_B z = 0, \quad N_A z = N_{A_0} \quad (f^u(t))$$

$$\therefore N_{A_0} = x_{A_0} N_{A_0} - c k_{AB} \frac{\partial x_A}{\partial z} \Big|_{z=0}$$

$$\text{so } N_{A_0} = \frac{-c k_{AB}}{1 - x_{A_0}} \frac{\partial x_A}{\partial z} \Big|_{z=0}$$

$$\therefore N_{AZ} = x_A \left(-\frac{c D_{AB}}{1-x_{A_0}} \right) \frac{\partial x_A}{\partial z} \Big|_{z=0} - c D_{AB} \frac{\partial x_A}{\partial z}$$

(249)

extra term due to convection

$$so \frac{\partial C_A}{\partial t} = c \frac{\partial x_A}{\partial t} = - \frac{\partial N_{AZ}}{\partial z}$$

$$\therefore \frac{\partial x_A}{\partial t} = \underbrace{D_{AB} \frac{\partial^2 x_A}{\partial z^2}}_{\text{diffn}} + \underbrace{\frac{D_{AB}}{1-x_{A_0}} \frac{\partial x_A}{\partial z}}_{\text{convection from diffusion}} \Big|_{z=0} \frac{\partial x_A}{\partial z}$$

accum diffn convection from diffusion

$$BC's \text{ are } x_A \Big|_{z=0} = x_{A_0}, x_A \Big|_{t=0} = 0, x_A \Big|_{z \rightarrow \infty} = 0$$

$$\text{Let's scale: } x_A^* = \frac{x_A}{x_{A_0}} \quad (\text{from BC})$$

$$t^* = \frac{t}{t_c}, \quad z^* = \frac{z}{z_c}$$

$$\therefore \frac{x_{A_0}}{t_c} \frac{\partial x_A^*}{\partial t^*} = \frac{D_{AB} x_{A_0}}{z_c^2} \frac{\partial^2 x_A^*}{\partial z^{*2}}$$

$$+ \frac{D_{AB} x_{A_0}}{z_c^2} \frac{x_{A_0}}{1-x_{A_0}} \frac{\partial x_A^*}{\partial z^*} \Big|_{z^*=0} \frac{\partial x_A^*}{\partial z^*}$$

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Divide out:

$$\left[\frac{z_c^2}{D_{AB} t_c} \right] \frac{\partial x_A^*}{\partial t^*} = \frac{\partial x_A^*}{\partial z^{*2}} + \left. \frac{x_{A_0}}{1-x_{A_0}} \frac{\partial x_A^*}{\partial z^*} \right|_{z^*=0} \frac{\partial x_A^*}{\partial z^*}$$

"

$$\therefore \frac{z_c}{(D_{AB} t_c)^{1/2}} = 1 \quad \text{or } z_c = (D_{AB} t_c)^{1/2}$$

$$\text{B.C.'s } x_A^* \Big|_{z^*=0} = 1 \quad x_A^* \Big|_{t^*=0} = x_A^* \Big|_{z^* \rightarrow \infty} = 0$$

Note that t_c disappeared - but we never specified it! That means that our problem is self-similar!

\therefore from scaling (or affine stretching!)

$$x_A^* = f(\tilde{z}) ; \quad \tilde{z} = \frac{z^*}{t^{*1/2}}$$

Getting the transformed ODE isn't too bad:

$$\frac{\partial x_A^*}{\partial z^*} = t^{*1/2} f' \quad \frac{\partial^2 x_A^*}{\partial z^{*2}} = t^{*-1} f''$$

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$$\frac{\partial x_A^*}{\partial t^*} = -\frac{1}{2} \frac{3}{t^*} f'$$

$$\therefore -\frac{1}{2} \frac{3}{t^*} f' = \frac{1}{t^*} f'' + \frac{x_{A_0}}{1-x_{A_0}} f'(0) f' \frac{1}{t^*}$$

$$\begin{aligned} \text{so } f'' &= -\frac{1}{2} 3 f' - \frac{x_{A_0}}{1-x_{A_0}} f'(0) f' \\ &= -\left(\frac{1}{2} 3 + \frac{x_{A_0}}{1-x_{A_0}} f'(0)\right) f' \end{aligned}$$

$$f(0) = 1, \quad f(\infty) = 0$$

It's probably easier to solve numerically,
but the analytic solution is:

$$f = \frac{1 - \operatorname{erf}\left(\frac{1}{2} 3 + \frac{x_{A_0}}{1-x_{A_0}} f'(0)\right)}{1 - \operatorname{erf}\left(\frac{x_{A_0}}{1-x_{A_0}} f'(0)\right)}$$

$$\text{where } f'(0) = \frac{e^{-\left(\frac{x_{A_0}}{1-x_{A_0}} f'(0)\right)}}{1 - \operatorname{erf}\left(\frac{x_{A_0}}{1-x_{A_0}} f'(0)\right)}$$

which is an implicit expression for $f'(0)$

(252)

This is useful for measuring D_{AB} for volatile materials. Note that if $x_{A_0} \ll 1$ (dilute), then we get

$$\frac{\partial x_A}{\partial t} = D_{AB} \frac{\partial^2 x_A}{\partial z^2}$$

and (from heat transfer problems!)

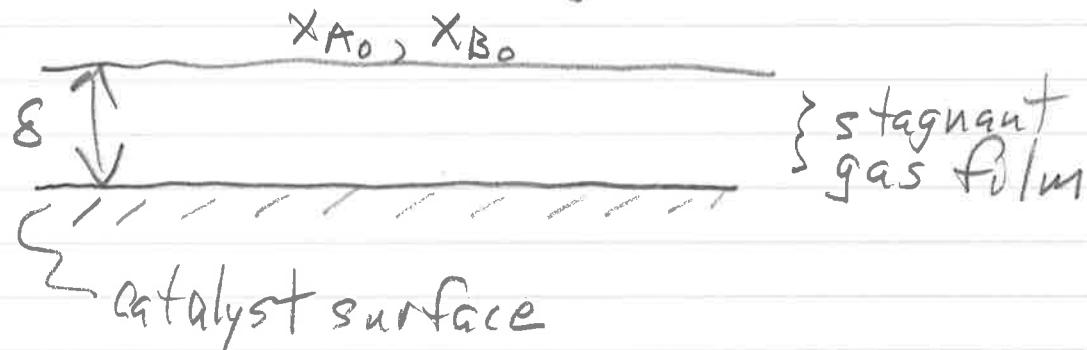
$$\frac{x_A}{x_{A_0}} = 1 - \operatorname{erf}\left(\frac{1}{2}z\right)$$

(253)

A key difference between mass & energy transfer is the possibility of chemical rxn: turning one species into another! This leads to all sorts of possibilities!

If a rxn is heterogeneous (e.g. on a catalyst surface) then it appears in the BC's. If it is homogeneous (e.g., occurs per volume in a fluid) then it is a source or sink in the DE.

Let's look at heterogeneous rxn's first!



Let's look at case where $2A \rightarrow B$ (dimerization rxn) in the gas phase

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So 2 molecules of A diffuse to surface & form one molecule of B.

This yields a net convection towards the catalyst!

We have balances:

$$\left. \begin{array}{l} \frac{\partial C_A}{\partial t} + \frac{\partial N_{A2}}{\partial z} = R_A \\ 0 \end{array} \right| \quad \left. \begin{array}{l} \frac{\partial C_B}{\partial t} + \frac{\partial N_{B2}}{\partial z} = R_B \\ SS \end{array} \right|$$

O !!

(at surface,
not in bulk)

$$So \quad N_{A2} = cst = N_{A2} \Big|_{z=0}$$

$$N_{B2} = cst = N_{B2} \Big|_{z=0}$$

$$\text{From stoichiometry } N_{A2} = -2N_{B2}$$

$$\therefore N_{A2} + N_{B2} = -N_{B2} = \frac{1}{2}N_{A2}$$

$$\text{and } N_{A2} = x_A (N_{A2} + N_{B2}) - c \alpha_{AB} \frac{\partial x_A}{\partial z}$$

(255)

$$\text{so: } N_{AZ} = \text{cst} = -\frac{c D_{AB}}{1 - \frac{x_A}{2}} \frac{\partial x_A}{\partial z}$$

Solving:

$$N_{AZ} = +2c D_{AB} \frac{2 \ln(1 - \frac{x_A}{2})}{\partial z}$$

$$\therefore \frac{z}{2c D_{AB}} N_{AZ} = \ln(1 - \frac{x_A}{2}) + C_1$$

At $z = \delta$ $x_A = x_{A_0}$ (conc. at film edge)

$$\therefore \frac{\delta}{2c D_{AB}} N_{AZ} = \ln(1 - \frac{x_{A_0}}{2}) + C_1$$

$$\text{so } \frac{z - \delta}{2c D_{AB}} N_{AZ} = \ln\left(\frac{1 - \frac{x_A}{2}}{1 - \frac{x_{A_0}}{2}}\right)$$

To finish, we need the rxn rate at the surface!

If we have instantaneous rxn, then

$$x_A \Big|_{z=0} = 0$$

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Thus:

$$\frac{0-s}{2c\alpha_{AB}} N_{AZ} = \ln \left(\frac{1}{1-x_{A0}/2} \right)$$

$$\text{or } N_{AZ} = - \frac{2c\alpha_{AB}}{s} \ln \left(\frac{1}{1-x_{A0}/2} \right)$$

If $x_{A0}/2 \ll 1$ then we get

$$N_{AZ} \approx - \frac{2c\alpha_{AB}}{s} \frac{x_{A0}}{2} = - \frac{ca}{s} \alpha_{AB}$$

This is equivalent to a simple shear flow ($\gamma_w = \frac{U}{s} \alpha$)

or ht cond. in a slab ($\dot{q} = -k \frac{\Delta T}{s}$)

More often, we have a limited rxn rate! Suppose it is 1st order:

$$N_{AZ} \Big|_{z=0} = -k_1 c_A \Big|_{z=0} = -k_1 c x_A \Big|_{z=0}$$

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$$\text{so } \frac{-\delta}{2C\kappa_{AB}} N_{A2} = \ln \left(\frac{1 - \frac{x_A}{2}|_{z=0}}{1 - \frac{x_{A0}}{2}} \right)$$

$$= \frac{\kappa_1 \delta}{2 \kappa_{AB}} x_A|_{z=0}$$

which yields a transcendental eq'n for $x_A|_{z=0}$
 Going the other way, $x_A|_{z=0} = \frac{-N_{A2}}{\kappa_1 C}$

$$\therefore \frac{-\delta N_{A2}}{2C\kappa_{AB}} = \ln \left(\frac{1 + \frac{1}{2} \frac{N_{A2}}{\kappa_1 C}}{1 - \frac{x_{A0}}{2}} \right)$$

Note: $N_{A2} < 0$ as flux is towards surface

If κ_1 is large then $x_A|_{z=0}$ is small
 and expanding the log term yields:

$$N_{A2} \propto \frac{-2C\kappa_{AB}/\delta}{1 + \frac{\kappa_{AB}}{\kappa_1 \delta}} \ln \left(\frac{1}{1 - \frac{x_{A0}}{2}} \right)$$

The ratio $\frac{\kappa_1 \delta}{\kappa_{AB}}$ is known as the

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second Damkohler # $D_a^{\frac{II}{z=0}}$

This is the ratio of rxn rate / difⁿ rate
and is important in diffusion limited reactions!

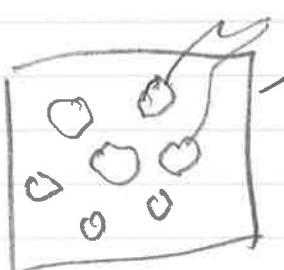
For 2nd order reactions ($\text{NAZ} = -k_2 \text{CA}_1^2$)

we would get equivalent expressions (just a bit messier!)

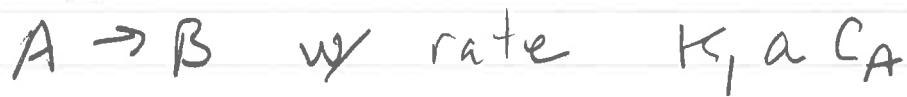
Although heterogeneous catalysis occurs at surfaces, a catalyst pellet is usually modeled as an effective porous medium/homogeneous rxn!

The idea is that you have a volume which has some surface per volume

$$a : \frac{\text{effective surface area}}{\text{Volume}} \equiv a$$



Suppose we have a 1st order rxn



Then this is a homogeneous 1st order rxn over both solid & pores!

If $A \rightarrow B$ then we have equi-molar counter diffusion: diffusion does not lead to convection!

$$\text{Let } N_{A_p} = -D_A \frac{\partial C_A}{\partial r}$$

↳ "effective" diffusivity

$$\text{In general, } D_A \approx \frac{\epsilon D_{AB}}{\xrightarrow{\text{void}} \leftarrow \text{tortuosity}}$$

fraction

but it may be quite different! If the pores are smaller than the mean free path, you get knudsen diffusion instead of D_{AB} !

(26G)

In a spherical geometry (usual model for a catalyst pellet) :

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 N_A r \right) = R_A = - k_1 a C_A$$

or, w/ Fick's law :

$$D_A \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial C_A}{\partial r} \right) = k_1 a C_A$$

We have BC at $r=R$: $C_A \Big|_{r=R} = C_{A_0}$

Let's render dimensionless :

$$r^* = r/R, \quad C_A^* = C_A/C_{A_0}$$

$$\therefore \frac{1}{r^{*2}} \frac{\partial}{\partial r^*} \left(r^{*2} \frac{\partial C_A^*}{\partial r^*} \right) = \frac{k_1 a R^2}{D_A} C_A^*$$

Let's let $\frac{k_1 a R^2}{D_A} \equiv \phi^2$

or $\phi = \left(\frac{k_1 a}{D_A} \right)^{1/2} R \equiv \text{Thiele Modulus}$

(26)

Ernest Thiele was a famous ChtE
for Standard Oil, later an ND prof.
for 10 years.

$$\text{So: } \frac{1}{r^{*2}} \frac{\partial}{\partial r^*} \left(r^{*2} \frac{\partial c_A^*}{\partial r^*} \right) = \phi^2 c_A^*$$

$$c_A^* \Big|_{r^*=0} = \text{finite}, \quad c_A^* \Big|_{r^*=1} = 1$$

We can solve this via the substitution

$$c_A^* = \frac{f(r^*)}{r^*}$$

$$\therefore \frac{\partial c_A^*}{\partial r^*} = \frac{1}{r^*} f' - \frac{1}{r^{*2}} f$$

$$r^{*2} \frac{\partial c_A^*}{\partial r^*} = r^* f' - f$$

$$\frac{\partial}{\partial r^*} \left(r^{*2} \frac{\partial c_A^*}{\partial r^*} \right) = f' + r^* f'' - f'$$

So plugging in yields:

$$f'' = \phi^2 f \quad ; \quad f(0) = 0, \quad f(1) = 1$$

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The solution is just:

$$f = A \sinh \phi r^* + B \cosh \phi r^*$$

$$\text{and w/ } f(1) = 1 \therefore f = \frac{\sinh \phi r^*}{\sinh \phi}$$

$$\therefore C_A^* = \frac{1}{r^*} \frac{\sinh \phi r^*}{\sinh \phi}$$

We need $N_{A_r} \Big|_{r=R}$ as this is the overall rxn rate ($\propto 4\pi R^2$)

$$\begin{aligned} \therefore W_{A_r} &= 4\pi R^2 N_A \Big|_{r=R} = -4\pi R^2 \alpha_A \frac{\partial C_A}{\partial r} \Big|_{r=R} \\ &= -4\pi R \alpha_A C_{A_0} \frac{\partial C_A^*}{\partial r^*} \Big|_{r^*=1} \\ &= 4\pi R \alpha_A C_{A_0} (1 - \phi \coth \phi) \end{aligned}$$

Now if all the surface was exposed to the catalyst (no $\Delta \phi$ = limitation)

$$\text{we would get } W_{A_r} = \left(\frac{4}{3}\pi R^3\right) \alpha (-k_1, C_{A_0})$$

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The ratio of these is Thiele's effectiveness factor $\gamma = \frac{W_{AR}}{W_{AR_0}}$

$$\gamma = \frac{3}{\phi^2} (\phi \coth \phi - 1)$$

For slow reaction $\phi \ll 1$

$$\text{Then } \coth \phi \approx \frac{1}{\phi} \left(1 + \frac{1}{3} \phi^2 - \frac{1}{45} \phi^4 + \dots \right)$$

$$\therefore \gamma = 1 - \frac{1}{15} \phi^2$$

For $\phi \gg 1$ (fast rxn)

$$\gamma \approx \frac{3}{\phi}$$

for a general shape

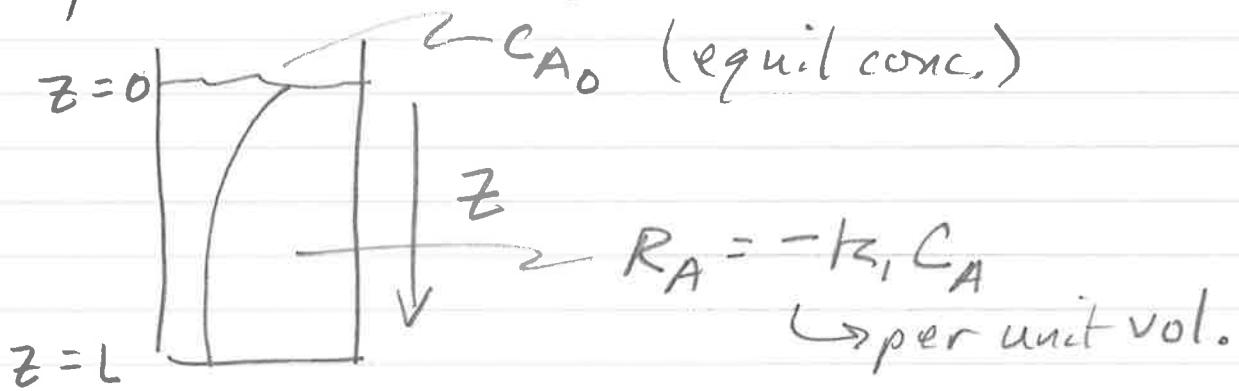
$$|W_{AR}| \approx V_p a k_1 C_{A_0} \gamma_A$$

$$\text{where } \gamma_A = \frac{1}{3 \Lambda^2} (3 \Lambda \coth 3 \Lambda - 1)$$

$$\text{and } \Lambda = \left(\frac{k_1 a}{W_A} \right) \left(\frac{V_p}{S_p} \right)^{\frac{1}{3}} \stackrel{\text{for sphere}}{=} \frac{R}{3}$$

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A classic problem of homogeneous reaction in liquids is gas absorption. Say you are absorbing a gas like CO_2 . To increase the capacity of the liquid for the gas you have a compound which reacts with it!



(large excess of absorbing compound, so 1st order rxn is reasonable)

$$\text{So: } \frac{\partial C_A}{\partial t} + \nabla \cdot N_A = R_A = -k_1 C_A$$

$$\text{At steady state } \frac{\partial N_{Az}}{\partial z} = -k_1 C_A$$

We have:

$$N_{Az} = \frac{x_A}{A} (N_{Az} + N_{Bz}) - c_{AB} \frac{\partial x_A}{\partial z}$$

Small \rightarrow stagnant

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In general, convection from diffusion in liquids is negligible!

$$\therefore N_{Az} = - D_{AB} \frac{\partial C_A}{\partial z} \quad (\text{take } C = \text{cst})$$

so $D_{AB} \frac{Q^2 C_A}{Qz^2} = K_1 C_A$

$$C_A \Big|_{z=0} = C_{A0} \quad D_{AB} \frac{\partial C_A}{\partial z} \Big|_{z=0} = 0$$

\hookrightarrow $z=L$
no flux BC.

Let's scale

$$C_A^* = \frac{C_A}{C_{A0}} \quad z^* = \frac{z}{L}$$

$$\therefore \frac{Q^2 C_A^*}{Qz^{*2}} = \left[\frac{K_1 L^2}{D_{AB}} \right] C_A^*$$

$\parallel b_1^2$

So we get a dimensionless parameter:

$$b_1 = \frac{L}{\left(\frac{D_{AB}}{K_1} \right)^{1/2}} \equiv \text{Hatta \#}$$

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This is the ratio of the film depth L to diffusion length during rxn time $\frac{1}{k_1}$ (k_1 has units $\frac{1}{T}$)

$$\therefore \frac{\partial^2 C_A^*}{\partial z^{*2}} = b_1^2 C_A^* ; \quad C_A^* \Big|_{z^*=0} = 1, \quad \frac{\partial C_A^*}{\partial z^*} \Big|_{z^*=1} = 0$$

Solution is hyperbolics!

$$C_A^* = A \sinh b_1 z^* + B \cosh b_1 z^*$$

$$C_A^* \Big|_{z^*=0} = B = 1$$

$$\frac{\partial C_A^*}{\partial z^*} \Big|_{z^*=1} = 0 = A b_1 \cosh b_1 + b_1 \sinh b_1$$

$$\therefore A = -\tanh b_1$$

$$\text{so } C_A^* = \cosh b_1 z^* - \tanh b_1 \sinh b_1 z^*$$

We are interested in the total rxn rate.

This is just the flux at $z^*=0$!

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$$N_{Az} \Big|_{z=0} = - \left. \mathcal{Q}_{AB} \frac{\partial C_A}{\partial z} \right|_{z=0} = - \left. \frac{\mathcal{Q}_{AB} C_{A_0}}{L} \frac{\partial C_A^*}{\partial z^*} \right|_{z^*=0}$$

Now:

$$\left. \frac{\partial C_A^*}{\partial z^*} \right|_{z^*=0} = \left[b, \sinh b, z^* - b, \tanh b, \cosh b, z^* \right]_{z^*=0}$$

$$= -b, \tanh b,$$

$$\text{so } N_{Az} \Big|_{z=0} = \frac{\mathcal{Q}_{AB} C_{A_0}}{L} b, \tanh b,$$

There are two interesting limits!

If $b_i \ll 1$ then $\tanh b_i \approx b_i$,

$$\text{and } N_{Az} \Big|_{z=0} \approx \frac{\mathcal{Q}_{AB} C_{A_0}}{L} b_i^2 = C_{A_0} k_1 L$$

This corresponds to the whole film being at $C_A = C_{A_0}$ — no diff limitation!

The other limit is more interesting:

$$b_i \gg 1$$

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Here $\tanh b_1 \approx 1$, so:

$$N_{A2} \Big|_{z=0} = \frac{D_{AB} C_{A0}}{L} \left(\frac{k_1}{D_{AB}} \right)^{1/2} L$$

$$= C_{A0} (D_{AB} k_1)^{1/2}$$

so the reaction rate is independent of L !

This makes sense: the rxn is fast enough that all A is consumed over distance of $O\left(\frac{(D_{AB})^{1/2}}{k_1}\right)$ and it doesn't make it to the bottom!

The transient problem is also relevant:

$$\frac{\partial C_A}{\partial t} = D_{AB} \frac{\partial^2 C_A}{\partial z^2} - k_1 C_A$$

Let's scale: $C_A^* = C_A / C_{A0}$, $z^* = \frac{z}{L}$,

$$t^* = t / t_c :$$

$$\frac{C_{A0}}{t_c} \frac{\partial C_A^*}{\partial t^*} = \frac{D_{AB} C_{A0}}{L^2} \frac{\partial^2 C_A^*}{\partial z^{*2}} - k_1 C_{A0} C_A^*$$

So:

$$\left(\frac{L^2}{D_{AB}t_c}\right) \frac{\partial C_A^*}{\partial t^*} = \frac{\partial^2 C_A^*}{\partial z^{*2}} - b_1^2 C_A^*$$

||
so $t_c = \frac{L^2}{D_{AB}}$

Note that we could have taken $t_c = \frac{1}{K_1}$, would get a b_1^2 mult. the transient term in this case.

OK, we have:

$$\frac{\partial C_A^*}{\partial t^*} = \frac{\partial^2 C_A^*}{\partial z^{*2}} - b_1^2 C_A^*$$

$$C_A^* \Big|_{t^*=0} = 0 \quad C_A^* \Big|_{z^*=0} = 1 \quad \frac{\partial C_A^*}{\partial z^*} \Big|_{z^*=1} = 0$$

This problem is linear so we will use separation of variables again!

First we subtract off the asymp.
solution

$$C_{A\infty}^* = \cosh b_1 z^* - \tanh b_1 \sinh b_1 z^*$$

So we let :

$$C_A^* = C_{A\infty}^* + C_{Ad}^*$$

$$\therefore \frac{\partial C_{Ad}^*}{\partial t^*} = \frac{\partial^2 C_{Ad}^*}{\partial z^{*2}} - b_1^2 C_{Ad}^*$$

$$C_{Ad}^* \Big|_{z^*=0} = -C_{A\infty}^*; \quad C_{Ad}^* \Big|_{z^*=0} = 0, \quad \frac{\partial C_{Ad}^*}{\partial z^*} \Big|_{z^*=1} = 0$$

This 1st order decay has a very curious solution :

$$C_A^* = e^{-b_1^2 t^*} f(z^*, t^*)$$

$$\text{so } \frac{\partial C_A^*}{\partial t^*} = -b_1^2 C_A^* + e^{-b_1^2 t^*} \frac{\partial f}{\partial t^*}$$

$$\text{and } \frac{\partial^2 C_A^*}{\partial z^{*2}} = \frac{\partial f}{\partial z^{*2}} e^{-b_1^2 t^*}$$

$$\therefore \frac{\partial f}{\partial t^*} = \frac{\partial^2 f}{\partial z^{*2}}; \quad f \Big|_{z^*=0} = 0, \quad \frac{\partial f}{\partial z^*} \Big|_{z^*=1} = 0$$

$$f \Big|_{z^*=0} = -C_{A\infty}^*$$

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Why does this work? We have
homogeneous BC's - molecules of A are
just leaving away (or not) at the
boundaries. The reaction is also 1^{st}
order - each molecule's fate doesn't depend
on the local concentration. Thus, it's
much like radioactive decay: the
concentration is decreasing exponentially
in time!

The solution for f is exactly what
we've done before:

$$f = G(t^*) F(z^*)$$

$$\frac{G'}{G} = \frac{F''}{F} = -\sigma^2$$

$$G = e^{-\sigma^2 t^*}, \quad F = A \sin \sigma z^* + B \cos \sigma z^*$$

$$F(0) = 0 \therefore B = 0$$

$$F'(1) = 0 \therefore \sigma_n = (n - \frac{1}{2})\pi$$

So:

$$c_{Ad}^* = e^{-b_1^2 t^*} \sum_{n=1}^{\infty} A_n e^{-\sigma_n^2 t^*} \sin \sigma_n z^*$$

where $\sigma_n = (n - \frac{1}{2})\pi$

and $A_n = \frac{\int_0^1 -c_{Ad}^* \sin \sigma_n z^* dz^*}{\frac{1}{2} \int_0^1 \sin^2 \sigma_n z^* dz^*}$

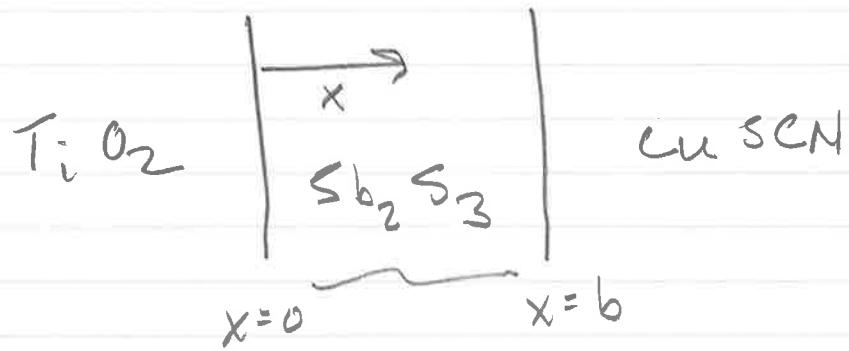
So the solution approaches S.S. as

$$-(b_1^2 + \sigma_1^2)t^*$$

e

A bit faster than just the lead eigenvalue alone!

A nearly identical problem was encountered in the Kamat lab in their study of Sb_2S_3 solar cells. Such a thin film solar cell looks like:



Illumination of the Antimony sulfide layer produces "holes" which diffuse to the Copper thiocyanate layer. They have some resistance crossing (e.g., a mass transfer coef.) and also decay over a time scale τ . You want to collect the holes, so you want a high diffusivity, a high mass transfer rate & a low recombination rate. The Kamat group could measure the decay rate independently but needed to tease apart diffusional and interfacial transfer limitations.

The hole concentration in the Sb_2S_3 layer (the total could be measured) was governed by:

$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial x^2} - \frac{C}{\tau} \leftarrow \begin{array}{l} \text{decay time} \\ (\text{homogeneous}) \\ - \propto x \\ \text{recombination} \end{array}$$

$$C|_{t=0} = C_0 e^{-\frac{x}{\lambda}} \leftarrow \text{absorbance decay length scale}$$

$$\left. \frac{\partial C}{\partial x} \right|_{x=0} = 0 \quad (\text{nothing goes through } TiO_2 \text{ layer})$$

$$-D \left. \frac{\partial C}{\partial x} \right|_{x=b} = k_1 C \Big|_{x=b}$$

\uparrow
mass transfer coef.
at Cu SCN interface

Let's render dimensionless!

$$x^* = \frac{x}{b} \quad C^* = \frac{C}{C_0} \quad t^* = \frac{Dt}{b^2}$$

$$\therefore \frac{\partial C^*}{\partial t^*} = \frac{\partial^2 C^*}{\partial x^{*2}} - \lambda C^* \rightarrow \text{Hatta} \times \text{squared}$$

$$C^*|_{t^*=0} = e^{-\frac{x^*}{\lambda b}} \rightarrow \text{dimensionless absorbance profile}$$

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$$\text{BC's: } \left. \frac{\partial c^*}{\partial x^*} \right|_{x^*=0} = 0 \quad \left. \frac{\partial c^*}{\partial x^*} \right|_{x^*=1} = \left[\frac{\kappa b}{D} \right] c^* \Big|_{x^*=1}$$

where $\frac{\kappa b}{D} \equiv \text{Bi}_t$ for mass transfer!

The problem already has homogeneous BC's, so we remove exponential decay and use sep. of variables!

$$c^* = e^{-\lambda t^*} f(x^*, t^*)$$

$$\therefore \frac{\partial f}{\partial t^*} = \frac{\partial^2 f}{\partial x^{*2}} \quad f \Big|_{t^*=0} = e^{-\alpha b x^*}$$

$$\left. \frac{\partial f}{\partial x^*} \right|_{x^*=0} = 0 \quad \left. \frac{\partial f}{\partial x^*} \right|_{x^*=1} = -\text{Bi} f \Big|_{x^*=1}$$

$$\text{Let } f = G(t^*) F(x^*)$$

$$\therefore \frac{G'}{G} = \frac{F''}{F} = -\tau^2$$

$$G = e^{-\tau^2 t^*} \quad F'' + \tau^2 F = 0$$

$$F'(0) = 0 \quad F'(1) = -\text{Bi} F(1)$$

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Solutions are just sines & cos!

$$F = A \sin \sigma x^* + B \cos \sigma x^*$$

$$F'(0) = 0 \quad \therefore A = 0$$

$$F'(1) = -B \sigma \sin \sigma = -B \cdot B_i \cos \sigma$$

$$\text{so} \quad \sigma \tan \sigma = B_i$$

determines eigenvalues!

$$\text{so } C^* = e^{-\lambda t^*} \sum_{n=1}^{\infty} B_n e^{-\sigma_n^2 t^*} \cos \sigma_n x^*$$

$$\text{where } B_n = \frac{\int_0^1 e^{-\lambda t^*} \cos \sigma_n x^* dx^*}{\int_0^1 \cos^2 \sigma_n x^* dx^*}$$

We need the total hole amount:

$$\int_0^1 C^* dx^* = e^{-\lambda t^*} \sum_{n=1}^{\infty} \frac{B_n}{\sigma_n} e^{-\sigma_n^2 t^*} \sin \sigma_n$$

Jeff Christians used measurements of this decay rate to get both K & D by fitting different thicknesses of Sb_2S_3

Rate limiting interfacial hole transfer in Sb_2S_3 solid-state solar cells†

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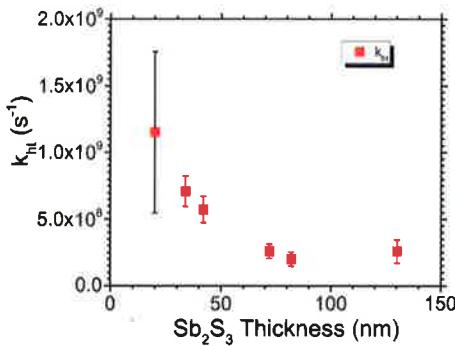


Fig. 5 Trace showing how the estimated hole transfer rate calculated decreases with increasing Sb_2S_3 film thickness. Error bars represent the error in k_{ht} as calculated from the error of the fitting parameters as shown in Table 1.

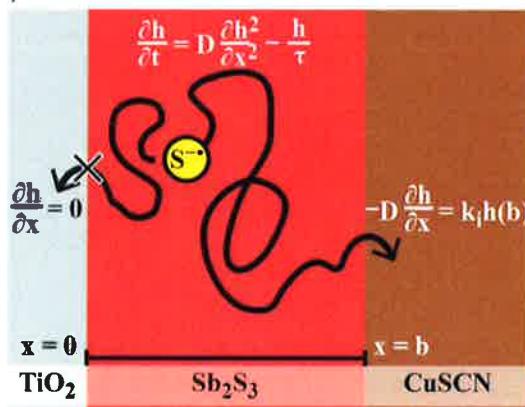


Fig. 6 (A) Scheme showing the TiO_2 – Sb_2S_3 – $CuSCN$ system modeled using Fick's second law of diffusion with appropriate boundary conditions.

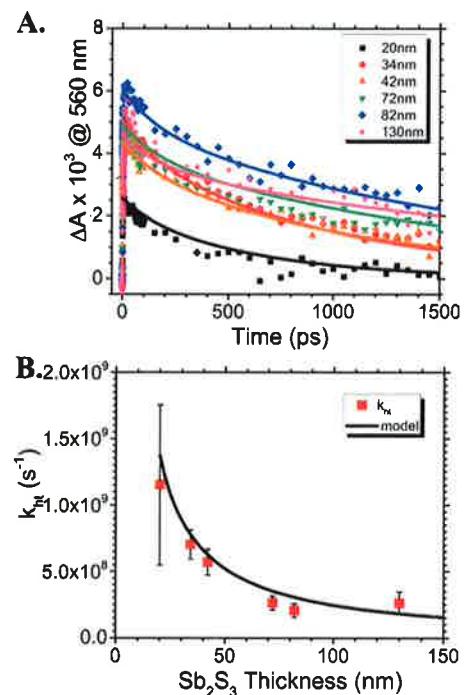


Fig. 7 (A) Plots of transient absorption decay model fit to experimental time resolved transient kinetic data at 560 nm. (B) Plot of modeled & experimentally calculated hole transfer rate vs. Sb_2S_3 film thickness.

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A key problem in processing is the absorption or desorption of a gas from a falling liquid film:



We assume that diffusion doesn't affect the velocity profile of the liquid.

What's the velocity profile? Assume a laminar falling film

Let's solve this!

For constant properties:

$$\nabla \cdot \underline{u} = 0$$

$$\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla P + \mu \nabla^2 \underline{u} + \rho g$$

First look at C.E.:

$$\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = 0$$

No variation in y (into paper)

Assume that u_x is small (due to diffusion!)

$$\therefore \frac{\partial u_z}{\partial z} = 0 \quad (\text{uni-directional flow})$$

z -mom:

$$\begin{aligned} & \rho \left(\frac{\partial u_z}{\partial t} + u_x \frac{\partial u_z}{\partial x} + u_y \frac{\partial u_z}{\partial y} + u_z \frac{\partial u_z}{\partial z} \right) \\ &= -\frac{\partial P}{\partial z} + \mu \left(\frac{\partial^2 u_z}{\partial x^2} + \frac{\partial^2 u_z}{\partial y^2} + \frac{\partial^2 u_z}{\partial z^2} \right) + \rho g_z \end{aligned}$$

$$\text{ss: } \frac{\partial u_z}{\partial t} = 0$$

only $u_z \neq 0$ but $\frac{\partial u_z}{\partial z} = 0$ from CE

so all convective terms vanish!

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$$\frac{\partial u_z}{\partial z} = 0 \quad \text{so} \quad \frac{\partial^2 u_z}{\partial z^2} = 0 \text{ too!}$$

No variation in y direction!

$$\therefore 0 = -\frac{\partial P}{\partial z} + \mu \frac{\partial^2 u_z}{\partial x^2} + \gamma g_z$$

Now recall that it is the deviation from hydrostatics that drives the flow!

In this case $\frac{\partial P}{\partial z} = 0$ and $g_z = g$

$$\therefore 0 = \mu \frac{\partial^2 u_z}{\partial x^2} + \gamma g$$

we have B.C.'s $\mu \frac{\partial u_z}{\partial x} \Big|_{x=0} = 0$ (no shear stress at interface)

and $u_z \Big|_{x=\delta} = 0$ (no slope at wall)

so:

$$u_z^* = \frac{u_z}{U_c} \quad x^* = \frac{x}{\delta}$$

$$\therefore \mu \frac{U_c}{\delta^2} \frac{\partial^2 u_z^*}{\partial x^{*2}} = -\gamma g$$

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$$\therefore \frac{\partial^2 u_z^*}{\partial x^{*2}} = - \left[\frac{89d^2}{\mu U_c} \right]$$

$$\text{so } U_c = \frac{89d^2}{\mu}$$

$$\text{and } u_z^* = -\frac{1}{2}x^{*2} + Ax^* + B$$

$$\frac{\partial u_z^*}{\partial x^*} \Big|_{x^*=0} = 0 \quad \therefore A = 0$$

$$u_z^* \Big|_{x^*=1} = 0 \quad \therefore -\frac{1}{2} + 0 + B = 0$$

$$\text{so } B = +\frac{1}{2}$$

$$\text{and } u_z^* = -\frac{1}{2}x^{*2} + \frac{1}{2} = \frac{1}{2}(1-x^{*2})$$

$$\text{w/ } u_z^* \Big|_{x^*=0} = \frac{1}{2} \quad (\text{velocity at interface})$$

We also have the average velocity \bar{u}_z^*

$$\bar{u}_z^* = \int_0^1 u_z^* dx^* = \frac{1}{2} \left(1 - \frac{1}{3} \right) = \frac{1}{3}$$

which is also useful.

OK, now for mass transfer!

We have:

$$\cancel{\frac{\partial C_A}{\partial t}} + \vec{v} \cdot \vec{n}_A = R_A$$

\vec{v} No rxn

$$\therefore \frac{\partial N_{Ax}}{\partial x} + \frac{\partial N_{Az}}{\partial z} = D$$

$$\text{Now } N_{Az} = x_A (N_{Az} + N_{Bz}) - c D_{AB} \frac{\partial x_A}{\partial z}$$

$$= c_A (x_A u_{Az} + x_B u_{Bz}) - c D_{AB} \frac{\partial x_A}{\partial z}$$

we take $u_{Az} = u_{Bz} = u_z$! (D_f is much too small to affect velocity in z direction!)

IF $c \approx \text{cst}$ then:

$$N_{Az} = c_A u_z - c D_{AB} \frac{\partial c_A}{\partial z}$$

Also small!

$$\text{Now } N_{Ax} = x_A (N_{Ax} + N_{Bx}) - c D_{AB} \frac{\partial x_A}{\partial x}$$

$$= c_A (x_A u_{Ax} + x_B u_{Bx}) - c D_{AB} \frac{\partial c_A}{\partial x}$$

If there is no net flow in x-dir,
and $x_A \ll 1$ then

$$N_{AX} \approx - D_{AB} \frac{\partial C_A}{\partial x}$$

so since $\nabla \cdot \vec{N}_A = 0$ we get

$$\frac{\partial}{\partial z} (u_z C_A) - \frac{\partial}{\partial x} \left(D_{AB} \frac{\partial C_A}{\partial x} \right) = 0$$

if D_{AB} is constant and since $\frac{\partial u_z}{\partial z} = 0$

we get

$$u_z \frac{\partial C_A}{\partial z} = D_{AB} \frac{\partial^2 C_A}{\partial x^2}$$

This is just a specific example of the convective diffusion equation usually used for liquids:

$$\frac{\partial C_A}{\partial t} + \vec{u} \cdot \nabla C_A = D_{AB} \nabla^2 C_A + R_A$$

Note the similarity w/ energy:

$$\frac{\partial T}{\partial t} + \vec{u} \cdot \nabla T = \alpha \nabla^2 T + \frac{S}{\rho C_p}$$

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These equations are identical and w/ the same B.C.'s have identical solutions!

Ok, for this problem we have

$$\frac{3}{2} \bar{U} \left(1 - \frac{x^2}{Q^2}\right) \frac{\partial C_A}{\partial z} = D_{AB} \frac{\partial^2 C_A}{\partial x^2}$$

where $\bar{U} = \frac{1}{3} U_c = \frac{1}{3} \frac{g g d^2}{\mu}$

$$C_A \Big|_{x=0} = C_{A_0} \quad \frac{\partial C_A}{\partial x} \Big|_{x=Q} = 0 \quad (\text{impermeable})$$

Let's scale

$$x^* = \frac{x}{Q}, \quad z^* = \frac{z}{z_c}, \quad C_A^* = \frac{C_{A_0} - C_A}{C_{A_0}}$$

choose so that
 $C_A^* \rightarrow 0$ as $z^* \rightarrow p$

$$\frac{3}{2} \frac{\bar{U} C_{A_0}}{z_c} \left(1 - x^{*2}\right) \frac{\partial C_A^*}{\partial z^*} = \frac{D_{AB} C_{A_0}}{Q^2} \frac{\partial^2 C_A^*}{\partial x^{*2}}$$

Or dividing:

$$\frac{3}{2} \left(1 - x^{*2}\right) \frac{\partial C_A^*}{\partial z^*} = \left[\frac{z_c D_{AB}}{\bar{U} Q^2} \right] \frac{\partial^2 C_A^*}{\partial x^{*2}} = 1$$

So $Z_c = \frac{\bar{U} \Delta^2}{\Delta_{AB}} = \bar{U} \left(\frac{\Delta^2}{\Delta_{AB}} \right)$ 285

↑
average diff' time
velocity

and $\frac{3}{2}(1-x^{*2}) \frac{\partial C_A^*}{\partial z^*} = \frac{\partial C_A^*}{\partial x^{*2}}$

w/ BC's: $C_A^* \Big|_{x^*=0} = 0 \quad \frac{\partial C_A^*}{\partial x^*} \Big|_{x^*=1} = 0$

Solve via sep. variables:

$$C_A^* = G(z^*) F(x^*)$$

$$\therefore \frac{G'}{G} = \frac{F''}{\frac{3}{2}(1-x^{*2}) F} = -\sigma^2$$

$\rightarrow \sigma^2 z^*$

$$G = e^{\int -\sigma^2 z^* dz^*} \quad \left\{ F'' + \frac{3}{2}(1-x^{*2}) F \sigma^2 = 0 \right.$$

$$\left. \begin{array}{l} F(0) = 0 \\ F'(1) = 0 \end{array} \right.$$

SL problem w/

weight $f \triangleq \frac{3}{2}(1-x^{*2})$

$$\text{So } C_A^* = \sum_{n=1}^{\infty} A_n e^{-\sqrt{n}^2 z^*} F_n(x^*)$$

Because of wt f^n , there is no analytical solution. If $\frac{3}{2}(1-x^2)$ is replaced by 1 (e.g., avg. value) then:

$$F = A \sin \sigma x^* + B \cos \sigma x^*$$

$$F(0) = 0 \therefore B = 0$$

$$F'(1) = 0 \therefore \sigma_n = (n - \frac{1}{2})\pi$$

and

$$C_A^* \approx \sum_{n=1}^{\infty} A_n e^{-\sigma_n^2 z^*} \sin \sigma_n x^*$$

where A_n would be determined from the IC via orthogonality!

Just as in heat transfer we want to define a mass transfer coefficient!

$$N_{Ax} \Big|_{x=0} = -k_m (C_A)_{x=0} - (C_A)_{bulk}$$

$$\text{where } (C_A)_{bulk} = \frac{\int_0^d u_z C_A dx}{\int_0^d u_z dx}$$

$$\text{Now } N_A \Big|_{x=0} = -D_{AB} \frac{\partial C_A}{\partial x} \Big|_{x=0}$$

so since $C_A \Big|_{x=0} = C_{A_0}$ we get

$$\frac{k_m d}{D_{AB}} = \frac{-1}{(C_A^*)_{\text{bulk}}} \frac{\partial C_A^*}{\partial x^*} \Big|_{x^*=0}$$

If $z^* \gg 1$ we are dominated by the lead eigenvalue!

$$\therefore \frac{k_m d}{D_{AB}} \approx \frac{\sigma_1}{\int_0^1 \sin \sigma_1 x^* dx^*} = \sigma_1^2 = \frac{\pi^2}{4}$$

A similar result is obtained for the parabolic profile numerically.

The problem is that this takes a huge distance to reach the asymptote!

How far? Look at some numbers:

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Suppose we have $d = 1\text{mm}$ (very thick)
 w/ water ($\nu = \frac{m}{g} = 0.01\text{cm}^2/\text{s}$)

Now suppose we have a typical small molecule diffusing in water, $D \approx 10^{-5}\text{cm}^2/\text{s}$

$$\begin{aligned} \text{we get } z_c &= \frac{\bar{D}d^2}{D_{AB}} = \frac{1}{3} \frac{d^2}{D_{AB}} \frac{9d^2}{\nu} \\ &= \frac{1}{3} \frac{9d^4}{D_{AB}\nu} = \frac{1}{3} \frac{(980)(0.1)^4}{(10^{-5})(0.01)} = 3.3\text{ Km}!! \end{aligned}$$

For any reasonable length we don't reach the asymptote! Only the surface matters unless d was $\sim 100\mu\text{m}$ or less!
 (note that approach to ss is governed by the decay of the second eigenvalue $(\frac{3\pi}{2})^2$)
Still, we now turn to the thin boundary layer problem!

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Just as in heat transfer, we have:

$$\frac{3}{2} \bar{U} \left(1 - \frac{x^2}{d^2}\right) \frac{\partial C_A}{\partial z} = D_{AB} \frac{\partial^2 C_A}{\partial x^2}$$

We are looking for a thin layer of $O(\delta/d \ll 1)$. So:

$$x^* = \frac{x/\delta}{}, z^* = \frac{z/z_c}{}, C_A^* = \frac{C_A}{C_{A_0}}$$

$$\text{So: } \frac{3}{2} \bar{U} \left(1 - \frac{\delta^2}{d^2} x^{*2}\right) \frac{C_{A_0}}{z_c} \frac{\partial C_A^*}{\partial z^*} = D_{AB} \frac{C_{A_0}}{\delta^2} \frac{\partial^2 C_A^*}{\partial x^{*2}}$$

↓
small!

$$\therefore \left[\frac{\frac{3}{2} \bar{U} \delta^2}{D_{AB} z_c} \right] \frac{\partial C_A^*}{\partial z^*} = \frac{\partial^2 C_A^*}{\partial x^{*2}}$$

$$\therefore \delta = \left(\frac{D_{AB} z_c}{\frac{3}{2} \bar{U}} \right)^{1/2} \quad \text{- diffusion length!}$$

$$\text{BC's: } C_A^* \Big|_{x^*=0} = 1, \frac{\partial C_A^*}{\partial x^*} \Big|_{x^* \rightarrow \delta/\delta} = 0$$

$$C_A^* \Big|_{z^*=0} = 0 \quad (\text{clean at start - but really only the difference matters!})$$

This is identical to unsteady heating
of a slab (or equiv. convection prob!) (290)

We know the answer!

$$C_A^* = f(\zeta), \quad \zeta = \frac{x^*}{z^{*1/2}} \quad (\text{from scaling or stretching})$$

$$\text{So: } \frac{\partial C_A^*}{\partial x^*} = f' \frac{\partial \zeta}{\partial x^*} = \frac{1}{z^{*1/2}} f'$$

$$\frac{\partial^2 C_A^*}{\partial x^{*2}} = \frac{1}{z^*} f''$$

$$\frac{\partial C_A^*}{\partial z^*} = f' \left(-\frac{1}{2} \frac{\zeta}{z^*} \right)$$

$$\therefore f'' = -\frac{1}{2} \zeta f'$$

$$f(0) = 1, \quad f'(\infty) = 0$$

$$\text{Solving: } \frac{1}{f'} f'' = \frac{d \ln f'}{d \zeta} = -\frac{1}{2} \zeta$$

$$f' = c_1 e^{-\zeta^2/4}$$

$$f = 1 + c_1 \int_0^\zeta e^{-\zeta'^2/4} d\zeta$$

(291)

Now $f(\infty) = 0$ ($f'(\infty)$ too...)

$$\therefore C_1 = \frac{-1}{\int_0^\infty e^{-\frac{z^2}{4}} dz} = -\frac{1}{\sqrt{\pi}} = f'(0)!$$

We want to get the mass transfer coefficient:

$$N_{Ax} = -k_{m_{loc}} (C_{A0} - (C_A)_b) = -D_{AB} \left. \frac{\partial C_A}{\partial x} \right|_{x=0}$$

Now $(C_A)_b = 0$ (BL is thin)

$$\begin{aligned} \therefore k_{m_{loc}} &= -\frac{D_{AB}}{S} \left. \frac{\partial C_A}{\partial x} \right|_{x=0} \\ &= +\frac{D_{AB}}{S} \frac{1}{z^{*1/2}} \frac{1}{\sqrt{\pi}} \\ &= \frac{D_{AB}}{\left(\frac{3}{2} \bar{U} \right)^{1/2}} \frac{1}{\sqrt{\pi}} = \left(\frac{3}{2} \bar{U} D_{AB} \right)^{1/2} \frac{1}{\sqrt{\pi}} \end{aligned}$$

We want the average k_m over some height H :

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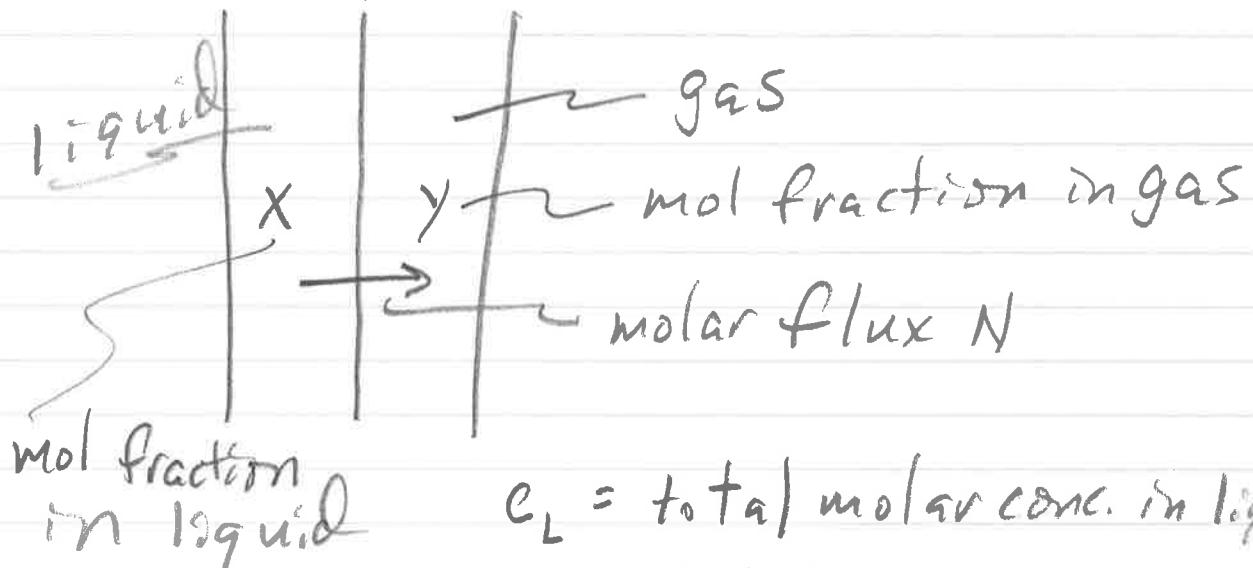
$$\bar{K}_m = \frac{1}{H} \int_0^H K_{m,loc} dz = \frac{2}{\sqrt{\pi}} \left(\frac{\frac{3}{2} \bar{O} D_{AB}}{H} \right)^{1/2}$$

In general, we would do gas-liquid contacting in a packed column.

It's filled with packing rings, saddles, lot's of shapes that give you a large surface area for mass transfer. The liquid side mass transfer coef. K_L will scale like that above, but (because the flow pattern is very complex) is given by correlation for different shapes.

In the last lecture we looked at the mass transfer coef. for a liquid film K_m (or k_L). This was for a gas A absorbing into a liquid, so there was no gas phase resistance. In general there's both (but liquid is usually larger!) and we want an overall mass transfer coef. (analogous to overall heat transfer coef!). Let's look at this:

$\{x_i, y_i\}$ interfacial values



c_L = total molar conc. in liquid

c_G = total molar conc. in gas

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Just as the heat flux is the same on both sides of an interface, so is the molar flux!

$$\text{Let } N = k_L c_L (x - x_i) = k_g c_g (y_i - y)$$

$$\therefore \frac{N}{k_L c_L} = x - x_i; \quad \frac{N}{k_g c_g} = y_i - y$$

We have the equilibrium Henry's Law equilibrium relation at the interface:

$$y_i = m x_i \quad (\text{dilute sol'n})$$

$$\therefore \frac{N}{k_g c_g m} = x_i - \frac{y}{m}$$

Adding these up yields:

$$N \left(\frac{1}{k_L c_L} + \frac{1}{m k_g c_g} \right) = x - \frac{y}{m}$$

$$\text{so } N = \frac{x - \frac{y}{m}}{\frac{1}{k_L c_L} + \frac{1}{m k_g c_g}}$$

2.95

So the molar flux depends on the difference between the bulk liquid concentration and the liquid concentration that would be in equilibrium with the gas concentration. The overall (liquid side) mass transfer coef. is obtained by adding resistances in each side, w/ gas side adjusted by Henry's law constant.

This works on a mass basis too!

In a packed tower - like a catalyst pellet - you have some area/vol a of interface.

We can define an overall liquid mass transfer coef: $k_L^0 a$

$$K_L^0 a = \frac{1}{\frac{1}{K_L a} + \frac{1}{H K_g a}}$$

$K_L^0 a$ has units $\frac{1}{\text{Time}}$

and H is the Henry's Law constant
(adjusted for gas & liquid total molar conc.)

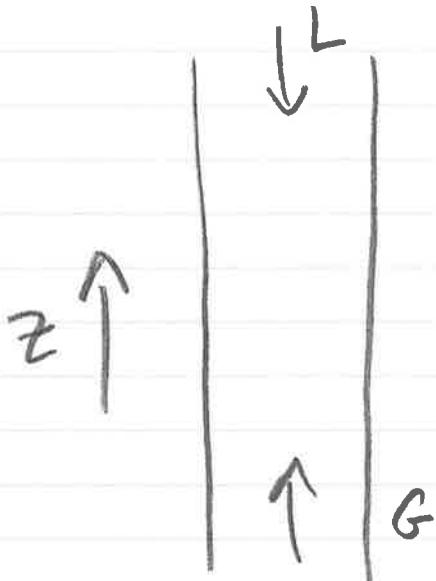
Now in general:

$$K_L^0 a = K_L a \left(\frac{1}{1 + \frac{K_L}{H K_g}} \right)$$

For many cases $\frac{H K_g}{K_L} \gg 1$ so
we are liquid phase limited. This
has the advantage that gas phase
mass transfer is less important in
tower design.

Ok, how do we use all this? Let's
look at designing a tower to strip
out a pollutant (VOC) from water:

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c_L = liquid conc. of pollutant

c_G = gas conc. of pollutant

L = superficial liquid flow rate
(Vol/Area·Time)

G = superficial gas flow

$k_L^0 a$ = overall liquid mass transfer coef (units YT)

We have the mass (or molar) balance:

$$L \frac{\partial c_L}{\partial z} = k_L^0 a (c_L - c_L^*)$$

where $c_L^* = \frac{c_G}{H}$ (conc. in eq. w/ c_G)

so just like heat exchanger:

$$\frac{L}{k_L^0 a} \frac{\partial c_L}{c_L - c_L^*} = \partial z$$

So

$$Z_T = \frac{L}{k_L^0 a} \left\{ \begin{array}{l} (C_L)_{out} + \\ \frac{\Delta C_L}{C_L - C_L^*} \\ \hline (C_L)_{in} \end{array} \right.$$

where $(C_L)_{out}$ is the conc. at the bottom and $(C_L)_{in}$ is the conc. at the top.

This is usually written as:

$$Z_T = H_{ox} N_{ox} \quad \begin{matrix} \leftarrow & \text{number of transfer} \\ \uparrow & \text{units based} \\ & \text{on liquid phase} \end{matrix}$$

ht of a transfer unit
based on liquid phase

$$\text{where } N_{ox} = \left\{ \begin{array}{l} (C_L)_{out} \\ \frac{\Delta C_L}{C_L - C_L^*} \\ \hline (C_L)_{in} \end{array} \right.$$

$$= \int_{x_{in}}^{x_{out}} \frac{\Delta x}{x - x^*} \quad \begin{matrix} \text{based on mole fractions} \\ \text{(same thing)} \end{matrix}$$

$$H_{ox} = \frac{L}{k_L^0 a} \equiv \text{ht of a transfer unit.}$$

Now we need to determine the NTUE_{N_{ox}}
We need a mass (or mole) balance:

$$(C_G - (C_G)_{in})G = (C_L - (C_L)_{out})L$$

rate mass (or moles)
are gained from
 z to bottom

rate mass (or moles)
are lost to liquid
from z to bottom

Now $C_L^* = \frac{C_G}{H}$ ← Henry's law

$$\therefore C_L^* = \frac{(C_G)_{in}G}{H} + (C_L - (C_L)_{out}) \frac{L}{H}$$

We shall take $(C_G)_{in} = 0$ (cleangas) as
it makes things a little simpler

We also define a stripping factor

$$R \equiv \frac{HG}{L}$$

This is the capacity of the gas stream
to absorb our pollutant. If $R < 1$
you can't get it all out even for an
infinite z_T !

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$$\text{So: } C_L^* = \frac{C_L - (C_L)_{\text{out}}}{R}$$

$$\therefore N_{\text{ox}} = \begin{cases} (C_L)_{\text{out}} & \frac{Q C_L}{C_L - \frac{(C_L - (C_L)_{\text{out}})}{R}} \\ (C_L)_{\text{in}} & \end{cases}$$

$$= \frac{R}{R-1} \ln \left[\frac{\frac{(C_L)_{\text{in}} / (C_L)_{\text{out}}}{R} (R-1) + 1}{R} \right]$$

if $R \neq 1$

and $\left[\frac{(C_L)_{\text{in}}}{(C_L)_{\text{out}}} \right] - 1 \leq R = 1$

So to size a tower for some desired separation (e.g., you know $(C_L)_{\text{in}} / (C_L)_{\text{out}}$), you need to know your gas & liquid flow rates and Henry's law constant to get Q and N_{ox} , then estimate $H_{\text{ox}} \equiv \frac{L}{K_L^0 a}$ to get the tower height!

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This made a number of assumptions:

- 1) Gas enters "clean" (e.g. $(C_G)_{in} = 0$) - usually good for this application.
- 2) H (or m) is constant: This requires a constant temperature in your tower.
(You also assume it's valid!)
- 3) There's no mixing in your tower (plug flow for both phases) and that it's uniform.
- 4) $K_L^0 a$ is constant.

These are actually the sorts of approx. we made for a double-pipe heat exch, but they were more robust there!

Now let's turn to correlations for $K_L a$ and $K_G a$, necessary to get $K_L^0 a$

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In the last lecture we showed that there were two limits.

If the film depth approaches equilibrium then $K_L \sim D_{AB}$ - but this almost never happens! Instead we use penetration theory

$$K_L \sim \frac{D_{AB}}{(D_{AB} t_c)^{1/2}}$$

where t_c is a contact time. For our falling film this was $\frac{1}{2}$.

There are a number of correlations based on experimental measurements. These can get pretty complicated!

A sophisticated one is the Onda correlation. Suppose we have some total area/vol. of our packing a_t . Not all of this is wetted. The wetted area a_w is given by:

$$\frac{a_w}{a_t} = 1 - \exp \left[-1.45 \left(\frac{\tau_c}{\sigma_L} \right)^{0.75} \times (Re_L)^{0.1} (Fr)^{-0.05} (We_L)^{0.2} \right]$$

The ratio σ_c/σ_L is the ratio of the packing surface tension to the liquid surface tension - basically a measure of wettability. Re_L is the liquid phase Reynolds number $(\frac{\rho_L L}{\alpha_t \mu_L})$ (recall α_t has units of length). Fr_L is the Froude ~~**~~ = $(\frac{L^2 \alpha_t}{g})$, the ratio of inertia/gravity. We_L is the Weber number = $(\frac{L^2 \rho_L}{\sigma_L \alpha_t})$ which is inertia/surface tension.

So as L increases (more liquid) the wetted area approaches the total area. The key correlation is that for k_L : we have the Sherwood number:

$$Sh = \frac{k_L}{a D_L}$$

units $\frac{\text{length}}{\text{length}}$ \rightarrow liquid side diff.

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$$\text{So: } Sh = 0.0051 \left(\frac{\mu_L a_t^3}{g_L^2 g} \right)^{-1/3} (Re_L)^{2/3} (Sc_L)^{1/2} (a_t d_p)^{0.4}$$

Where $\frac{\mu_L a_t^3}{g_L^2 g}$ = Galileo number, which
is a Reynolds number for a falling film,
 Sc_L = Schmidt $\approx = \frac{v_L}{D_L} \leftarrow \frac{\mu_L}{\rho_L}$
 d_p = nominal packing size.

so $a_t d_p$ = shape factor note neg

This would yield

$$K_L = 0.0051 \left(\frac{\mu_L g}{g_L} \right)^{1/3} Re^{2/3} Sc^{-1/2} (a_t d_p)^{0.4}$$

$$\text{so } K_L \sim D_L^{1/2}$$

For the gas phase:

$$K_G = C a_t D_G \left(\frac{G \rho_G}{a_t \mu_G} \right)^{0.7} \left(\frac{\mu_G}{\rho_G D_G} \right)^{1/3} (a_t d_p)^{-2}$$

\uparrow
 Re_G

\uparrow
 Sc_G

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The constant $c = 2.0$ if $d_p < 15\text{ mm}$
and $= 5.23$ otherwise.

The key thing to note is that $K_G \sim D_G^{2/3}$,
a different dependence than the liquid
side.

Finally, you calculate the overall
coefficient:

$$K_L^o a = K_L^o a_w = a_w \left[\frac{1}{K_L} + \frac{1}{H K_G} \right]^{-1}$$

A note on Henry's law constants: These
are given in different ways: either
a molar basis (e.g. $y = mx$) or
a volume basis, or a mass basis.

$$\text{our } H = \frac{(C_A)_{\text{gas}}}{(C_A)_{\text{liquid}}} = \frac{\text{total molar conc gas} * Y}{\text{total molar conc. liq.} * X}$$

$$= \frac{P_{\text{gas}} / M_{\text{gas}}}{P_{\text{liq}} / M_{\text{liq}}} \cdot M$$

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This gets it onto a volume basis which is necessary for calculating $R = \frac{HG}{L}$ if G and L are superficial velocities (vol/area-time) which is easier to work with. Any form works - you just have to be consistent and check!

If you ever have to design a stripper for VOCs, read through the award winning thesis of Staudinger - it's a remarkably clear discussion of the problem! It's linked into today's notes.

Nowadays industry is moving towards structured packings as they have lower resistance. A recent review (2021) of correlations for these is provided by Flagiello, et al., also linked in.

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Now that we've looked at interfacial transport, let's look at problems in convective diffusion which are functions of both space and time. A classic phenomenon in this area is Taylor (or Taylor-Aris) Dispersion. This is the mechanism which leads to peak broadening in a GC, among many examples!

If diffusion is so slow, why do you get peak broadening? It's because diffusion is so slow!!

Taylor dispersion is the combination of shear (or anything which causes different molecules of the same species to move w/ different velocities coupled with the slow interchange between

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different velocities due to slow diffusion.

This means that the Taylor dispersivity is inversely proportional to the (small) molecular diffusivity. That's why it's so big!

To understand this phenomenon, we start with a much simpler problem: transient diffusion from an initial point distribution (no shear!)

so:

$$\frac{\partial c}{\partial t} = D \frac{\partial^2 c}{\partial x^2} \quad c \Big|_{t=0} = I \delta(x)$$

$$c \Big|_{x \rightarrow \pm\infty} = 0 \quad \text{total amount of solute}$$

Solute is conserved, so $\int_{-\infty}^{\infty} c dx = I$
at all times!

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$\delta(x)$ is known as the Dirac δ function

$$\delta(x) = 0 \text{ if } x \neq 0$$

$$\int_{-\infty}^{\infty} \delta(x) dx = 1$$

(e.g., a GL peak w/ zero width)

We want to get $c(x, t)$!

Let's scale:

$$c^* = \frac{c}{c_c}, \quad x^* = \frac{x}{x_c}, \quad t^* = \frac{t}{t_c}$$

$$\text{So: } \frac{\partial c^*}{\partial t^*} = \left[\frac{\partial t_c}{x_c^2} \right] \frac{\partial^2 c^*}{\partial x^{*2}} \quad \text{so} \quad \frac{x_c}{(Dt_c)^{1/2}} = 1$$

and $\int_{-\infty}^{\infty} [c_c x_c] c^* dx^* = I$

$$\therefore \int_{-\infty}^{\infty} c^* dx^* = \left[\frac{I}{c_c x_c} \right] = 1$$

$$\text{so } c_c = \frac{I}{x_c} = \frac{I}{(Dt_c)^{1/2}}$$

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Because our problem is dimensionless and we never specified t_c , it will be self-similar! From scaling (in canonical form!):

$$c^* t^{*^{1/2}} = f(\zeta) \quad \zeta = \frac{x^*}{t^{*^{1/2}}}$$

Let's solve! $c^* = t^{*^{-1/2}} f$

$$\therefore \frac{\partial^2 c^*}{\partial x^{*2}} = t^{*^{-3/2}} f''$$

$$\begin{aligned} \frac{\partial c^*}{\partial t^*} &= -\frac{1}{2} t^{*^{-3/2}} f - \frac{1}{2} \frac{\zeta}{t^*} t^{*^{-1/2}} f' \\ &= -\frac{1}{2} t^{*^{-3/2}} (f + \zeta f') \end{aligned}$$

$$\text{so: } f'' = -\frac{1}{2} (f + \zeta f')$$

$$f \Big|_{\zeta=\pm\infty} = 0 \quad \int_{-\infty}^{\infty} f d\zeta = 1$$

The trick to solving is:
 $f + \zeta f' \equiv (\zeta f)'$

$$\therefore f'' = -\frac{1}{2} (\gamma f)'$$

so

$$f' = -\frac{1}{2} \gamma f + cst \xrightarrow{\gamma \rightarrow 0} as f|_{\gamma=+\infty} = 0$$

$$\therefore \frac{f'}{f} = \frac{Q \ln f}{Q \gamma} = -\frac{1}{2} \gamma - \frac{1}{4} \gamma^2$$

$$so \quad f = C_1 e$$

$$Now \int_{-\infty}^{\infty} f dy = 1 = C_1 \int_{-\infty}^{\infty} e^{-\frac{1}{4} \gamma^2} dy = C_1 \sqrt{4\pi}$$

$$so: \quad f = \frac{1}{\sqrt{4\pi}} e^{-\frac{1}{4} \gamma^2}$$

$$and \quad C = \frac{I}{\sqrt{4\pi \sigma t}} e^{-\frac{x^2}{4\sigma^2 t}}$$

This is exactly the Gaussian (Normal) Distribution from statistics!

The mean location of the solute molecules is:

$$\bar{x} = \frac{\int_{-\infty}^{\infty} x c(x, t) dx}{\int_{-\infty}^{\infty} c(x, t) dx}$$

This is the first moment of the distribution $= m_1$

For this problem, $m_1 = 0$ by symmetry!

We can define the second moment

$$m_2 = \frac{\int_{-\infty}^{\infty} x^2 c(x, t) dx}{\int_{-\infty}^{\infty} c(x, t) dx}$$

and the (closely related) variance:

$$\sigma^2 = \frac{\int_{-\infty}^{\infty} (x - \bar{x})^2 c(x, t) dx}{\int_{-\infty}^{\infty} c(x, t) dx}$$

$$= m_2 - m_1^2$$

For this problem:

$$m_1 = 0, m_2 = \int_{-\infty}^{\infty} \frac{x^2}{\sqrt{4\pi D t}} e^{-\frac{x^2}{4Dt}} dx$$

$$= \underline{2Dt}$$

so $\sigma^2 \equiv 2Dt$: The variance of the distribution grows linearly w/
a rate $2D$!

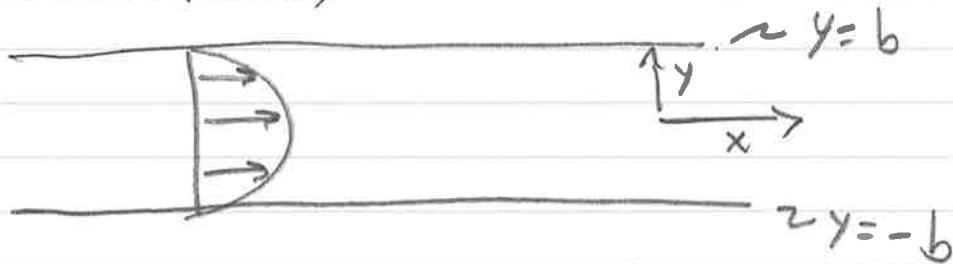
You can measure the Stokes-Einstein diffusivity of a colloidal particle by watching it move w/ Brownian motion and plotting the variance of location vs. time. The slope vs. t is just $2D$!

OK, how do we use this? If we calculate the rate of growth of the variance of our concentration distribution, in a shear flow, it's just $2L^2$ ^{Taylor} _{Dispersivity!}

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Let's look at the simpler problem:

TA Dispersion in Channel Flow (plane - Poiseuille flow):



$$u = u_x = \frac{3}{2} U \left(1 - \frac{y^2}{b^2} \right)$$

$$\text{Now } \frac{\partial c}{\partial t} + u \cdot \nabla c = D \nabla^2 c$$

$$\text{so: } \frac{\partial c}{\partial t} + u \frac{\partial c}{\partial x} = D \left(\frac{\partial^2 c}{\partial x^2} + \frac{\partial^2 c}{\partial y^2} \right)$$

$$\left. \frac{\partial c}{\partial y} \right|_{y=0} = 0 \quad (\text{sym.}) \quad \left. \frac{\partial c}{\partial y} \right|_{y=\pm b} = 0 \quad (\text{no flux})$$

$$\text{and: } \int_0^b \int_{-\infty}^{\infty} c \, dx \, dy = I \quad (\text{total amount})$$

\curvearrowright just use top half of channel (sym)

We'll leave the IC alone for a bit!

Let's scale

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$$y^* = \frac{y}{b} \quad u^* = \frac{u}{U} = \frac{3}{2} (1 - y^{*2})$$

$$x^* = \frac{x}{x_c} \quad c^* = \frac{c}{c_c} \quad t^* = \frac{t}{t_c}$$

So:

$$\frac{c_c}{t_c} \frac{\partial c^*}{\partial t^*} + \frac{U c_c}{x_c} u^* \frac{\partial c^*}{\partial x^*} = \frac{D c_c}{b^2} \frac{\partial^2 c^*}{\partial y^{*2}} + \frac{D c_c}{x_c^2} \frac{\partial^2 c^*}{\partial x^{*2}}$$

We anticipate that the key mechanisms are diffusion in the y-dir & convection in the x-dir, with diffusion in the x-dir small

$$\therefore \left[\frac{b^2}{D t_c} \right] \frac{\partial c^*}{\partial t^*} + \left[\frac{U b^2}{D x_c} \right] u^* \frac{\partial c^*}{\partial x^*} = \frac{\partial^2 c^*}{\partial y^{*2}} + \frac{b^2}{x_c^2} \frac{\partial^2 c^*}{\partial x^{*2}}$$

" "

| |

$$\text{so } t_c = \frac{b^2}{D} \quad (\text{diff}^n \text{ time!})$$

$$x_c = U \frac{b^2}{D} \equiv U t_c \quad (\text{convection length in diff^n time!})$$

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So:

$$\frac{\partial c^*}{\partial t^*} + u^* \frac{\partial c^*}{\partial x^*} = \frac{\partial^2 c^*}{\partial y^{*2}} + \left(\frac{D}{U_b}\right)^2 \frac{\partial^2 c^*}{\partial x^{*2}}$$

and the integral condition:

$$\int_0^1 \int_{-\infty}^{\infty} c^* dx^* dy^* = \left[\frac{I}{c_c x_c b} \right] = 1$$

where we just use the top half.

We have $\frac{\partial c^*}{\partial y^*} \Big|_{y^*=0,1} = 0$

We will use the method of moments
approach of Aris. We define:

$$c_p^* = \int_{-\infty}^{\infty} x^* P c^* dx^*$$

$$m_p^* = \int_0^1 c_p^* dy^* \quad (\text{the } p^{\text{'th}} \text{ moment})$$

Recall we need to figure out the

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rate of growth of the variance
to get $K!$

$$\sigma_x^2 = \frac{\int_{-\infty}^{\infty} \int_0^b (x - \bar{x})^2 c dy dx}{\int_{-\infty}^{\infty} \int_0^b c dy dx}$$

where $\bar{x} = \frac{\int_{-\infty}^{\infty} \int_0^b x c dy dx}{\int_{-\infty}^{\infty} \int_0^b c dy dx}$

and $\frac{d \sigma_x^2}{dt} = 2K$

Scaling: $\bar{x}^* = \frac{\bar{x}}{X_c}$ and $\bar{x}^* = m_1^*$
by definition!

Likewise, $\sigma_x^2 = \left(\frac{Ub^2}{D}\right)^2 (m_2^* - m_1^{*2})$

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$$\text{so } 2K = \frac{\partial \sigma_x^2}{\partial t} = \left(\frac{Ub^2}{D}\right) \left(\frac{D}{b^2}\right) \frac{\partial}{\partial t} (m_2^* - m_1^{*2})$$

$$\text{or } \frac{K}{D} = \frac{1}{2} \left(\frac{Ub}{D}\right)^2 \left(\frac{\partial m_2^*}{\partial t^*} - 2m_1^* \frac{\partial m_1^*}{\partial t^*} \right)$$

so to get $\frac{K}{D}$ we need:

$$\frac{\partial m_1^*}{\partial t^*}; m_1^*; \frac{\partial m_2^*}{\partial t^*}$$

To get these moments we multiply the equation by x^{*P} and integrate!

We had:

$$\frac{\partial C^*}{\partial t^*} + u^* \frac{\partial C^*}{\partial x^*} = \left(\frac{D}{Ub}\right)^2 \frac{\partial^2 C^*}{\partial x^{*2}} + \frac{\partial^2 C^*}{\partial y^{*2}}$$

$$\text{w/ } \frac{\partial C^*}{\partial y^*} \Big|_{y^*=0,1} = 0$$

Mult by x^{*P} & integrate over x^* !

$$\frac{\partial C_p^*}{\partial t^*} + \int_{-\infty}^{\infty} x^{*P} u^* \frac{\partial C^*}{\partial x^*} dx^* = \left(\frac{D}{Ub}\right)^2 \int_{-\infty}^{\infty} x^{*P} \frac{\partial^2 C^*}{\partial x^{*2}} dx^* + \frac{\partial^2 C_p^*}{\partial y^{*2}}$$

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$$\text{where } C_p^* \equiv \int_{-\infty}^{\infty} x^{*P} C^* dx^*$$

The two integrals are integrated by parts:

$$\int_{-\infty}^{\infty} x^{*P} u^* \frac{\partial C^*}{\partial x^*} dx^* = x^{*P} u^* C^* \Big|_{-\infty}^{\infty} - P \int_{-\infty}^{\infty} x^{*P-1} u^* C^* dx^*$$

$$\text{Now } C^* \Big|_{x^*=\pm\infty} = 0 \quad (\text{far away from peak!})$$

$$\therefore \int_{-\infty}^{\infty} x^{*P} u^* \frac{\partial C^*}{\partial x^*} dx^* = - P u^* C_{P-1}^*$$

Similarly (doing it twice):

$$\int_{-\infty}^{\infty} x^{*P} \frac{\partial^2 C^*}{\partial x^{*2}} dx^* = P(P-1) C_{P-2}^*$$

So:

$$\frac{\partial C_p^*}{\partial t^*} = P u^* C_{P-1}^* + P(P-1) \left(\frac{D}{U_b}\right)^2 C_{P-2}^* + \frac{\partial^2 C_p^*}{\partial y^{*2}}$$

$$\text{and } \frac{\partial C_p^*}{\partial y^*} \Big|_{y^*=0,1} = 0$$

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Integrating again yields m_p^* :

$$\frac{d m_p^*}{dt^*} = P \int_0^1 u^* c_{p-1}^* dy^* + \left(\frac{D}{D_b}\right)^2 P(P-1) m_{p-2}^*$$

where the integral $\int_0^1 \frac{\partial^2 c_p^*}{\partial y^{*2}} dy^* = 0$
from BC's.

We thus have the sequence of problems!

$$\underset{P=0}{\frac{d m_0^*}{dt^*}} = 0 \quad \text{constant, so } m_0^* = 1$$

$$\frac{\partial c_0^*}{\partial t^*} = \frac{\partial^2 c_0^*}{\partial y^{*2}}, \quad \left. \frac{\partial c_0^*}{\partial y^*} \right|_{y^*=0,1} = 0, \quad \int_0^1 c_0^* dy^* = 1$$

This also has the solution $C_0^* = 1$

Interpretation: Solute is conserved and the solute is uniformly distributed in the y -direction!

$P=1:$

$$\frac{\partial m_1^*}{\partial t^*} = \int_0^1 u^* c_0^* dy^*$$

$$\frac{\partial c_1^*}{\partial t^*} = u^* c_0^* + \frac{\partial^2 c_1^*}{\partial y^{*2}}$$

w/ BC's $\left. \frac{\partial c_1^*}{\partial y^*} \right|_{0,1} = 0, \quad \int_0^1 c_1^* dy^* = m_1^*$

and for $P=2:$

$$\frac{\partial m_2^*}{\partial t^*} = 2 \int_0^1 u^* c_1^* dy^* + 2 \left(\frac{D}{U_b} \right) m_0^*$$

which is all we need - c_2^* would be messy to get, but we don't need it!

So:

$$m_0^* = 1 \quad (\text{total amount of solute is conserved})$$

$$c_0^* = 1 \quad (\text{uniform distribution in } y\text{-dir})$$

(3.22)

$$P = 1 :$$

$$\frac{dm_i^*}{dt^*} = \int_0^1 u^* \cdot c_i dy^* = 1$$

$\hookrightarrow u^*$ chosen to have avg. value = 1

We need an initial condition. We shall take the average x position of the solute at $t=0$ to be zero

$$\text{so } m_i^* = t^* \quad (\text{or } \langle u^* \rangle t^*)$$

Now for the only hard part!

$$\frac{\partial c_i^*}{\partial t^*} = u^* + \frac{\partial^2 c_i^*}{\partial y^{*2}} ; \left. \frac{\partial c_i^*}{\partial y^*} \right|_{y^*=0,1} = 0$$

$$\int_0^1 c_i^* dy^* = m_i^* = t^* \quad (\text{or } \langle u^* \rangle t^*)$$

We seek a solution of the form

$$c_i^* = m_i^* + f(y^*)$$

so we get the equation:

$$\langle u^* \rangle = u^* + f''$$

$$\text{or } f'' = \langle u^* \rangle - u^* \quad \left. \begin{array}{l} f \text{ is driven by} \\ \text{deviation from} \\ \text{avg. velocity} \end{array} \right\}$$

$$f'(0) = 0, f'(1) = 0$$

$$\int_0^1 f dy^* = 0 \quad \left. \begin{array}{l} \langle u^* \rangle \\ u^* \end{array} \right.$$

$$\text{So: } f'' = 1 - \frac{3}{2} (1 - y^{*2})$$

$$= \frac{3}{2} y^{*2} - \frac{1}{2}$$

$$f' = \frac{1}{2} y^{*3} - \frac{1}{2} y^* + C \quad \left. \begin{array}{l} \\ \\ 0 \end{array} \right. \text{ since } f'(0) = 0$$

(note that $f'(1) = 0$ is automatically satisfied!)

$$\therefore f = \frac{1}{8} y^{*4} - \frac{1}{4} y^{*2} + C$$

$$\text{Integrating: } \int_0^1 f dy^* = \frac{1}{40} - \frac{1}{12} + C = 0$$

$$\therefore C = \frac{7}{120}$$

$$\text{and } f = \frac{1}{8} y^{*4} - \frac{1}{4} y^{*2} + \frac{7}{120}$$

$$5_0 \quad C_1^* = m_1^* + f(y^*)$$

Now for $P = 2$:

$$\begin{aligned} \frac{Qm_2^*}{\Delta t^*} &= 2 \int_0^1 u^* C_1^* dy^* + 2 \left(\frac{D}{U_b} \right)^2 m_0^* \\ &= 2 m_1^* + 2 \left(\frac{D}{U_b} \right)^2 m_0^* + 2 \int_0^1 u^* f dy^* \end{aligned}$$

$$\underline{\underline{\text{But}}} \quad \frac{\kappa}{D} = \frac{1}{2} \left(\frac{U_b}{D} \right)^2 \left(\frac{Qm_2^*}{\Delta t^*} - 2 m_1^* \underbrace{\frac{Qm_1^*}{\Delta t^*}}_{=1} \right)$$

molecular dif.

$$\underline{\underline{\text{So}}} \quad \frac{\kappa}{D} = 1 + \left(\frac{U_b}{D} \right)^2 \int_0^1 u^* f dy^*$$

since $\int_0^1 f dy^* = 0$ we get:

$$\begin{aligned} \frac{\kappa}{D} &= 1 + \left(\frac{U_b}{D} \right)^2 \int_0^1 (u^* - \langle u^* \rangle) f dy^* \\ &= 1 + \frac{2}{105} \left(\frac{U_b}{D} \right)^2 \end{aligned}$$

For a tube you get

$$\frac{\kappa}{D} = 1 + \frac{1}{48} \left(\frac{U_a}{D} \right)^2, \text{ almost the } \underline{\text{same}}$$

So what does this mean?

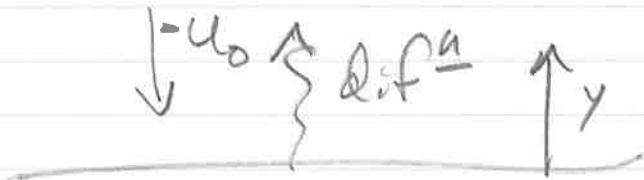
- The coefficient $\frac{2}{105}$ is small, but $\left(\frac{U_b}{D}\right)^2$ is usually huge, so Taylor disp. dominates solute spread in the flow direction.
- It scales as $\langle (u^* - \bar{u}^*)^2 \rangle$ so it is the difference between local and avg. velocities that drives it!
- It scales as $\kappa \sim U_b \left(\frac{U_b}{D}\right)$ so it is cut off by diffusion - molecules sample different streamlines and (eventually) move with the average.
- The TA limit is reached only after molecules have a chance to diffuse across the channel : the transient is a SL eigenvalue problem.

A nice example of convective diffusion as applied to separations is Field Flow Fractionation (FFF). There are many subtypes of this, but the key is that they use a field (electric, gravity, magnetic, convection, etc.) to force a solute to one wall of a flow cell (usually channel or tube). This field force is balanced by diffusion yielding an equilibrium conc. distribution. This distribution combines with the shear flow in the flow cell to get separation!

To understand this, we need to know what a concentration polarization layer is.

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Suppose, either due to convection through
a porous membrane, or electric field,
or gravity we have a solute velocity
- u_0 toward an accumulating wall.



We have the convective diffusion eq'n:

$$-u_0 \frac{\partial c}{\partial y} = D \frac{\partial^2 c}{\partial y^2}$$

at steady state.

The flux at the wall is $-u_0 c \Big|_{y=0} - D \frac{\partial c}{\partial y} \Big|_{y=0} = 0$
as the solute doesn't penetrate!

The conc. as $y \rightarrow a = 0$

Let's scale:

$$c^* = \frac{c}{c_0} \quad y^* = \frac{y}{y_c}$$

$$-\frac{u_0 c_0}{y_c} \frac{\partial c^*}{\partial y^*} = \frac{D c_0}{y_c^2} \frac{\partial^2 c^*}{\partial y^{*2}}$$

or - $\left[\frac{y_c u_0}{D} \right] \frac{\partial c^*}{\partial y^*} = \frac{\partial^2 c^*}{\partial y^{*2}}$

$\therefore y_c = \frac{D}{u_0}$ which is the length scale

of the concentration polarization layer.

We determine c_0 from the integral balance:

$$I = \int_0^\infty c dy$$

$$\therefore c_0 = \frac{I}{y_c} = \frac{I}{(D/u_0)}$$

so low D or high u_0 yields high concentrations at the wall.

The solution is just:

$$c^* = e^{-y^*}$$

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OK, how can we use this for sep.?
We induce a tangential flow!

Let $u_x = \dot{\gamma}y$ (simple shear)

so the average solute velocity is

$$\frac{\int_0^\infty u_x c dy}{\int_0^\infty c dy} = \dot{\gamma} y_c \int_0^\infty y^* e^{-y^*} dy^*$$

where $\int_0^\infty y^* e^{-y^*} dy^* = -y^* e^{-y^*} \Big|_0^\infty + \int_0^\infty e^{-y^*} dy^* = 1$

$$\stackrel{=0}{\uparrow}$$

so the average solute velocity is

$$\langle u_x \rangle = \dot{\gamma} \frac{D}{U_0}$$

This would separate, say, nanoparticles by size through the Stokes-Einstein

Diffusivity: $D = \frac{kT}{6\pi\alpha\eta}$

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Alternatively if u_0 is different for different species (say, you had an electro
field and different electrophoretic mobility,
or a gravitational field and different
sedimentation velocities) you would also
separate.

To achieve separation you need the peak width to be smaller than the difference in elution time. The peak width is governed by Taylor dispersion.
Let's look at this:

$$\frac{\partial C}{\partial t} + \dot{y}_c \frac{\partial C}{\partial x} - u_0 \frac{\partial C}{\partial y} = D \frac{\partial^2 C}{\partial y^2} \quad (\text{x-dif is very small})$$

Let's scale:

$$t^* = \frac{t}{t_c}, \quad x^* = \frac{x}{x_c}, \quad y^* = \frac{y}{y_c}, \quad C^* = \frac{C}{C_0}$$

So:

$$\frac{C_0}{t_c} \frac{\partial C^*}{\partial t^*} + \dot{y}_c \frac{C_0}{x_c} y^* \frac{\partial C^*}{\partial x^*} - \frac{u_0 C_0}{y_c} \frac{\partial C^*}{\partial y^*} = \frac{D C_0}{y_c^2} \frac{\partial^2 C^*}{\partial y^{*2}}$$

Dividing by $y - \text{diff}^{\frac{1}{2}}$:

$$\left[\frac{y_c^2}{D t_c} \right] \frac{\partial c^*}{\partial t^*} + \left[\frac{y_c^3}{D x_c} \right] y^* \frac{\partial c^*}{\partial x^*} - \left[\frac{\mu_0 y_c}{D} \right] \frac{\partial c^*}{\partial y^*} = \frac{\partial^2 c^*}{\partial y^{*2}}$$

so $y_c = \frac{D}{u_0}$ as before

$$x_c = \frac{y_c^3}{D} = \frac{y_c D^2}{u_0^3}$$

char. length in separation direction

$$t_c = \frac{y_c^2}{D} = \frac{D}{u_0^2}$$

char. time scale to reach TA limit.

and $\int_{-\infty}^{\infty} \int_0^{\infty} c \, dy \, dx = I$ (total amount)

$$\therefore c_0 = \frac{I}{y_c x_c}$$

$$\text{so } \int_{-\infty}^{\infty} \int_0^{\infty} c^* \, dy^* \, dx^* = 1$$

and we have the BCs:

$$c^* \Big|_{y^* \rightarrow \infty} = 0 \quad \Rightarrow \quad c^* \Big|_{y^*=0} + \frac{\partial c^*}{\partial y^*} \Big|_{y^*=0} = 0$$

(no flux at wall)

From Scaling alone we expect the Taylor Dispersivity κ to scale as:

$$\frac{\kappa}{D} \sim \frac{x_c^2}{Dt_c} = \frac{(\dot{\gamma} y_c t_c)^2}{Dt_c} = \frac{\dot{\gamma}^2 y_c^2 t_c}{D} = \frac{\dot{\gamma}^2 y_c^4}{D^2}$$

but $y_c = \frac{D}{U_0}$

$$\therefore \frac{\kappa}{D} \sim \frac{\dot{\gamma}^2 D^2}{U_0^4}$$

How do we get the constant? We can use the method of moments again!

$$\frac{\partial C^*}{\partial t^*} + Y^* \frac{\partial C^*}{\partial x^*} - \frac{\partial C^*}{\partial y^*} = \frac{\partial^2 C^*}{\partial y^{*2}}$$

We define:

$$C_p^* = \int_{-\infty}^{\infty} x^{*P} C^* dx^*$$

$$m_p^* = \int_0^{\infty} C_p^* dy^*$$

and $\frac{\kappa}{D} = 1 + \frac{\dot{\gamma}^2 D^2}{U_0^4} \left(\frac{\partial m_2^*}{\partial t^*} - 2m_1^* \frac{\partial m_1^*}{\partial t^*} \right)$

After a fair amount of algebra, we get: 333

$$m_0^* = 1 - y^*$$

$$c_0^* = e$$

$$m_1^* = t^*$$

$$c_1^* = t^* e^{-y^*} + f(y^*)$$

where:

$$f(y^*) = e^{-y^*} \left(1 - y^* + \frac{1}{2} y^{*2} - \frac{1}{6} y^{*3} \right)$$

and

$$\frac{K}{D} = 1 + 2 \frac{\dot{y}^2 D^2}{u_0^4}$$

Ok, now that we have the solute velocity and dispersivity, what do we do with it?

For chromatography it is usual to calculate the NTP : number of theoretical plates.

This is the ^{square of the} ratio of elution time to peak SD (in time domain) or column length to peak SD in spatial domain.

We had the average velocity:

$$\langle u_x \rangle = \frac{\dot{V} D}{u_0}$$

so if our plate length is L then our elution time is $t = \frac{L}{\langle u_x \rangle} = \frac{L u_0}{\dot{V} D}$

our peak SD is just $(2kt)^{1/2}$

so the ratio is:

$$\begin{aligned} NTP &= \left[\frac{L}{(2kt)^{1/2}} \right]^2 = \frac{L^2}{4 \frac{\dot{V}^2 D^3}{u_0^4} \frac{L u_0}{\dot{V} D}} \\ &= \frac{1}{2} \cdot \frac{u_0^3 L}{\dot{V} D^2}. \end{aligned}$$

of course, as $D/u_0 \rightarrow 0$ the solute moves very slowly!

In a practical FFF device you don't have a simple shear, instead you have plane-Poiseuille flow! For a channel of height h this yields:

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$u_x = 6U \frac{y}{h} (1 - \frac{y}{h})$ where U is the average velocity. Near the wall (where the solute is - $\frac{D}{U_0 h} \ll 1$ for efficient separations) the shear rate is just

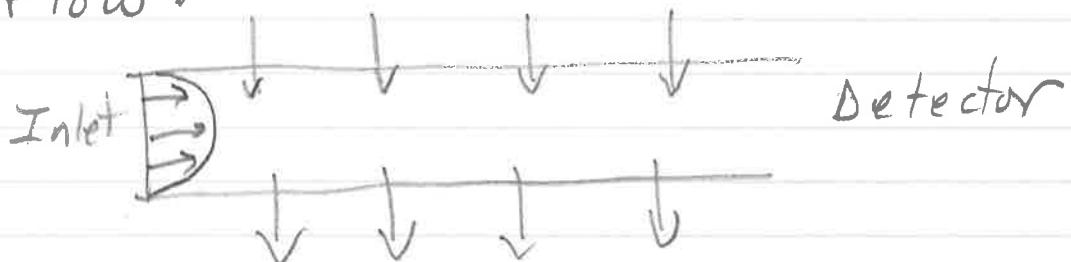
$$\dot{\gamma} = 6 \frac{U}{h}$$

We can obtain a retention ratio

$$\frac{\langle u_x \rangle}{U} = 6 \frac{D}{U_0 h}$$

In general this is in the range of [0.02, 0.1]

The first cross-flow FFF device had a channel w/ two porous walls for the cross flow:



This was pretty hard to make work.

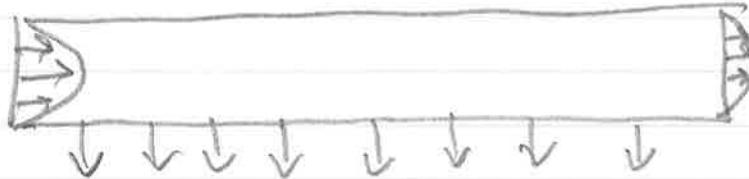
A better idea was proposed by Giddings

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(Synonymous w/ most FFF techniques)

of asymmetric flow field flow frac.

(AF4 for short). Basically, it just replaced the top wall w/ glass! The lower (accumulating) wall was membrane supported on a glass frit:



This means that the y direction velocity (and x too) isn't uniform!

By continuity:

$$\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} = 0$$

Now u_x is still a parabola, but it's leaning out!

$$\therefore u_x = (U_0 - U_0 \frac{x}{h}) \cdot \frac{y}{h} (1 - \frac{y}{h})$$

by a mass balance.

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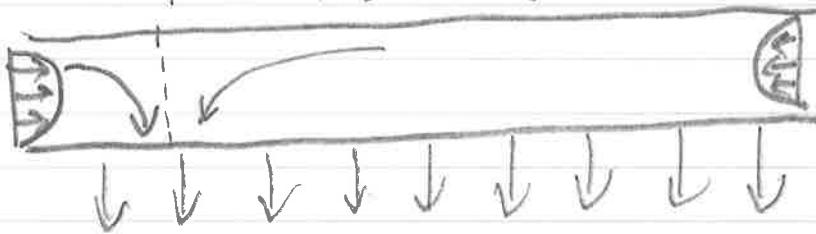
Plugging in we get for u_y :

$$\frac{\partial u_y}{\partial y} = - \frac{\partial u_x}{\partial x} = + \frac{u_0}{h} 6 \frac{y}{h} \left(1 - \frac{y}{h}\right)$$

$$\text{so } u_y = -u_0 \left(1 - 3 \frac{y^2}{h^2} + 2 \frac{y^3}{h^3}\right)$$

Now because there is no flow through the top wall, you have to concentrate the solute at the lower wall prior to separation. In addition, you need to focus your solute slug (reduce initial width). This is done by running your outflow backwards!

(line of zero avg. x flow)



By adjusting the two flows you control where the solute starts!

The AF4 techniques separates based on diffusivity! Suppose we have two species w/ dif. D_1 & D_2

At the outlet L they would be separated (on average) by $\Delta L = L \left(1 - \frac{D_2}{D_1}\right)$
 we require this to be greater than twice the σ of the peaks (generally 4x for good resolution).

$$\text{So: } \frac{L \left(1 - \frac{D_2}{D_1}\right)}{\left(2K \frac{Lu_0}{8D_1}\right)^{1/2}} \gg 2$$

$$\text{but } K = 2 \frac{\dot{\gamma}^2 D^3}{u_0^4} \text{ for simple shear}$$

$$\therefore \left(\frac{1}{2} \frac{Lu_0^3}{\dot{\gamma}^2 D^2}\right)^{1/2} \left(1 - \frac{D_2}{D_1}\right) \gg 2$$

$$\text{or } (NTP)^{1/2} \left(1 - \frac{D_2}{D_1}\right) \gg 2$$

for separation! Plugging in values allows you to design an efficient separation!

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In these calculations we have ignored the decrease in x velocity with x . Since u_0 (cross flow) is produced by U_0 they are all related! In fact, for some U_0 there is a lower bound on U (or upper bound on L) s.t.:

$$U_0 > u_0 \frac{L}{h}$$

This means, since $\dot{\gamma} = 6 \frac{U_0}{h} \left(1 - \frac{u_0 x}{U_0 h}\right)$

they are all related. If we define

$L^* = \frac{u_0 L}{U_0 h}$ and plug this in, we get

$$\frac{L u_0^3}{\dot{\gamma} D^2} = \frac{1}{6} \frac{L^*}{1 - L^* \frac{x}{L}} \frac{u_0^2 h^2}{D^2}$$

So we require

$$\left[\frac{1}{12} \left(\frac{L^*}{1 - L^* \frac{x}{L}} \right) \right]^{1/2} \frac{u_0 h}{D} \left(1 - \frac{D_2}{D_1} \right) \gg 2$$

$\hookrightarrow \approx \frac{1}{5}$ for typical values

Properties of an Asymmetrical Flow Field-Flow Fractionation Channel Having One Permeable Wall

Karl-Gustav Wahlund and J. Calvin Giddings
 Anal. Chem. 1987, 59, 1332-1339

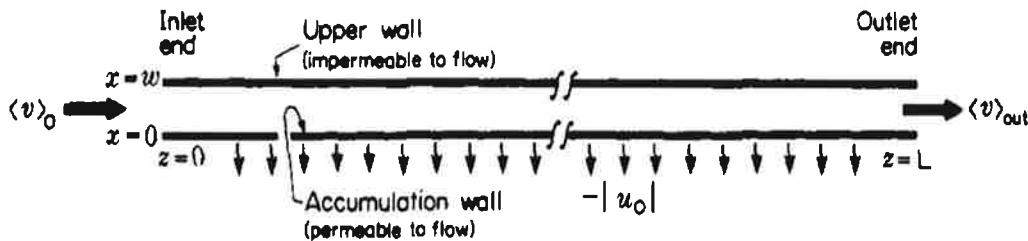


Figure 1. Schematic illustration of asymmetrical channel for flow field-flow fractionation. Flow velocities at designated locations are shown as $\langle v \rangle_0$, $\langle v \rangle_{out}$, and u_0 , where the first two are the longitudinal flow velocities at the inlet and outlet ends, respectively, and u_0 is the crossflow velocity at the accumulation wall.

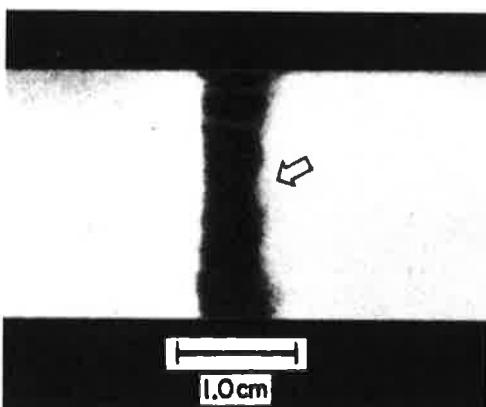


Figure 9. Photograph of focused sample of cytochrome c using opposing flow relaxation. The focusing point was at $z' = 22.5$ cm and the cross flowrate ($\dot{V}_{in}' + \dot{V}_{out}'$) was 6.2 mL/min.

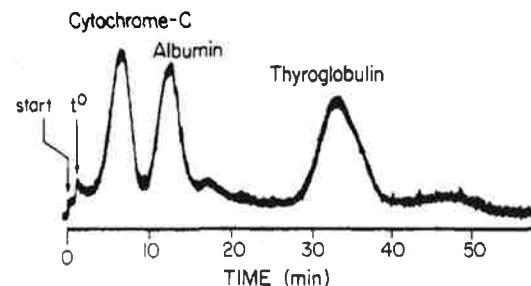
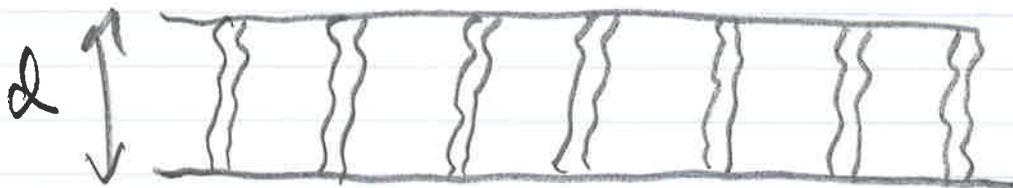


Figure 10. Separation of cytochrome c, albumin, and thyroglobulin in an asymmetrical system using opposing flow relaxation with $z' = 4.0$ cm, relaxation/focusing time (preceding "start") = 23 min ($\tau(95\%) = 10$ min), and cross flowrate = 3.1 mL/min. Flowrates during elution are $V_{out} = 1.69$ mL/min and $V_c = 3.24$ mL/min. Retention ratios were 0.20, 0.10, and 0.04, which gave diffusion coefficients of 1.2×10^{-6} , 6.0×10^{-7} , and 2.3×10^{-7} cm^2/s , respectively.

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In FFF concentration polarization is good: it's what leads to separation!
In filtration it's bad because it reduces the permeate flux through the membrane. Let's look at this!

What is a membrane? Simplistically, it is a solid layer with pores:



ϵ = open area

a = pore radius

d = membrane thickness

λ = tortuosity

Pores are usually small, so inertial effects are negligible.

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We can approximate the flow through a single pore w/ Poiseuille's Law:

$$Q_{\text{pore}} = \frac{1}{8} \frac{\Delta P}{\mu \lambda d} \frac{\pi a^4}{l} \leftarrow \begin{matrix} \text{pore radius} \\ \text{pressure drop} \\ \text{fluid viscosity} \end{matrix}$$

\uparrow \uparrow \curvearrowright effective length

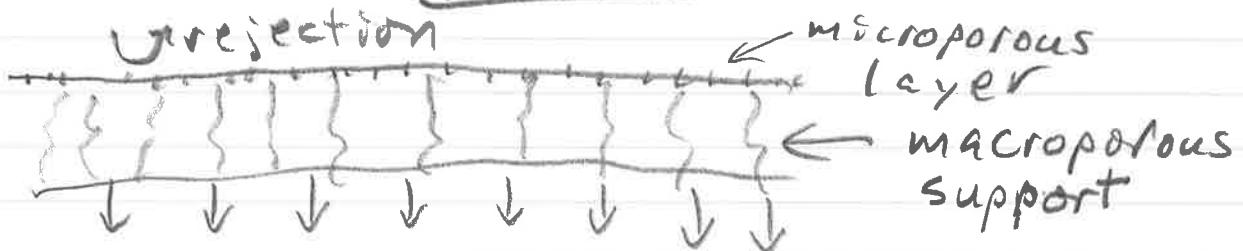
$$\text{We have } n \text{ pores/area} = \frac{\epsilon}{\pi a^2}$$

$$\therefore \text{trans-membrane flux} = u_0 = n Q_{\text{pore}} = \frac{\Delta P}{\mu} \left(\frac{\epsilon a^2}{8 \lambda d} \right)$$

the quantity $K_H = \frac{\epsilon a^2}{8 \lambda d}$ is the hydraulic permeability of the membrane! For tract etched membranes (nucleopore) where pores are circular & straight this works ($w/\lambda = 1$). For more complicated membranes it is just a scaling and K_H is determined empirically.

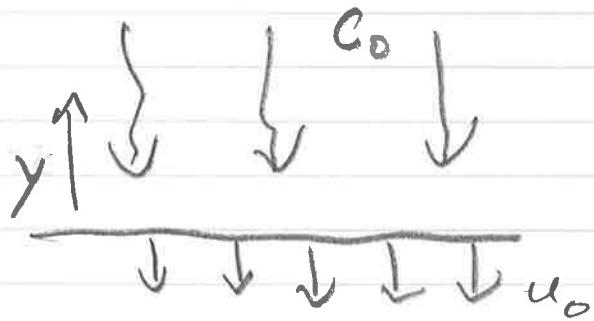
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Because of the strong dep. on pore size, for rejecting small species you want to use asymmetric membranes:



Most of the hydrodynamic resistance is in the thin microporous layer.

ok, so what happens in dead end filtration:



We have one-D diffusion:

$$\frac{\partial c}{\partial t} - u_0 \frac{\partial c}{\partial y} = D \frac{\partial^2 c}{\partial y^2}$$

$$c|_{y \rightarrow \infty} = C_0 \quad u_0 c|_{y=0} + D \frac{\partial c}{\partial y}|_{y=0} = 0$$

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Let's scale:

$$c^* = C/C_0, \quad y^* = Y/Y_C, \quad t^* = t/t_C$$

$$\therefore \frac{C_0}{t_C} \frac{\partial c^*}{\partial t^*} - \frac{u_0 C_0}{Y_C} \frac{\partial c^*}{\partial y^*} = D \frac{C_0}{Y_C^2} \frac{\partial^2 c^*}{\partial y^{*2}}$$

$$\text{So } \left[\frac{Y_C^2}{D t_C} \right] \frac{\partial c^*}{\partial t^*} - \left[\frac{u_0 Y_C}{D} \right] \frac{\partial c^*}{\partial y^*} = \frac{\partial^2 c^*}{\partial y^{*2}}$$

" " "

$$\text{So } Y_C = D/u_0, \quad t_C = \frac{Y_C^2}{D} = \frac{D}{u_0^2}$$

$$\therefore \frac{\partial c^*}{\partial t^*} - \frac{\partial c^*}{\partial y^*} = \frac{\partial^2 c^*}{\partial y^{*2}}$$

$$c^* \Big|_{y^* \rightarrow \infty} = 1 \quad c^* \Big|_{y^*=0} + \frac{\partial c^*}{\partial y^*} \Big|_{y^*=0} = 0$$

Ignoring the IC, this has the solution:

$$c^* = 1 + t^* e^{-y^*} + (1-y^*) e^{-y^*}$$

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The problem is that the conc. at the membrane grows linearly in time! This has three primary effects:

1) For dilute small molecules (e.g., salt) you will have more unwanted solute flux (e.g., the rejection ratio of, say, Li^+/K^+ will go down due to buildup of K^+)

2) For more conc. small molecules you will increase the osmotic pressure

$$\Pi = i C R T \leftarrow \begin{matrix} \text{temp} \rightarrow 0^\circ\text{K} \\ \xrightarrow{\text{A}} \text{Ideal gas const} \\ \text{van't Hoff Index} \\ (\propto \text{dissociated ions/mol}) \end{matrix}$$

This reduces the permeate flux by effectively reducing the driving force (e.g., $\mu_0 = K_H (\Delta P - \Pi)$)

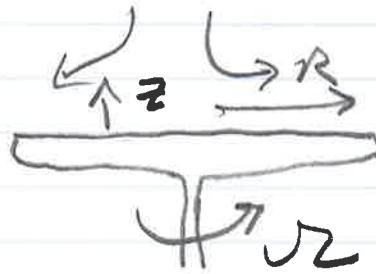
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3) For larger species you may exceed the solubility limit, or simply build up a cake layer! This would plug the holes, or otherwise reduce k_{H+} .

How do we control the buildup?

Introduce a cross-flow! This would sweep away the concentration polarization layer and permit steady operations!

A classic approach used for study of membranes is a rotating filter:



The rotation introduces a centrifugal force which causes fluid to sweep the membrane surface. The

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reason why this works so well is
the mass transfer BL is uniform
over the whole surface. Let's look
at this!

First, we need the velocity profile!
we have an axi-sym. problem: no θ
variation!

\therefore CE:

$$\frac{1}{r} \frac{\partial}{\partial r} (r u_r) + \frac{\partial u_z}{\partial z} = 0$$

Θ mom:

$$g \left(u_r \frac{\partial u_\theta}{\partial r} + u_z \frac{\partial u_\theta}{\partial z} + \frac{u_r u_\theta}{r} \right) \\ = \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r u_\theta) \right) + \frac{\partial^2 u_\theta}{\partial z^2} \right]$$

r -mom:

$$g \left(u_r \frac{\partial u_r}{\partial r} + u_z \frac{\partial u_r}{\partial z} - \frac{u_r^2}{r} \right) \\ = - \frac{\partial P}{\partial r} + \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r u_r) \right) + \frac{\partial^2 u_r}{\partial z^2} \right]$$

We have BCs:

$$u_\theta \Big|_{z=0} = \Omega r \quad (\text{rotation})$$

$$u_\theta \Big|_{z \rightarrow \infty} = 0$$

$$u_r \Big|_{z=0, \infty} = 0$$

$$u_z \Big|_{z=0} = -u_0 \quad (\text{permeate flux!})$$

We are interested in the boundary layer limit. We anticipate that $z_c \ll R$! Recall that in this limit the pressure gradient outside the BL is impressed on the BL. Thus,

$$\frac{\partial P}{\partial r} = 0$$

Let's scale this!

$$\text{From BC } u_\theta^* = \frac{u_\theta}{\Omega R}, \quad r^* = \frac{r}{R}$$

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We take $u_r^* = \frac{u_r}{U_{rc}}$, $u_z^* = \frac{u_z}{U_{zc}}$
 $z^* = \frac{z}{z_c}$

From the CE:

$$\frac{U_{rc}}{R} \frac{1}{r^*} \frac{\partial}{\partial r^*} \left(r^* u_r^* \right) + \frac{U_{zc}}{z_c} \frac{\partial u_z^*}{\partial z^*} = 0$$

$$\therefore U_{zc} = \frac{z_c}{R} U_{rc}$$

θ mom:

$$\begin{aligned} g \frac{U_{rc} \sqrt{2} R}{R} & \left(u_r^* \frac{\partial u_\theta^*}{\partial r^*} + u_z^* \frac{\partial u_\theta^*}{\partial z^*} + u_r^* u_\theta^* \right) \\ &= \mu \frac{\sqrt{2} R}{z_c^2} \left(\frac{\partial^2 u_\theta^*}{\partial z^{*2}} + \underbrace{\frac{z_c^2}{R^2} \frac{\partial}{\partial r^*} \left(\frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* u_\theta^*) \right)}_{\text{small}} \right) \end{aligned}$$

$$\text{so } \frac{U_{rc} z_c^2}{2R} = 1$$

r mom:

$$\begin{aligned} g \frac{U_{rc}^2}{R} & \left(u_r^* \frac{\partial u_r^*}{\partial r^*} + u_z^* \frac{\partial u_r^*}{\partial z^*} \right) - g \sqrt{2} R \frac{u_\theta^*}{r^*} \\ &= \mu \frac{U_{rc}}{z_c^2} \left[\frac{\partial^2 u_r^*}{\partial z^{*2}} + \underbrace{\frac{z_c^2}{R^2} \frac{\partial}{\partial r^*} \left(\frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* u_r^*) \right)}_{\text{small}} \right] \end{aligned}$$

$$\text{so: } \frac{U_{rc} z_c^2}{\sqrt{R}} = 1 \text{ (as before)}$$

and $\frac{\sqrt{2}^2 R z_c^2}{U_{rc} \nu} = 1$ (balancing centrifugal force w/ & of " of radial mom in z-dir)

This has the solution:

$$U_{rc} = \sqrt{2} R ; z_c = \left(\frac{\nu}{\sqrt{2}}\right)^{1/2}$$

$$\text{and } U_{zc} = \sqrt{2} \left(\frac{\nu}{\sqrt{2}}\right)^{1/2}$$

We have the dimensionless eqn's:

$$\frac{\partial u_z^*}{\partial z^*} = - \frac{1}{\nu^*} \frac{\partial}{\partial \nu^*} (\nu^* u_r^*)$$

$$\frac{\partial^2 u_\theta^*}{\partial z^{*2}} = u_r^* \frac{\partial u_\theta^*}{\partial \nu^*} + u_z^* \frac{\partial u_\theta^*}{\partial z^*} + \frac{u_r^* u_\theta^*}{\nu^*}$$

$$\frac{\partial^2 u_r^*}{\partial z^{*2}} = u_r^* \frac{\partial u_r^*}{\partial \nu^*} + u_z^* \frac{\partial u_r^*}{\partial z^*} - \frac{u_\theta^{*2}}{\nu^*}$$

w/ BC's $u_\theta^*|_{z^*=0} = \nu^*$, $u_z^*|_{z^*=0} = -\frac{u_0}{(\sqrt{2}\nu)^{1/2}} = -u_0^*$

and $u_\theta^*|_{z^* \rightarrow \infty} = u_r^*|_{z^* \rightarrow 0, \infty} = 0$

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OK, now for the concentration:

$$u_r \frac{\partial C}{\partial r} + u_z \frac{\partial C}{\partial z} = D \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial C}{\partial r} \right) + \frac{\partial^2 C}{\partial z^2} \right]$$

or, w/ $C^* = \gamma_{C_0}$:

$$u_r^* \frac{\partial C^*}{\partial r^*} + u_z^* \frac{\partial C^*}{\partial z^*} = \frac{D}{\gamma_{Sc}} \frac{\partial^2 C^*}{\partial z^{*2}}$$

$\hookrightarrow \gamma_{Sc}$

Recall for liquids $Sc \gg 1$

$$\text{BC's: } C^* \Big|_{z^* \rightarrow \infty} = 1$$

$$\text{and at } z=0: -u_0 C \Big|_{z=0} - D \frac{\partial C}{\partial z} \Big|_{z=0} = 0$$

(this is for complete rejection - if some solute gets through, it would be equal to the solute flux)

$$\text{This yields } u_0^* C^* \Big|_{z^*=0} + \frac{1}{Sc} \frac{\partial C^*}{\partial z^*} \Big|_{z^*=0} = 0$$

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These equations are non-linear, but
 they admit a similarity solution!

$$u_\theta^* = r^* f(z^*)$$

$$u_r^* = r^* g(z^*)$$

$$u_z^* = h(z^*)$$

and $c^* = f^{-1}(z^*)$ alone!

So:

$$f'' = fg + hf' + fg \equiv 2fg + hf'$$

$$g'' = g^2 + hg' - f^2$$

$$h' = -2g$$

$$\text{w/ } f(0) = 1, f(\infty) = 0$$

$$g(0) = g(\infty) = 0$$

$$h(0) = -u_0^*$$

$$\text{and } c^{*''} = 5e h c^*$$

$$c^*(\infty) = 1 \quad c^{*\prime}(0) + 5e u_0^* e(0) = 0$$

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So our dimensionless conc. at $z=0$ is a function of $u_0^* = \frac{u_0}{(\sqrt{2} \nu)^{1/2}}$ and Sc . we can solve these for arbitrary u_0^* and Sc , but since $Sc \gg 1$ we can get at the scaling another way. We want to remove the concentration polarization layer via radial convection. If our polarization layer is thin, the excess concentration needs to balance the inward flux:

$$(2\pi R) \frac{(\sqrt{2}R)^{1/2}}{(\frac{\nu}{\sqrt{2}})^{1/2}} g'(0) \left(\frac{D}{u_0} \right)^2 (c^*|_{z=0} - 1) = u_0 \pi R^2$$

↑ ↑ ↑ ↑
 circumference Shear rate at length scale flux in
 membrane membrane of polarization from outside

$$\therefore c^*|_{z=0} - 1 \sim \frac{1}{2g'(0)} \left(\frac{\nu^2}{D^2} \right) \left(\frac{u_0^3}{(\sqrt{2}\nu)^{3/2}} \right)$$

$$= \frac{1}{2g'(0)} Sc^2 u_0^{*3}$$

Let's see how this works! In the Bruening lab they are using a track etched membrane (30 nm pores) to separate Li^+ and K^+ . They get great selectivity (RR 150) at 1000 RPM rotation, but at 100 RPM it drops to 2! (K^+ gets through). The hydraulic permeability is 22.5 LMH (liters/m².hr at 1 bar) and the ΔP is about 6 bar. The radius $R = 1.45\text{cm}$, and the diffusivity of K^+ in solution is about $1.8 \times 10^{-5}\text{ cm}^2/\text{s}$. So:

$$u_0 = (6 \text{ bar}) \left(22.5 \times \frac{1000}{10^4} \frac{1}{3600} \right) = 0.0038 \text{ cm/s}$$

$$(2\pi)^{1/2} = \left(1000 \times \frac{2\pi}{60} \times 0.01 \right)^{1/2} = 1.02 \text{ cm/s}$$

$$\text{so } u_0^* = 0.0038 \text{ at 1000 RPM}$$

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$$Sc = \frac{D}{\Delta} = \frac{0.01}{1.8 \times 10^{-5}} = 555$$

$$\therefore Sc^2 u_0^{*3} = 0.016$$

A numerical solution shows $g'(0) \sim \frac{1}{2}$ (not exact), so from scaling

$$c^*|_{z^*=0} \sim 1 + 0.016 \quad \text{at this rotation rate.}$$

At 100 RPM, however, $(\sqrt{2})^{1/2} \sim 0.32 \text{ cm/s}$

and thus:

$$c^*|_{z^*=0} \sim 1 + 0.5$$

so we are starting to see buildup of K^+

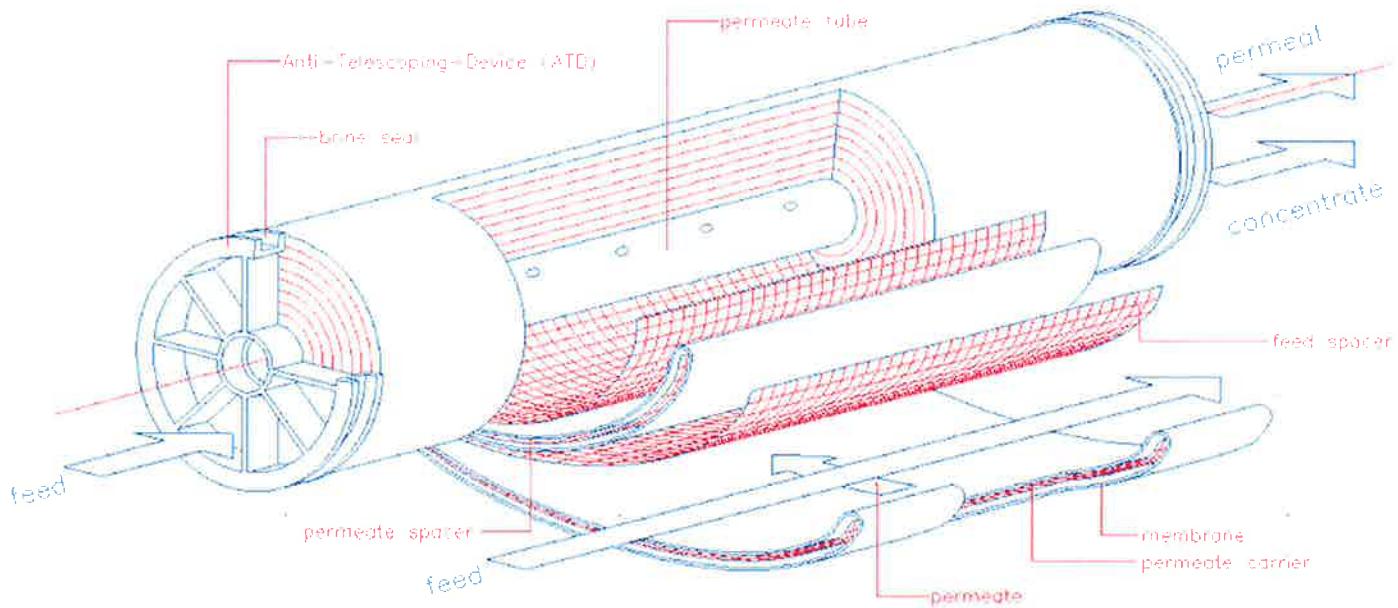
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The rotating membrane considered on the last lecture was particularly useful for the study of a small membrane sample, for larger scale systems two other geometries are much more useful: spiral wound and hollow fiber modules. Let's look at these!

An industrially important membrane application is seawater desalination using spiral wound RO (reverse osmosis) membranes. These allow water to pass, but reject $\sim 99.8\%$ of the salt, yielding drinkable water!

The active membrane is a polyamide layer on a porous backing. A blown up view of an SWRO is below:

FUNCTIONAL SCHEME OF A SPIRAL WOUND MODULE



(from Unisol Global)

The RO membrane forms a sealed pouch or envelope around a permeate spacer (porous mesh) and the open end is sealed to the permeate tube. These pouches are separated by the feed spacer (another porous mesh about 1 mm thick) and coiled up. The brine goes through axially, and the permeate goes in the Θ direction, winding up in the tube.

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Water is a pretty inexpensive (if vital) fluid, so costs of a desalination unit are critical. For SWRO this is capital cost and recurring costs. The latter is membrane replacement due to fouling and energy. Let's look at energy costs!

This is all on pumping! For a 100% efficient pump, the energy cost is:

$$\frac{E}{\text{time}} = Q \Delta P$$

↑ ↑
Vol flow pressure
rate applied

The problem is that the pressure necessary must exceed the osmotic pressure of seawater at the concentrated exit to get anything out! $\Delta P_{\text{osm}} \Big|_{\text{seawater}} = 27 \text{ atm}!$

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Concentration polarization and flow

losses make the energy cost higher!

Suppose we have a membrane w/ hydraulic permeability K_H . Our local flux

$$\text{is } j_w = K_H (\Delta P - \Pi_m)$$

$$\text{where } \Pi_m = \frac{z C_m R T}{2.0}$$

\uparrow conc. at membrane
for dissociated salt

$$\text{In general } \Pi_m = \Pi e^{\left(\frac{j_w / K_m}{n}\right)}$$

\downarrow osmotic pressure in feed layer mass transf. coef to membrane

$$\text{where } K_m = \frac{D}{8} \rightarrow \text{BL thickness}$$

You need to use empirical data to get K_m

Π changes along the length too!

From a mass balance:

$$\Pi = \Pi_F \frac{Q_F}{Q_F - \int_0^z j_w \frac{A}{L} dz}$$

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where L is the length of the module and A is the total area. Π_F , Q_F are the feed osm. pressure and flow rate.

ΔP is reduced w/ π due to pressure losses flowing through the 1mm thick feed spacer mesh.

If you have all these parameters you can predict performance - but what is the best you can do? (No losses! No polarization!)

We can define a minimum specific energy consumption.

Suppose we have a feed flow rate Q_F and permeate flow rate Q_P . We have a recovery ratio $RR = Q_P/Q_F$.

What is the optimal choice for RR ?

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$$\text{our SEC} = \frac{Q_F (P_F - P_p)}{Q_p} \approx \frac{Q_F P_F}{Q_p} = \frac{P_F}{RR}$$

where P_p is usually ~ 0 (language)

Now our pressure at the feed must be greater than the osmotic pressure at the exit

$$\pi|_{z=L} = \pi_F \frac{Q_F}{Q_F - Q_p} = \pi_F \frac{1}{1 - RR}$$

$$\text{so SEC} = \frac{\pi_F}{RR(1 - RR)}$$

This has a minimum when $RR = \frac{1}{2}$
(half is filtered).

For salt water the best you could do
is $\sim 4\pi_F$ (ignoring recovery - later...)

Now $\pi_F = 27 \text{ atm}$ so it takes $\sim 4 \times 2.7 \text{ MJ}$
to obtain 1 m^3 permeate. $1 \text{ kwhr} = 3.6 \text{ MJ}$

$$\text{so this is } \frac{4 \times 2.7}{3.6} = 3 \text{ kwhr / 1 m}^3$$

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You always have losses, so the number goes up from this - but you can also recover some energy from the brine coming off at high pressure. In fact, if you get complete recovery, your energy cost goes to $SEC = \frac{\pi_f}{1-RR}$ and the optimum shifts to lower RR.

Current systems are as low as $2.5 \text{ kwh}/\text{m}^3$ so you are close to optimum; increasing K_H doesn't save you much! Lots of trade offs: higher K_H means more flux/area - so lower capital costs.

But higher flux means more conc. polarization and more rapid fouling!

Main area for improvement: cheaper, more selective membranes with comparable K_H !

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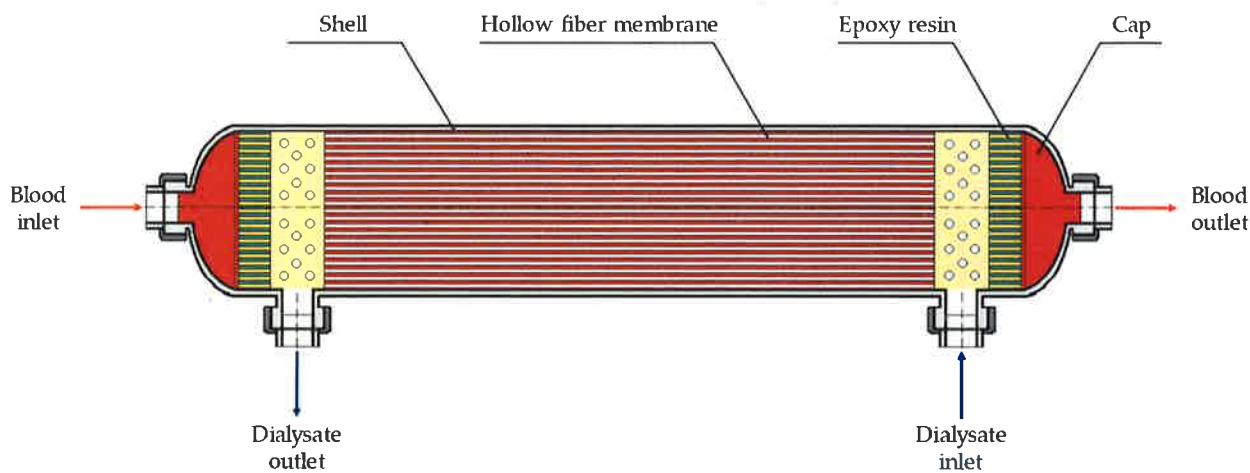
While increasing membrane performance can't do much on energy consumption, other methods such as staging (so not all the feed is at the final pressure) does help some.

Still, the absolute minimum is 0.75 kwhr/m^3 (no losses anywhere, total recovery of ΔP , etc.) and current systems get within ~3x of this.

Improving K_H does have a large impact on waste water treatment because Π_F is far lower and so other losses are more significant! Other applications such as metal ion separations are also significant. (These aren't RO membranes, but use other mechanisms). An active area of research!

Another critical application of cross-flow filtration is hemodialysis: the use of hollow fiber membranes to remove undesired waste products from blood. This procedure is done nearly 1 M times per year in the US!

Your kidneys are remarkable active filters, removing urea & other compounds you don't want from the blood, maintaining salt & fluid balance, & even pumping glucose (which gets through the filters) back into the blood! It processes about 180 l/day of fluid! If it fails you have renal failure which requires (until a transplant is available) dialysis 3 times/wk for 3-4 hours each using a hollow fiber membrane



From: Performance Comparison of Alternative Hollow-Fiber Modules for Hemodialysis by Means of a CFD-Based Model, Nunzio Cancilla, et al., Membranes 2022

Blood is drawn from a patient, injected w/ heparin to prevent clotting, and pumped through the tube side of a hollow fiber bundle. The Dialysate flows through the shell side. Unlike R/O membranes, the fibers are permeable to ions & small molecules. Water moves across due to both hydrostatic and osmotic pressure.

You need to remove water - but not too much! (or too little)

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The exact composition of the dialysate (and the patient's blood pressure) must be matched throughout the process.

OK, so what does the mass transfer process look like? A lot like a shell & tube heat exchanger!

We have a mass transfer coef. for the lumen (k_L), the membrane (K_m) and the shell (k_S). The overall transfer coef. is:

$$\frac{1}{K_o} = \left(\frac{1}{k_L} + \frac{1}{K_m} + \frac{1}{k_S} \right)^{-1}$$

(add resistances)

Originally the resistance of the membrane was very high (low flux cellulose acetate membranes). Now hemodialysis is moving toward high flux low resistance.

membranes. This does interesting things: because of pressure drop in the lumen the direction of flow can be reversed at the distal end: convection into the lumen. This can be useful, but requires careful control of pressure differential.

What is a typical hollow fiber system?

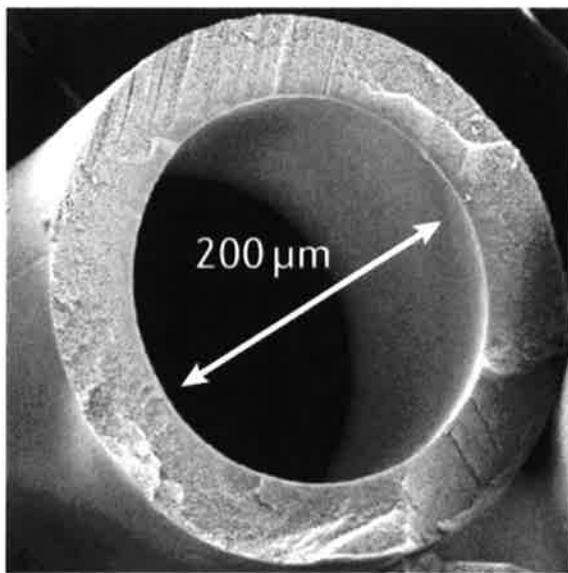
Bundle of $\sim 15\text{K}$ fibers, $200\mu\text{m ID}$

asymmetric membrane, $\sim 20\text{ cm long}$.

Total flow is $\sim 300\text{ mL/min}$

Human blood vol $\sim 5\text{L}$, so $\sim 17\text{ min}$ for exchange (but regard person as CSTR - only a small fraction is processed on each pass). $\sim 10 \times$ volume filtered in each session.

Polyethersulfone
Wall thickness 30 µm



Haemodialysis membranes
Claudio Ronco & William R. Clark
Nature Reviews Nephrology volume 14, pages 394–410 (2018)

It is interesting to look at some parameters:

$$U = \frac{Q}{A} = 1 \text{ cm/s} \text{ in each fiber}$$

$$Re = \frac{UD}{\eta} = \frac{(1)(0.02 \text{ cm})}{0.05 \text{ cm}^2/\text{s}} = 0.4 \ll 1$$

↪ viscosity of blood

$$\dot{\gamma}|_{\text{wall}} = \frac{1 \text{ cm/s}}{0.01 \text{ cm}} \times 4 = 400 \text{ s}^{-1}$$

this is less than the critical shear rate
for cell lysis of $\sim 1000 \text{ s}^{-1}$

$$\Delta P = L \mu \frac{8U}{d} \approx 800 \frac{\text{dynes}}{\text{cm}^2} = 80 \text{ Pa}$$

For whole blood, diffusion is actually
dominated by shear-induced dispersion.

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This is the dispersion caused by the motion of the RBC's in the shear flow. This is characterized by $\dot{\gamma}a^2$

→ RBC radius $\sim 4\mu\text{m}$

for $\dot{\gamma} = 400 \text{ s}^{-1}$ this is $\sim 6 \times 10^{-5} \text{ cm}^2/\text{s}$, much greater than the molecular dif. of proteins or large molecules. It's comparable to the diffusivity of small molecules.

For small molecules resistance to mass transfer is dominated by transport in the blood, but for larger molecules it is diffusion through the membrane. Thus, exact choice of membrane material and dialysate (and operating conditions) needs to be optimized for each patient - a tough problem!

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In many systems from charged membrane separations to electrokinetic flows, the behavior of ions in aqueous media plays a crucial role. There are a number of elective courses available dedicated to this topic - here we will just look at some of the basics.

The starting point is Maxwell's Equations for the electric field in a vacuum:

$$\epsilon_0 \nabla \cdot \mathbf{E} = \rho^{(e)} ; \nabla \times \mathbf{E} = 0$$

$\rho^{(e)}$ = electric charge/volume

ϵ_0 = permittivity of the vacuum

\mathbf{E} is the electric field vector

If we apply this to a spherical volume containing total charge Q

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$$\text{we get } \tilde{E} = \frac{Q}{4\pi\epsilon_0 r^3} \hat{r}$$

so the electric field (like gravity!) goes as $\frac{1}{r^2}$. If you have two charges Q_1 & Q_2 sep. by r_{12} the force is:

$$\tilde{F}_{12} = \tilde{E}_1 Q_2 = \frac{Q_1 Q_2}{4\pi\epsilon_0 r_{12}^3} \hat{r}_{12}$$

Now because $\nabla \times \tilde{E} = 0$ (irrotational) it must be represented as the gradient of a scalar (potential)

$$\tilde{E} = -\nabla \psi$$

Plugging this into Maxwell's eq'n we get: $\epsilon_0 \nabla^2 \psi = -\rho^{(e)}$

So around an isolated charge Q :

$$\psi = \frac{Q}{4\pi\epsilon_0 r} r^{-1}$$

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If you have a sphere of radius a and charge Q , the surface potential ψ_s is just $\psi_s = \frac{Q}{4\pi\epsilon_0 a}$.

This was for a vacuum. In a dielectric medium the capacitance ($4\pi\epsilon_0 a$) increases due to polarization. This is due to orientation of permanent dipoles and deformation of electron clouds.

We define a polarization vector \tilde{P}
 s.t. $\tilde{P} = N \frac{\uparrow \text{dipoles}}{\text{vol}} Q \underset{\substack{\text{charge separated to} \\ \text{produce dipole}}}{\text{distance}} \underset{\substack{\text{orientation of} \\ \text{separation}}}{\text{}}$

For a linear dielectric

$$\tilde{P} = N \times \epsilon_0 \tilde{E}$$

\hookrightarrow polarizability of mat'l (units L^3)

The product $\chi\epsilon_0$ is the electric susceptibility of the material $\chi \equiv N \alpha$. If we have a non-zero divergence of \mathbf{P} we get an effective charge! This is known as the polarization charge density

$$\rho^{(p)} : \nabla \cdot \mathbf{P} = -\rho^{(p)}$$

combining this with the total charge density we get :

$$\epsilon_0 \nabla \cdot \mathbf{E} = \rho^{(e)}$$

$$\epsilon_0 \nabla \cdot \chi \mathbf{E} = -\rho^{(p)}$$

$$\therefore \epsilon_0 \nabla \cdot (1 + \chi) \mathbf{E} = \rho^{(e)} - \rho^{(p)} = \rho^{(f)}$$

where $\rho^{(f)}$ is the free charge density

Now if there are no free charges, then

$$\epsilon_0 \nabla \cdot (1 + \chi) \mathbf{E} = 0$$

If we put a charged sphere in our dielectric there will be an effective polarization charge at the surface

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which reduces the potential & electric field. Putting this together you get

$$Q = 4\pi \epsilon_0 (1+\chi) a \psi_s$$

ϵ : dielectric constant
of the material

What does this do?

- 1) For a given ψ_s (surface potential, voltage) it increases the charge (capacitance). That's why capacitors have high ϵ !
- 2) For a given charge it reduces ψ_s and the electric field. This reduces the force between two charges by a factor of ϵ too!

All this was for dielectrics w/ no free charge (e.g., no ions). In aqueous solutions ions respond to the electric field to produce a non-uniform dist!

In an aqueous system, surfaces tend to acquire a charge! While this can be due to a different affinity for electrons or ionizable species it is often due to ionizable species that are bound to the surface: a sialic acid group on the surface of an RBC will ionize, leaving a bound negative charge. Proteins are usually amphoteric where amine groups will protonate (yielding + charge) or COOH groups will ionize (yielding - charge) depending on the pH!

At a charged surface in an electrolyte the counter ion will be attracted by the electric field, but will also diffuse away. This leads to the

"diffuse layer": we need to model
this!

At equilibrium,

$$\epsilon \epsilon_0 V^2 4 = -\varphi^{(P)}$$

For a particular ion K the force on the ion balances the gradient in the chemical potential: $\downarrow_{K}^{\text{charge (sign) of } K^+ \text{ ion}}$

$$kT \nabla \ln n^K + e z \nabla \varphi = 0$$

$\uparrow_{\text{Boltzmann's const.}}^{\text{of } K}$ $\uparrow_{\text{* density electron of } K^+ \text{ charge ion}}$ $\nabla \varphi \rightarrow E \text{ (elec. field)}$

If we integrate this we get Boltzmann distribution:

$$n^K = n_b^K e^{-\left(\frac{e z^K \varphi}{kT}\right)}$$

where n_b^K is the concentration where $\varphi = 0$

Now in your electrolyte you have at least two types of ions! The free charge density is the excess charge from the mixture. Thus:

$$\delta^{(f)} = \sum_1^N e z^k n^k$$

Putting this together, you get the Poisson-Boltzmann eqn:

$$\epsilon \epsilon_0 \nabla^2 \psi = -e \sum_1^N z^k n_b^k e^{-\left(\frac{e z^k \psi}{kT}\right)}$$

This equation has the B.C. at the surface $-\epsilon \epsilon_0 \nabla \psi \cdot \hat{n} = \sigma$ where σ is the surface charge density which is driving the non-uniform ion distribution.

Suppose we have a flat interface and a Z-Z electrolyte (e.g., $\text{Na}^+ \text{Cl}^-$)

our balance becomes:

$$\frac{d^2\psi}{dx^2} = \frac{2eZ}{\epsilon\epsilon_0} n_b \sinh(eZ\psi/kT)$$

If $eZ\psi/kT \ll 1$ (small potentials)

we get the Debye - Hückel approx:

$$\frac{d^2\psi}{dx^2} = \left(\frac{2e^2 Z^2 n_b}{\epsilon\epsilon_0 kT} \right) \psi$$

(\rightarrow units of $\frac{1}{L^2}$)

We can use this to define a Debye decay length (or double layer thickness)

$$\kappa^{-1} \equiv \left(\frac{\epsilon\epsilon_0 kT}{2e^2 Z^2 n_b} \right)^{1/2}$$

This is the length scale of the cloud of counter ions near a charged surface!
It is also the most important part

of this lecture! The key is the relationship between K^{-1} and, say, pore radii. If you have a pore w/ fixed surface charges whose diameter is less than K^{-1} then the surface charge modifies the ion distribution across the pore and you can get selective ion transport! If K^{-1} is smaller than the pore diameter, the pore is unaffected (mostly) by the surface charge!

So how big is it?

$$K^{-1} = \left(\frac{\epsilon \epsilon_0 kT}{2 e^2 z^2 n_b} \right)^{1/2}$$

Water: $\epsilon = 80$ (dimensionless)

$$T = 298^\circ K$$

$$\varepsilon_0 = 8.854 \times 10^{-12} \frac{F}{m}$$

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Farad

$z = 1$ (e.g., NaCl)

$$K = 1.381 \times 10^{-23} \text{ m}^2 \text{ kg/s}^2 \text{ F}^2$$

OK, now for n_b : this is the salt concentration. Say we have a 0.01M solution of NaCl:

$$n_b = 0.01 \frac{\text{moles}}{\text{L}} \times 1000 \frac{\text{L}}{\text{m}^3} \times 6.022 \times 10^{23}$$

(oh⁻ and e = 1.602×10^{-19} coulombs)

So for these numbers:

$$K^{-1} = 3.07 \times 10^{-9} \text{ m} = 3 \text{ nm}$$

As an example, Prof Bruening's Li⁺/K⁺ separation w/ 15 nm radius pores works fine at 2×10^{-4} M ionic strength, but fails at 0.2 M ionic strength. At 2×10^{-4} M (0.2 mM) $K^{-1} = 22 \text{ nm}$, greater than the pore radius. At 0.2 M

$K^{-1} = 0.7 \text{ nm}$, much less than the pore radius!

It is interesting that there is an exact solution to the potential without linearizing.

If we define $\bar{\Psi} = \frac{e z \Psi}{kT}$ (e.g., normalized)

we get:

$$\bar{\Psi} = 2 \ln \left(\frac{1 + e^{-Kx} \tanh(\frac{1}{4} \bar{\Psi}_s)}{1 - e^{-Kx} \tanh(\frac{1}{4} \bar{\Psi}_s)} \right)$$

$$\text{and } q = 2 (2 \varepsilon \varepsilon_0 K T n_b)^{1/2} \sinh(\frac{1}{2} \bar{\Psi}_s)$$

Now if $\bar{\Psi}_s$ is small, we get the linearized result. If $\bar{\Psi}_s \gg 1$, however,

$$\bar{\Psi} \sim 4 \tanh(\frac{1}{4} \bar{\Psi}_s) e^{-Kx}$$

away from the surface. since $\tanh(\frac{1}{4} \bar{\Psi}_s) \rightarrow 1$ at large $\bar{\Psi}_s$, the

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Potential and electric field away from the surface behave as if there is a saturation potential $\Psi_s = \psi$ no matter how large the charge is!

All this is for a flat plate. If we have a colloidal particle it's usually a sphere of radius a ! The behavior depends on ka - the ratio of the radius to the Debye length. If $ka \ll 1$ (say, a nanoparticle in a dilute electrolyte) then the force between two charged spheres is :

$$F \approx 2\pi\epsilon\epsilon_0 \left(\frac{kT}{ze}\right)^2 ka \Psi_s \frac{e^{-Kh}}{1+e^{-Kh}}$$

where h is the separation distance

If $ka \gg 1$ (usual case)

$$F \approx 32\pi\epsilon\epsilon_0 \left(\frac{kT}{ze}\right)^2 ka \left[\tanh\left(\frac{\psi}{\Psi_s}\right)\right]^2 e^{-Kh}$$

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The rapid decrease (exponential) w/ K_h means that decreasing K^{-1} (e.g., increasing K) reduces the force. Since K^{-1} goes as $\frac{1}{n_b^{1/2}}$, increasing salt concentration reduces electrostatic repulsion! That means adding salt to a colloidal suspension usually leads to aggregation as attractive short-range van der Waals forces take over!

Next lecture we'll look at what happens in an imposed electric field: electroosmosis & electrophoresis!

Because of the net free charge in the diffuse layer, if you apply a tangential electric field you get motion! This is called electroosmosis and is very useful in μ fluidic systems.

First, what is the free charge density $\delta^{(f)}$? Recall that we had

the Boltzmann distribution:

$$n^k = n_b e^{-\frac{eZkT}{kT}}$$

we defined $\Psi = \frac{eZkT}{kT} - \Psi(\frac{ZkT}{Z})$ +1 or -1
dep. on + or -
charge

$$\text{so } n^k = n_b e^{-\Psi(\frac{ZkT}{Z})}$$

That's because, say, positive ions are attracted to a negative surface & neg. ions are repelled!

Suppose we have a $Z-Z$ electrolyte where the bulk concentration of each is n_b

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(They have to be the same for electro-
neutrality). The net free charge is:

$$g^{(f)} = e \sum n^k z^k = e n_b z \left(e^{-\bar{\Psi}} - e^{\bar{\Psi}} \right)$$

For 1-1 electrolytes, $z=1$

We also had, for some surface potential $\bar{\Psi}_s$:

$$\bar{\Psi} = 2 \ln \left(\frac{1 + e^{-Kx} \tanh(\frac{1}{4}\bar{\Psi}_s)}{1 - e^{-Kx} \tanh(\frac{1}{4}\bar{\Psi}_s)} \right)$$

$$\text{so } e^{-\bar{\Psi}} = \left(\frac{1 - e^{-Kx} \tanh(\frac{1}{4}\bar{\Psi}_s)}{1 + e^{-Kx} \tanh(\frac{1}{4}\bar{\Psi}_s)} \right)^2$$

and $e^{\bar{\Psi}}$ is just the inverse.

It is convenient (but not necessary!) to work w/ the low $\bar{\Psi}_s$ limit:

$$\bar{\Psi} \approx \bar{\Psi}_s e^{-Kx}$$

$$\text{and so } g^{(f)} = -2e n_b z \sinh(\bar{\Psi})$$

$$x = -2e n_b z \bar{\Psi}_s e^{-Kx}$$

If we recall that $\kappa^{-1} = \left(\frac{\epsilon \epsilon_0 kT}{2e^2 z^2 n_b} \right)^{1/2}$

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we can recast this as:

$$\phi^{(f)} \approx -\epsilon \epsilon_0 \kappa^2 \psi_s e^{-\kappa x}$$

or, as usually written,

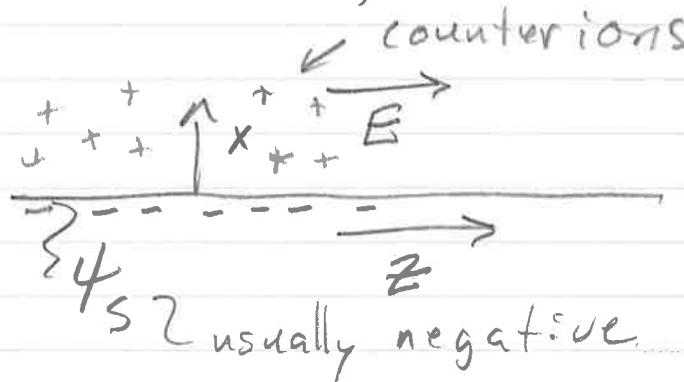
$$\phi^{(f)} = -\epsilon \epsilon_0 \kappa^2 \zeta e^{-\kappa x}$$

known as the zeta potential

The ζ zeta potential is known as the potential at the shearing surface, but for small ζ it is just ψ_s - for large potentials there is a "bound" Stern layer of counter-ions that have low mobility.

Ok, now we apply a tangential field

E .



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There is a force per volume on the fluid:

$$\sigma = \mu \frac{\partial^2 u_z}{\partial x^2} + \sigma^{(f)} E$$

$$\text{so: } \frac{\partial^2 u_z}{\partial x^2} = - \frac{\sigma^{(f)} E}{\mu} = \frac{\epsilon \epsilon_0 K^2 \xi}{\mu} e^{-Kx} E$$

Let's scale:

$$x^* = Kx \quad u_z^* = \frac{u_z}{U_c}$$

~~$$\therefore K^2 U_c \frac{\partial^2 u_z^*}{\partial x^{*2}} = E \frac{\epsilon \epsilon_0 K^2 \xi}{\mu} e^{-x^*}$$~~

$$\therefore U_c = \left(\frac{\epsilon \epsilon_0 \xi}{\mu} \right) E$$

$$\text{and } \frac{\partial^2 u_z^*}{\partial x^{*2}} = e^{-x^*}$$

Integrating once:

$$\frac{\partial u_z^*}{\partial x^*} = -e^{-x^*} + C_1$$

At infinity the stress is zero, so $C_1 = 0$

Integrating again:

$$u_z^* = e^{-x^*} + C_2$$

$$\text{but } u_z^*|_{x^*=0} = 0 \quad (\text{no-slip}) \therefore C_2 = -1$$

$$\text{so } u_z^* = e^{-x^*} - 1$$

Far away (but remember how short K^{-1} is!)

$$u_z^* = -1$$

So our electroosmotic velocity is just $-U_0$!

The quantity $\frac{\epsilon\epsilon_0\zeta}{\mu}$ is the electroosmotic mobility. Note that this is independent of n_b ! It only depends on ζ and fluid properties!

Why? If n_b increases, so does $\zeta^{(f)}$ but since K^{-1} decreases viscous drag (which goes as K^2) cancels this out!

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So what is $\mu_{eo} = \frac{\epsilon \epsilon_0 \xi}{\mu}$ = electroosmotic mobility?

We can plug in some numbers!

Say $\xi = 100 \text{ mV}$ (typical value)

$\mu = 10^{-3} \text{ Pas}$ (or 1 cP) and $\epsilon = 80$ (water)

This yields:

$$\mu_{eo} = 7.08 \times 10^{-8} \frac{\text{m/s}}{\text{V/m}}$$

The more usual units are:

$$\mu_{eo} = 7.08 \frac{\text{mm/s}}{\text{V/cm}}$$

as microfluidic channels are pretty short!

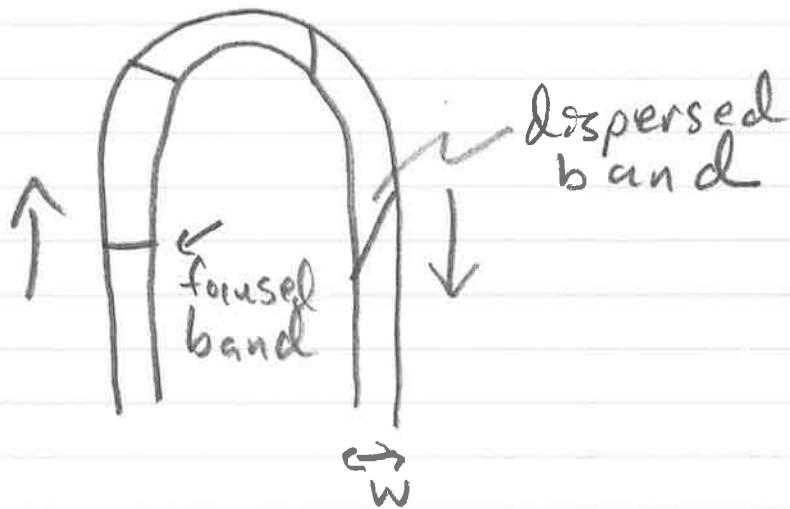
This is a good approx provided ξ isn't too big. For larger values, just integrate the exact solution numerically!

EO velocities are small, but they are very useful for driving fluid through thin channels! For pressure driven flow

The velocity goes as depth². That means that for, say, $50\mu\text{m}$ deep channels you need a large ΔP ! For EO the velocity is order of depth.

Another advantage - there's no shear as you get plug flow - essentially slip at the walls! For a straight channel there's no dispersion!

Now for disadvantage: For a large aspect ratio channel curves are huge sources of dispersion due to the "race track effect":



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The explanation is simple: The inside of the 180° bend is πW shorter than the outside. This means a higher electric field and a shorter distance. A focused band smears out by $2\pi W$ after every bend, which really adds up on a serpentine channel (needed for length). Modifications to the width profile can reduce this, but it's still a problem!

Another issue is the generation of the electric field. To get any field beyond K^{-1} thickness (really short) you have to have a current! That means an electrode reaction at each end! This is usually producing electrolysis, acid & base (pH change) and bubbles -

all of which cause trouble!

A last disadvantage: If you have a slug of mixed solutes, the electric field will separate them. This can be undesirable, but is actually the basis of capillary electrophoresis, our next topic!

Suppose we have a particle of radius a and surface charge Q . If $Ka \ll 1$ (e.g. really small particle or a low n_0) then the diffuse layer is spread out! If we apply an electric field E_∞ then the force is just $E_\infty Q$. This is balanced by Stokes Law drag:

$$E_\infty Q = 6\pi\mu La u$$

The electrophoretic mobility of the particle is :

$$\mu_{\text{ep}} = \frac{Q}{6\pi\mu a} ; u = \mu_{\text{ep}} E_{\infty}$$

For a thin double layer $Ka \gg 1$ and we have a more complicated result. Essentially, you get EO flow at the surface of the particle (in the double layer) and the particle moves in the opposite direction of this!

We get :

$$u = \frac{Q}{4\pi\mu a} \frac{1}{Ka} E_{\infty}$$

or, in terms of the ξ potential :

$$u = \frac{\epsilon \epsilon_0 \xi}{\mu} E_{\infty}$$

which is indep of a as $\frac{Q}{4\pi a^2}$ is the charge density

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Because of this, mobilities in an electric field are used to measure the potential of colloids.

So how is this used in capillary electrophoresis? A mixture of analytes (pos or neg charge!) are drawn through the capillary by electroosmosis: The EO velocity needs to be higher than the neg. vel of opposite charge species.

Species w/ different charge or size move w/ dif. velocities and separate into bands for detection at the end of the capillary.

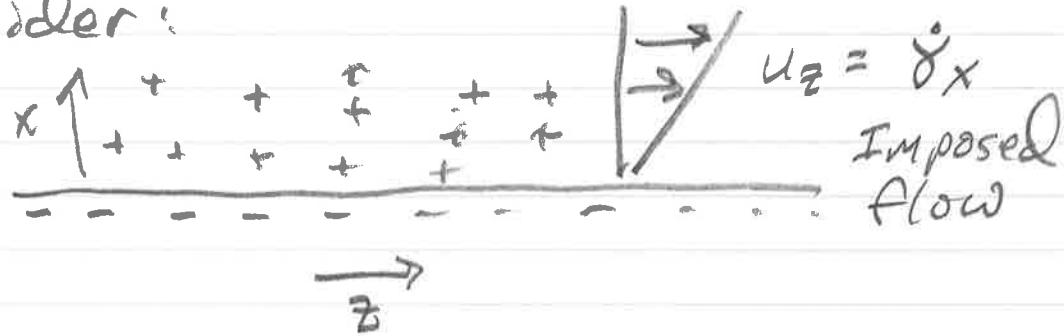
A key is initial focusing of the band at injection using stacking: If you suspend the analyte in a low conc. buffer at the entrance it will focus at the

lead edge due to a higher electric field in the initial slug (low conductivity = high field for same current).

Other tricks are things like iso-electric focusing: The charge on a protein depends on the pH. If you put it in an axial pH gradient it will focus at its isoelectric point (pH of neutral charge) and be convected along w/ the EO velocity. Many other variations have also been developed!

Another way the diffuse layer, EO and electrophoresis can combine is if you also have a shear flow in the absence of an imposed electric field. This leads to a streaming potential.

Consider:



If there's no electric field the positive counter ions are swept along with the shear flow. This net current will (like a Van de Graaf generator) lead to a charge buildup! The current

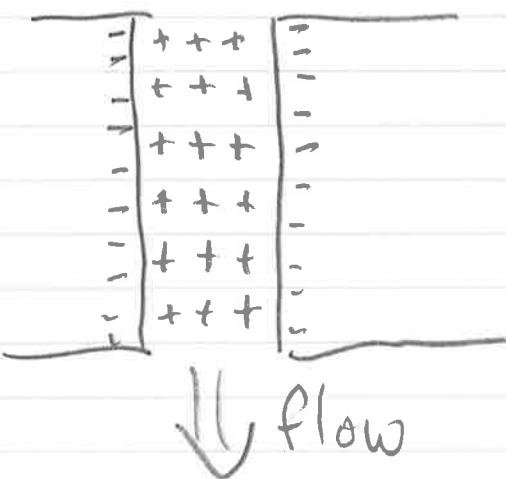
scales as $(K^{-1}\delta) K^{-1} \cdot w \cdot g^{(f)}$

$\underbrace{K^{-1}\delta}_{\substack{\text{char. vel.} \\ \text{velocity}}}$
 $\underbrace{w}_{\substack{\text{length} \\ \text{in to paper}}}$
 $\underbrace{g^{(f)}}_{\substack{\text{avg. free charge} \\ \text{extension}}}$

Since it goes as $(K^{-1})^2$ it is most important for large K^{-1} (low ion conc. in the bulk) and is quite a problem in pumping gasoline! Ground your pipes to avoid sparks!

This is also important for charged pores in membranes.

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If the pore radius is comparable to k_f^{-1} pressure driven flow leads to a net convection of counter ions across the membrane. By overall electro neutrality this leads to a membrane polarization and EO flow back the other way!

Polarization can also occur if a membrane is permeable to some ions but not others - Diffusion alone can lead to a Donnan potential - which is how your nerves work! Electrophysics is a huge subject! This is just an introduction!