Exploring the limits of mixed precision FEM based computations on the Tegra-K1 micro-architecture

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Content

- Mixed precision definition and history overview
 - History overview
 - Definition
- 2 Floating point operations
 - Precision
 - Computational precision vs accuracy of result
 - Floting point operations. A deeper analysis
- 3 Example calculation
 - Algorithm
 - Problem definition
 - Testresults

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A brief history overview

Trends:

- Memory clock speeds are increasing
 - GTX 980 Ti Memory clock speed: 2x 1753 MHz
 - GTX 1080 Memory clock speeds: 4x 2500 MHz (+185%)
- Alternative computing architectures
 - APU's
 - SoC's such as the NVIDIA Tegra K1 micro-architecture
- NVIDIA pushing the use of half precision.
 - half and half2 were announced as important new features in the CUDA Toolkit version 7.5 [1]
- ightarrow Sharing memory between CPU and GPU is becoming easier and more common

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Definition: Mixed precision algorithm

An algorithm that uses different precisions in its computation

Goal

Obtain the **same** accuracy by using high precision but **better performance** by utilizing low precision computations

Performance gains for bandwidth bound algorithms

- 64 bit = 1 double = 2 floats = 4 halfs
- More variables per bandwidth and variables per storage
- Applies to all memory levels: network, disc, cache, main, device, local, register

Performance gains for computation bound algorithms

- lacksquare 1 double addition pprox 2 float additions pprox 4 half additions (linear)
- 1 double multip. \approx 4 float multip. \approx 16 half multip. (quadratic)
- → up to 16 times better computational efficiency

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Challenges and past achievements

Challenges when it comes to Mixed precision

- Data has to be converted
- When using GPU accelleration data has to be transferred from the host to the device (usually) over the relatively slow PCIe bus
- We are being bottlenecked be memory interfaces
 - \rightarrow a lot of time is wasted while waiting for data

Past achievements:

In the year 2013. M. Madesen, S. L. Glimberg and A. P. Engsig-Karup were able to achieve a 38% performance increase using GPU accelerated mixed precision algorithms for full nonlinear water wave computation.[2]

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Roundoff and Cancellation

Definition Machine Precision

The smallest positive number ϵ for wich a floating point calculation evaluates the expression $1+\epsilon>1$ to be true.

Examples:

- $\epsilon_{double} \approx 2.220446049250313 \cdot 10^{-16}$
- $\epsilon_{float} \approx 1.1920929 \cdot 10^{-7}$
- $\epsilon_{half} \approx 9.765625 \cdot 10^{-4}$
- So more precision is usually better

Examples for cancellation effects in float

```
additive roundoff a = 1 + 0.00000004 = 1.00000004 = f_l \ 1 multiplicative roundoff b = 1.0002 \cdot 0.9998 = 0.999999996 = f_l \ 1 cancellation c \in \{a,b\} \qquad \pm 4 = (c-1) \cdot 10^8 = f_l \ 0 order of operations 1 + 0.00000004 - 1 = f_l \ 0 1 - 1 + 0.00000004 = f_l \ 0.0000004
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```

Computational precision vs accuracy of result

Instructive Example [S.M. Rump, 1988]

$$f(x,y) = (333.75 - x^2)y^6 + x^2(11x^2y^2 - 121y^4 - 2) + 5.5y^8 + 0.5x/y$$

 $x_0 = 77617, y_0 = 33096$

$$\begin{array}{ccc} {\rm float~s23e8} & & 1.1726 \\ {\rm double~s52e11} & & 1.17260394005318 \end{array}$$

The correct result is:

-0.82739605994682136814116509547981629

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Floting point operations. A deeper analysis

Number representation— almost all numbers have to be truncated

half s10e5 a	\mid 1 bit sign s_a	\mid 10 bit mantissa m_a	5 bit exp. e_a
float s23e8 b	1 bit sign s_b	23 bit mantissa m_b	8 bit exp. e_b
double s52e11 c	1 bit sign s_c	52 bit mantissa m_c	11 bit exp. e_c

multiplication		
	_	
precision	exact format	mantissa truncation:
half(a) · half(b)	s20e6	from 20 to 10 bit
float(a) · float(b)	s46e9	from 46 to 23 bit
double(a) · double(b)	s104e12	from 104 to 52 bit
addition		
precision	exact format	mantissa truncation:
half(a) + half(b)	s41e5	from 41 to 10 bit
float(a) + float(b)	s278e8	from 278 to 23 bit
double(a) + double(b)	s2099e11	from 2099 to 52 bit

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Algorithm 1 mixed precision iterative refinement

```
1: while ||r_{m-1}|| \cdot ||r_0||^{-1} > TOL do
2: r_m^h = b - Ax_m
3: r_m^l = r_m^h //convert from high to low precision
4: Ad_m^l = r_m^l //solve using a fixed number of iterations
5: d_m^h = d_m^l //convert from low to high precision
6: x_{m+1} = x_m + d_m
7: end while
```

- Mixed precision iterative refinement deals with the truncation errors of lower precision data formats
- The optimal number of inner iterations was empirically determined

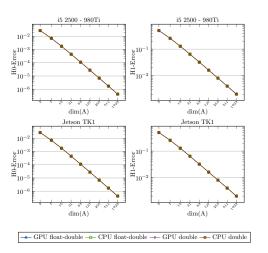
Problem definition and Hardware configuration

Problem

Solve the Poission problem $-\Delta u=1,\ x\in\Omega$ with dirichlet boundary conditions $u\equiv0,\ x\in\partial\Omega$ using conforming quadrilateral elements for the finite-element discretization of the unit square $\Omega=(-1,1)^2$

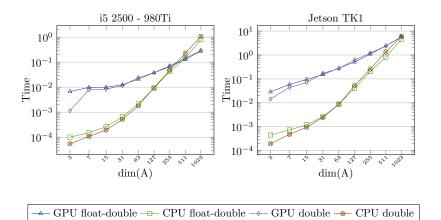
- Method 1: Using a V-cycle MG Solver
- Method 2: Using a V-cycle MG Solver inside of an iterative refinement loop
- Hardware configuration 1: i5 2500 + 980Ti
 →representing a high preformance convetional setup
- Hardware configuration 2: Tegra K1
 - \rightarrow representing alternative computing hardware

Testresults - Accuracy



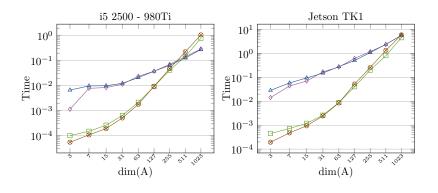
- (virtually) same accuracy as double calculation
- H0-Error is $O(m^2)$, H1-Error is $O(m^1)$. $[V_h = Q_1]$

Testresults - Performance on comodity Hardware



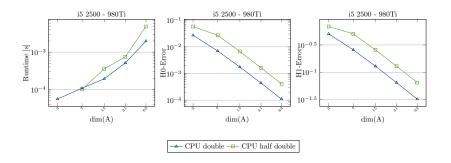
■ up to 57% increase in performance on x86

Testresults - Performance on the Tegra K1



- —— GPU float-double —— CPU float-double —→ GPU double —— CPU double
- up to 65% increase in performance on a Jetson TK1
- → Speedup of about 1.6
- \blacksquare \rightarrow performance model show that a speedup of 2 is optimal
- \blacksquare \rightarrow for longer calculations a speedup of 1.6 can save multiple days

Testresults - Half



 $lue{}$ Accuracy loss. Inner solver diverges at more than 63^2 DOF's.

Discussion and Future work

Future work

■ Try combining half, float and double precision in order to achieve an even greater performance increase

Thank you for your attention!

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