Task 3bc

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b

```
clear, clf
N = 2e6;
a = 1.4;
b = 0.3;
transient_length = 1e3;
epsilon_min = 1e-3;
epsilon_max = 2*1e-2;
epsilon_range = logspace(log10(epsilon_min), log10(epsilon_max),
1000);
x0 = 0; y0 = 0;
[x_data,y_data] = get_henon_data(x0, y0, transient_length, a, b, N);
x_min = min(x_data);x_max = max(x_data);
y_min = min(y_data);y_max = max(y_data);
plot0 = zeros(1,length(epsilon range));
plot1 = zeros(1,length(epsilon_range));
plot2 = zeros(1,length(epsilon_range));
for i_epsilon = 1:length(epsilon_range)
    epsilon = epsilon range(i epsilon);
    P = zeros(ceil((x_max - x_min)/epsilon), ceil((y_max-y_min)/
epsilon));
    for i_point = 1:length(x_data)
        x = x_{data(i_point)};
        y = y_data(i_point);
        P_x_{index} = floor((x - x_{min})/epsilon)+1;
        P_y_index = floor((y - y_min)/epsilon)+1;
        P(P_x_{index}, P_y_{index}) = P(P_x_{index}, P_y_{index}) + 1;
    end
    P = P/sum(sum(P));
    P nonzero = P(P \sim = 0);
    I0 = get_Iq(P_nonzero, 0);
    I2 = get_Iq(P_nonzero,2);
    plot0(i epsilon) = 1/(1-0) * log(I0);
    plot1(i_epsilon) = sum(P_nonzero.*log(1./P_nonzero));
    plot2(i_epsilon) = 1/(1-2)*log(I2);
```

```
end
clf
hold on
plot(log(1./epsilon_range), plot0, '.', 'MarkerSize', 10)
plot(log(1./epsilon_range), plot1, '.', 'MarkerSize', 10)
plot(log(1./epsilon_range), plot2, '.', 'MarkerSize', 10)
legend("$\ln[I(q = 0, \epsilon)]$", "$
\sum_{k=1}^{N_{boxes}}p_k\ln(1/p_k)", "$-\ln[I(q = 2,
\epsilon)]$", 'interpreter', 'latex', 'FontSize', 20)
set(gca, 'FontSize', 20)
xlabel('$\ln(\frac{1}{\epsilon})$', 'interpreter', 'latex')
title('Plot of quantities used to calculate $D_q
$ against $\ln(\frac{1}{\epsilon})$ for $q \in
\{0,1,2\}; 'interpreter', 'latex')
polyfit(log(1./epsilon_range), plot0, 1)
polyfit(log(1./epsilon_range), plot1, 1)
polyfit(log(1./epsilon_range), plot2, 1)
function Iq = get_Iq(P_nonzero, q)
    Iq = sum(sum(P_nonzero.^q));
end
function [x,y] = get_henon_data(x0, y0, transient_length, a, b, N)
    [x0, y0] = discard_initial_transient(x0, y0, transient_length, a,
 b);
    x = zeros(1, N);
    y = zeros(1, N);
    x(1) = x0;
    y(1) = y0;
    for n = 1:N-1
        x(n+1) = y(n) + 1 - a*x(n)^2;
        y(n+1) = b*x(n);
    end
end
function [x0, y0] = discard initial transient(x0, y0,
 transient_length, a, b)
    x = zeros(1, transient_length);
    y = zeros(1, transient_length);
    x(1) = x0;
    y(1) = y0;
    for n = 1:transient_length-1
```

C

```
x(n+1) = y(n) + 1 - a*x(n)^2;
y(n+1) = b*x(n);
end

x0 = x(transient_length);
y0 = y(transient_length);
end
```

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