

①

① One-step error probability in deterministic Hopfield model.

- Update rule: $S_i \leftarrow \text{sgn} \left(\sum_{j=1}^N w_{ij} S_j \right)$

- Weights:
$$\begin{cases} w_{ij} = \frac{1}{N} \sum_{\mu=1}^P y_i^{(\mu)} y_j^{(\mu)}, \text{ for } i \neq j \\ w_{ii} = 0 \end{cases}$$

- Input patterns: $\underline{y}^{(v)}$; $y_i^{(v)}$ - bit i of input pattern $\underline{y}^{(v)}$; $y_i^{(v)} = +1$ or -1 .

a) Condition for bit $y_i^{(v)}$ to be stable after a single step of asynchronous update?

Apply $\underline{y}^{(v)}$, obtain:

$$S_i = \text{sgn} \left[\sum_{j=1}^N w_{ij} y_j^{(v)} \right]$$

For stability of $y_i^{(v)}$ require: $\boxed{S_i \stackrel{!}{=} y_i^{(v)}} \quad (*)$

Rewrite the left-hand-side of Eq. (*):

$$\begin{aligned} S_i &= \text{sgn} \left(\sum_{j=1}^N w_{ij} y_j^{(v)} \right) = \text{sgn} \left[\sum_{j \neq i}^N \left(\frac{1}{N} \sum_{\mu=1}^P y_i^{(\mu)} y_j^{(\mu)} \right) y_j^{(v)} \right] \\ &= \text{sgn} \left[\frac{1}{N} \sum_{\substack{j=1 \\ j \neq i}}^N y_i^{(v)} \underbrace{y_j^{(v)} y_j^{(v)}}_{=1} + \frac{1}{N} \sum_{\substack{j=1 \\ j \neq i}}^N \sum_{\substack{\mu=1 \\ \mu \neq v}}^P y_i^{(\mu)} y_j^{(\mu)} y_j^{(v)} \right] \end{aligned}$$

$$S_i = \text{sgn} \left[\frac{N-1}{N} y_i^{(v)} + \frac{1}{N} \sum_{\substack{j=1 \\ j \neq i}}^N \sum_{\substack{\mu=1 \\ \mu \neq v}}^P y_i^{(\mu)} y_j^{(\mu)} y_j^{(v)} \right] \quad (\#)$$

(2)

Rewrite the right hand side of (#):

$$\text{RHS of (\#)} = \text{sgn} \left[y_i^{(v)} - \frac{1}{N} y_i^{(v)} + \frac{1}{N} \sum_{\substack{j=1 \\ j \neq i}}^N \sum_{\substack{\mu=1 \\ \mu \neq v}}^P y_i^{(\mu)} y_j^{(\mu)} y_j^{(v)} \right]$$

"cross-talk term"

Stability condition:

$$(**) \left| y_i^{(v)} = \text{sgn} \left[\left(1 - \frac{1}{N}\right) y_i^{(v)} + \frac{1}{N} \sum_{\substack{j=1 \\ j \neq i}}^N \sum_{\substack{\mu=1 \\ \mu \neq v}}^P y_i^{(\mu)} y_j^{(\mu)} y_j^{(v)} \right] \right|$$

Stability condition satisfied when:

$$\left| 1 - \frac{1}{N} y_i^{(v)} + \frac{1}{N} \sum_{\substack{j=1 \\ j \neq i}}^N \sum_{\substack{\mu=1 \\ \mu \neq v}}^P y_i^{(\mu)} y_j^{(\mu)} y_j^{(v)} \right| < 1$$

Alternatively, one can define $C_i^{(v)}$ as follows:

$$C_i^{(v)} = \frac{1}{N} - \frac{1}{N} \sum_{\substack{j=1 \\ j \neq i}}^N \sum_{\substack{\mu=1 \\ \mu \neq v}}^P y_i^{(\mu)} y_j^{(\mu)} y_j^{(v)} y_i^{(v)}$$

(= cross-talk term $\times (1 - y_i^{(v)})$)

Multiply (**) by $(1 - y_i^{(v)})$ and rewrite the stability condition (**) as follows:

$$\left| -1 = \text{sgn}(-1 + C_i^{(v)}) \right|$$

This condition is satisfied for $C_i^{(v)} < 1$.

Note: no limits were taken so far. In the limit of $N \gg 1$, $C_i^{(v)}$ is

$$C_i^{(v)} \approx -\frac{1}{N} \sum_{j=1}^N \sum_{\mu=1}^P y_i^{(\mu)} y_j^{(\mu)} y_j^{(v)} y_i^{(v)}, \text{ for } N \gg 1$$

(3)

b) Random patterns : $y_i^{(\mu)} = \begin{cases} +1, & \text{with prob. } \frac{1}{2}, \\ -1, & \text{with prob. } \frac{1}{2}. \end{cases}$

Bit $y_i^{(v)}$ is stable after a single step of asynchronous update if $C_i^{(v)} < 1$ (task a).

Therefore, the probability that $y_i^{(v)}$ is unstable is:

$$| \text{Perror} = \text{Prob} (C_i^{(v)} > 1) |$$

To evaluate Perror, consider $C_i^{(v)}$:

$$C_i^{(v)} = \frac{1}{N} - \frac{1}{N-1} \sum_{\substack{j=1 \\ j \neq i}}^N \sum_{\substack{\mu=1 \\ \mu \neq v}}^P y_i^{(\mu)} y_j^{(\mu)} y_i^{(v)} y_j^{(v)} \Rightarrow$$

$N \gg 1$

$$C_i^{(v)} \downarrow \approx - \frac{1}{N} \sum_{\substack{k=1 \\ k \neq i}}^{(p-1)(N-1)} \text{random variables } (x_k) \text{ with } \pm 1$$

[(p-1)(N-1) terms]

Since we assume $p \gg 1$ and $N \gg 1$, we can use the Central limit theorem (patterns are random!)

Variables x_k have the mean 0, and variance $\sigma_k^2 = 1$.

It follows that $C_i^{(v)}$ has the following properties:

- $C_i^{(v)}$ is approximately Gaussian distributed,
- the mean of $C_i^{(v)}$ is equal to 0 (since the mean of the random variables x_k is 0)
- the variance σ^2 of $C_i^{(v)}$ is :

$$\sigma^2 = \frac{1}{N^2} \cdot (N-1)(p-1) \sigma_k^2 \approx \frac{p}{N}$$

$$\Rightarrow \sigma^2 \approx \frac{p}{N} \quad (\text{since } p \gg 1, N \gg 1)$$

④

It follows that

$$\operatorname{erf}(z) = \frac{2}{\sqrt{\pi}} \int_0^z e^{-y^2} dy$$

$$P_{\text{error}} = \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x^2}{2\sigma^2}} dx = \frac{1}{2} \left[1 - \operatorname{erf}\left(\frac{1}{\sqrt{2}\sigma}\right) \right]$$

Gaussian distribution

$$\Rightarrow P_{\text{error}} = \frac{1}{2} \left[1 - \operatorname{erf}\left(\frac{1}{\sqrt{2} \frac{\sigma}{N}}\right) \right]$$

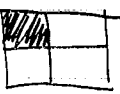
$$P_{\text{error}} = \frac{1}{2} \left[1 - \operatorname{erf}\left(\sqrt{\frac{N}{2\sigma^2}}\right) \right]$$

② Hopfield model: recognition of one pattern.

Stored pattern: $\underline{y}^{(1)} = \begin{pmatrix} 1 \\ -1 \\ -1 \\ -1 \end{pmatrix}$

weight matrix: $\underline{w} = \frac{1}{N} \underline{y}^{(1)} \underline{y}^{(1)T} = \frac{1}{4} \begin{pmatrix} 1 \\ -1 \\ -1 \\ -1 \end{pmatrix} \begin{pmatrix} 1 & -1 & -1 & -1 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix}$

- Feeding in the 2^4 possible patterns:

1) 

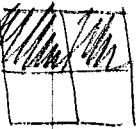
$$\underline{S}_0 = -\underline{y}^{(1)} = \begin{pmatrix} 1 \\ -1 \\ -1 \\ -1 \end{pmatrix}$$

$$\rightarrow \underline{S}_1 = \operatorname{sgn}\left(\underline{w} \underline{S}_0\right) = \frac{1}{4} \underline{y}^{(1)} \underline{y}^{(1)T} \underline{S}_0 = \frac{1}{4} \cdot 4 \underline{y}^{(1)} = \underline{y}^{(1)}$$

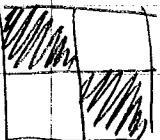
2) 

$$\underline{S}_0 = \begin{pmatrix} -1 \\ -1 \\ -1 \\ -1 \end{pmatrix}$$

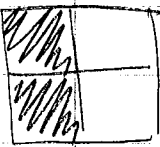
$$\rightarrow \underline{S}_1 = \operatorname{sgn}\left(\underline{w} \underline{S}_0\right) = \frac{1}{4} \begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ -1 \\ -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -1 \\ -1 \end{pmatrix} = \underline{y}^{(1)}$$

3) 
 $\underline{S}_0 = \begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix}$

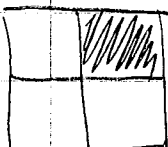
$$\rightarrow \underline{S}_1 = \text{sgn}(\underline{w}, \underline{S}_0) = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix} \right] = \begin{pmatrix} 1 \\ -1 \\ -1 \\ -1 \end{pmatrix} = \underline{y}^{(1)}$$

4) 
 $\underline{S}_0 = \begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix}$

$$\underline{S}_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix} \right] = \begin{pmatrix} 1 \\ -1 \\ -1 \\ -1 \end{pmatrix} = \underline{y}^{(1)}$$

5) 
 $\underline{S}_0 = \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix}$

$$\underline{S}_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} \right] = \begin{pmatrix} 1 \\ -1 \\ -1 \\ -1 \end{pmatrix} = \underline{y}^{(1)}$$

6) 
 $\underline{S}_0 = \begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix}$

$$\underline{S}_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix} \right] = \underline{\underline{\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}}}$$

Orthogonal pattern to the stored pattern. The network does not restore the stored pattern. In fact, it retrieves zero vector; failure of the network performance.

⑥

7)

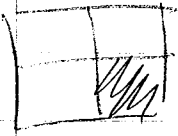


$$S_0 = \begin{pmatrix} -1 \\ -1 \\ 1 \\ -1 \end{pmatrix}$$

$$S_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ -1 \\ 1 \\ -1 \end{pmatrix} \right] = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Same as case 6 orthogonal pattern.

8)

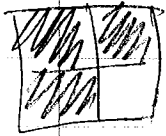


$$S_0 = \begin{pmatrix} -1 \\ -1 \\ -1 \\ 1 \end{pmatrix}$$

$$S_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ -1 \\ -1 \\ 1 \end{pmatrix} \right] = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Same as cases 6-7.

9)

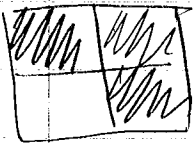


$$S_0 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ -1 \end{pmatrix}$$

$$S_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \\ -1 \end{pmatrix} \right] = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Same as cases 6-8.

10)

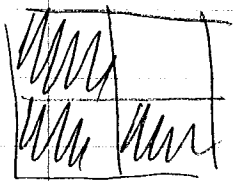


$$S_0 = \begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix}$$

$$S_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix} \right] = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Same as cases 6-9.

11)



$$S_0 = \begin{pmatrix} 1 \\ -1 \\ 1 \\ 1 \end{pmatrix}$$

$$S_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \\ 1 \\ 1 \end{pmatrix} \right] = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Same as cases 6-10.

(7)

12)

$$\underline{S}_0 = \begin{pmatrix} -1 \\ 1 \\ 1 \\ -1 \end{pmatrix}$$

$$\underline{S}_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ 1 \\ -1 \end{pmatrix} \right] = \begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\boxed{\underline{S}_1 = -\underline{y}^{(1)}}$$

13)

$$\underline{S}_0 = \begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\underline{S}_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ +1 \\ -1 \\ +1 \end{pmatrix} \right] = \begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\boxed{\underline{S}_1 = -\underline{y}^{(1)}}$$

14)

$$\underline{S}_0 = \begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\underline{S}_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ -1 \\ 1 \\ 1 \end{pmatrix} \right] = \begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = -\underline{y}^{(1)}$$

15)

$$\underline{S}_0 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\underline{S}_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right] = \begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow$$

$$\boxed{\underline{S}_1 = -\underline{y}^{(1)}}$$

16)

$$\underline{S}_0 = \begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\underline{S}_1 = \text{sgn} \left[\begin{pmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right] = \begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

In summary: In the first 5 cases, the network retrieves the stored pattern. 1.

Note: in cases 2, 3, 4, 5, the pattern that was fed had only one distorted bit in comparison to the stored pattern.
Case 1: fed pattern = stored pattern.

② In cases when more than 2 bits are distorted, the network retrieves the inverted version of the stored pattern (cases 12-16)

Cases 6-11 ③ When exactly $\frac{N}{2} = 2$ bits are distorted, the network fails to be unable to deal with patterns orthogonal to the stored pattern (due to Hebb's rule).

13] Back-propagation (two hidden layers)

- Two hidden layers.
- Input patterns $\underline{\xi}^{(1)} = (\xi_1, \xi_2, \dots, \xi_n)^T$
- Target output $p_1^{(1)}$
- Network output $O_1^{(1)}$
- First hidden layer: $V_j^{(1,1)} = g(b_j^{(1,1)})$, $b_j^{(1,1)} = \sum_i w_{ji}^{(1)} \xi_i^{(1)} - \theta_j^{(1)}$
- Second hidden layer: $V_k^{(2,1)} = g(b_k^{(2,1)})$, $b_k^{(2,1)} = \sum_j w_{kj}^{(2)} V_j^{(1,1)} - \theta_k^{(2)}$
- Output layer: $O_1^{(1)} = g(b_1^{(1)})$, $b_1^{(1)} = \sum_k W_{1k} V_k^{(2,1)} - \theta_1$

(9)

- Energy function: $H = \frac{1}{2} \sum_{\mu} (y_1^{(\mu)} - o_1^{(\mu)})^2$

- Gradient descent: find the parameters that minimise H .

- Start from the output layer:

$$\begin{aligned} \delta W_{1k} &= -\eta \frac{\partial H}{\partial W_{1k}} = -\eta \frac{\partial}{\partial W_{1k}} \left\{ \frac{1}{2} \sum_{\mu} [y_1^{(\mu)} - g(b_1^{(\mu)})]^2 \right\} = \\ &= -\eta \left[\sum_{\mu} [y_1^{(\mu)} - \underbrace{g(b_1^{(\mu)})}_{o_1^{(\mu)}}] \left(-\frac{\partial g(b_1^{(\mu)})}{\partial W_{1k}} \right) \right] = \\ &= \eta \left[\sum_{\mu} [y_1^{(\mu)} - o_1^{(\mu)}] \cdot \frac{\partial g(b_1^{(\mu)})}{\partial W_{1k}} \right] \end{aligned}$$

$$\frac{\partial g(b_1^{(\mu)})}{\partial W_{1k}} = \frac{\partial}{\partial W_{1k}} \left[g \left(\sum_l W_{1l} v_l^{(2,\mu)} - \Theta_1 \right) \right] =$$

$$= g'(b_1^{(\mu)}) \cdot v_k^{(2,\mu)}$$

$$\parallel \text{Since } \frac{\partial W_{1l}}{\partial W_{1k}} = \delta_{lk}$$

$$\Rightarrow \delta W_{1k} = \eta \sum_{\mu} [y_1^{(\mu)} - o_1^{(\mu)}] \cdot g'(b_1^{(\mu)}) \cdot v_k^{(2,\mu)} \quad \parallel \equiv \eta \sum_{\mu} \delta_1^{(3,\mu)} v_k^{(2,\mu)}$$

$$\delta \Theta_1 = -\eta \frac{\partial H}{\partial \Theta_1} = -\eta \frac{\partial}{\partial \Theta_1} \left\{ \frac{1}{2} \sum_{\mu} [y_1^{(\mu)} - g(b_1^{(\mu)})]^2 \right\} =$$

$$= -\eta \sum_{\mu} (y_1^{(\mu)} - o_1^{(\mu)}) \cdot \left(-\frac{\partial g(b_1^{(\mu)})}{\partial \Theta_1} \right) =$$

$$= \eta \sum_{\mu} (y_1^{(\mu)} - o_1^{(\mu)}) \cdot g'(b_1^{(\mu)}) \cdot (-1)$$

$$\Rightarrow \delta \Theta_1 = -\eta \sum_{\mu} (y_1^{(\mu)} - o_1^{(\mu)}) \cdot g'(b_1^{(\mu)}) \quad \parallel \equiv -\eta \sum_{\mu} \delta_1^{(3,\mu)}$$

$$\delta o_1^{(3,\mu)} = (y_1^{(\mu)} - o_1^{(\mu)}) g'(b_1^{(\mu)})$$

- Second hidden layer

$$\delta w_{kj}^{(2)} = -\eta \frac{\partial H}{\partial w_{kj}^{(2)}} = -\eta \frac{\partial}{\partial w_{kj}^{(2)}} \left\{ \frac{1}{2} \sum_{\mu} (y_1^{(\mu)} - o_1^{(\mu)})^2 \right\} =$$

$$= \eta \sum_{\mu} (y_1^{(\mu)} - o_1^{(\mu)}) \frac{\partial o_1^{(\mu)}}{\partial w_{kj}^{(2)}}$$

$$o_1^{(\mu)} = g(b_1^{(\mu)}) = g\left[\sum_l w_{1l} v_l^{(2,\mu)} - \theta_1\right] =$$

$$= g\left[\sum_l w_{1l} g(b_l^{(2,\mu)}) - \theta_1\right] =$$

$$= g\left[\sum_l w_{1l} g\left(\sum_{\Delta} w_{l\Delta}^{(2)} v_{\Delta}^{(1,\mu)} - \theta_l\right) - \theta_1\right]$$

$$\Rightarrow \frac{\partial o_1^{(\mu)}}{\partial w_{kj}^{(2)}} = g'(b_1^{(\mu)}) \cdot \frac{\partial}{\partial w_{kj}^{(2)}} \left[\sum_l w_{1l} g\left(\underbrace{\sum_{\Delta} w_{l\Delta}^{(2)} v_{\Delta}^{(1,\mu)}}_{= b_l^{(2,\mu)}} - \theta_l\right) - \theta_1 \right]$$

$$= g'(b_1^{(\mu)}) \cdot \sum_l w_{1l} g'(b_l^{(2,\mu)}) \cdot \frac{\partial b_l^{(2,\mu)}}{\partial w_{kj}^{(2)}} =$$

$$= g'(b_1^{(\mu)}) \cdot w_{1k} g'(b_k^{(2,\mu)}) \cdot v_j^{(1,\mu)} = \sum_{\Delta} v_{\Delta}^{(1,\mu)} \delta_{k\Delta} \delta_{j\Delta}$$

$$\Rightarrow \delta w_{kj}^{(2)} = \eta \underbrace{\sum_{\mu} (y_1^{(\mu)} - o_1^{(\mu)})}_{\delta_1^{(3,\mu)}} g'(b_1^{(\mu)}) \cdot w_{1k} g'(b_k^{(2,\mu)}) v_j^{(1,\mu)}$$

$$\delta w_{kj}^{(2)} = \eta \underbrace{\sum_{\mu} \delta_1^{(3,\mu)} w_{1k} g'(b_k^{(2,\mu)})}_{\delta_k^{(2,\mu)}} v_j^{(1,\mu)}$$

$$\boxed{\delta w_{kj}^{(2)} = \eta \sum_{\mu} \delta_k^{(2,\mu)} v_j^{(1,\mu)}}$$

Thresholds $\theta_k^{(2)}$:

$$\delta \theta_k^{(2)} = -\eta \frac{\partial H}{\partial \theta_k^{(2)}} = \eta \sum_{\mu} (y_1^{(\mu)} - o_1^{(\mu)}) \frac{\partial o_1^{(\mu)}}{\partial \theta_k^{(2)}}$$

from previous page

$$\frac{\partial o_1^{(\mu)}}{\partial \theta_k^{(2)}} \downarrow = g'(b_1^{(\mu)}) \frac{\partial}{\partial \theta_k^{(2)}} \left[\sum_{\ell} W_{1\ell} g\left(\sum_{\lambda} w_{\ell\lambda}^{(2)} v_{\lambda}^{(1,\mu)} - \theta_k^{(2)}\right) - \theta_1 \right]$$

$$= g'(b_1^{(\mu)}) \sum_{\ell} W_{1\ell} g'(b_{\ell}^{(2,\mu)}) (-1) \delta_{\ell k}$$

$$= -g'(b_1^{(\mu)}) \cdot W_{1k} g'(b_k^{(2,\mu)})$$

$$\Rightarrow \delta \theta_k^{(2)} = -\eta \sum_{\mu} \underbrace{(y_1^{(\mu)} - o_1^{(\mu)}) g'(b_1^{(\mu)})}_{\delta_1^{(3,\mu)}} W_{1k} g'(b_k^{(2,\mu)})$$

$$= -\eta \sum_{\mu} \underbrace{\delta_1^{(3,\mu)} W_{1k}}_{\delta_k^{(2,\mu)}} g'(b_k^{(2,\mu)})$$

$$\boxed{\delta \theta_k^{(2)} = -\eta \sum_{\mu} \delta_k^{(2,\mu)}}$$

For the first hidden layer we should proceed as above. Alternatively, we note that δ 's for the 3rd and 2nd layer obey the following relation:

$$\delta_k^{(2,\mu)} = \delta_1^{(3,\mu)} W_{1k} g'(b_k^{(2,\mu)})$$

We can use this to find the δ 's for the first hidden

layer:

$$\delta_j^{(1,M)} = \sum_k \delta_k^{(2,M)} w_{kj}^{(2)} g'(b_j^{(1,M)})$$

The update formulae are, therefore, as follows:

$$\text{Output layer: } \delta W_{1k} = \eta \sum_{\mu} \delta_1^{(3,M)} V_k^{(2,M)}$$

$$\delta \Theta_1 = -\eta \sum_{\mu} \delta_1^{(3,M)}$$

$$\text{Second hidden layer: } \delta w_{kj}^{(2)} = \eta \left(\sum_{\mu} \delta_k^{(2,M)} \right) V_j^{(1,M)}$$

$$\delta \Theta_k = -\eta \sum_{\mu} \delta_k^{(2,M)}$$

$$\text{First hidden layer: } \delta w_{ji}^{(1)} = \eta \sum_{\mu} \delta_j^{(1,M)} z_i^{(\mu)}$$

$$\delta \Theta_j = -\eta \sum_{\mu} \delta_j^{(1,M)}$$

Summation over μ only for batch mode!
Other wise = no summation!

Here we have the following:

$$\delta_1^{(3,M)} = (y_1^{(M)} - o_1^{(M)}) g'(b_1^{(1,M)}), \quad b_1^{(1,M)} = \sum_k W_{1k} V_k^{(2,M)} - \Theta_1$$

$$\delta_k^{(2,M)} = \delta_1^{(3,M)} W_{1k} g'(b_k^{(2,M)}), \quad b_k^{(2,M)} = \sum_j w_{kj}^{(2)} V_j^{(1,M)} - \Theta_k$$

$$\delta_j^{(1,M)} = \sum_k \delta_k^{(2,M)} w_{kj}^{(2)} g'(b_j^{(1,M)}), \quad b_j^{(1,M)} = \sum_i w_{ji}^{(1)} z_i^{(M)} - \Theta_j$$

④ Backpropagation II - discussion of the implementation of the algorithm above. Explain how you program backpropagation.

(13)

(17) Oja's rule \rightarrow Output $y = \sum_{j=1}^N w_j \xi_j = \underline{w}^T \underline{\xi}$
 $\delta w_j = 2 y (\xi_j - y w_j)$

or prove that \underline{w}^* maximises $\langle y^2 \rangle$ using that

$|\underline{w}^*|^2 = 1$ and \underline{w}^* is the leading eigenvector of \underline{C} , with elements $C_{ij} = \langle \xi_i \xi_j \rangle$.

$$\langle y^2 \rangle = \langle (\underline{w}^T \underline{\xi}) (\underline{\xi}^T \underline{w}) \rangle = \langle \underline{w}^T \underline{C} \underline{w} \rangle$$

For $\underline{w} = \underline{w}^*$, find $\langle y^2 \rangle_{\underline{w}^*} = \langle \underline{w}^{*T} \underbrace{\underline{C} \underline{w}^*}_{\lambda_{\max} \underline{w}^*} \rangle = \lambda_{\max} \underbrace{\langle \underline{w}^{*T} \underline{w}^* \rangle}_{\substack{= 1 \\ (\text{from i})}}$

$$\Rightarrow \boxed{\langle y^2 \rangle_{\underline{w}^*} = \lambda_{\max}}, \text{ where } \lambda_{\max} \text{ is the maximum eigenvalue of } \underline{C}.$$

Since \underline{C} is symmetric ($\langle \xi_i \xi_j \rangle = \langle \xi_j \xi_i \rangle$) it has real eigenvalues λ_α and its eigenvectors \underline{u}_α are orthogonal:

$$\underline{u}_\alpha \underline{u}_\beta^T = \delta_{\alpha\beta}, \text{ where } \delta_{\alpha\beta} = \begin{cases} 1, & \text{for } \alpha = \beta \\ 0, & \text{otherwise} \end{cases}$$

Furthermore, all eigenvalues of \underline{C} are positive, since

$$\begin{aligned} \lambda_\alpha &= \underline{u}_\alpha^T \underline{C} \underline{u}_\alpha = \underline{u}_\alpha^T \langle \underline{\xi} \underline{\xi}^T \rangle \underline{u}_\alpha = \langle \underline{u}_\alpha^T \underline{\xi} \underline{\xi}^T \underline{u}_\alpha \rangle = \\ &= \langle |\underline{u}_\alpha^T \underline{\xi}|^2 \rangle \geq 0 \end{aligned}$$

For any unit vector $\underline{w} = \sum_\alpha k_\alpha \underline{u}_\alpha$ that can be represented as a linear combination of the eigenvectors \underline{u}_α with coefficients k_α (assuming that $|\underline{w}|^2 = 1$) we find

$$\begin{aligned} \langle y^2 \rangle_{\underline{w}} &= \langle \left(\sum_\alpha k_\alpha \underline{u}_\alpha \right)^T \underline{C} \left(\sum_\beta k_\beta \underline{u}_\beta \right) \rangle = \langle \sum_\alpha (k_\alpha \underline{u}_\alpha)^T \left(\sum_\beta k_\beta \lambda_\beta \underline{u}_\beta \right) \rangle = \\ &= \langle \sum_{\alpha, \beta} k_\alpha k_\beta \lambda_\beta \underbrace{\underline{u}_\alpha^T \underline{u}_\beta}_{\delta_{\alpha\beta}} \rangle = \langle \sum_\alpha (k_\alpha)^2 \lambda_\alpha \rangle \leq \lambda_{\max} \langle \sum_\alpha (k_\alpha)^2 \rangle \end{aligned}$$

(14)

From $|\underline{w}|^2 = 1$, we find $\sum_{\alpha} |k_{\alpha}|^2 = 1$

Therefore: $\langle \mathcal{Y}^2 \rangle_{\underline{w}} \leq \lambda_{\max} \langle \sum_{\alpha} |k_{\alpha}|^2 \rangle = \lambda_{\max}$

\Downarrow

$$\boxed{\langle \mathcal{Y}^2 \rangle_{\underline{w}} \leq \lambda_{\max}} \quad \text{and} \quad \underline{w}^* = \underline{w}_{\max}$$

This shows that $\langle \mathcal{Y}^2 \rangle_{\underline{w}^*}$ is maximal in comparison to $\langle \mathcal{Y}^2 \rangle$ evaluated for any other \underline{w} such that $|\underline{w}|^2 = 1$.

b) Assume that \underline{w}^* is a steady state. In other words:

$$\langle \delta \underline{w} \rangle_{\underline{w}^*} = 0$$

$$\Rightarrow \langle \eta \mathcal{Y} (\underline{\xi} - \mathcal{Y} \underline{w}) \rangle_{\underline{w}^*} = 0$$

$$\Rightarrow \langle \underline{w}^{*T} \underline{\xi} (\underline{\xi} - \underline{w}^{*T} \underline{\xi} \underline{w}^*) \rangle = 0 \quad / \quad (\underline{w}^{*T} \underline{\xi}) \underline{\xi} = \underline{\xi} (\underline{w}^{*T} \underline{\xi})$$

$$\langle \underline{\xi} \underline{\xi}^T \underline{w}^* - \underline{w}^{*T} \underline{\xi} \underline{\xi}^T \underline{w}^* \underline{w}^* \rangle = 0$$

$$\mathbb{C} \underline{w}^* - (\underline{w}^{*T} \mathbb{C} \underline{w}^*) \underline{w}^* = 0$$

scalar; let's call it $\underline{\lambda}$

(*) $\Rightarrow \boxed{\mathbb{C} \underline{w}^* = \lambda \underline{w}^*} \Rightarrow$ Thus, \underline{w}^* is an eigenvector of \mathbb{C} , with eigenvalue

$$\boxed{\lambda = \underline{w}^{*T} \mathbb{C} \underline{w}^*}$$

Norm of \underline{w}^* (property 1)

$$\lambda = \underline{w}^{*T} \underbrace{\mathbb{C} \underline{w}^*}_{\text{from (*)}} = \underline{w}^{*T} \lambda \underline{w}^* = \lambda \underline{w}^{*T} \underline{w}^* = \lambda |\underline{w}^*|^2$$

$$\Rightarrow \boxed{|\underline{w}^*|^2 = 1} \quad \text{Shown (2)}$$

Now we must show that \underline{w}^* has the maximum eigenvalue λ_{\max} . Note: in order for the network to converge to a steady state, this steady state needs to be stable. Otherwise, the network would not converge to it.

Therefore, check the stability of \underline{w}^* .

Evaluate $\langle \delta \underline{w} \rangle$ at $\underline{w} = \underline{w}^* + \underline{\varepsilon}$, where $|\underline{\varepsilon}|$ is small.

$$\langle \delta(\underline{w}^* + \underline{\varepsilon}) \rangle = \eta \langle (\underline{w}^* + \underline{\varepsilon})^T \underline{\varepsilon} [\underline{\varepsilon} - (\underline{w}^* + \underline{\varepsilon})^T \underline{\varepsilon} (\underline{w}^* + \underline{\varepsilon})] \rangle$$

up to linear order in $\underline{\varepsilon}$ ≈ 0 because \underline{w}^* is steady (previous page)

$$\approx \eta \langle \underline{w}^{*T} \underline{\varepsilon} (\underline{\varepsilon} - \underline{w}^{*T} \underline{\varepsilon} \underline{w}^*) \rangle$$

$$+ \langle \underline{\varepsilon}^T \underline{\varepsilon} \underline{\varepsilon} \rangle - \langle \underline{\varepsilon}^T \underline{\varepsilon} (\underline{w}^{*T} \underline{\varepsilon} \underline{w}^*) \rangle$$

$$- \langle \underline{w}^{*T} \underline{\varepsilon} \underline{w}^{*T} \underline{\varepsilon} \underline{\varepsilon} \rangle$$

$$- \langle \underline{w}^{*T} \underline{\varepsilon} \underline{\varepsilon}^T \underline{\varepsilon} \underline{w}^* \rangle$$

same as $\underline{w}^* = \underline{u}_\alpha$ one of the eigenvectors.

$\lambda_\alpha \underline{u}_\alpha$

$\underline{0}$

\underline{u}_α

$$\Rightarrow \langle \delta(\underline{w}^* + \underline{\varepsilon}) \rangle \approx \eta \left[\langle \underline{\varepsilon} \underline{\varepsilon}^T \underline{\varepsilon} \rangle - \langle \underline{\varepsilon}^T \underline{\varepsilon} \underline{\varepsilon}^T \underline{w}^* \underline{w}^* \rangle \right]$$

$$- \langle \underline{w}^{*T} (\underline{\varepsilon} \underline{\varepsilon}^T \underline{w}^*) \underline{\varepsilon} \rangle - \langle \underline{w}^{*T} \underline{\varepsilon} \underline{\varepsilon}^T \underline{\varepsilon} \underline{w}^* \rangle$$

$$= \eta [\underline{0} \underline{\varepsilon} - \underline{\varepsilon}^T \lambda_\alpha \underline{u}_\alpha \underline{u}_\alpha] = \underline{\varepsilon}^T \underline{u}_\alpha$$

$$- \underline{u}_\alpha^T \lambda_\alpha \underline{u}_\alpha \underline{\varepsilon} - \lambda_\alpha \underline{u}_\alpha^T \underline{\varepsilon} \underline{u}_\alpha]$$

$$= \eta [\underline{0} \underline{\varepsilon} - 2\lambda_\alpha (\underline{\varepsilon}^T \underline{u}_\alpha) \underline{u}_\alpha - \lambda_\alpha \underline{\varepsilon}]$$

Multiply both sides by \underline{u}_β^T .

$$= \lambda_\beta \underline{u}_\beta^T$$

(16)

$$\underline{u}_\beta^T \langle \delta(\underline{w}^* + \underline{\epsilon}) \rangle = \eta \left(\underline{u}_\beta^T \underline{\Phi} \underline{\epsilon} - 2\lambda_\alpha (\underline{\epsilon}^T \underline{u}_\alpha) \underline{u}_\beta^T \underline{u}_\alpha - \lambda_\alpha \underline{u}_\beta^T \underline{\epsilon} \right)$$

$$= \eta \left(\underbrace{\lambda_\beta - 2\lambda_\alpha \delta_{\alpha\beta} - \lambda_\alpha}_{=0} \right) \underline{u}_\beta^T \underline{\epsilon}$$

Recall: λ_α is the eigenvalue assigned to \underline{w}^* .

Assume that this is not the maximal eigenvalue. In this case, thus, there will be at least one β with $\lambda_\beta > \lambda_\alpha$. In this case, it follows that an initially small fluctuation around \underline{w}^* (denoted by $\underline{\epsilon}$ above) will grow! This is because the right-hand-side of the equation above is, in this case, positive:

$$\lambda_\beta > \lambda_\alpha \Rightarrow (\lambda_\beta - \underbrace{2\lambda_\alpha \delta_{\alpha\beta}}_{=0} - \lambda_\alpha) = \lambda_\beta - \lambda_\alpha > 0$$

Therefore, in this case \underline{w}^* is not the weight vector to which the network converges.

What happens if λ_α is the maximum eigenvalue?

From the above argument, find that $\underline{\epsilon}$ will shrink in size in all directions \underline{u}_β ($\beta \neq \alpha$). What happens in the direction $\underline{u}_\alpha = \underline{w}^*$? In this direction $\underline{\epsilon}$ also shrinks because the right-hand-side of the equation above is negative:

$$\lambda_\alpha - 2\lambda_\alpha - \lambda_\alpha = -2\lambda_\alpha < 0$$

Thus, we have shown that if the network converges to \underline{w}^* , then \underline{w}^* is the leading eigenvector of Φ , and $|\underline{w}^*|^2 = 1$.

c) Generalisation of Oja's rule for learning M principal components for zero-mean data

$$\Delta w_{ij} = \eta \sum_i \left(\xi_j - \sum_{k=1}^M \sum_i w_{kj} \right)$$

where $\sum_i = \sum_{j=1}^N w_{ij} \xi_j$.

When $M=1$, this rule reduces to the rule (5) in the exam text.

Weight decay (second term in the rule) assures that the weight vectors remain normalised.