

Exercise 1: Implement ResNet-18

```
import torchvision.models as models
from torchsummary import summary
```

[25]

✓ 0.0s

Python

```
resnet_18 = models.resnet18()
input = torch.randn(1, 3, 224, 224)
```

[26]

✓ 0.2s

Python

```
summary(resnet_18, (3, 224, 224))
```

[]

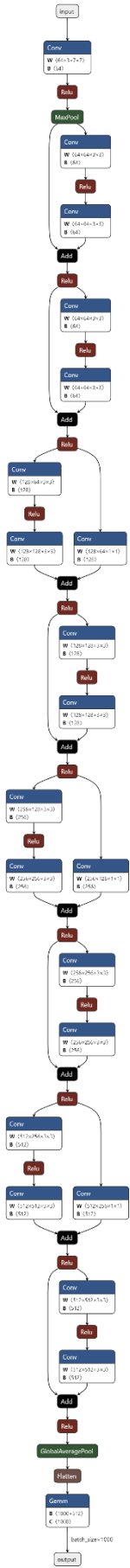
Python

```
torch.onnx.export(resnet_18,
                  input,
                  "resnet_18.onnx",
                  export_params=True,
                  opset_version=10,
                  do_constant_folding=True,
                  input_names = ['input'],
                  output_names = ['output'],
                  dynamic_axes={'input' : {0 : 'batch_size'},
                               'output' : {0 : 'batch_size'}})
```

[31]

✓ 0.7s

Python



Exercise 2: Use thop library to verify the number of parameters & FLOPs of VGG16 and ResNet 101

```
import torch
from torchvision.models import vgg16, resnet101
from thop import profile
from thop import clever_format
```

[32] ✓ 0.0s

Python

Params and FLOPs of VGG 16

```
vgg16_ = vgg16()
input = torch.randn(1, 3, 224, 224)
flops, params = profile(vgg16_, inputs=(input, ))
flops, params = clever_format([flops, params], "%.3f")
```

[33] ✓ 4.5s

Python

```
... [INFO] Register count_convNd() for <class 'torch.nn.modules.conv.Conv2d'>.
[INFO] Register zero_ops() for <class 'torch.nn.modules.activation.ReLU'>.
[INFO] Register zero_ops() for <class 'torch.nn.modules.pooling.MaxPool2d'>.
[INFO] Register zero_ops() for <class 'torch.nn.modules.container.Sequential'>.
[INFO] Register count_adap_avgpool() for <class 'torch.nn.modules.pooling.AdaptiveAvgPool2d'>.
[INFO] Register count_linear() for <class 'torch.nn.modules.linear.Linear'>.
[INFO] Register zero_ops() for <class 'torch.nn.modules.dropout.Dropout'>.
```

```
flops, params
```

[34] ✓ 0.0s

Python

```
... ('15.470G', '138.358M')
```

Params and FLOPs of ResNet 101

```
vgg16_ = resnet101()
input = torch.randn(1, 3, 224, 224)
flops, params = profile(vgg16_, inputs=(input, ))
flops, params = clever_format([flops, params], "%.3f")
```

[35] ✓ 1.7s

Python

```
... [INFO] Register count_convNd() for <class 'torch.nn.modules.conv.Conv2d'>.
[INFO] Register count_normalization() for <class 'torch.nn.modules.batchnorm.BatchNorm2d'>.
[INFO] Register zero_ops() for <class 'torch.nn.modules.activation.ReLU'>.
[INFO] Register zero_ops() for <class 'torch.nn.modules.pooling.MaxPool2d'>.
[INFO] Register zero_ops() for <class 'torch.nn.modules.container.Sequential'>.
[INFO] Register count_adap_avgpool() for <class 'torch.nn.modules.pooling.AdaptiveAvgPool2d'>.
[INFO] Register count_linear() for <class 'torch.nn.modules.linear.Linear'>.
```

```
flops, params
```

[36] ✓ 0.0s

Python

```
... ('7.866G', '44.549M')
```