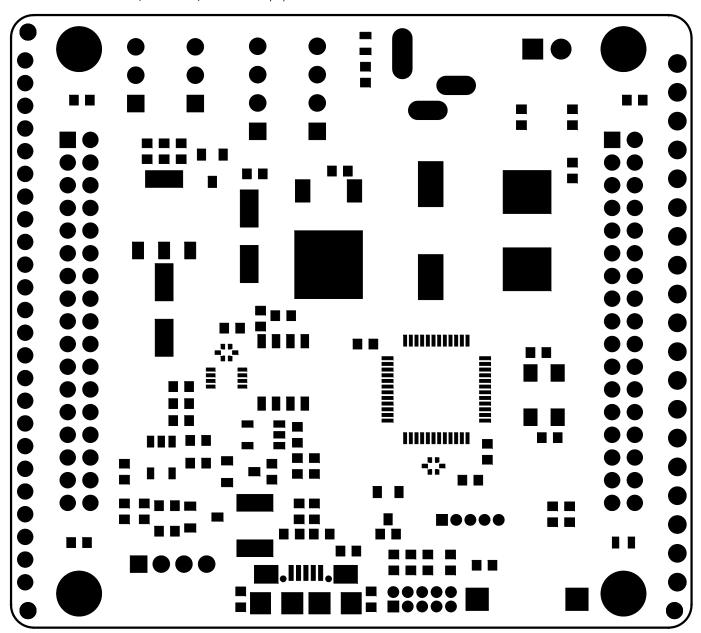
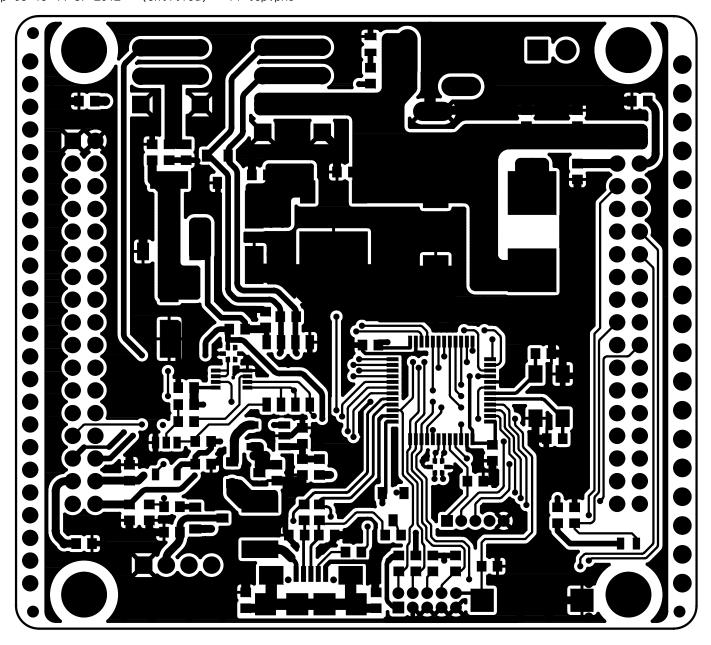


COMPANY	Robotis	Layer Name	Top Silk	REV	В
PROJECT	CM-900_B (4 Layer)	DATE	2012.08.17	SIZE	60.0*54.0(mm)

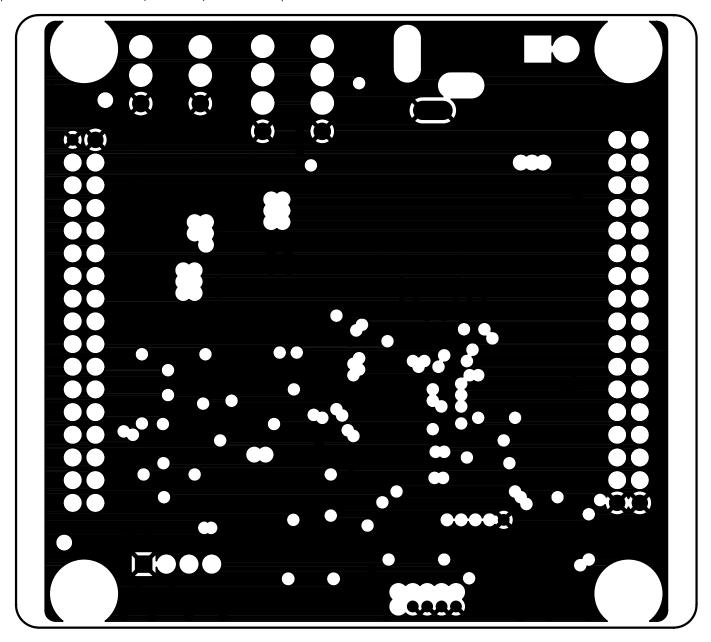


COMPANY	Robotis	Layer Name	SolderMask-TOP	REV	В
PROJECT	CM-900_B (4 Layer)	DATE	2012.08.17	SIZE	60.0*54.0(mm)



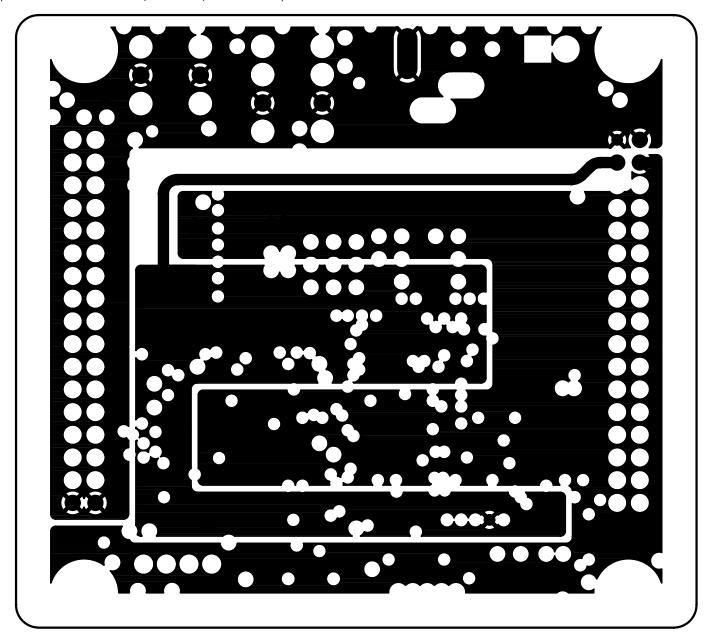
COMPANY	Robotis	Layer Name	L1-T0P	REV	В
PROJECT	CM-900_B (4 Layer)	DATE	2012.08.17	SIZE	60.0*54.0(mm)

L1-T0P



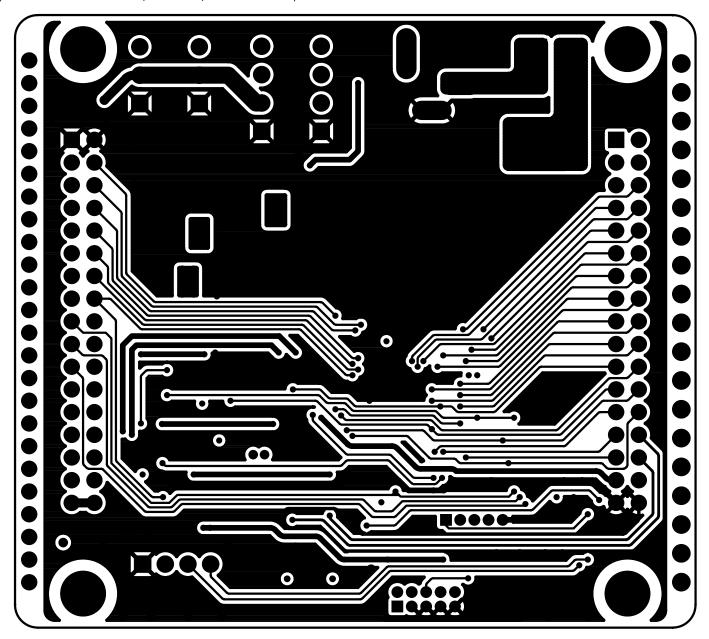
COMPANY	Robotis	Layer Name		REV	В
PROJECT	CM-900_B (4 Layer)	DATE	2012.08.17	SIZE	60.0*54.0(mm)

L2-GND

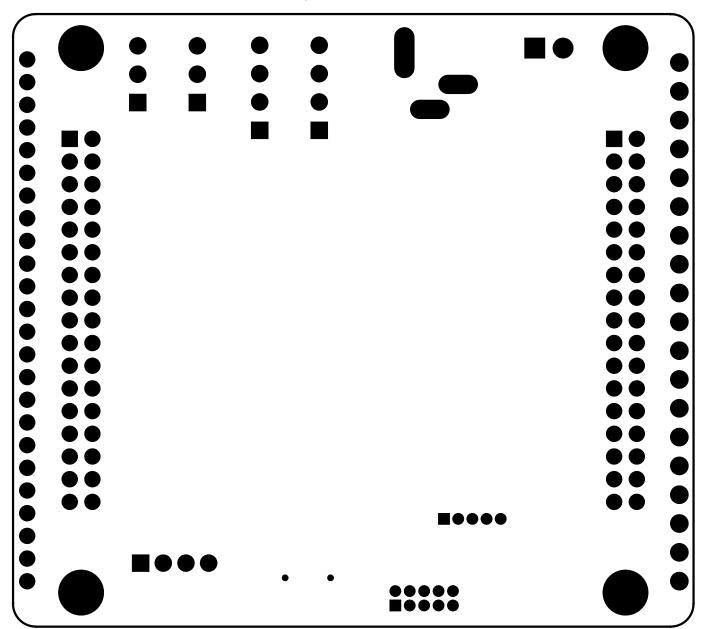


COMPANY	Robotis	Layer Name		REV	В
PROJECT	CM-900_B (4 Layer)	DATE	2012.08.17	SIZE	60.0*54.0(mm)

L3-POWER



COMPANY	Robotis	Layer Name	L2-Bottom	REV	В
PROJECT	CM-900_B (4 Layer)	DATE	2012.08.17	SIZE	60.0*54.0(mm)



COMPANY	Robotis	Layer Name	SolderMask-BOTTOM	REV	В
PROJECT	CM-900_B (4 Layer)	DATE	2012.08.17	SIZE	60.0*54.0(mm)

18 1	{	DATA 12V GND	{	- V S)))	12V		18 1
GND - C	GND PB9	Dedicated	CAN/USB		TIMER T2_CH1		PAO	ROBOTIS	12V 12V 5.3V
	PB10 (PB11 PB12 PB12	Zigbee_TXD Zigbee_RXD		TX2 RX2	T2_CH2 T2_CH3 T2_CH4	CH2 CH3	PA1 PA2 PA3 PA4	www.robotis.com	PAO Booto PA1 PA13
	PB13 PB14	USB_ID			Т3_СН1 Т2_СН2	СН5 СН6	PA5 PA6 PA7	CM-900 BCM13-B01-E001	PA2 PA3 PA15 PA4 PB0
PC13	PB15 (Na gou	Hal VI	TX1 RX1	T1_CH1 T1_CH2 T1_CH3	0	PA8 PA9 PA10		PA5 PB1
PC14) –) –	USB_DP	TX/DM RX/DP		T1_CH4 T3_CH3 T3_CH4	2 CH8	PA11 PA12 PB0 PB1		PA7 PB3
) –) –	STATUS_LED ENABLE_TX					PB2 PB3 PB4		PA9 PB5
RST 485	— (485 D-	ENABLE_RX DXL_TXD DXL_RXD			T4_CH1 T4_CH2		PB5 PB6 PB7		PA11 PB7
5v 12v 12v	3.3V 12V			TX3	T4_CH3 T4_CH4		PB8 PB9 PB10 PB11]В0010) ТХ1) БХ1) З З А) З З А	GND GND TILL
34 17	г	ZIGBEE_RESET USB_DISCONNECT		J.M		i	PB15 PC13		34 17
	;	3.3v SIG-EX SIG-LX)					3.3A SMDIO LINE GND SMDCCTK LCK GND SMDCCTK LCK GND SMO LDD GND MC LDI GND KEZEL	

COMPANY	Robotis	Layer Name	Bottom Silk	REV	В
PROJECT	CM-900_B (4 Layer)	DATE	2012.08.17	SIZE	60.0*54.0(mm)