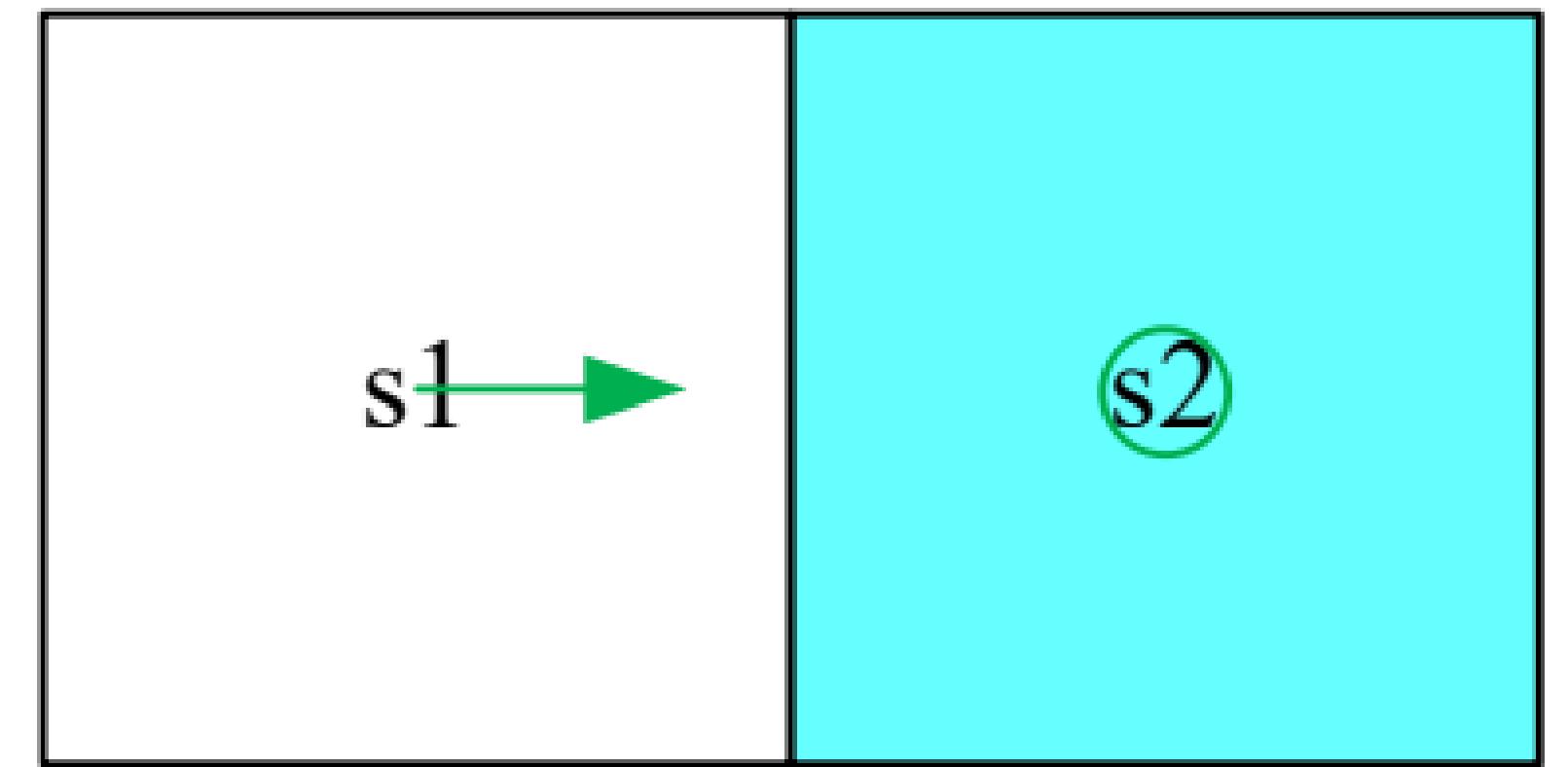


$s_1$

$s_2$

(a) initial policy



$s_1$

$s_2$

(b) optimal policy