

# The Pilot Al Vision Framework: From Doorbells to Defense





### What is the Pilot Al Vision Framework





# **Deep Learning on Limited Compute**



- Deep learning based computer vision platform to solve real problems with limited compute.
  - Better neural network algorithms that run efficiently on modern memory architectures
  - Optimized compute kernels across target platforms (from DSP to Cortex M to GPUs)
  - Vision Toolkit that exposes functionality like detection, classification, and tracking
  - Plug and play API/binaries that drop into existing customer products
  - Customer deployable data storage and labeling infrastructure



#### The Pilot Al Vision Framework



At the center of the Pilot Al Vision Framework is the CoreML module: a core set of machine learning building blocks optimized for speed.

CoreML

#### Goal: Run deep learning faster

Alternatives:

- Low-precision: limited acceleration, need retraining
- Connection pruning: sparsity tends to be unstructured
- · Weight quantization: limited win



#### The Pilot Al Vision Framework: CoreML





#### Our approach:

- Structured sparsity that works
- Dynamic evaluation
- Built in a way that is extensible to a variety of vector widths
- Layer on other techniques like lower precision, quantization, custom silicon, etc.
- Abstracted away from the user API

2-10x performance increase, depending on the problem

#### The Pilot Al Vision Framework: Math Kernels



#### **Custom Math Kernels**

# Goal: Exploit hardware features to further accelerate numerics

- s/dgemm, s/dgemv type operations
- Implemented in assembly/intrinsics on DSPs, Cortex M, Cortex A, x86, GPU
- Abstracted away from user API
- 1.5-3x performance boost

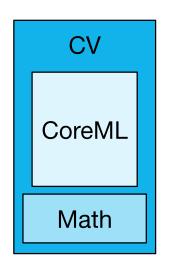


Math



# The Pilot Al Vision Framework: CV Library





Computer Vision Library

# Goal: Implement common CV tasks on top of the Pilot Al CoreML library

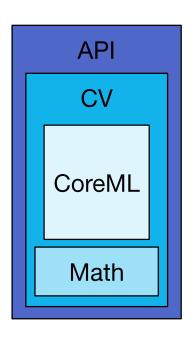
- Detection
- Classification
- Tracking

Proprietary algorithms based on the literature, but built in the context of our CoreML building blocks for acceleration.

#### The Pilot Al Vision Framework: API



#### The Pilot Al Vision Framework



Computer Vision API

Goal: Plug and play interface for customers to access the features of the Pilot Al Vision Framework

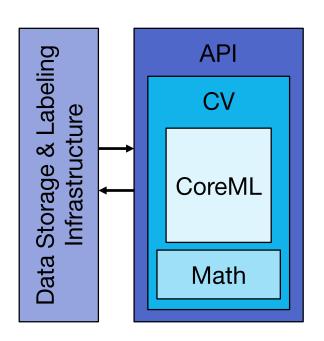
- C++ style interface
- Lightweight binaries (no external dependencies)
- Currently deployed into Linaro, RTOS, Linux, and Windows environments



#### The Pilot Al Vision Framework: Data Infrastructure



#### The Pilot Al Vision Framework



Data Storage/Labeling Infrastructure

# Goal: Quality labeled data is critical; make it easily accessible to our customers

- Provide large off-the-shelf datasets
- 70K+ objects labeled every day
- Make it easy for our customers to ingest data and iterate models
- Data infrastructure is easily deployable for onpremise applications





### Pilot AI in the Real World





# **Pilot Al's Target Markets**



#### Deployed on 1M+ cameras over the last 2.5 years

Consumer → Commercial → Government

#### **IoT**

- Security cameras
  - Drones
  - Retail analytics
    - AR/VR

#### **Automotive**

- Inward facing car cameras
- Driver assistance cameras
- Multiple cameras per car
- Mobileye \$250M Rev 2015

#### **Industrial Robotics**

- Autonomous robot navigation
  - Picking/Packing
- Labor cost increasing, robotics will to solve more complex tasks
  - \$26B in 2013



#### Home/Appliances

- Smart Refrigerators/Washers
- IP Cameras
- Home robotics
- 2015 global appl. sales \$180B



# Example Application #1 – Retail Analytics





For retail analytics, we built an detection and classification system that runs directly on existing security cameras installed in stores.

analytics like people counting, zone counting, heat maps, gender, and race.
This will be deployed in 10,000 stores, with an average of 15 cameras per store.

This allows retailers to collect

https://www.youtube.com/watch?v=8iUtEqoB4Ks



# Example Application #2 – Security/Doorbell



For home security and automation our embedded robust computer vision algorithms can support a variety of applications, from smart IP cameras, intelligent door bells, to smart appliances. Running directly on the edge device allows service providers to reduce bandwidth and cloud computing costs by performing that function on the consumer premises.



## **Example Application #3 – Drone Follow-Me**





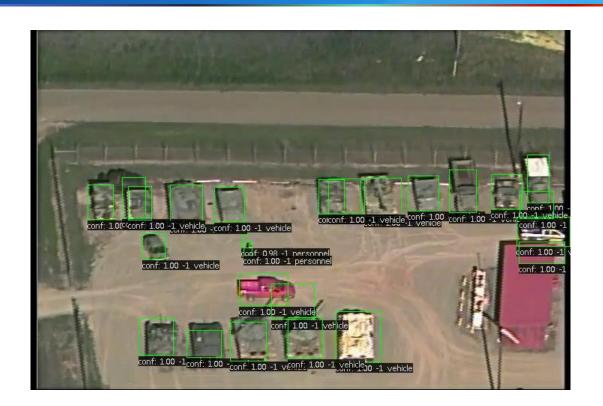
For drones, we built a robust deep learning based object detection and tracking system that runs directly on a small action camera. When this is connected to a drone, this solves various problems encountered by drones, such as allowing a drone to follow an object, or allowing the drone to determine a safe place to land.

https://www.youtube.com/watch?v=LWjwkl\_cu-E



## **Example Application #4 – Government**





Pilot Al's government work spans both the intelligence community as well as the DoD.

These applications range in distance from a few feet to satellites. As such, the applications span ARM cores, x86, and GPUs.

Though the hardware platforms are diverse, all the use cases are compute constrained.





# **Looking Ahead**





# **Forward Looking**



#### **Extending the Pilot Al Framework**

- Deployment of temporal detectors
  - Fighting, shoplifting, etc.
- Visual Search
  - Both real-time and forensic
- Other sensor inputs
  - Depth, Radar, etc.
- Extend beyond vision to speech and other applications



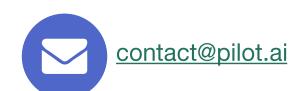
### Thank You





We would love to hear from you!

#### **CONTACT US**





425-761-9140



www.pilot.ai

