Individuals and Moving Range Charts – Known Mathematical Model

Data Science for Quality Management: X and Moving Range Charts for Non-Normally Distributed Data with Wendy Martin

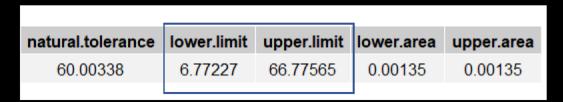
#### Learning objective:

Calculate Control Limits for data that is distributed exponentially

- To generate control limits, we would use the following procedure.
- For 3 standard error limits, we need to find the values associated with the center 99.73% (UNPL and LNPL) of the distribution.

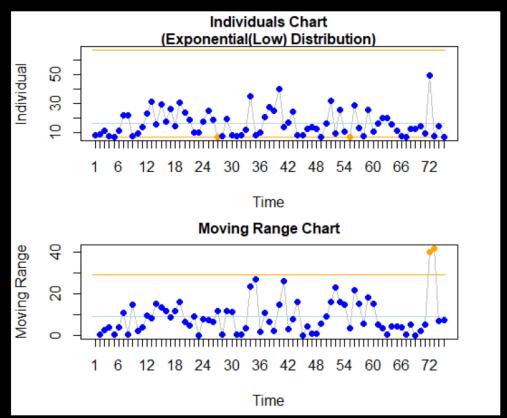
• To accomplish this, we first generate the mean and lowest observed value associated with the data, so that we can obtain an estimate of Omicron from X<sub>L</sub> (the minimum value).

- Next, using the natural tolerance function for the Exponential Low Distribution function in lolcat, obtain the LNPL and UNPL
- > natural.tolerance.exp.low( )



 Next, using the variables chart for the Exponential Low Distribution function in lolcat, generate the chart

```
spc.chart.variables.individual.and.movi
ngrange.exponential.low.simple(individu
als =, low =)
```



#### Sources

The material used in the PowerPoint presentations associated with this course was drawn from a number of sources. Specifically, much of the content included was adopted or adapted from the following previously-published material:

- Luftig, J. An Introduction to Statistical Process Control & Capability. Luftig & Associates, Inc. Farmington Hills, MI, 1982
- Luftig, J. Advanced Statistical Process Control & Capability. Luftig & Associates, Inc. Farmington Hills, MI, 1984.
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- Spooner-Jordan, V. Understanding Variation. Luftig & Warren International, Southfield, MI 1996
- Luftig, J. and Petrovich, M. Quality with Confidence in Manufacturing. SPSS, Inc. Chicago, IL 1997
- Littlejohn, R., Ouellette, S., & Petrovich, M. Black Belt Business Improvement Specialist Training, Luftig & Warren International, 2000
- Ouellette, S. Six Sigma Champion Training, ROI Alliance, LLC & Luftig & Warren, International, Southfield, MI 2005