Base matc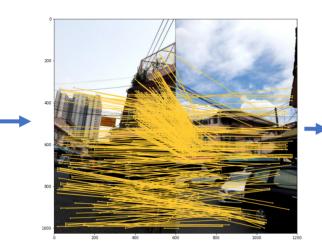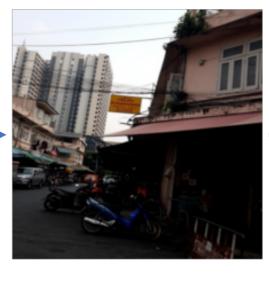her (usually LOFTR and SuperGlue) → Cluster matches to find co-visible area → Base matcher → Filter matchers (NMS-like) → MAGSAC++ (OpenCV)