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## Proving a measure of lattice differences

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#### Abstract

Abstract Unit cells

**Note:** In his later publications, Boris Delaunay used the Russian version of his surname, Delone.

### 1. Introduction

A recent article (Bright <u>et al.</u>, 2023) questioned the formal basis of the measures of differences between lattices that are described by Andrews & Bernstein (2023) (and references therein).

Here we present a formal description of the above mentioned methods.

#### 2. Finding a minimum distance

Consider some metric space X in which a distance can be determined between any two objects in X.

A distance in X is defined as

$$d = | \mathbf{x} \cdot \mathbf{y} | \text{ for } \mathbf{x}, \mathbf{y} \in \mathbf{X}.$$

The question that immediately arises how to represent the object in **X**. The conventional choices are to choose either the basis vectors of the lattice, a description of the unit cell itself, or as objects in some space, such as ...

The points in lattices in 2 dimensions are addressed by the operations of the "modular group", also named  $PSL(2, \mathbf{Z})$ . The corresponding 3 dimensional group is  $PSL(3, \mathbf{Z})$ .

Invariants are known for lattices in two dimensions (see Jones & Singerman (1987), page 176 and following). Bright  $\underline{et}$  al. (2023) have considered alternatives. However, invariants are not known for  $PSL(3,\mathbf{Z})$  or in higher dimensions.

To compute the distance between two lattices (represented in a metric space, with operators  $g_i$  in the group  $\mathbf{G}$ ), we define

$$d_{min} = \min \left| g_i \mathbf{y} - \mathbf{x} \right| \text{ for } \mathbf{x}, \mathbf{y} \in \mathbf{X} \text{ and } \mathbf{g_i} \in \mathbf{G}.$$

We conjecture that

$$dy_{min} = \min \mid g_i \mathbf{x} - \mathbf{y} \mid \text{ for } \mathbf{x}, \mathbf{y} \in \mathbf{X} \text{ and } \mathbf{g_i} \in \mathbf{G}.$$

has the same value as  $d_{min}$  above.

#### 3. Computing the minimum distance

While Section 2 contains a definition for a minimum distance, a problem still exists. The group  $PSL(3, \mathbf{Z})$  is an infinite group. For practicality, a finite algorithm is required.

The first step is compute the distance between the two points of interest with  $g_i$  as the identity operation. From the group  $\mathbf{G}$ , a set of operators must be chosen. It should include those operations that do not change the norm of the affected point plus

a sufficient set of the other operations. The generators of the G is a minimal set, but for efficiency an expanded set is useful.

The above set of operations must then be applied iteratively until the distance between the two points exceeds some limit.

## 4. Summary

Summary blah blah blah

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#### Synopsis

Unit cells