VIETNAM NATIONAL UNIVERSITY, HO CHI MINH CITY UNIVERSITY OF TECHNOLOGY FACULTY OF COMPUTER SCIENCE AND ENGINEERING



Natural Language Processing (CO3085)

Comparing Deep Learning Models For Sentiment Analysis In Customer Reviews

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1 Introduction

Sentiment analysis is a field in natural language processing (NLP) that seeks to understand and interpret the sentiments, opinions, and emotions expressed in textual data. In an era dominated by massive amounts of digital information, sentiment analysis has emerged as a crucial tool for extracting valuable insights from the opinions shared on various platforms, such as social media, product reviews, news articles, and customer feedback.

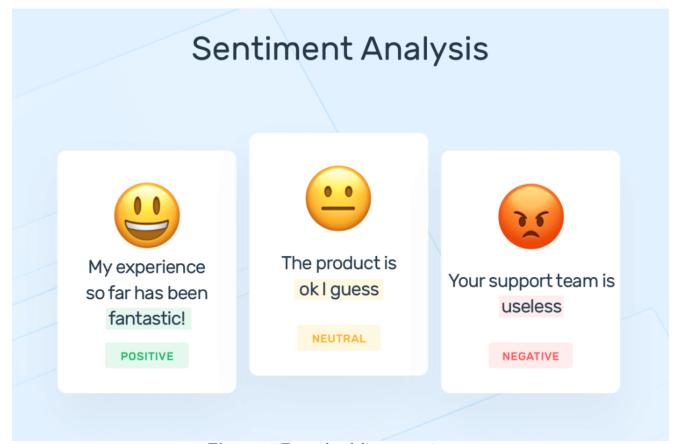


Figure 1: Example of diverse sentiments

The primary objective of sentiment analysis is to classify and analyze the subjective information present in text, categorizing it into predefined sentiment categories such as positive, negative, or neutral. This classification enables businesses, researchers, and individuals to gain a deeper understanding of public perceptions, customer sentiments, and trends within different domains.

One of the key challenges in sentiment analysis lies in the inherent complexity of human language. Language is rich, context-dependent, and often filled with nuances, making it challenging to accurately interpret the sentiment behind a piece of text. Ambiguities, variations in expression, and the use of sarcasm or irony further contribute to the intricacies involved in sentiment analysis.

The field of sentiment analysis encompasses a range of techniques, from traditional machine learning approaches to more advanced deep learning methods. Its role in distilling actionable insights from the vast sea of textual data makes sentiment analysis an invaluable tool for shaping business strategies, enhancing customer experiences, and understanding the ever-changing pulse of public sentiment.



2 Dataset

The dataset is from VLSP, comprises customer reviews in Vietnamese language on various tech products, categorized into three distinct classes: negative, neutral, and positive sentiments. There are 5100 records in training data and 1050 records in testing data.



Figure 2: Training data

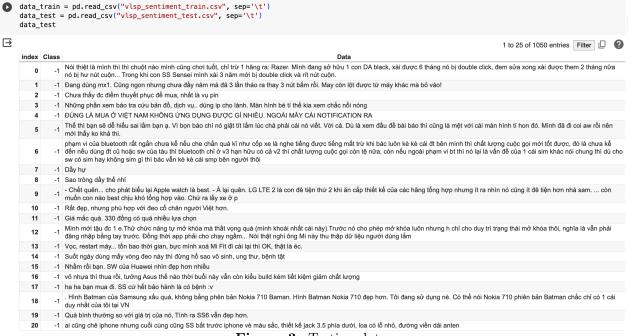


Figure 3: Testing data



Data pre-processing:

- Encode labels to one-hot vectors.
 - [1, 0, 0] for negative.
 - -[0, 1, 0] for neutral.
 - [0, 0, 1] for positive.

```
| labels = data_train.iloc[:, 0].values
2 labels_test = data_test.iloc[:, 0].values
  encoded_labels = np.array(
      [1, 0, 0] if label == -1
6
          else [0, 1, 0] if label == 0
          else [0, 0, 1]
                for label in labels
      ]
10
  )
11
12
  encoded_labels_test = np.array(
13
14
                [1, 0, 0] if label == -1
15
           else [0, 1, 0] if label == 0
          else [0, 0, 1]
17
                for label in labels_test
18
      ]
19
20 )
22 labels = encoded_labels
23 labels_test = encoded_labels_test
```

• Remove words with digits in each reviews: Word with digits is usually unique(product names, prices...) and hard to trained to actually contribute to the sentiment analysis.

Word with digits is usually unique and hard to trained to actually contribute to the sentiment analysis.

Figure 4: Testing data

Apply the remove word with digits function to the 'Data' column.



```
1 # Function to detect word with digits
2 def contains_digits(word) :
     for char in word:
          if char.isdigit():
              return True
      return False
s # Function to remove word with digits
e remove_word_with_digits = lambda review: ' '.join(
     word for word in review.split(' ') if not contains_digits(
         word)
11 )
12
13 # Apply the function to the 'Data' column
14 data_train['Data'] = data_train['Data'].apply(
     remove_word_with_digits)
| data_test['Data'] = data_test['Data'].apply(
     remove_word_with_digits)
16
reviews = data_train.iloc[:, 1].values
18 reviews_test = data_test.iloc[:, 1].values
```

Class		Data
0	-1	Mình đã dùng anywhere thế hệ đầu, quả là đầy t
1	-1	Quan tâm nhất là độ trễ có cao không, dùng thi
2	-1	dag xài con cùi bắp 98kpin trâu, mỗi tội đ
3	-1	logitech chắc hàng phải tiền triệu trở lên dùn
4	-1	Đang xài con m175 cùi mía , nhà xài nhiều chuộ
5095	0	Mình mua máy về đc 1 ngày mà điện thoại khác g
5096	0	Có bạn nào dùng f1w ko.mình dùng m cảm thấy qu
5097	0	Dùng oppo mà bộ nhớ 4gb thì k chơi games
5098	0	Sao tui thích xài hàng oppo mà lựa toàn mấy đứ
5099	0	mới mở hộp ,oy mở vào camera mà đã có ảnh chụp
5100 rd	ws × 2 c	olumns

(Class	Data
0	-1	Mình đã dùng anywhere thế hệ đầu, quả là đầy t
1	-1	Quan tâm nhất là độ trễ có cao không, dùng thi
2	-1	dag xài con cùi bắp trâu, mỗi tội đánh liên mi
3	-1	logitech chắc hàng phải tiền triệu trở lên dùn
4	-1	Đang xài con cùi mía , nhà xài nhiều chuột nên
5095	0	Mình mua máy về đc ngày mà điện thoại khác gọi
5096	0	Có bạn nào dùng ko.mình dùng m cảm thấy quanh
5097	0	Dùng oppo mà bộ nhớ thì k chơi games đc đ
5098	0	Sao tui thích xài hàng oppo mà lựa toàn mấy đứ
5099	0	mới mở hộp ,oy mở vào camera mà đã có ảnh chụp
5100 row	s × 2 c	olumns

(a) Training data before apply

(b) Testing data after apply

Figure 5: Comparison of training and testing data



• Tokenization: Using pyvi module to tokenize each reviews.

```
# Use PyVi for Vietnamese word tokenizer
word_reviews = []
word_reviews_test = []

for review in reviews:
    review = ViTokenizer.tokenize(review.lower())
    word_reviews.append(review.split())

for review in reviews_test:
    review = ViTokenizer.tokenize(review.lower())
    word_reviews_test.append(review.split())
```

• Embedding Dimensions and Sequence Length:

- EMBEDDING DIM: Specifies the dimensionality of the word vectors.
- MAX_VOCAB_SIZE: Defines the maximum number of unique words to be used in the word embedding.
- MAX_SEQUENCE_LENGTH: Sets the maximum number of words in a review.

The Tokenizer class from Keras is used to vectorize the text corpus, turning each word into a numerical sequence. First I fit the tokenizer on the training data (word_reviews), building the vocabulary, then convert Texts to Sequences and Padding, and converts the tokenized training data into sequences of integers. Pads the sequences to ensure uniform length (MAX_SEQUENCE_LENGTH).

Similar steps are repeated for the testing data.

```
| EMBEDDING_DIM = 400 # how big is each word vector
2 MAX_VOCAB_SIZE = 10000 # how many unique words to use (i.e num
     rows in embedding vector)
3 MAX_SEQUENCE_LENGTH = 300 # max number of words in a comment
5 tokenizer = Tokenizer(num_words=MAX_VOCAB_SIZE, lower=True,
     char_level=False)
6 tokenizer.fit_on_texts(word_reviews)
s sequences_train = tokenizer.texts_to_sequences(word_reviews)
9 data = pad_sequences(sequences_train, maxlen=
     MAX_SEQUENCE_LENGTH)
word_index = tokenizer.word_index
12
sequences_test = tokenizer.texts_to_sequences(
     word_reviews_test)
14 data_test = pad_sequences(sequences_test, maxlen=
     MAX_SEQUENCE_LENGTH)
```



```
[ ] print('Shape of X train and X validation tensor:', data.shape)
    print('Shape of label train and validation tensor:', labels.shape)

print('Shape of X test and X validation tensor:', data_test.shape)
print('Shape of label test and validation tensor:', labels_test.shape)

Shape of X train and X validation tensor: (5100, 300)
Shape of label train and validation tensor: (1050, 300)
Shape of X test and X validation tensor: (1050, 300)
Shape of label test and validation tensor: (1050, 30)
```

Figure 6: Shape of training and testing data

• Embedding matrix: I utilize pre-trained word vectors from the 'vi-model-CBOW.bin' file, load them into 'word_vectors'. An 'embedding_matrix' is initialized as a matrix of zeros with dimensions corresponding to the determined vocabulary size and the chosen embedding dimension ('EMBEDDING_DIM'). The matrix is populated by the corresponding vector, otherwise a random vector. The final step involves creating an Embedding layer in Keras ('embedding_layer') with the determined vocabulary size, embedding dimension, and weights set to the constructed embedding matrix.

```
u|word_vectors = KeyedVectors.load_word2vec_format('vi-model-
     CBOW.bin', binary=True)
3 vocabulary_size=min(len(word_index)+1,MAX_VOCAB_SIZE)
4 embedding_matrix = np.zeros((vocabulary_size, EMBEDDING_DIM))
5 for word, i in word_index.items():
      if i>=MAX_VOCAB_SIZE:
          continue
      try:
8
          embedding_vector = word_vectors[word]
9
          embedding_matrix[i] = embedding_vector
10
      except KeyError:
11
          embedding_matrix[i]=np.random.normal(0,np.sqrt(0.25),
12
             EMBEDDING_DIM)
14 del (word_vectors)
16 from keras.layers import Embedding
| embedding_layer = Embedding(vocabulary_size,
                                EMBEDDING_DIM,
18
                                weights = [embedding_matrix],
19
                                trainable=True)
20
```



3 Deep Learning Models

3.1 Convolutional Neural Networks

Convolutional Neural Networks (CNNs) are a class of deep neural networks designed for processing and analyzing visual data, they are particularly well-suited for tasks such as classification, object detection, and facial recognition, where the spatial relationships and patterns within images play a crucial role. The key innovation of CNNs lies in their ability to automatically learn hierarchical and spatial feature representations from the input data.

One of the strengths of CNNs is their parameter sharing, meaning that the same filter is applied to different parts of the input, enabling the network to learn translation-invariant features. This property makes CNNs highly effective in recognizing patterns and objects in various positions and orientations within an image.

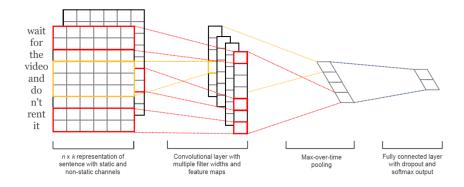


Figure 7: CNN model visualized in NLP

CNNs employ convolutional layers that apply convolutional operations to input images, extracting local features through the use of filters. These filters detect specific patterns like edges, textures, or more complex structures within the input data. The use of pooling layers further reduces the spatial dimensions of the data, emphasizing the most important features and enhancing the network's ability to generalize.

CNNs have achieved remarkable success in a wide range of applications, including image recognition, object detection, and even tasks beyond computer vision, such as natural language processing. Their ability to automatically learn hierarchical features has positioned CNNs as a foundational architecture in the field of deep learning, playing a pivotal role in advancing the capabilities of artificial intelligence systems.

3.2 Recurrent Neural Network

Recurrent Neural Networks (RNNs) represent a class of artificial neural networks designed for sequential data processing, making them particularly effective for tasks involving patterns across time or sequences. Unlike traditional feedforward neural networks, RNNs maintain hidden states that allow them to retain information from previous inputs, enabling them to capture dependencies and relationships within sequential data. This architecture makes RNNs well-suited for various applications, including natural language processing, speech recognition, and time series analysis. However, standard RNNs have limitations in capturing long-term dependencies, known as the vanishing and exploding gradient problems, which can hinder their performance on tasks requiring memory over extended sequences.



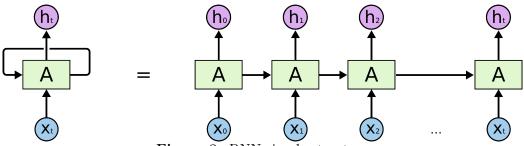


Figure 8: RNN simple structure

Long Short-Term Memory (LSTM) networks emerged as a solution to the challenges posed by standard RNNs. LSTMs are a type of RNN that incorporates memory cells and gating mechanisms to better manage and control the flow of information. The key innovation of LSTMs lies in their ability to selectively learn, remember, and forget information over long sequences. The architecture includes three gates - input, forget, and output gates - which regulate the flow of information through the network. LSTMs are particularly effective for tasks requiring the understanding of context and long-range dependencies, such as machine translation, sentiment analysis, and speech recognition. Their success has made LSTMs a foundational component in the field of deep learning, providing a powerful tool for modeling sequential data with improved memory and context retention.

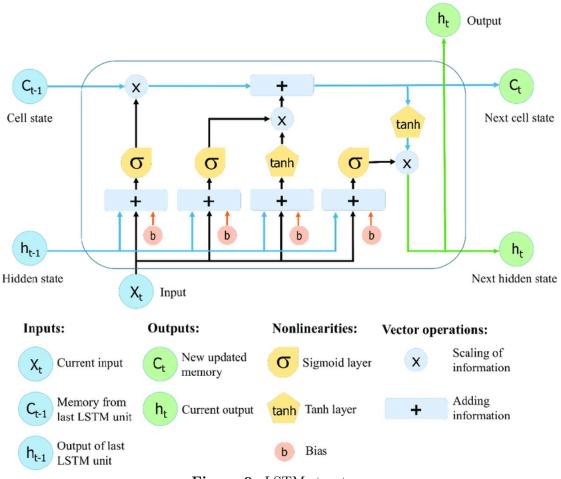


Figure 9: LSTM structure

The core strength of LSTMs lies in their ability to selectively remember or forget information over extended time intervals, allowing them to capture dependencies over long sequences more effectively. This is achieved through the use of memory cells, input, output, and forget gates, each serving a distinct purpose in the learning process.



Memory cells act as storage units that store information over time. The input gate controls the flow of new information into the memory cell, while the forget gate regulates the removal of outdated or irrelevant information. The output gate then determines what information should be passed on to the next time step or output layer. This intricate architecture enables LSTMs to retain relevant information and discard unnecessary details, facilitating the learning of sequential patterns.

LSTMs have proven highly successful in a variety of applications, particularly in natural language processing tasks like language modeling, sentiment analysis, and machine translation. Their ability to model long-range dependencies makes them well-suited for scenarios where understanding the context over extended sequences is crucial. LSTMs have become a fundamental building block in deep learning architectures, contributing significantly to the advancement of sequence-based learning and enabling the development of more sophisticated and capable AI systems.

3.3 Combined Models

A neural network architecture that combines Convolutional Neural Networks (CNNs) with Long Short-Term Memory networks (LSTMs) is commonly referred to as a CNN-LSTM model. This hybrid architecture is particularly effective for tasks that involve sequential data with spatial dependencies, such as video analysis, action recognition, or even certain types of natural language processing tasks.

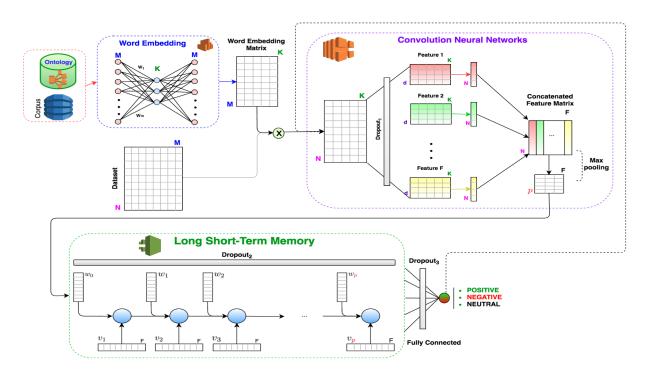
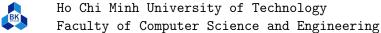


Figure 10: CNN combined with LSTM structure

In a typical CNN-LSTM architecture, the initial layers of the network are comprised of CNN layers. These convolutional layers are well-suited for capturing spatial features and patterns within the input data. In the context of image data, CNNs excel at learning hierarchical representations of visual features, enabling them to recognize patterns such as edges, textures, and object parts.

Following the CNN layers, the output is reshaped and fed into one or more LSTM layers. The LSTM layers are responsible for processing the sequential information, capturing temporal dependencies, and learning patterns over longer sequences. The combination of CNNs and LSTMs leverages the strengths of both architectures: CNNs for spatial feature extraction and LSTMs for sequential modeling.

This architecture is beneficial in scenarios where understanding both spatial and temporal aspects of the data is essential. For instance, in video analysis, CNNs can identify spatial features in individ-





ual frames, while LSTMs can effectively model the temporal evolution of these features over the entire sequence.

The CNN-LSTM model allows for more comprehensive and nuanced representations of complex data, making it a versatile choice for tasks requiring a combined understanding of spatial and temporal patterns. The combination of CNNs and LSTMs has been successfully applied in various domains, showcasing its efficacy in tasks ranging from video analysis to action recognition and beyond.



4 Reused Models for Sentiment Analysis

In the configuration of the reused models below, I tune the Adam optimizer with a learning rate of 0.0005 as the default value of 0.001 is a little bit high, result in uncontrolled oscillating validation loss through training instead of decreasing through testing. The categorical cross-entropy loss function is selected as the optimization criterion. During training, 15% of the data is reserved for validation to monitor the model's performance. The training process is set to run for a maximum of 100 epochs with a batch size of 512. Early stopping is implemented as a callback, which monitors the validation loss. If the validation loss does not improve by at least 0.01 over the course of 4 consecutive epochs, the training will be stopped early, preventing overfitting and optimizing the training time.

4.1 CNN

• **Structure:** A CNN with three convolutional layers, each with 100 filters, filter size respectively are 3, 4, and 5.

Layer (type)	Output Shape	Param #	Connected to
input_9 (InputLayer)	[(None, 300)]	0	[]
embedding (Embedding)	(None, 300, 400)	3110400	['input_9[0][0]']
conv1d_17 (Conv1D)	(None, 298, 100)	120100	['embedding[8][0]']
conv1d_18 (Conv1D)	(None, 297, 100)	160100	['embedding[8][0]']
conv1d_19 (Conv1D)	(None, 296, 100)	200100	['embedding[8][0]']
max_pooling1d_17 (MaxPooling1D)	(None, 1, 100)	0	['conv1d_17[0][0]']
max_pooling1d_18 (MaxPooli ng1D)	(None, 1, 100)	0	['conv1d_18[0][0]']
max_pooling1d_19 (MaxPooli ng1D)	(None, 1, 100)	0	['conv1d_19[0][0]']
concatenate_6 (Concatenate)	(None, 3, 100)	0	['max_pooling1d_17[0][0]', 'max_pooling1d_18[0][0]', 'max_pooling1d_19[0][0]']
flatten_6 (Flatten)	(None, 300)	0	['concatenate_6[0][0]']
dropout_8 (Dropout)	(None, 300)	0	['flatten_6[0][0]']
dense_8 (Dense)	(None, 3)	903	['dropout_8[0][0]']

Figure 11: CNN model details



• Training results: The metrics after training for 32 epochs before early stopping are measured as below.

 Table 1: Model Evaluation

Model	Train Loss	Train Accuracy	Val. Loss	Val. Accuracy
CNN	1.0251	0.9841	2.9828	0.1686

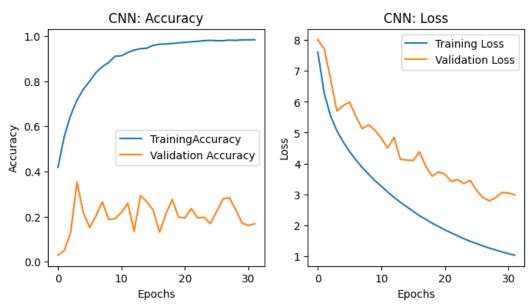


Figure 12: Training accuracy and loss

• Testing results: Accuracy: 65.33%(Loss: 1.7449). Confusion matrix:



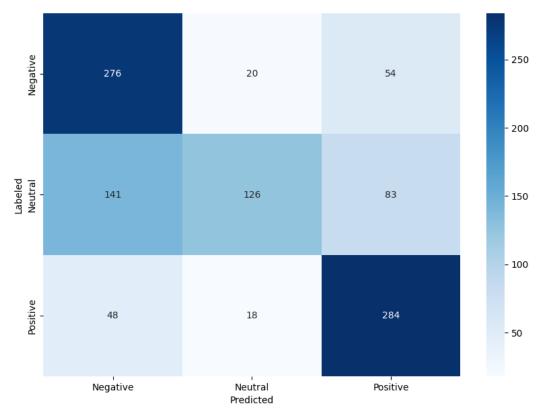


Figure 13: Confusion matrix

Table 2: Testing results

Model	Accuracy	Recall	Precision	F1-Score
CNN	0.6533	0.6533	0.6788	0.6348

4.2 LSTM one layer

• Structure: A simple LSTM model with 512 units.

Layer (type)	Output Shape	Param #
input_7 (InputLayer)	[(None, 300)]	0
embedding (Embedding)	(None, 300, 400)	3110400
reshape_11 (Reshape)	(None, 300, 400)	0
lstm_1 (LSTM)	(None, 512)	1869824
dropout_6 (Dropout)	(None, 512)	0
dense_6 (Dense)	(None, 3)	1539

Total params: 4981763 (19.00 MB) Trainable params: 4981763 (19.00 MB) Non-trainable params: 0 (0.00 Byte)

Figure 14: LSTM 1 layer model details

• Training results: The metrics after training for 11 epochs before early stopping are measured as



below.

Table 3: Model Evaluation

Model	Train Loss	Train Accuracy	Val. Loss	Val. Accuracy
LSTM 1 layer	0.2616	0.9303	2.6989	0.2209

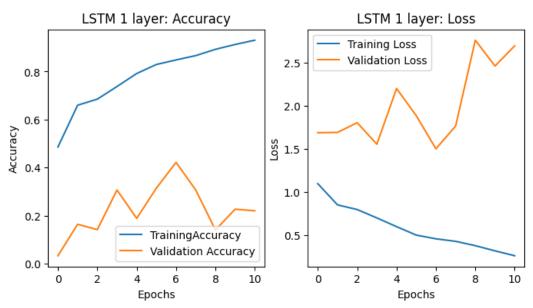


Figure 15: Training accuracy and loss

• Testing results: Accuracy: 65.33%(Loss: 1.0714). Confusion matrix:

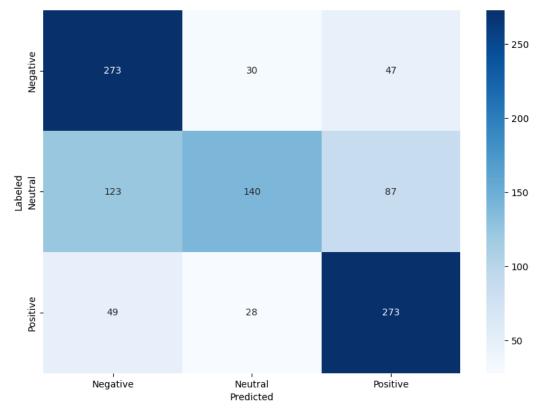


Figure 16: Confusion matrix



Table 4: Testing results

Model	Accuracy	Recall	Precision	F1-Score
LSTM 1 layer	0.6533	0.6533	0.6638	0.6397

4.3 LSTM three layer

• Structure: A LSTM model with 3 layers, unit sizes are 1024, 512, 256 respectively.

Layer (type)	Output Shape	Param #
input_15 (InputLayer)	[(None, 300)]	0
embedding (Embedding)	(None, 300, 400)	3110400
reshape_31 (Reshape)	(None, 300, 400)	0
lstm_6 (LSTM)	(None, 300, 1024)	5836800
lstm_7 (LSTM)	(None, 300, 512)	3147776
lstm_8 (LSTM)	(None, 256)	787456
dropout_14 (Dropout)	(None, 256)	0
dense_14 (Dense)	(None, 3)	771

Total params: 12883203 (49.15 MB)
Trainable params: 12883203 (49.15 MB)
Non-trainable params: 0 (0.00 Byte)

Figure 17: LSTM 3 layers model details

• Training results: The metrics after training for 5 epochs before early stopping are measured as below.

 Table 5: Model Evaluation

Model	Train Loss	Train Accuracy	Val. Loss	Val. Accuracy
LSTM 3 layers	0.4739	0.8544	2.6398	0.1346



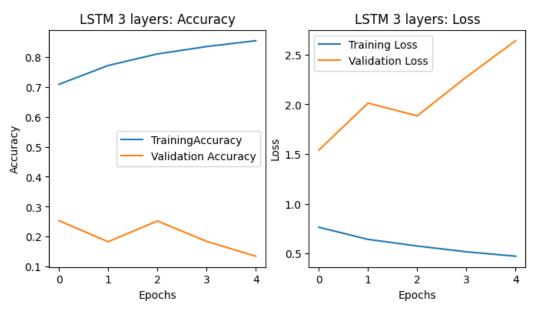


Figure 18: Training accuracy and loss

• Testing results: Accuracy: 61.33%(Loss: 1.1439). Confusion matrix:

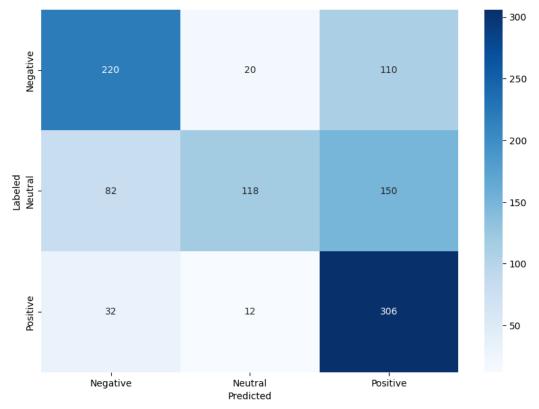


Figure 19: Confusion matrix

Table 6: Testing results

\mathbf{Model}	Accuracy	Recall	Precision	F1-Score	
LSTM 3 layers	0.6133	0.6133	0.6620	0.5945	



5 Modified Models for Sentiment Analysis

Same tuning of the reuse models(learning rate, validation split, batch sizes...) are applied to the configuration and training progress of these models below.

5.1 Larger CNN

• **Structure:** A CNN with three convolutional layers, each with 200 filters, filter size respectively are 6, 10, and 14.

Layer (type)	Output Shape	Param #	Connected to
input_10 (InputLayer)	[(None, 300)]	0	[]
embedding (Embedding)	(None, 300, 400)	3110400	['input_10[0][0]']
conv1d_20 (Conv1D)	(None, 295, 200)	480200	['embedding[9][0]']
conv1d_21 (Conv1D)	(None, 291, 200)	800200	['embedding[9][0]']
conv1d_22 (Conv1D)	(None, 287, 200)	1120200	['embedding[9][0]']
<pre>max_pooling1d_20 (MaxPooli ng1D)</pre>	(None, 1, 200)	0	['conv1d_20[0][0]']
<pre>max_pooling1d_21 (MaxPooli ng1D)</pre>	(None, 1, 200)	0	['conv1d_21[0][0]']
<pre>max_pooling1d_22 (MaxPooli ng1D)</pre>	(None, 1, 200)	0	['conv1d_22[0][0]']
<pre>concatenate_7 (Concatenate)</pre>	(None, 3, 200)	0	['max_pooling1d_20[0][0]', 'max_pooling1d_21[0][0]', 'max_pooling1d_22[0][0]']
flatten_7 (Flatten)	(None, 600)	0	['concatenate_7[0][0]']
dropout_9 (Dropout)	(None, 600)	0	['flatten_7[0][0]']
dense_9 (Dense)	(None, 3)	1803	['dropout_9[0][0]']
Total params: 5512803 (21.03 Trainable params: 5512803 (2 Non-trainable params: 0 (0.0	1.03 MB)		

Figure 20: Larger CNN model details

• Training results: The metrics after training for 20 epochs are measured as below.

 Table 7: Model Evaluation

Model	Train Loss	Train Accuracy	Val. Loss	Val. Accuracy
Larger CNN	2.7503	0.9896	4.7600	0.2131



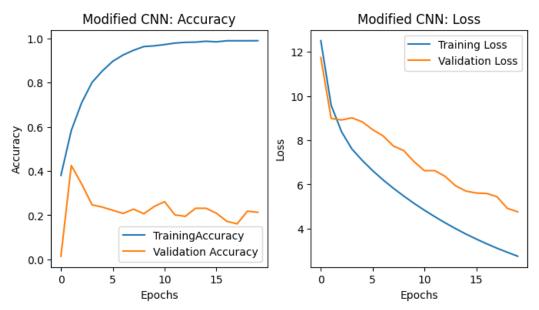


Figure 21: Training accuracy and loss

• Testing results: Accuracy: 66.29%(Loss: 3.3278). Confusion matrix:

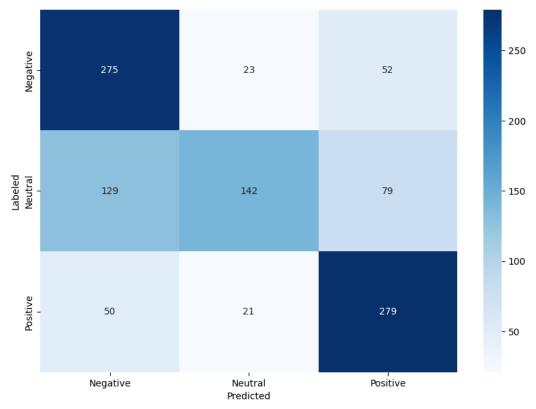


Figure 22: Confusion matrix

Table 8: Testing results

Model	Accuracy	Recall	Precision	F1-Score
Larger CNN	0.6629	0.6629	0.6832	0.6494



5.2 BiLSTM

• Structure: A Bidirectional Long Short-Term Memory (BiLSTM) is an architecture that enhances the capabilities of traditional LSTM networks. In a BiLSTM, the input sequence is processed in both forward and backward directions simultaneously by two separate hidden layers. This bidirectional processing allows the network to capture contextual information from both past and future inputs for each time step.

Layer (type)	Output Shape	Param #
input_16 (InputLayer)	[(None, 300)]	0
embedding (Embedding)	(None, 300, 400)	3110400
reshape_32 (Reshape)	(None, 300, 400)	0
<pre>bidirectional_4 (Bidirectional)</pre>	(None, 2048)	11673600
dropout_15 (Dropout)	(None, 2048)	0
dense_15 (Dense)	(None, 3)	6147

Total params: 14790147 (56.42 MB)
Trainable params: 14790147 (56.42 MB)
Non-trainable params: 0 (0.00 Byte)

Figure 23: BiLSTM model details

• Training results: The metrics after training for 5 epochs before early stopping are measured as below.

Table 9: Model Evaluation

Model	Train Loss	Train Accuracy	Val. Loss	Val. Accuracy
BiLSTM	0.2792	0.9239	1.9211	0.3595

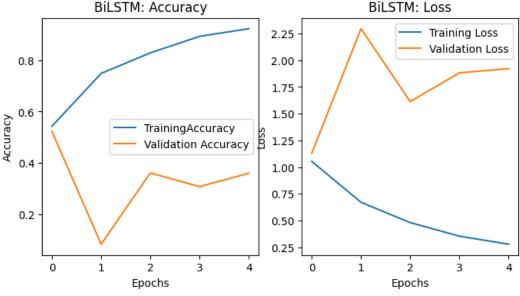


Figure 24: Training accuracy and loss



• Testing results: Accuracy: 66.10%(Loss: 3.3278). Confusion matrix:

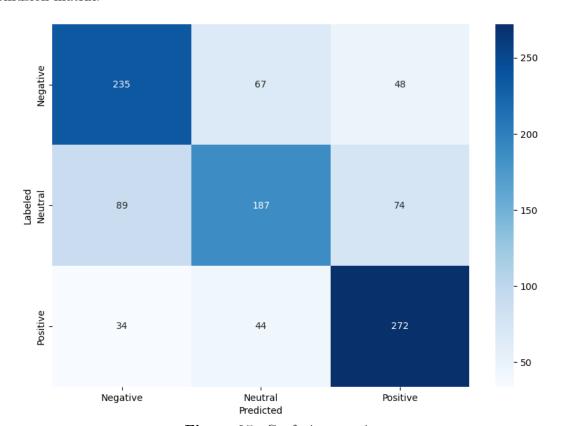


Figure 25: Confusion matrix

Table 10: Testing results

Model	Accuracy	Recall	Precision	F1-Score
BiLSTM	0.6610	0.6610	0.6581	0.6574

5.3 Larger CNN and BiLSTM combined

• Structure: Upon analysis above, it becomes clear that the Larger CNN model outperforms its original counterpart, while the BiLSTM model surpasses both the single-layer and three-layer LSTM models. Recognizing these performance trends, I am motivated to propose a hybrid model of Larger CNN and BiLSTM combined(CNN+BiLSTM) that leverages the strengths of both the CNN and BiLSTM architectures, anticipating enhanced results through their collaborative synergy.



Layer (type)	Output Shape	Param #	Connected to
input_14 (InputLayer)	[(None, 300)]	0	[]
embedding (Embedding)	(None, 300, 400)	3110400	['input_14[0][0]']
reshape_27 (Reshape)	(None, 300, 400)	0	['embedding[13][0]']
conv1d_29 (Conv1D)	(None, 300, 200)	480200	['reshape_27[0][0]']
conv1d_30 (Conv1D)	(None, 300, 200)	800200	['reshape_27[0][0]']
conv1d_31 (Conv1D)	(None, 300, 200)	1120200	['reshape_27[0][0]']
max_pooling1d_29 (MaxPooli ng1D)	(None, 1, 200)	0	['conv1d_29[0][0]']
max_pooling1d_30 (MaxPooli ng1D)	(None, 1, 200)	0	['conv1d_30[0][0]']
max_pooling1d_31 (MaxPooli ng1D)	(None, 1, 200)	0	['conv1d_31[0][0]']
reshape_28 (Reshape)	(None, 1, 200)	0	['max_pooling1d_29[0][0]']
reshape_29 (Reshape)	(None, 1, 200)	0	['max_pooling1d_30[0][0]']
reshape_30 (Reshape)	(None, 1, 200)	0	['max_pooling1d_31[0][0]']
concatenate_10 (Concatenat e)	(None, 1, 600)	0	['reshape_28[0][0]', 'reshape_29[0][0]', 'reshape_30[0][0]']
bidirectional_3 (Bidirecti onal)	(None, 1024)	4558848	['concatenate_10[0][0]']
dropout_13 (Dropout)	(None, 1024)	0	['bidirectional_3[0][0]']
dense_13 (Dense)	(None, 3)	3075	['dropout_13[0][0]']

Figure 26: CNN+BiLSTM model details

• Training results: The metrics after training for 7 epochs are measured as below.

Table 11: Model Evaluation

Model	Train Loss	Train Accuracy	Val. Loss	Val. Accuracy
CNN+BiLSTM	0.4330	0.9993	1.6749	0.5451

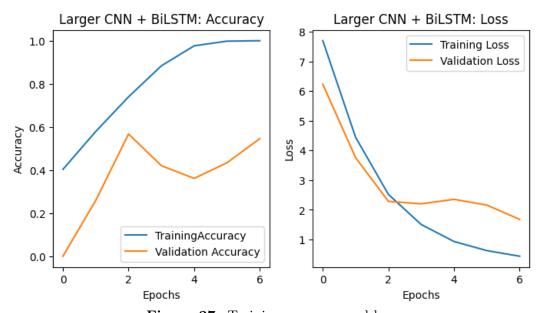


Figure 27: Training accuracy and loss



• Testing results: Accuracy: 70.00%(Loss: 1.1747). Confusion matrix:

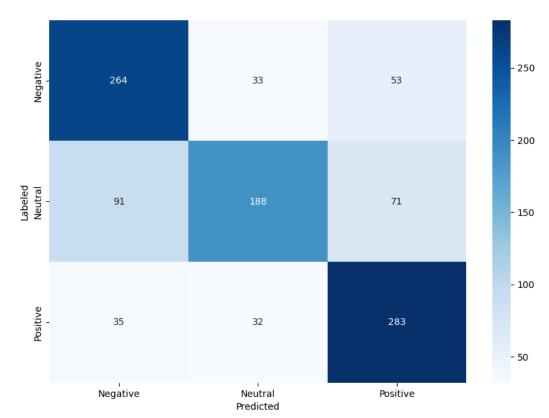


Figure 28: Confusion matrix

Table 12: Testing results

Model	Accuracy	Recall	Precision	F1-Score
CNN+BiLSTM	0.7000	0.7000	0.7051	0.6949



6 Results

The training and testing progress has notable similarities across the various models. While the models demonstrate rapid convergence to high training accuracy, a discernible disparity emerges in achieving commensurate validation accuracy. This suggests potential overfitting tendencies, where the models might excel in memorizing the training data but face challenges in generalizing well to new, unseen data during validation.

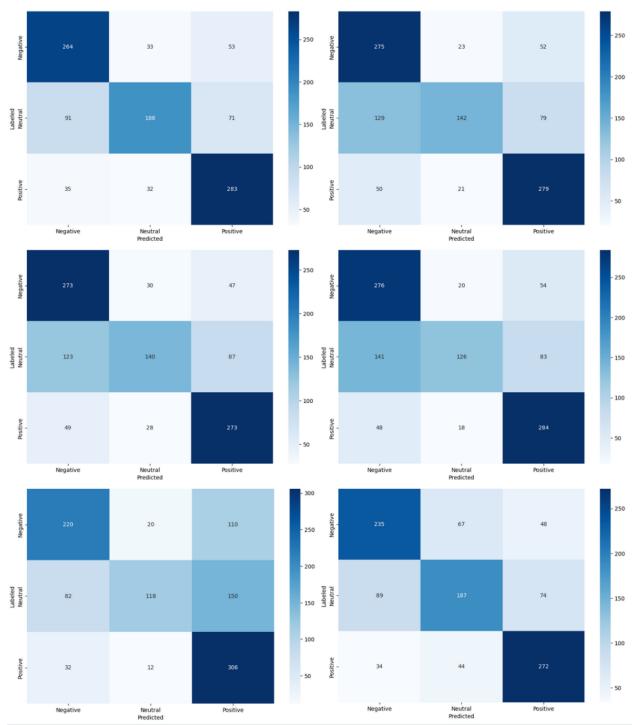


Figure 29: Confusion matrices

Analyzing the confusion matrices reveals a clear pattern in the models' proficiency in predicting sentiments labeled as Negative and Positive. These sentiments are generally handled with relative ease,



showcasing the models' capability in capturing the nuances of these categories. However, a substantial challenge surfaces when it comes to accurately classifying instances within the Neutral category. The models often struggle with this specific sentiment, resulting in a considerable number of misclassifications into other sentiment categories. Addressing this challenge is pivotal for enhancing the overall accuracy and effectiveness of sentiment classification.

These are the final results of the models.

Model	Test Accuracy
CNN+BiLSTM	70.00%
Larger CNN	66.29%
BiLSTM	66.10%
LSTM 1 layer	65.33%
CNN	65.33%
LSTM 3 layers	61.33%

In the pursuit of enhancing sentiment analysis performance, several modified and original models have been evaluated. The results indicate that the Larger CNN combined with BiLSTM model achieved the highest accuracy at 70.00%, outperforming both the Larger CNN (66.29%) and the standalone BiLSTM (66.10%). This suggests that the modifications introduced, particularly the combination of Convolutional Neural Networks (CNN) and Bidirectional Long Short-Term Memory (BiLSTM), contributed to a more effective sentiment analysis framework, showcasing the importance of model architecture in achieving superior results.

As expected, Larger CNN or BiLSTM also surpassed the accuracy of the original models, namely LSTM with one layer (65.33%) and standalone CNN (65.33%). Surprisingly, BiLSTM performs better than LSTM with three layers (61.33%). This finding suggests that the Bidirectional LSTM, with its ability to capture contextual information from both past and future sequences, demonstrated superior performance compared to a deeper but unidirectional LSTM architecture. The efficiency of BiLSTM in understanding nuanced patterns within text sequences underscores its potential as a powerful tool for sentiment analysis tasks.

7 Conclusion

The presented accuracy percentages across various models highlight the inherent complexities of the sentiment analysis task. Achieving accurate sentiment classification is a challenging endeavor, as indicated by the modest performance across different architectures. Notably, the CNN+BiLSTM model stands out with an accuracy of 70.00%, surpassing other configurations. This suggests that combining Convolutional Neural Networks (CNN) with Bidirectional Long Short-Term Memory (BiLSTM) networks provides a more effective approach in capturing and understanding sentiment patterns within the given dataset. The superior performance of the CNN+BiLSTM model underscores the significance of leveraging both spatial hierarchies through CNN and contextual dependencies through BiLSTM for a more robust sentiment analysis solution.

Working Notebook: https://colab.research.google.com/drive/1AUk9NNu-WqArcDST1x0VNSMGQT7er521?usp=sharing