

Create the constrained expression:

Create parameters $\theta(x)$ and $n(y)$. Use a univariate constrained expression to force $\theta(x)$ to adhere to the following constraints:

$$\sqrt{2} \sin(\theta(0)) = (-1)^{\text{UnitStep}(n(0))} \text{ and } \sqrt{2} \cos(\theta(0)) = (-1)^{\text{UnitStep}(n(1))}.$$

This can be rewritten as one constraint:

$$\tan(\theta(0)) = \frac{(-1)^{\text{UnitStep}(n(0))}}{(-1)^{\text{UnitStep}(n(1))}}.$$

```
In[1]:=  $\theta\text{Func}[x\_ , n\_ \text{Symbol}, \theta\_ \text{Symbol}] := \theta[x] + \text{ArcTan}\left[(-1)^{\text{UnitStep}[n[1]]}, (-1)^{\text{UnitStep}[n[0]]}\right] - \theta[0]$ 
```

Check that the univariate constrained expression we created has the properties we want:

```
In[2]:= FullSimplify[ $\sqrt{2} \cos[\theta\text{Func}[0, n, \theta]] == (-1)^{\text{UnitStep}[n[1]]}$ ]
FullSimplify[ $\sqrt{2} \sin[\theta\text{Func}[0, n, \theta]] == (-1)^{\text{UnitStep}[n[0]]}$ ]
FullSimplify[( $\sqrt{2} \cos[\theta\text{Func}[0, n, \theta]]$ )2 + ( $\sqrt{2} \sin[\theta\text{Func}[0, n, \theta]]$ )2 == 2]
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Out[2]= True
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Out[3]= True
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Out[4]= True
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Create the rest of the multivariate constrained expression.

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In[5]:= s2[x_] := {1, x};
S2 = {s2[0], 2 Integrate[s2[1], {y, 0, 1}]};
 $\alpha 2$  = Inverse[S2];
 $\phi 2[x_] := s2[x].\alpha 2$ ;
 $\rho 2[x\_ , y\_ , n\_ \text{Symbol}, g\_ \text{Symbol}] :=$ 
  {(-1)UnitStep[n[y]] - g[0, y], 1 - 2 Integrate[g[1,  $\tau$ ], { $\tau$ , 0, 1}]};
u2[x_, y_, n_Symbol, g_Symbol] := g[x, y] +  $\phi 2[x].\rho 2[x, y, n, g]$ ;

s1[y_] := {1, y, y2};
S1 = {s1[0], s1[1], 2 Integrate[s1[y], {y, 0, 1}]};
 $\alpha 1$  = Inverse[S1].{{1, 0}, {0, 1}, {0, 0}};
 $\phi 1[y_] := s1[y].\alpha 1$ ;
 $\rho 1[x\_ , y\_ , n\_ \text{Symbol}, \theta\_ \text{Symbol}, g\_ \text{Symbol}] :=$ 
  { $\sqrt{2} \sin[\theta\text{Func}[x, n, \theta]] - u2[x, 0, n, g]$ ,  $\sqrt{2} \cos[\theta\text{Func}[x, n, \theta]] - u2[x, 1, n, g]$ };
u[x_, y_, n_Symbol,  $\theta\_ \text{Symbol}, g\_ \text{Symbol}] := u2[x, y, n, g] +  $\phi 1[y].\rho 1[x, y, n, \theta, g]$ ;$ 
```

Check the constraints:

```
In[17]:= FullSimplify[u[0, y, n,  $\theta$ , g]2 == 1]
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Out[17]= True
```

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In[18]:= FullSimplify[u[x, 0, n,  $\theta$ , g]2 + u[x, 1, n,  $\theta$ , g]2 == 2]
```

```
Out[18]= True
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```
In[19]:= FullSimplify[2 Integrate[u[1, y, n,  $\theta$ , g], {y, 0, 1}] == 1]
```

```
Out[19]= 2  $\int_0^1 \left( \sqrt{2} y (-2 + 3 y) \cos \left[ \text{ArcTan} \left[ (-1)^{\text{UnitStep}[n[1]]}, (-1)^{\text{UnitStep}[n[0]]} \right] - \theta[0] + \theta[1] \right] + \right.$   

 $(2 - 3 y) y g[1, 1] + g[1, y] + 6 (-1 + y) y \int_0^1 g[1, \tau] d\tau + (-1 + y) \left( g[1, 0] - 3 y (1 + g[1, 0]) + \right.$   

 $\left. \left. \sqrt{2} (-1 + 3 y) \sin \left[ \text{ArcTan} \left[ (-1)^{\text{UnitStep}[n[1]]}, (-1)^{\text{UnitStep}[n[0]]} \right] - \theta[0] + \theta[1] \right] \right) \right) dy == 1$ 
```

One can verify that the above is true the long tedious way, or more simply by proving that the following is true (which it is)

```
In[20]:= FullSimplify[2 Integrate[u2[1, y, n, g], {y, 0, 1}] == 1]
```

```
Out[20]= 2  $\int_0^1 \left( \frac{1}{2} + g[1, y] - \int_0^1 g[1, \tau] d\tau \right) dy == 1$ 
```

and observing that ρ_1 is not a function of y and $2 \int_0^1 \phi[y] dy = 0$, so $2 \int_0^1 \rho_1 * \phi_1[y] dy = 2 \rho_1 \int_0^1 \phi_1[y] dy = 0$

```
In[21]:= FullSimplify[2 Integrate[\phi_1[y], {y, 0, 1}]]
```

```
Out[21]= {0, 0}
```