# **Homework 3**

```
In [1]: import numpy as np import math import matplotlib.pyplot as plt import IPython.display as ipd from scipy import signal

%matplotlib inline
```

### Proakis 5.3a:

```
In [3]: | w = np.linspace(-np.pi, np.pi, 1000)
           w, H = signal.dfreqresp(systemH, w)
           plt.figure(figsize = (15,5))
           plt.plot(w, np.abs(H));
           plt.figure(figsize = (15,5))
plt.plot(w, np.angle(H));
           2.0
           1.8
           1.4
           1.2
           1.0
           0.8
            0.4
            0.2
            0.0
            -0.2
           -0.4
```

**Proakis 5.3b** 

```
In [4]: x_n = np.cos(3*np.pi*w/10)
          X_k = np.fft.fft(x_n,)
           Y_k = X_k^*H
           plt.figure(figsize = (15,5))
           plt.plot(w, np.abs(Y_k));
           plt.figure(figsize = (15,5))
plt.plot(w, np.angle(Y_k));
           300
           250
           200
           150
           100
            50
                                  -2
                    -3
            2
            0
           -2
           -3
                                                -1
```

```
In [5]: x_n = [1,0,0,1,1,1,0,1,1,1,0,1]
           X_k = np.fft.fft(x_n, n=1000)
          w = np.linspace(-3,8,1000)
w, H = signal.dfreqresp(systemH, w)
           Y_k = X_k^*H
           plt.figure(figsize = (15,5))
plt.plot(w, np.abs(X_k));
           plt.figure(figsize = (15,5))
           plt.plot(w, np.angle(X_k));
           5
           3
           1
            1
            0
           -1
            -2
            -3
```

#### **Proakis 5.4b**

```
In [6]: numX = [0.5, -1]
         denX = [1, 0]
         ##################
         # compute the impulse response
         systemX = signal.dlti(numX, denX)
         w = np.linspace(0, np.pi, 10000)
         w, H = signal.dfreqresp(systemX, w)
         plt.figure(figsize = (15,5))
         plt.plot(w, np.abs(H));
         plt.figure(figsize = (15,5))
         plt.plot(w, np.angle(H));
          1.4
          1.2
          1.0
          0.8
          0.6
                                                                 2.0
               0.0
                                                                                          3.0
          3.0
          2.5
          2.0
          1.5
          1.0
          0.5
          0.0
```

### **Proakis 5.4c**

0.0

0.5

1.0

1.5

2.0

2.5

```
In [7]: j = np.complex(0,1)
          w = np.linspace(0, np.pi, 10000)
          H = np.sin(w)*np.exp(j*np.pi/2)
          plt.figure(figsize = (15,5))
          plt.plot(w, np.abs(H));
          plt.figure(figsize = (15,5))
          plt.plot(w, np.angle(H));
           1.0
           0.8
           0.6
           0.4
           0.2
           0.0
                                                         1.5
                                                                       2.0
                              0.5
                                            1.0
                                                                                    2.5
                                                                                                  3.0
           1.6
           1.4
           1.2
           1.0
           0.8
           0.6
           0.2
           0.0
                0.0
                                            1.0
                                                         1.5
                                                                       2.0
                                                                                                  3.0
```

**Proakis 5.4i** 

```
In [8]: | w = np.linspace(0,np.pi,10000)
          H = 2*np.exp(-j*w) - np.exp(-j*2*w)
          plt.figure(figsize = (15,5))
          plt.plot(w, np.abs(H));
          plt.figure(figsize = (15,5))
          plt.plot(w, np.angle(H));
           3.00
           2.75
           2.50
           2.25
           2.00
           1.75
           1.50
           1.25
           1.00
                  0.0
                                0.5
                                                                         2.0
            0.0
           -0.5
           -1.0
           -1.5
           -2.0
           -2.5
           -3.0
                                0.5
                                             1.0
                                                           1.5
                                                                                       2.5
                                                                                                     3.0
                  0.0
                                                                         2.0
```

# Proakis 5.4j

```
In [9]: | w = np.linspace(0,np.pi,10000)
           H = np.cos(w)*np.cos(w/2)*np.exp(-j*3*w/2)
           plt.figure(figsize = (15,5))
           plt.plot(w, np.abs(H));
           plt.figure(figsize = (15,5))
plt.plot(w, np.angle(H));
            1.0
            0.8
            0.6
            0.4
            0.2
            0.0
                  0.0
                                 0.5
                                                1.0
                                                               1.5
                                                                                             2.5
                                                                                                           3.0
             0.5
             0.0
            -0.5
            -1.0
            -1.5
            -2.0
            -2.5
```

#### **Proakis 5.4k**

```
In [10]: | w = np.linspace(0,np.pi,10000)
           H = np.cos(w/2)*np.cos(w/2)*np.cos(w/2)*np.exp(-j*3*w/2)
           plt.figure(figsize = (15,5))
           plt.plot(w, np.abs(H));
           plt.figure(figsize = (15,5))
           plt.plot(w, np.angle(H));
           1.0
           0.8
           0.6
           0.4
           0.2
           0.0
                 0.0
                              0.5
                                           1.0
                                                                     2.0
                                                                                  2.5
                                                                                               3.0
            2
            0
           -1
           -2
           -3
                                           1.0
                                                        1.5
                                                                     2.0
                                                                                               3.0
```

## **Proakis 7.17**

```
In [11]: x_n = [1,1,1,1,1,0,0]
N = 8

X_k = np.fft.fft(x_n, n=N)
k = np.linspace(0,N,N)
print(k)

plt.figure(figsize = (15,5))
plt.stem(k, np.abs(X_k));

plt.figure(figsize = (15,5))
plt.stem(k, np.angle(X_k));
```

[0. 1.14285714 2.28571429 3.42857143 4.57142857 5.71428571 6.85714286 8. ]

/home/sweet/2-coursework/ecec434/labs/lib/python3.6/site-packages/ipykernel\_laun cher.py:11: UserWarning: In Matplotlib 3.3 individual lines on a stem plot will be added as a LineCollection instead of individual lines. This significantly imp roves the performance of a stem plot. To remove this warning and switch to the n ew behaviour, set the "use\_line\_collection" keyword argument to True.

# This is added back by InteractiveShellApp.init\_path()
/home/sweet/2-coursework/ecce434/labs/lib/python3.6/site-packages/ipykernel\_laun
cher.py:14: UserWarning: In Matplotlib 3.3 individual lines on a stem plot will
be added as a LineCollection instead of individual lines. This significantly imp
roves the performance of a stem plot. To remove this warning and switch to the n
ew behaviour, set the "use\_line\_collection" keyword argument to True.

