Assignment 6 report

In this assignment, i gathered soil moisture sensor readings, measured as values from 0-4000 (using ESP32- 3.3Volt). To convert these into actual soil moisture readings, i need to calibrate your sensor, taking readings from soil samples, then calculating the gravimetric soil moisture content from these samples.

Part 1. Take a soil moisture reading using the soil moisture sensor and write down this reading.

The data collected by 3 sample of soil is measured by kitchen **microscale** and esp32 microprocessor displayed through Laptop monitor and recorded as follow

• Sample 1: 2883 Volt / 11 Grams

• Sample 2: 2332 Volt / 13 Grams

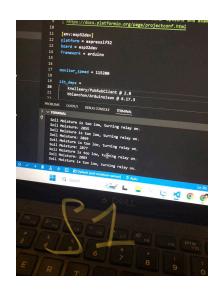
Sample 3: 1527 Volt/ 22 Grams

The actual footages of the Test are given below

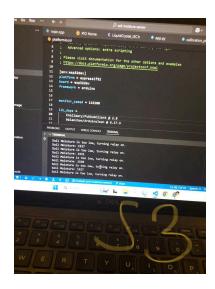




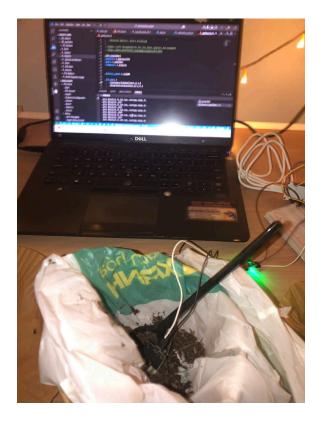




```
12 platform = espressif32
13 board = esp32dev
14 framework = arduino
15
16
17 monitor_speed = 115200
18
19 lib_deps =
20 knolleary/PubSubClient @ 2.8
21 bblanchon/ArduinoJson @ 6.17.3
22
22
23 bblanchon/ArduinoJson @ 6.17.3
24
25 coll koisture is to low, turning relay on.
50il koisture is to low, turning relay on.
```







Part 2: Drying in the oven for completely dry the soil sample

The 3 soil sample is then dried in the oven for 3 hours with low heat and uncovered oven (For the moisture to disappear), then weigh again for final calculation.

• Sample 1: 8 grams

• Sample 2: 8 grams

• Sample 3: 12 grams

The result is depicted below for 3 sample:

*





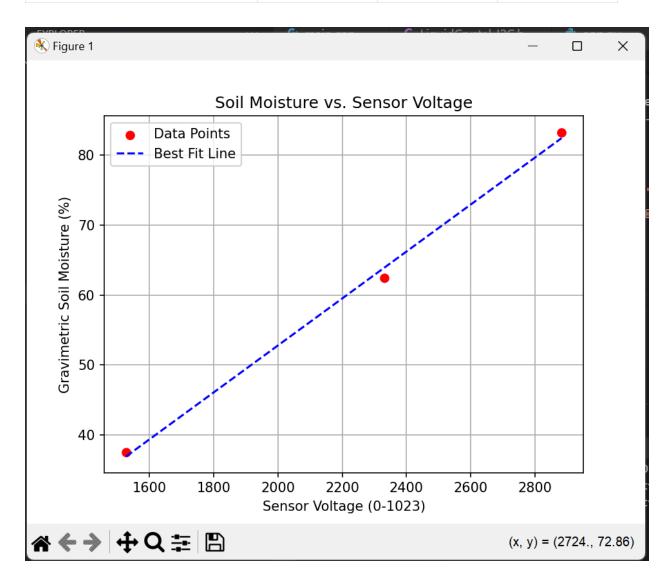


Part 3: gravimetric soil moisture calculation

Soil moisture
$$\% = \frac{W_{\text{wet}} - W_{\text{dry}}}{W_{\text{dry}}} \times 100$$

Statistic table

Sample	1	2	3
Weight with moisture (gram)	11	13	22
Weight without moisture (gram)	8	8	12



#Code for connecting Moisture sensor with Arduino (include the output of LED1606 using LiquidCrystal_I2C.h)

```
#include <Arduino.h>
#define M_PIN A1 // Moisture sensor pin
#define RELAY_PIN 4 // Relay connected to D4
void setup() {
  Serial.begin(9600);
  pinMode(M_PIN, INPUT);
  pinMode(RELAY_PIN, OUTPUT);
  digitalWrite(RELAY_PIN, LOW); // Start with relay OFF
}
void loop() {
  int moisture = analogRead(M_PIN); // Read moisture sensor
  // Check moisture level and control relay
  if (moisture > 450) {
    Serial.println("Moisture level too low, turning relay ON");
    digitalWrite(RELAY_PIN, HIGH); // Turn relay ON
  } else {
    Serial.println("Moisture level sufficient, turning relay OFF");
    digitalWrite(RELAY_PIN, LOW); // Turn relay OFF
  }
  // Print moisture value to Serial Monitor
  Serial.print("Moisture Level: ");
  Serial.println(moisture);
  delay(1000); // Wait 1 second before next reading
}
```

#Code of Jupiter notebook used for calibration graph

```
import numpy as np
import matplotlib.pyplot as plt
from scipy.stats import linregress
# Sample data: Voltage (sensor readings) and Gravimetric Soil Moisture (%)
voltage_values = [2883, 2331, 1527] # Example voltage values
moisture_values = [83.3, 62.5, 37.5] # Example moisture percentages
# 22 - 12 = 10 / 12 = 0.833 | 13 - 8 = 5 / 8 = 62,5 % | 11 - 8 = 3 / 8 = 37,5 %
# Perform linear regression to find the best-fit line
slope, intercept, r_value, p_value, std_err = linregress(voltage_values, moisture_value)
print(f"Equation: y = {slope:.4f}x + {intercept:.4f}")
# Generate x values for the line
x_values = np.linspace(min(voltage_values), max(voltage_values), 100)
y_values = slope * x_values + intercept
# Plot the data points
plt.scatter(voltage_values, moisture_values, color='red', label='Data Points')
plt.plot(x_values, y_values, linestyle='--', color='blue', label='Best Fit Line')
# Labels and title
plt.xlabel('Sensor Voltage (0-1023)')
plt.ylabel('Gravimetric Soil Moisture (%)')
plt.title('Soil Moisture vs. Sensor Voltage')
plt.legend()
plt.grid()
# Show the plot
plt.show()
```