

command
""
"--help"
"<script>alert('hi');</script>"
"<script>alert('hi')</script>"
"ASas"
"a"
"a;"
"a=2;"
"a=2;a;"
"adsads"
"adsdddd"
"asd"
"asda"
"asdad"
"asdadasda"
"asdadsadadad"
"asdasd"
"asdddddddddddddddddddddddddd"
"asdsadasd"
"asdss"
"body"
"d"
"dd"
"ddd"
"dd"
"disp(\"hello\");"
"disp(\"hello\");1;"
"ds"
"dsdsd"
"gonna"
"help"
"me"
"once"
"roll"
"round(quad(@sin, 0, pi/2));"
"s"
"sd"
"sdsd"
"sdsdadad"
"sdsdsd"
"sdsdsddsd"
"sdsdsddsdaasdsad"
"sdsdsdsda"
"some"
"the"
"told"
"tralalala"
"world's"
a
a + a
a = 10;\na + a * 3;
a = 1;
a = 2; a;
a = 50;
a = 50; a + a

a;
asd
asda
asdad
asdasd
ball(r=-0.4)
ball(r=-0.45)
ball(r=-0.5)
ball(r=-0.75)
ball(r=-0.8)
ball(r=-1.0)
ball(r=0.2)
ball(r=0.35)
ball(r=0.5)
ball(r=0.55)
ball(r=0.65)
ball(r=0.75)
ball(r=0.9)
ball(r=1.0)
ball(r=15.3)
d
disp("hello");
disp("hello");1;
disp(a);
display('hello')
display(a);
ds
foo = [1, 2];
for i = 1:3; disp(i);end
fuck you matlab
hello\n
hello;\n
help
help;\n
kk
linspace
ls
pendulum(r=-0.4)
pendulum(r=-1.0)
pendulum(r=0.0)
pendulum(r=0.05)
pendulum(r=0.2)
pendulum(r=0.25)
pendulum(r=0.3)
pendulum(r=0.35)
pendulum(r=0.4)
pendulum(r=0.45)
pendulum(r=0.5)
pendulum(r=0.55)
pendulum(r=0.6)
pendulum(r=0.7)
pendulum(r=1.0)
pendulum(r=14.3)
pendulum(r=15.3)
pendulum(r=19.8)
pendulum(r=24.7)
pendulum(r=26.2)

pendulum(r=35.0)
pendulum(r=35.6)
plane(r=-0.15)
plane(r=-0.75)
plane(r=-1.0)
plane(r=0.2)
plane(r=0.4)
plane(r=0.45)
plane(r=0.5)
plane(r=0.55)
plane(r=0.6)
plane(r=0.65)
plane(r=0.7)
plane(r=0.75)
plane(r=1.0)
plane(r=18.6)
plane(r=20.8)
plane(r=21.3)
plane(r=3.4)
plane(r=31.0)
plane(r=35.6)
round(quad(@sin, 0, pi/2));
sad
sada
sdsad
sdsd
sdsda
suspension(r=-0.2)
suspension(r=-0.95)
suspension(r=-1.0)
suspension(r=0.0)
suspension(r=0.2)
suspension(r=0.3)
suspension(r=0.4)
suspension(r=0.5)
suspension(r=0.55)
suspension(r=0.65)
suspension(r=0.95)
suspension(r=1.0)
suspension(r=10.0)
suspension(r=2.0)
suspension(r=29.4)
suspension(r=5.0)