

Groverize Monotone Local Search. (Short Note)

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1 Todo.

1. Write the table (sage script).
2. Add definitions. Problem description.
3. Complete the 'proof'.
4. Prove lower bound.

2 Introduction.

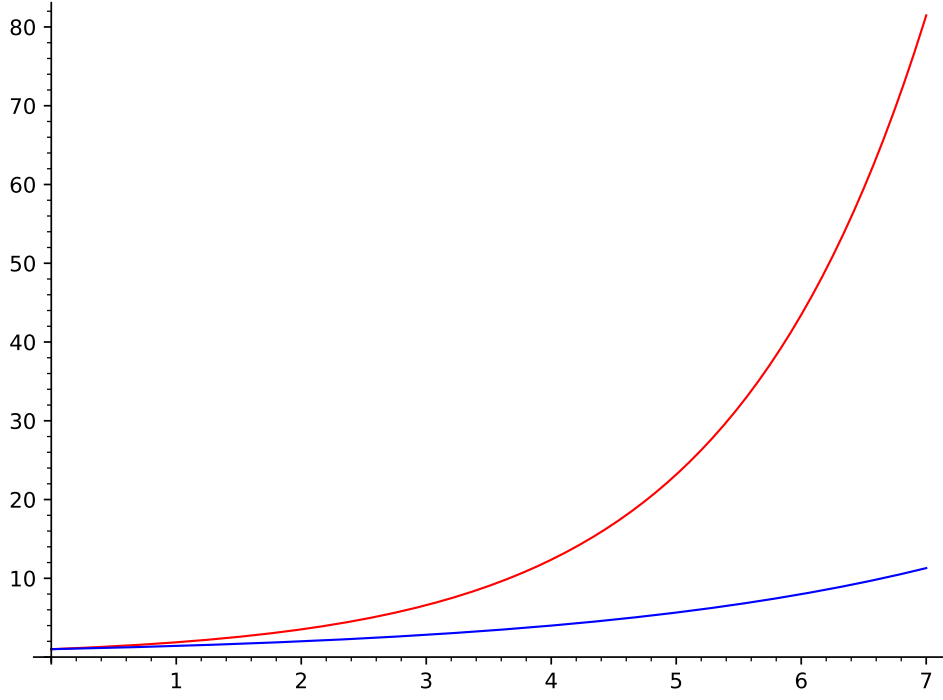
We follow the study of [Fom+15], who relate between the parametrized complexity to the general average case complexity. Crudely put, they shown that for particular wide range of **NP** hard problems, a solution which run exponentially at some complexity parameter, for example the tree-width of a graph, can be used to derive a batter than bruteforce solution for the general problem. We continue their work by plugin the Grover search [Gro96] routine instead the original sampling process. We will simplify the definitions given at [Fom+15] and use the following definitions instead:

Consider a decision problem inside **NP**, in this paper, we will associate two verifiers U, V with each language. U stands for input validation, conceptually it uses for checking that the solution 'live' inside the problem world. For example, for the **3-SAT**, U checks that the input indeed encode an assignment. Formally the role of U is to restrict the inputs to certain form. And V responsible to verify that the word indeed in the language, ie check that the assignment satisfies the formula. We will say that a problem is an *extension problem* if requiring any of the input bits to be 1 could reduced to another instance of the problem. For example, consider **3-SAT**, fixing an arbitrary bit x_i to be 1 could reduced to another **3-SAT** formula by erase any of the clauses contain x_i and replacing any of the occurrences of \bar{x}_i by other termianl on the same clouser (i.e $\bar{x}_i \wedge \bar{y} \wedge z \mapsto \bar{y} \wedge \bar{y} \wedge z$). the input any instance of the problem could be representated as the bit-wise union of two strings which pass U verification. For example, any assignment satisfies a **3-SAT** instance could be write as or-wise of two assignments.

Definition 1. A directed graph G is a pair (V, E) where V is a set of vertices and E is a set of directed edges.

Definition 2. The directed shortest path problem is the problem of finding the directed path with the minimum weight between two given vertices in a directed weighted graph.

$$\begin{aligned}
\sum_{k' \leq k} \frac{1}{\sqrt{p(k')}} \cdot c^{k'-t} N^{\mathcal{O}(1)} &\leq \max_{k' \leq k} \left(\frac{\binom{n-|X|}{t}}{\binom{k'}{t}} \right)^{\frac{1}{2}} \cdot c^{k'-t} N^{\mathcal{O}(1)} = \\
\left(\max_{k' \leq k} \frac{\binom{n-|X|}{t}}{\binom{k'}{t}} \cdot c^{2(k'-t)} \right)^{\frac{1}{2}} N^{\mathcal{O}(1)} &= \left(\max_{k \leq n-|X|} \frac{\binom{n-|X|}{t}}{\binom{k}{t}} \right)^{\frac{1}{2}} \cdot c^{2(k-t)} N^{\mathcal{O}(1)} \leq \\
\Rightarrow \left(2 - \frac{1}{c^2} \right)^{\frac{n-|X|}{2}} N^{\mathcal{O}(1)}
\end{aligned}$$



Problem Name	Parameterized	Groverize	New bound	Previous Bound
FEEDBACK VERTEX SET	3^k (r) [Cyg+11]	1.3744^k	1.6667^n (r)	
FEEDBACK VERTEX SET	3.592^k [KP14]	1.3865^k	1.7217^n	1.7347^n [FTV13]
SUBSET FEEDBACK VERTEX SET	4^k [Wahlstrom14]	1.3919^k	1.7500^n	1.8638^n [Fom+14]
FEEDBACK VERTEX SET IN TOURNAMENTS	1.6181^k [KL16]	1.2720^k	1.3820^n	1.4656^n [KL16]
GROUP FEEDBACK VERTEX SET	4^k [Wahlstrom14]	1.3919^k	1.7500^n	NPR
NODE UNIQUE LABEL COVER	$ \Sigma ^{2k}$ [Wahlstrom14]	1.3919^k	$(2 - \frac{1}{ \Sigma })^n$	NPR
VERTEX (r, ℓ) -PARTIZATION $(r, \ell \leq 2)$	3.3146^k [KolayP15; Bas+17]	1.3817^k	1.6984^n	NPR
INTERVAL VERTEX DELETION	8^k [Cao16]	1.3466^k	1.8750^n	$(2 - \varepsilon)^n$ for $\varepsilon < 10^{-20}$ [BFP13]
PROPER INTERVAL VERTEX DELETION	6^k [tV13; Cao16]	1.4087^k	1.8334^n	$(2 - \varepsilon)^n$ for $\varepsilon < 10^{-20}$ [BFP13]
BLOCK GRAPH VERTEX DELETION	4^k [Agr+16]	1.4044^k	1.7500^n	$(2 - \varepsilon)^n$ for $\varepsilon < 10^{-20}$ [BFP13]
CLUSTER VERTEX DELETION	1.9102^k [Bor+14]	1.3919^k	1.4765^n	1.6181^n [Fom+10]
THREAD GRAPH VERTEX DELETION	8^k [Kan+15]	1.3919^k	1.8750^n	NPR
MULTICUT ON TREES	1.5538^k [Kan+14]	1.3138^k	1.3565^n	NPR
3-HITTING SET	2.0755^k [MagnusPhD07]	1.4087^k	1.5182^n	1.6278^n [MagnusPhD07]
4-HITTING SET	3.0755^k [Fom+10]	1.2593^k	1.6750^n	1.8704^n [Fom+10]
d -HITTING SET $(d \geq 3)$	$(d - 0.9245)^k$ [Fom+10]	1.1763^k	$(2 - \frac{1}{(d-0.9245)})^n$	[Coc+16; Fom+10]
MIN-ONES 3-SAT	2.562^k [abs-1007-1166]	1.3296^k	1.6097^n	NPR
MIN-ONES d -SAT $(d \geq 4)$	d^k	1.3763^k	$(2 - \frac{1}{d})^n$	NPR
WEIGHTED d -SAT $(d \geq 3)$	d^k	1.3763^k	$(2 - \frac{1}{d})^n$	NPR
WEIGHTED FEEDBACK VERTEX SET	3.6181^k [Agr+16]	1.1763^k	1.7237^n	1.8638^n [Fom+08]
WEIGHTED 3-HITTING SET	2.168^k [SZ15]	1.3593^k	1.5388^n	1.6755^n [Coc+16]
WEIGHTED d -HITTING SET $(d \geq 4)$	$(d - 0.832)^k$ [Fom+10; SZ15]	1.3919^k	$(2 - \frac{1}{d-0.932})^n$	[Coc+16]

Table 1: Summary of known and new results for different optimization problems. NPR means that we are not aware of any previous algorithms faster than brute-force. All bounds suppress factors polynomial in the input size N . The algorithms in the first row are randomized (r).

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