Hardness of Computing Fault Tolerance.

David Ponarovsky

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Introduction

- ▶ Brief overview of the topic
- ► Importance and relevance
- Objectives of the presentation

Key Points

- ▶ Main point 1
- ► Main point 2
- ► Main point 3

Nosiy Circuit.



Threshoold Theorem.

Pippenger's Construction.

Encode each bit with the repetition code $0 \mapsto 0^m$, $1 \mapsto 1^m$. Now observe that any logical operation, without decoding, can be made in O(1) depth.

For example, $OR(\bar{x}, \bar{y})$ can be computed by applying in parallel $OR(x_i, y_i)$ for each i.

The 'Decoding' trick.

Instead of completely decoding, we would apply only a single step of partial decoding. We assume that in each code block the bits are partitioned into random disjoint triples, and we will apply a local correction to each of the triples by majority.

Claim

There are constants $\alpha, \eta \in (0,1)$ such that for any bit string x at a distance $\leq \alpha n$ from the code (Repetition Code), one cycle of local correction on x yields x' such that:

$$d(x',C) \leq d(x,C)$$

The 'Decoding' trick.

Suppose that a bit obserb a bit flip with probability p. So in expectation we expect that entire bolck at length n will absorb pn flips.

$$\eta (\beta + p) n \le \beta n$$

$$\beta \ge \frac{p}{1 - \eta}$$

From now on, we will assume that the graphs are bipartite and we will denote the right and the left vertices by V^- and V^+ . Notice that such expanders near Ramanujan exist, see for example [?]. The partition into two subsets enable us to come with a simple efficient decoder.

Expanders code are known for having good decoders, beneath, in $\ref{eq:condition}$, we introduce a procedure to reduce an error. In overall, we alternately let to the right and then the left vertices to correct their own local view. In Theorem 1 we prove that when the applied error has size at most βn , for some constant β then the error's weight reduced by $\frac{1}{2}$. Repeating over the procedure $\Theta(\log(n))$ times completely correct the error.

We will call to the first stage, when only the right vertices suggest correction the right round, and to the second stage a left round. For the whole procedure, we will call a single correction round.

Lemma

If the error is at wight less than βn then a single round of the

Denote by $S^{(0)} \subset V^+$ and $T^{(0)} \subset V^-$ the subsets of left and right vertices adjacent to the error. And denote by $T^{(1)} \subset T^{(0)}$ the right vertices such any of them is connect by at least $\frac{1}{2}\delta_0\Delta$ edges to vertices at $S^{(0)}$. Note that that any vertex in $V^-/T^{(1)}$ has on his local view less than $\frac{1}{2}\delta_0\Delta$ faulty bits, So it corrects into his right local view in the first right correction round. Therefore after the right correction round the error is set only on $T^{(1)}$'s neighbourhood, namely at size at most $\Delta |T^{(1)}|$. We will show that this amount is strictly lower by a constant factor than |e|.

First, let's use the expansion property (??) for getting an upper bound on $\mathcal{T}^{(1)}$ size:

$$\begin{aligned} \frac{1}{2}\delta_0 \Delta |T^{(1)}| &\leq \Delta \frac{|T^{(1)}||S^{(0)}|}{n} + \lambda \sqrt{|T^{(1)}||S^{(0)}|} \\ \left(\frac{1}{2}\delta_0 \Delta - \frac{|S^{(0)}|}{n}\Delta\right) |T^{(1)}| &\leq \lambda \sqrt{|T^{(1)}||S^{(0)}|} \\ |T^{(1)}| &\leq \left(\frac{1}{2}\delta_0 \Delta - \frac{|S^{(0)}|}{n}\Delta\right)^{-2} \lambda^2 |S^{(0)}| \end{aligned}$$

Since any left vertex adjoins to at most Δ faulty bits we have that $\Delta |S^{(0)}| \leq |e|$. Combing with the inequality above we get:

$$|\Delta|T^{(1)}| \leq \left(\frac{1}{2}\delta_0\Delta - \frac{|e|}{n}\right)^{-2}\lambda^2|e|$$

Hence for $|e|/n \le \beta = \frac{1}{2}\delta_0\Delta - \sqrt{2\lambda}$ it holds that $\Delta|T^{(1)}| \le \frac{1}{2}|e|$. Namely the error is reduced by half.

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The Franch's Construction.



Figure: Caption for the image



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