

# Hardness of Computing Fault Tolerance.

David Ponnarovsky

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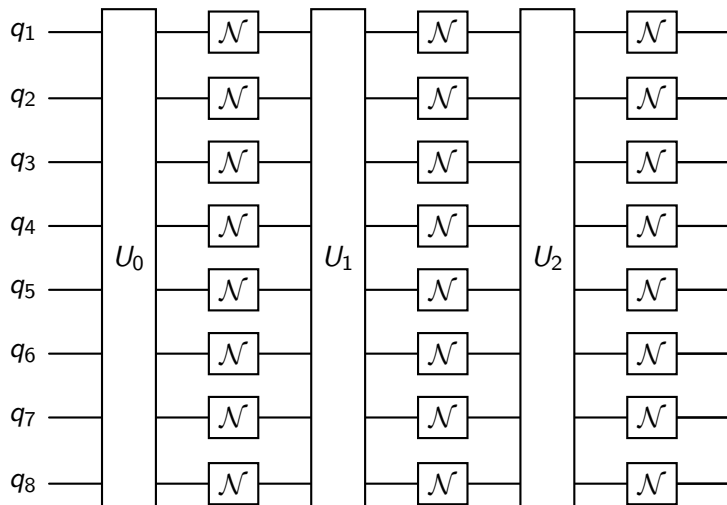
# Introduction

- ▶ Brief overview of the topic
- ▶ Importance and relevance
- ▶ Objectives of the presentation

# Key Points

- ▶ Main point 1
- ▶ Main point 2
- ▶ Main point 3

# Nosiy Circuit.



# Threshold Theorem.

# Pippenger's Construction.

Encode each bit with the repetition code  $0 \mapsto 0^m$ ,  $1 \mapsto 1^m$ . Now observe that any logical operation, without decoding, can be made in  $O(1)$  depth.

For example,  $\text{OR}(\bar{x}, \bar{y})$  can be computed by applying in parallel  $\text{OR}(x_i, y_i)$  for each  $i$ .

# The 'Decoding' trick.

Instead of completely decoding, we would apply only a single step of partial decoding. We assume that in each code block the bits are partitioned into random disjoint triples, and we will apply a local correction to each of the triples by majority.

## Claim

There are constants  $\alpha, \eta \in (0, 1)$  such that for any bit string  $x$  at a distance  $\leq \alpha n$  from the code (Repetition Code), one cycle of local correction on  $x$  yields  $x'$  such that:

$$d(x', C) \leq d(x, C)$$

# The 'Decoding' trick.

Suppose that a bit absorb a bit flip with probability  $p$ . So in expectation we expect that entire block at length  $n$  will absorb  $pn$  flips.

$$\eta(\beta + p)n \leq \beta n$$
$$\beta \geq \frac{p}{1 - \eta}$$



From now on, we will assume that the graphs are bipartite and we will denote the right and the left vertices by  $V^-$  and  $V^+$ . Notice that such expanders near Ramanujan exist, see for example [?]. The partition into two subsets enable us to come with a simple efficient decoder.

Expanders code are known for having good decoders, beneath, in ?? , we introduce a procedure to reduce an error. In overall, we alternately let to the right and then the left vertices to correct their own local view. In Theorem 1 we prove that when the applied error has size at most  $\beta n$ , for some constant  $\beta$  then the error's weight reduced by  $\frac{1}{2}$ . Repeating over the procedure  $\Theta(\log(n))$  times completely correct the error.

We will call to the first stage, when only the right vertices suggest correction the right round, and to the second stage a left round.  
For the whole procedure, we will call a single correction round.

**Data:**  $x \in \mathbb{F}_2^n$

**Result:**

$$\arg \min \{y \in C : |y + x|\}$$

if  $d(y, C) <$

1 **for**  $v \in V^+$  **do**

2      $x'_v \leftarrow$

$$\arg \min \{y \in C_0 : |y + x|_v|\}$$

3 **end**

4 **for**  $v \in V^-$  **do**

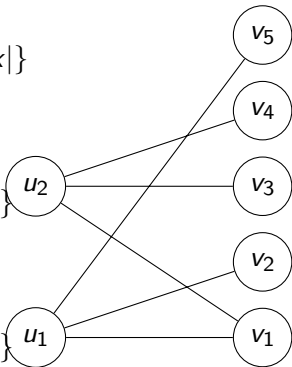
5      $x'_v \leftarrow$

$$\arg \min \{y \in C_0 : |y + x|_v|\}$$

6 **end**

7 **return**  $x$

: Single decoding round



(b) location.

## Lemma

If the error is at wight less than  $\beta n$  then a single round of the

### Proof.

Denote by  $S^{(0)} \subset V^+$  and  $T^{(0)} \subset V^-$  the subsets of left and right vertices adjacent to the error. And denote by  $T^{(1)} \subset T^{(0)}$  the right vertices such any of them is connect by at least  $\frac{1}{2}\delta_0\Delta$  edges to vertices at  $S^{(0)}$ . Note that that any vertex in  $V^-/T^{(1)}$  has on his local view less than  $\frac{1}{2}\delta_0\Delta$  faulty bits, So it corrects into his right local view in the first right correction round. Therefore after the right correction round the error is set only on  $T^{(1)}$ 's neighbourhood, namely at size at most  $\Delta|T^{(1)}|$ . We will show that this amount is strictly lower by a constant factor than  $|e|$ . First, let's use the expansion property (??) for getting an upper bound on  $T^{(1)}$  size:

$$\begin{aligned}\frac{1}{2}\delta_0\Delta|T^{(1)}| &\leq \Delta \frac{|T^{(1)}||S^{(0)}|}{n} + \lambda\sqrt{|T^{(1)}||S^{(0)}|} \\ \left(\frac{1}{2}\delta_0\Delta - \frac{|S^{(0)}|}{n}\Delta\right)|T^{(1)}| &\leq \lambda\sqrt{|T^{(1)}||S^{(0)}|} \\ |T^{(1)}| &\leq \left(\frac{1}{2}\delta_0\Delta - \frac{|S^{(0)}|}{n}\Delta\right)^{-2} \lambda^2 |S^{(0)}|\end{aligned}$$

# The Franch's Construction.

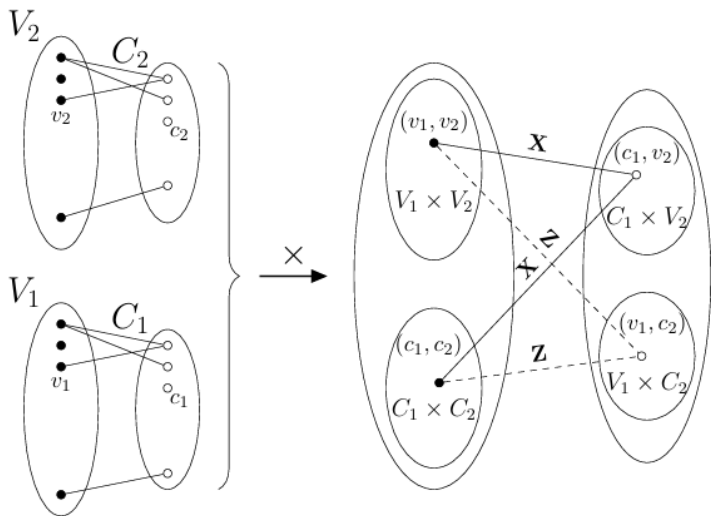


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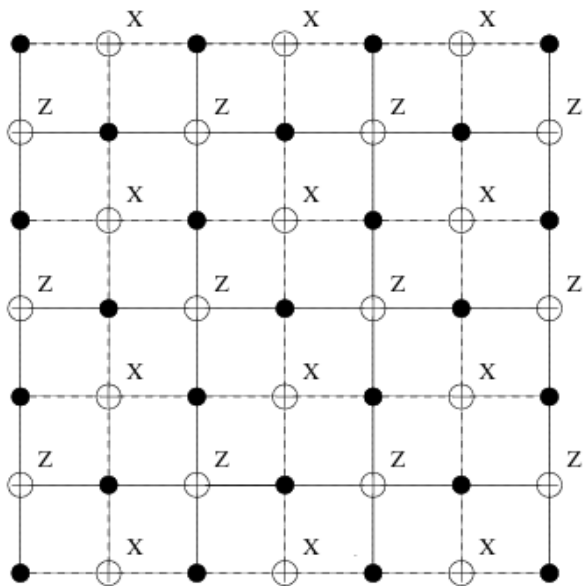


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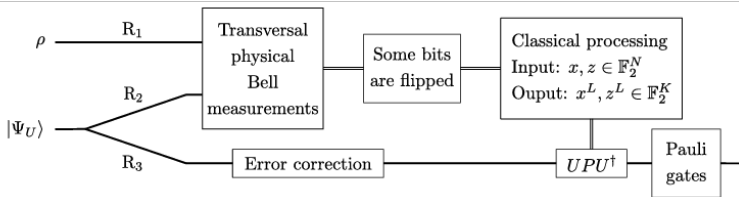


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