## Why The Following Doesn't Give Log-Local, Constant Gap Hamiltonian?

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## 1 What we would like to have:

Consider the LPS expander on n vertices and denote  $t \sim l$  if t is adjacent to l. Let  $M_{\Delta} \in \mathbb{C}^{n \times n}$  be the matrix defined by the product: [COMMENT] Such  $M_{\Delta}$  dosn't exists.

$$\langle u|M_{\Delta}|l\rangle^*\langle l+1|M_{\Delta}|t-1\rangle\langle t|M_{\Delta}|v\rangle = \mathbf{1}_{t\sim l}\mathbf{1}_{u=t}\mathbf{1}_{v=l}$$

Given the Hamiltonian  $H_{\text{init}} + m \cdot 2I - H_{\text{prop}} + H_{\text{end}}$ , consider the Hamiltonian  $\alpha H_{\text{init}} + m \cdot 2I - H_{\text{prop}} M_{\Delta} H_{\text{prop}} + \beta H_{\text{end}}$ . Denote  $H_{\text{prop}}$  by  $U_1 \otimes |2\rangle \langle 1| + U_2^{\dagger} \otimes |1\rangle \langle 2| + \cdots$ . Now let  $\Lambda_{t,l}$  be defined such that:

$$\Lambda_{l,t}^{\dagger} U_l^{\dagger} U_t \Lambda_{t,l} = U_l U_{l-1} ... U_{t+1} U_t$$

And consider the diagonalization  $W^{\dagger}H_{\text{prop}}M_{\Delta}H_{\text{prop}}W$ . Where:

$$\begin{split} W &= \sum \Lambda_{t,l} U_{t-1} U_{t-2} .. U_1 \otimes |t\rangle \left\langle t | M_{\Delta} \left| l \right\rangle \left\langle t \right| \\ \Rightarrow & W^{\dagger} = \sum U_1^{\dagger} U_2^{\dagger} .. U_{t-1}^{\dagger} \Lambda_{t,l}^{\dagger} \otimes |t\rangle \left\langle t | M_{\Delta} \left| l \right\rangle^* \left\langle t \right| \end{split}$$

Notice that:

$$\begin{split} W^{\dagger}U_{l}^{\dagger}U_{t}\left|l\right\rangle \left\langle l+1\right|M_{\Delta}\left|t-1\right\rangle \left\langle t\right|W &= \\ W^{\dagger}U_{l}U_{t}\left|l+1\right\rangle \left\langle l\right|M_{\Delta}\left|t\right\rangle \left\langle t\right|\left|t\right\rangle \left\langle t\right|M_{\Delta}\left|v\right\rangle \left\langle t\right|\Lambda_{t,v}U_{t-1}U_{t-2}..U_{1} &= \\ U_{1}^{\dagger}U_{2}^{\dagger}..\Lambda_{l,u}^{\dagger}U_{l-1}^{\dagger}U_{t}\Lambda_{t,l}U_{t-1}..U_{1}\left|l\right\rangle \left\langle l\right|M_{\Delta}\left|u\right\rangle^{*}\left\langle l\right|\left|l\right\rangle \left\langle l+1\right|M_{\Delta}\left|t-1\right\rangle \left\langle t\right|\left|t\right\rangle \left\langle l\right|M_{\Delta}\left|v\right\rangle \left|l\right\rangle \left\langle t\right| \\ U_{1}^{\dagger}..U_{l}^{\dagger}\Lambda_{l,t}^{\dagger}U_{l}^{\dagger}U_{t}\Lambda_{t,l}U_{t-1}..U_{1}\left|l\right\rangle \left\langle t\right| &= \left|l\right\rangle \left\langle t\right| \\ \Rightarrow W^{\dagger}H_{\mathrm{prop}}M_{\Delta}H_{\mathrm{prop}}W &= \sum_{i\sim j}\left|i\right\rangle \left\langle j\right| \end{split}$$

And the history state will look like:

$$\left|\eta\right\rangle = \sum \Lambda_{t,l} U_{t-1} U_{t-2} .. U_1 \left|x_0\right\rangle \otimes \left|t\right\rangle \left\langle t\right| M_{\Delta} \left|l\right\rangle$$

## 2 Lets change it a little bit.

Mabye we should define  $\Lambda$  to be depands on a single paramter, namely  $\Lambda_t$  and:

$$\Lambda_l^{\dagger} U_l^{\dagger} U_t \Lambda_t = U_l U_{l-1} ... U_{t+1}$$

That wil allow us to group terms, and if

$$\sum_{v,u} \langle u | D | l \rangle^* \langle l + 1 | M_{\Delta} | t - 1 \rangle \langle t | D | v \rangle = \mathbf{1}_{t \sim l}$$

Then we win. So now we ask wheter there exsits such  $D, M_{\Delta}$  and  $\Lambda_t$ 's. (Or approximation).

Claim 2.1. There are such  $\Lambda$ 's and they given by:

$$\Lambda_l^{\dagger} = U_l \Lambda_{l-1}^{\dagger} U_{l-1}^{\dagger} U_l$$

*Proof.* By induction, assume existness for any  $l, t \leq l-1$ , namely  $\Lambda_{l-1} = U_{l-1}^{\dagger} U_{l-2} \Lambda_{l-2} U_{l-1}^{\dagger}$ . Then:

$$\begin{split} \Lambda_l^\dagger U_l^\dagger U_t \Lambda_t = & \Lambda_l^\dagger U_l^\dagger U_{l-1} U_{l-1}^\dagger U_t \Lambda_t \\ & \Lambda_l^\dagger U_l^\dagger U_{l-1} \Lambda_{l-1} \Lambda_{l-1}^\dagger U_{l-1}^\dagger U_t \Lambda_t = \Lambda_l^\dagger U_l^\dagger U_{l-1} \Lambda_{l-1} \cdot \ U_{l-1}..U_{t+1} = \\ & U_l U_{l-1}..U_{t+1} = \\ & \Rightarrow \Lambda_l^\dagger = U_l \Lambda_{l-1}^\dagger U_{l-1}^\dagger U_l \end{split}$$

What about defining  $\tilde{D}=\langle t|\,\mathbf{1}_{t\sim l}\,|l\rangle,\,D=\tilde{D}/det(D)$  and  $\langle l+1|\,M_{\Delta}\,|t-1\rangle=\mathbf{1}_{t\sim l}1/\Delta^2$ ?

3 Ideas.

1.  $M_{\Delta}$  has to be unitar (and not just hermitan).

2.  $H_{\text{init}}$  and  $H_{\text{end}}$  are the critical terms and deserve more gentle treatment.