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למידת מכונה 5

2020 במאי 14

1 תרגיל

רי בארנו את $\mathcal{P}\left(y|x\right)=1$ בייס $\mathcal{P}\left(y|x\right)=1$ מצד שני מאחר ו $\mathcal{P}\left(y|x\right)\mathcal{P}\left(y\right)=\mathcal{P}\left(y|x\right)\mathcal{P}\left(x\right)$ בייס הגדרנו את $\mathcal{P}\left(y=1|x\right)\geq\frac{1}{2}$ מצד שני מאחר ו $\mathcal{P}\left(y=1|x\right)\geq\frac{1}{2}$ אז מתקיים כי אם $\mathcal{P}\left(y=1|x\right)\geq\frac{1}{2}$

$$\begin{split} h_{\mathcal{D}}\left(x\right) &= \arg\max_{y \in \{-1,1\}} \mathcal{P}\left(y|x\right) = \mathcal{P}\left(x\right) \arg\max_{y \in \{-1,1\}} \mathcal{P}\left(y|x\right) \overset{(1)}{=} \\ &= \arg\max_{y \in \{-1,1\}} \mathcal{P}\left(y|x\right) \mathcal{P}\left(x\right) = \arg\max_{y \in \{-1,1\}} \mathcal{P}\left(x|y\right) \mathcal{P}\left(y\right) \end{split}$$

. כאשר הכנסנו את x מאחר והוא מגדיל את כל האיברים מהם אנו מחלצים את המקסימום באופן זהה

:2 תרגיל 2

ולכן .arg $\max_y g(y) = \arg\max_y \ln\left(g(y)\right)$ נקבל כי ולכך ווער חזקה של פונקציית ה

$$\begin{split} &\Rightarrow h_{\mathcal{D}}\left(x\right) = \arg\max_{y \in \{-1,1\}} \mathcal{P}\left(x|y\right) \mathcal{P}\left(y\right) = \arg\max_{y \in \{-1,1\}} \ln\left(\mathcal{P}\left(x|y\right) \mathcal{P}\left(y\right)\right) = \\ &= \arg\max_{y \in \{-1,1\}} \left\{ \ln\left(\frac{1}{\sqrt{(2\pi)^{d} \det\left(\Sigma\right)}} e^{-\frac{1}{2}(x-\mu_{y})^{T} \Sigma^{-1}(x-\mu_{y})}\right) + \ln\left(\mathcal{P}\left(y\right)\right) \right\} = \\ &= \arg\max_{y \in \{-1,1\}} \left\{ \ln\left(\frac{1}{\sqrt{(2\pi)^{d} \det\left(\Sigma\right)}}\right) + \ln\left(e^{-\frac{1}{2}(x-\mu_{y})^{T} \Sigma^{-1}(x-\mu_{y})}\right) + \ln\left(\mathcal{P}\left(y\right)\right) \right\} = \\ &= \arg\max_{y \in \{-1,1\}} \left\{ \ln\left(e^{-\frac{1}{2}(x-\mu_{y})^{T} \Sigma^{-1}(x-\mu_{y})}\right) + \ln\left(\mathcal{P}\left(y\right)\right) \right\} = \arg\max_{y \in \{-1,1\}} \left\{ -\frac{1}{2}\left(x-\mu_{y}\right)^{T} \Sigma^{-1}\left(x-\mu_{y}\right) + \ln\left(\mathcal{P}\left(y\right)\right) \right\} = \\ &\arg\max_{y \in \{-1,1\}} \left\{ -\frac{1}{2}x^{T} \Sigma^{-1} x + x^{T} \Sigma^{-1} \mu_{y} - \frac{1}{2}\mu_{y}^{T} \Sigma^{-1} \mu_{y} + \ln\left(\mathcal{P}\left(y\right)\right) \right\} = \\ &\arg\max_{y \in \{-1,1\}} \left\{ x^{T} \Sigma^{-1} \mu_{y} - \frac{1}{2}\mu_{y}^{T} \Sigma^{-1} \mu_{y} + \ln\left(\mathcal{P}\left(y\right)\right) \right\} = \arg\max_{y \in \{-1,1\}} \delta_{y} \end{split}$$

3 תרגיל 3:

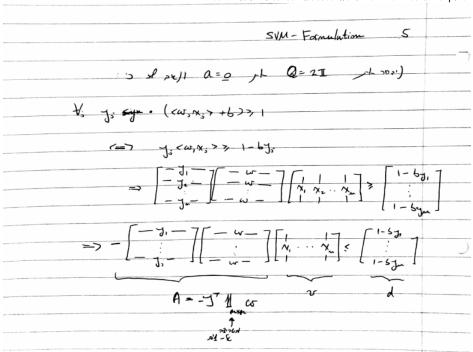
את μ_- את שב על ידי החישוב הרגיל על ה μ_+ ו μ_+ ו μ_+ ו החישוב של μ_+ ו μ_+ אבל גם μ_+ ו μ_+ אבל גם הרגיל על הואר פאוט. $\mu_\pm = Mean\left\{x|\left(x,y\right)=\left(x,\pm1\right)\right\}$ כאן זה מאוד פשוט.

4 תרגיל 4:

 $\{not-spam,true\}=False\ Positive$. ולכן נתייג כType-2-error: ולכן תייה ספאם תיהיה נורמטיבת כהודעת ספאם תיהיה ולכן נתייג כ $\{spam,\ false\}=True\ Positive.$

יהרגיל 5

אני מצרף תמונה בכתב יד מאחר וזה הרבה יותר ברור ככה:



6 תרגיל 6:

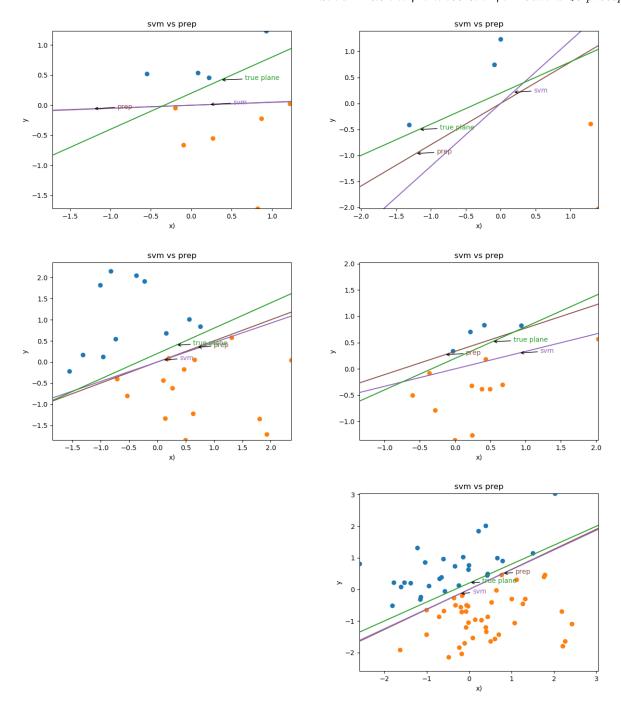
: נראה שקילות בין שתי הבעיות

$$\begin{split} \min_{\omega,\xi_i,y_i\langle\omega,x_i\rangle\geq 1-\xi_i} \frac{\lambda}{2}||\omega||^2 + \frac{1}{m}\sum_{i=1}^m \xi_i &= \min_{\omega,\omega,\xi_i,y_i\langle\omega,x_i\rangle\geq 1-\xi_i} \left\{\frac{\lambda}{2}||\omega||^2 + \frac{1}{m}\sum_{i=1}^m \min_{\xi_i} \xi_i\right\} = \\ &= \min\left\{\frac{\lambda}{2}||\omega||^2 + \frac{1}{m}\sum_{i=1}^m \left\{1-y_i\langle\omega,x_i\rangle & if \ 1-y_i\langle\omega,x_i\rangle\geq 0\\ 0 & otherwise \\ \end{bmatrix} = \\ &= \min_{\omega}\left\{\frac{\lambda}{2}||\omega||^2 + \frac{1}{m}\sum_{i=1}^m \max\left\{0,1-y_i\langle\omega,x_i\rangle\right\}\right\} \end{split}$$

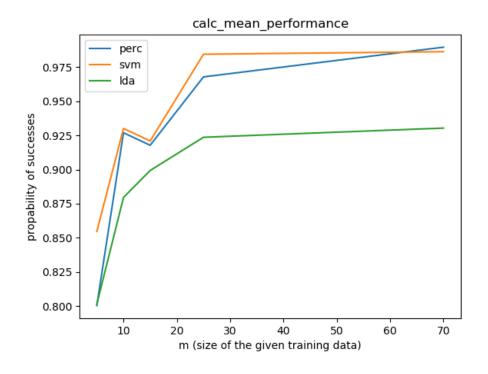
נשים לב שכל מעבר הוא בשיוון ולכן הבכרח פתרון של בעיה אחת פותר גם את הבעיה השניה.

השוואה בין שיטות למציאת ישר מפריד.

כל השיטות נמצאו יעילות מבחינת יכולת הדיוק, נציין ש LDA איטית באופן משמעותי, בעיקר השלב של מציאת המטריצה ההופכית (Σ^\dagger). הגרפים של : ניתן מתאחדים איך המישורים ניתן ניתן ניתן svmלעומת ליראות preception

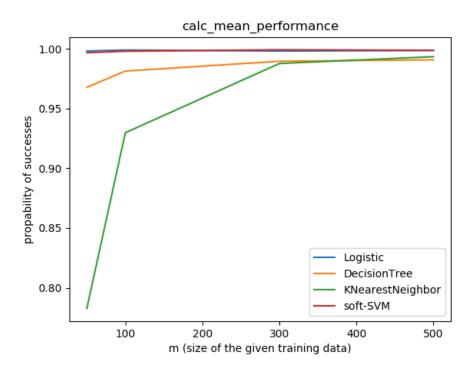


קל ליראות ש LDA לא נותן לנו שיערוך טוב. (כלומר כן טוב אבל פחות) אני מאמין שהוא סובל יותר מאובר פיט. מאחר ומראש הוא לא בהכרח מייצג מישור ולכן ספיציפית לבעייה הזאת הוא פחות מתאים.



: זיהוי ספרות

ההשוואה על זיהוי הספרות, אני חייב להגיש שממש הואשמתי מי מידת הדיוק. שיטת הSVM לקחה את רוב זמן החישוב כאשר על הקלטים הגדולים החישוב להגיש שממש הואשמתי ירדו מ0.025 שניות עבור הקלטים הגדולים. $\sim 0.05\,[sec]$ כל שאר השיטות ירדו מ0.025 שניות עבור הקלטים הגדולים.



2 ./comparsion.py

```
import numpy as np
    import pandas as pd
    from sklearn.svm import SVC
    from sklearn.linear_model import LogisticRegression
    from sklearn.tree import DecisionTreeClassifier
    from sklearn.neighbors import KNeighborsClassifier
    import matplotlib.pyplot as plt
    from mpl_toolkits.mplot3d import Axes3D # <--- This is important for 3d plotting</pre>
10
11
    import pandas as pd
12
    from pandas import DataFrame
    from plotnine import *
13
    import matplotlib as mpl
15
    import matplotlib.pyplot as plt
16
17
    from random import random
18
19
    from models import SVM, LDA, Perceptron
20
21
22
    def label_f(weight, bias):
23
         def _label_f(x):
24
25
             return np.sign( np.dot(weight, x) + bias)
        return _label_f
26
27
28
    def draw_points(m, label_function=label_f(np.array([0.3, -0.5]), 0.1)):
         {\tt def \_draw\_points\_n(m,n):}
29
30
             return np.random.multivariate_normal(
31
              np.zeros(n), np.identity(n), m)
32
         X = _draw_points_n(m, 2)
         y = np.array([ label_function(vec) for vec in X ])
34
35
         return X,y
36
    def analyze_clssifiers():
37
38
39
         # def generate_line_prec(prec):
40
41
         def plot(prec, _svm, X, y):
42
             plt.scatter( X[y == -1][:,0], X[y == -1][:,1])
plt.scatter( X[y == 1][:,0], X[y == 1][:,1])
43
45
46
             min_x, max_x = min(X[:,0]), max(X[:,0])
             min_y, max_y = min(X[:,1]), max(X[:,1])
47
             print(min_x, max_x)
48
             _min_range, _max_range = min(min_x, min_y) , max(max_x, max_y)
50
             print(prec.W)
51
             xx = [_min_range, _max_range]
53
54
                 return -(W[0] + _x * W[1]) / W[2] if W[2] != 0 else -W[0]
55
56
57
             def get_y_prep(_x):
                 return get_y(prec.W, _x )
58
59
```

```
60
              def get_y_svm(_x):
                  print(_svm.coef_()[0])
 61
 62
                   return get_y(_svm.coef_()[0], _x)
 63
              def get_true_y(_x):
 64
                  return 0.1/0.5 + 0.3/0.5 * _x
 65
 66
              plt.xlim([_min_range,_max_range])
 67
 68
              plt.ylim([_min_range,_max_range])
 69
 70
 71
              middle = (_min_range + _max_range) /2
 72
 73
 74
              def print_line(msg, _f, _color):
                  xx = [_min_range , _max_range ]
 75
 76
                  yy = [ f(x) for x in xx ]
                   _x = middle + 2 * (0.5 - random())
 77
                   _y = _f(_x)
 78
 79
                  plt.plot(xx, yy, color=_color )
                  plt.annotate(msg, color=_color,
 80
 81
                         xy=(_x, _y), xycoords='data',
                         xytext=(_x + 0.3 , _y), textcoords='data',
 82
                         arrowprops=dict(arrowstyle="->"))
 83
 84
 85
              print_line("prep", get_y_prep, "C5")
              print_line("svm" , get_y_svm , "C4")
print_line("true plane" , get_true_y , "C2")
plt.title("svm vs prep")
 86
 87
 88
 89
              plt.xlabel("x)")
 90
              plt.ylabel("y")
              plt.show()
 91
 92
 93
          for m in [5, 10, 15, 25, 70]:
              X, y = draw_points(m)
 94
 95
              blues, reds = X[y==1], X[y==-1]
              _modes = [Perceptron(), SVM()]
 96
              for _model in _modes:
 97
                   _model.fit(deepcopy(X),y)
 98
 99
              plot( _modes[0], _modes[1], X, y)
100
101
102
103
      def expanded_analyze_clssifiers():
          times, k = 500, 1000
104
          modles = []
105
106
          models_num = 3
107
108
109
          def genrate_real_plane(m):
               _f = label_f(np.array([random(), random()]), random())
110
111
              X, y = draw_points(m, label_function=_f )
112
              while (-1 not in y) or (1 not in y):
                   X, y = draw_points(m, label_function= _f)
113
              return X, y, _f
114
115
          def accur(mod, _f, Z):
116
              _prob = 0
117
              for x,y in zip(map(_f, Z), mod.predict(Z)):
118
119
                  if x == y:
                       _prob +=1
120
121
              return _prob/len(Z)
122
          def one_iteraion(m):
123
              _modes = [Perceptron(), SVM(), LDA()]
124
125
              X, y, _f = genrate_real_plane(m)
              ret = []
126
127
              for _model in _modes:
```

```
128
                  _{	t model.fit(deepcopy(X),y)}
                  Z, _ = draw_points(k)
129
                  ret.append( accur(_model, _f, Z) )
130
131
              return np.array(ret)
132
          def calc_mean_performance(M = [5, 10, 15, 25, 70] ):
133
134
              for m in M:
135
136
                  _mean = np.zeros(models_num)
                  for _ in range(times):
137
                  _mean += one_iteraion(m)
ret.append( _mean/ times )
138
139
              return M, np.array( ret )
140
141
142
          m, mean_performance = calc_mean_performance()
         for _model_num, _name in enumerate(["perc", "svm", "lda"]):
143
144
              print(mean_performance)
              plt.plot( m , mean_performance[:,_model_num] )
145
         plt.legend( ["perc", "svm", "lda"] )
146
147
          plt.title("calc_mean_performance")
148
          plt.xlabel("m (size of the given training data)")
          plt.ylabel("propability of successes")
149
150
         plt.show()
151
     if __name__ == "__main__" :
152
          X,y = draw_points(10)
153
          \#p = Perceptron()
154
155
156
157
         from copy import deepcopy
158
         models_class = [ Perceptron, SVM, Logistic, DecisionTree, LDA ]
159
160
         models = [ ]
161
          for mod in models_class:
              models.append( mod( ) )
162
163
              print("{} init ".format( type(mod) ))
164
          for mod in models:
165
              mod.fit(deepcopy(X),y)
166
              print("{} fit ".format( type(mod) ))
167
168
169
          for mod in models:
              print(mod.predict(deepcopy(X)))
170
171
              print("{} predict ".format( type(mod) ))
172
          analyze_clssifiers()
173
174
          expanded_analyze_clssifiers()
```

3 ./mnsit data.py

```
import pandas as pd
    import numpy as np
    import matplotlib.pyplot as plt
    import tensorflow as tf
    from models import Logistic, DecisionTree, KNearestNeighbor, SVM
    from copy import deepcopy
9
    import time
10
11
    def load_data():
12
        mnist = tf.keras.datasets.mnist
        (x_train, y_train),(x_test, y_test) = mnist.load_data()
13
        train_images = np.logical_or((y_train == 0), (y_train == 1))
        test_images = np.logical_or((y_test == 0), (y_test == 1))
15
16
        x_train, y_train = x_train[train_images], y_train[train_images]
        x_test, y_test = x_test[test_images], y_test[test_images]
17
18
19
        return x_train, y_train, x_test, y_test
20
21
22
    def rearrange_data(X):
        return np.array( [ x.flatten() for x in X ])
23
24
25
    def expanded_analyze_clssifiers(x_train, y_train, x_test, y_test):
26
27
        times, k = 50, 100
28
        modles = []
        models_num = 4
29
30
        def generate( m, X, y ):
31
            indexs = [False] * len(X)
32
             _indexs = np.random.choice( list(range(len(X)) ), size=m)
            for _index in _indexs:
34
35
                 indexs[_index] = True
36
            return X[indexs], y[indexs], indexs
37
38
        def accur(mod, indexs , Z):
39
40
            _prob = 0
41
            for x,y in zip(y_test[indexs], mod.predict(Z)):
                if x == y:
42
43
                    _prob +=1
            return _prob/len(Z)
45
46
        def one_iteraion(m):
             _modes = [Logistic(), DecisionTree(), KNearestNeighbor(), SVM()]
47
            X, y, indexs = generate(m, x_train, y_train)
48
            # your code
50
51
            while (0 not in y) or (1 not in y) :
53
54
                 X, y, indexs = generate(m, x_train, y_train)
            ret = []
55
56
            for _model in _modes:
57
                start_time = time.time()
                 _model.fit(deepcopy(X),y)
58
59
                elapsed_time = time.time() - start_time
```

```
60
                 print("train : {} takes {}".format(_model, elapsed_time))
                 Z, _, indexs = generate(k, x_test, y_test)
ret.append( accur(_model, indexs, Z) )
61
62
63
             return np.array(ret)
64
         def calc_mean_performance(M = [50, 100, 300, 500] ):
65
66
             for m in M:
67
68
                 _mean = np.zeros(models_num)
                 for _ in range(times):
69
70
71
                     _mean += one_iteraion(m)
                 ret.append( _mean/ times )
72
             return M, np.array( ret )
73
74
        m, mean_performance = calc_mean_performance()
75
         for _model_num, _name in enumerate(["Logistic", "DecisionTree", "KNearestNeighbor", "soft-SVM"]):
76
             plt.plot( m , mean_performance[:,_model_num] )
77
        plt.legend( ["Logistic", "DecisionTree", "KNearestNeighbor", "soft-SVM"] )
78
79
        plt.title("calc_mean_performance")
80
        plt.xlabel("m (size of the given training data)")
        plt.ylabel("propability of successes")
81
        plt.show()
82
83
84
    if __name__ == '__main__':
85
        x_train, y_train, x_test, y_test = load_data()
86
87
         expanded_analyze_clssifiers(rearrange_data(x_train),
         rearrange_data(y_train), rearrange_data(x_test), rearrange_data(y_test))
88
```

4 ./models.py

```
import numpy as np
    import pandas as pd
    {\tt from} \ {\tt sklearn.svm} \ {\tt import} \ {\tt SVC}
    from sklearn.linear_model import LogisticRegression
    from sklearn.tree import DecisionTreeClassifier
    from sklearn.neighbors import KNeighborsClassifier
    import matplotlib.pyplot as plt
    from mpl_toolkits.mplot3d import Axes3D # <--- This is important for 3d plotting</pre>
10
11
    import pandas as pd
    from pandas import DataFrame
12
    from plotnine import *
13
    import matplotlib as mpl
15
    import matplotlib.pyplot as plt
16
17
    from random import random
18
19
    class abcModel:
20
21
22
         def __init__(self):
             self.mod = None
23
24
25
         def fit(self, X, y):
26
             self.mod.fit(self.bias(X), y )
27
         def predict(self, X):
             return self.mod.predict(self.bias(X))
29
30
        def get_hyperplan(self):
31
32
             pass
        def bias(self, X):
34
             return np.insert(X,0, 1, 1)
35
        def draw(self):
37
38
             pass
39
        def score(self, X, y):
40
41
             return {
                     num_samples : 0,
42
43
                     error : 0,
                     accuracy :0,
                     FPR : 0,
45
46
                     TPR : 0,
                     precision : 0,
47
                     recall : 0
48
50
51
    class Perceptron(abcModel):
        def __init__(self):
53
54
             self.W = np.array( [] )
             super().__init__()
55
56
57
         def fit(self, _X, y):
             X = self.bias(_X)
58
59
```

```
60
             self.W = np.zeros( shape = X.shape[1] )
             def not_classifiy():
 61
                 return [ (x,y) for x in X if self.predict(x) != y ]
 62
             _updated = True
 64
 65
             while _updated:
                 _updated = False
 66
                 for i in range(len(y)):
 67
 68
                     if np.dot(self.W, X[i]) * y[i] <= 0:
                         self.W = self.W + (X[i]* y[i])
 69
                          _updated = True
 70
 71
             return self.W
 72
 73
         def predict(self, X):
 74
             return np.sign(self.W @ self.bias(X).transpose())
 75
 76
     class LDA(abcModel):
         def __init__(self):
 77
             super().__init__()
 78
 79
 80
         def fit (self, X, y):
 81
             X = self.bias(X)
 82
 83
 84
             def gen_delta_y(X ,y ,y_val):
                 _X = X[ y == y_val ]
 85
                 lnP = np.log(len(y == y_val) / len(y))
 86
 87
                 aritmetic_mean = np.array( [np.mean( u ) for u in _X.transpose()] )
 88
 89
                 _cov = np.cov( X.transpose() )
 90
                 _inv_cov = np.linalg.pinv(_cov)
 91
 92
                 def delta(x):
 93
                     return x.transpose() @ _inv_cov @ aritmetic_mean -\
 94
                      1nP
 95
 96
 97
 98
                 return delta
 99
             self.deltas = [ gen_delta_y(X ,y ,y_val) for y_val in [-1, 1] ]
100
101
         def predict(self, U):
102
             return np.array([{ 0 : -1.0, 1 : 1.0 }[np.argmax( [_delta(u) for _delta in self.deltas] ) ] for u in self.bias(U) ])
103
104
105
     class SVM(abcModel):
106
107
         def __init__(self):
             super().__init__()
108
109
             self.mod = SVC(C=1e10, kernel='linear')
110
         def coef_(self):
111
112
             return self.mod.coef_
113
114
     class Logistic(abcModel):
         def __init__(self):
115
             super().__init__()
116
             self.mod = LogisticRegression(solver='liblinear')
117
118
     class DecisionTree(abcModel):
119
120
         def __init__(self):
121
             super().__init__()
122
             self.mod = DecisionTreeClassifier()
123
     class KNearestNeighbor(abcModel):
124
125
         def __init__ (self):
    super().__init__()
126
127
```

```
128
               self.mod = KNeighborsClassifier(n_neighbors=40)
129
130
131
      def label_f(weight, bias):
132
          def _label_f(x):
133
               return np.sign( np.dot(weight, x) + bias)
134
          return _label_f
135
136
      def draw_points(m, label_function=label_f(np.array([0.3, -0.5]), 0.1)):
137
138
          def _draw_points_n(m,n):
139
               return np.random.multivariate_normal(
               np.zeros(n), np.identity(n), m)
140
141
142
          X = _draw_points_n(m, 2)
          y = np.array([ label_function(vec) for vec in X ])
143
144
          return X,y
145
      def analyze_clssifiers():
146
147
148
           # def generate_line_prec(prec):
149
150
          def plot(prec, _svm, X, y):
151
               plt.scatter( X[y == -1][:,0], X[y == -1][:,1])
plt.scatter( X[y == 1][:,0], X[y == 1][:,1])
152
153
154
155
               \min_{x, max_x = min(X[:,0]), max(X[:,0])}
               min_y, max_y = min(X[:,1]), max(X[:,1])
156
157
158
               _min_range, _max_range = min(min_x, min_y) , max(max_x, max_y)
               xx = [_min_range, _max_range]
159
160
161
               def get_y(W, _x):
                   return -(W[0] + _x * W[1])/ W[2] if W[2] != 0 else -W[0]
162
163
164
               def get_y_prep(_x):
                   return get_y(prec.W, _x )
165
166
               def get_y_svm(_x):
167
                   print(_svm.coef_()[0])
168
                   return get_y(_svm.coef_()[0], _x)
169
170
171
               def get_true_y(_x):
                   return 0.1/0.5 + 0.3/0.5 * _x
172
173
174
               plt.xlim([_min_range,_max_range])
               plt.ylim([_min_range,_max_range])
175
176
177
178
179
               middle = (_min_range + _max_range) /2
180
               def print_line(msg, _f, _color):
181
                   xx = [_min_range , _max_range ]
yy = [ _f(_x) for _x in xx ]
_x = middle + 2 * (0.5 - random())
182
183
184
                   _y = _f(_x)
185
                   plt.plot(xx, yy, color=_color )
186
187
                   plt.annotate(msg, color=_color,
                          xy=(_x, _y), xycoords='data',
188
189
                          xytext=(_x + 0.3, _y), textcoords='data',
190
                          arrowprops=dict(arrowstyle="->"))
191
               print_line("prep", get_y_prep, "C5")
192
               print_line("svm" , get_y_svm , "C4")
193
               print_line("true plane", get_true_y ,"C2")
plt.title("svm vs prep")
194
195
```

```
196
              plt.xlabel("x)")
197
              plt.ylabel("y")
198
              plt.show()
199
          for m in [5, 10, 15, 25, 70]:
200
201
              X, y = draw_points(m)
              blues, reds = X[y==1], X[y==-1]
202
              _modes = [Perceptron(), SVM()]
203
204
              for _model in _modes:
                  _model.fit(deepcopy(X),y)
205
206
              plot( _modes[0], _modes[1], X, y)
207
208
209
210
     def expanded_analyze_clssifiers():
          times, k = 7, 1000
211
212
          modles = []
213
         models_num = 3
214
215
216
          def genrate_real_plane(m):
              _f = label_f(np.array([random(), random()]), random())
217
              X, y = draw_points(m, label_function=_f )
218
              while (-1 not in y) or (1 not in y):
219
220
                   X, y = draw_points(m, label_function= _f)
221
              return X, y, _f
222
223
          def accur(mod, _f, Z):
224
              _prob = 0
225
              for x,y in zip(map(_f, Z), mod.predict(Z)):
226
                  if x == y:
                      _prob +=1
227
228
              return _prob/len(Z)
229
          def one_iteraion(m):
230
231
              _modes = [Perceptron(), SVM(), LDA()]
              X, y, _f = genrate_real_plane(m)
ret = []
232
233
              for _model in _modes:
234
                  print(type(_model))
235
236
                  _model.fit(deepcopy(X),y)
237
                  Z, _ = draw_points(k)
                  ret.append( accur(_model, _f, Z) )
238
239
              return np.array(ret)
240
          def calc_mean_performance(M = [5, 10, 15, 25, 70]):
241
242
              ret = []
              for m in M:
243
244
                  _mean = np.zeros(models_num)
245
                  for _ in range(times):
                       _mean += one_iteraion(m)
246
247
                  ret.append( _mean/ times )
248
              return M, np.array( ret )
249
250
          m, mean_performance = calc_mean_performance()
          for _model_num, _name in enumerate(["perc", "svm", "lda"]):
251
252
              print(_name)
253
              print(mean_performance)
              plt.plot( m , mean_performance[:,_model_num] )
254
255
          plt.legend( ["perc", "svm", "lda"] )
          plt.title("calc_mean_performance")
256
257
          plt.xlabel("m (size of the given training data)")
258
          plt.ylabel("propability of successes")
         plt.show()
259
260
     if __name__ == "__main__" :
261
          X,y = draw_points(10)
262
          #p = Perceptron()
263
```

```
^{264}
265
          from copy import deepcopy
266
267
          models_class = [ Perceptron, SVM, Logistic, DecisionTree, LDA ]
268
          models = [ ]
269
          for mod in models_class:
270
              models.append( mod( ) )
print("{} init ".format( type(mod) ))
271
272
273
          for mod \underline{in} models:
274
               mod.fit(deepcopy(X),y)
print("{} fit ".format( type(mod) ))
275
276
277
278
          for mod in models:
               print(mod.predict(deepcopy(X)))
279
               print("{} predict ".format( type(mod) ))
280
281
           #analyze_clssifiers()
282
           expanded_analyze_clssifiers()
283
```